# Maximal slicing for puncture evolutions of Schwarzschild and Reissner-Nordström black holes 

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#### Abstract

We prove by explicit construction that there exists a maximal slicing of the Schwarzschild spacetime such that the lapse has zero gradient at the puncture. This boundary condition has been observed to hold in numerical evolutions, but in the past it was not clear whether the numerically obtained maximal slices exist analytically. We show that our analytical result agrees with numerical simulation. Given the analytical form for the lapse, we can derive that at late times the value of the lapse at the event horizon approaches the value $\frac{3}{16} \sqrt{3} \approx 0.3248$, justifying the numerical estimate of 0.3 that has been used for black hole excision in numerical simulations. We present our results for the nonextremal Reissner-Nordström metric, generalizing previous constructions of maximal slices.


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## I. INTRODUCTION

When decomposing the 4-dimensional Einstein equations into (3+1)-dimensional form, a crucial role is played by the lapse function that determines how the 4-dimensional manifold is sliced into 3-dimensional hypersurfaces. For spatial hypersurfaces the lapse determines how time progresses between hypersurfaces. There is large freedom in choosing a lapse, but a particularly interesting possibility is to determine the lapse from the condition that the mean extrinsic curvature of the slices vanishes at all times. This condition corresponds to a certain maximal volume property of the hypersurface [1], and the resulting gauge condition is referred to as maximal slicing.

Maximal slicing has played an important role in both analytical and numerical work using $3+1$ decompositions. It was suggested as a geometrically motivated antifocusing slicing condition by Lichnerowicz [2] already in 1944; i.e., maximal slices avoid certain coordinate pathologies. Furthermore, maximal slicing helps to deal with physical singularities associated with black holes. For a single Schwarzschild black hole, maximal slicing can be constructed analytically [3,4]. One can obtain maximal slices that extend from the "right-hand" spatial infinity to the "left-hand" inner infinity of the extended Schwarzschild spacetime, and these slices give a complete foliation outside the event horizon while approaching a limiting slice inside that does not reach the physical singularity. In this sense maximal slices avoid the physical singularity, and even in more general situations maximal slices have been found to be singularity avoiding [5].

For these reasons, maximal slicing has been used frequently in numerical simulations of one black hole, e.g., Refs. [3,6,7], and also in binary black hole mergers in full 3D, e.g., Refs. [8,9]. The lapse for maximal slicing is obtained in general by solving an elliptic equation, but even though there now are algebraic lapse conditions that are computationally far less expensive and share the singularity avoidance property, maximal slicing is still being used when
smoothness of the lapse is an issue, say in the currently most advanced computations of gravitational waves from black hole mergers [10]. In addition, there are shift conditions [11] which in many cases overcome the so-called slice stretching problem of maximal slicing that previously limited black hole evolutions like Ref. [9] to short evolution times.

In this paper we establish the connection between the analytically known solutions for maximal slicing of the Schwarzschild spacetime [3,4] and the maximal slicing computed in the puncture evolution method for black holes [8]. In the puncture method, the left-hand asymptotically flat region of a black hole is effectively compactified by analytically factoring out a coordinate singularity and working on $R^{3}$, which can result in a significant technical simplification over approaches which implement an inner boundary for black hole excision. However, although the general solution to the linear elliptic equation for the maximal slicing lapse is known for Schwarzschild, this solution depends on the boundary condition imposed on the lapse. Only "odd" and "even" boundary conditions have been considered before, and the numerical lapse of the puncture evolutions is not of this type. Furthermore, there was no rigorous proof that in the presence of the puncture coordinate singularity a regular solution to the lapse equation exists, and while numerically quite robust, it was not clear that the numerics was able to reliably determine this lapse.

The key idea in this paper is to impose the numerically observed behavior of the lapse, namely that its first derivative vanishes at the puncture, as a novel boundary condition on the lapse. This boundary condition we call the "zero gradient at the puncture" (zgp) condition. Since it is the coordinate singularity at the puncture that implies the "zgp" condition, we refer to the resulting maximal slicing lapse also as the puncture lapse.

The main result of the paper is that we can prove by explicit construction that there exists a maximal slicing of the Schwarzschild spacetime such that the lapse has zero gradient at the puncture, and furthermore that our analytical result agrees with numerical simulation. Concretely, we ob-
tain the zgp or puncture lapse as a time-dependent linear superposition of the odd lapse and the even lapse. As an application of the analytical form for the puncture lapse, we can derive that at late times the value of the lapse at the right-hand event horizon approaches the value $\frac{3}{16} \sqrt{3}$ $\approx 0.3248$, justifying the numerical estimate of 0.3 that has been used for black hole excision in numerical simulations.

There are two technical difficulties to overcome. First, the analytic formulas of Refs. [3,4] are nontrivial, in particular the calculation is based on Schwarzschild coordinates which lead to complications in the numerical evaluation of the resulting integrals. And second, we have to establish an explicit mapping between the coordinates used in our analytical study and the numerical simulation before we can perform a comparison. In this paper we only consider the case of vanishing shift.

Since we have to discuss Refs. [3,4] in quite some detail, we take the opportunity to derive all relevant equations not only for Schwarzschild, but for a nonextremal ReissnerNordström black hole. This turns out to be possible without major changes to the formalism and extends in some places previous results [12].

The paper is organized as follows. In Sec. II, we recall the analytic solution to the lapse equation. In Secs. III and IV, we discuss in some detail the odd and even lapse, respectively, since these solutions will be superimposed to obtain the zgp lapse. Furthermore, in Sec. IV we make explicit contact between the equations given in Refs. [3] and [4]. In Sec. V, we construct the zgp lapse and discuss the late time limit of the lapse at the right-hand event horizon. In Sec. VI, we compare the analytical results for odd, even, and zgp maximal slices. In Sec. VII, we construct the coordinate transformation needed to make contact with the numerical zgp lapse and compare with our analytical result. We conclude in Sec. VIII.

## II. LAPSE FOR MAXIMAL SLICING OF THE REISSNER-NORDSTRÖM SPACETIME

To derive a differential equation for the lapse which maximally slices the Reissner-Nordström spacetime, we follow Ref. [3] closely. There in 1973-concentrating on even boundary conditions-Estabrook and Wahlquist were the first to find and Christensen, DeWitt, Smarr and Tsiang to verify numerically the analytic solution for maximal slicing of a Schwarzschild black hole. However, to simplify some calculations for a comparison of different boundary conditions imposed on this lapse, as done in Secs. III-V, the notation of Ref. [4] will be used to some extent and will be generalized to include electric charge. In the latter paper, Beig and O Murchadha re-derived this foliation based on a more geometrical ansatz and studied for even boundary conditions the late time behavior of the throat in the limit as proper time at infinity becomes arbitrarily large. We will make contact between formulas of those two references in Sec. IV.

We start with the source-free Einstein-Maxwell equations

$$
\begin{equation*}
G_{\mu \nu}:=R_{\mu \nu}-\frac{1}{2} R g_{\mu \nu}=8 \pi T_{\mu \nu}, \tag{1}
\end{equation*}
$$

$$
\begin{equation*}
\nabla^{\mu} F_{\mu \nu}=0 \tag{2}
\end{equation*}
$$

for a charged black hole, where the stress-energy tensor $T_{\mu \nu}$ is given in terms of the Maxwell tensor $F_{\mu \nu}$ by

$$
\begin{equation*}
T_{\mu \nu}=\frac{1}{4 \pi}\left(F_{\mu \sigma} F_{\nu}{ }^{\sigma}-\frac{1}{4} g_{\mu \nu} F_{\sigma \varrho} F^{\sigma \varrho}\right) \tag{3}
\end{equation*}
$$

The $3+1$ split of the equations in the ADM-formalism (see Arnowitt, Deser and Misner Ref. [13] or [1]) yields the Hamiltonian and momentum constraints

$$
\begin{align*}
& \mathcal{H}:=R+K^{2}-K_{i j} K^{i j}-16 \pi \rho=0  \tag{4}\\
& \mathcal{M}_{i}:=\nabla_{j}\left(K_{i}^{j}-\gamma_{i}^{j} K\right)+8 \pi s_{i}=0 \tag{5}
\end{align*}
$$

together with the evolution equations

$$
\begin{gather*}
\left(\partial_{t}-\mathcal{L}_{\beta}\right) \gamma_{i j}=-2 \alpha K_{i j}  \tag{6}\\
\left(\partial_{t}-\mathcal{L}_{\beta}\right) K_{i j}= \\
\left(-\nabla_{i} \nabla_{j}+R_{i j}+K K_{i j}-2 K_{i k} K_{j}^{k}\right) \alpha  \tag{7}\\
\\
-\left[8 \pi S_{i j}-4 \pi(S-\rho) \gamma_{i j}\right] \alpha
\end{gather*}
$$

Here the fundamental dynamical variables are the induced, positive definite 3-metric $\gamma_{i j}$ and the extrinsic curvature $K_{i j}$. Note that $\mathcal{L}_{\beta}$ is the Lie derivative with respect to the shift vector and $\nabla_{i}$ is the covariant spatial derivative associated with $\gamma_{i j}$. Furthermore, $R_{i j}$ is the 3-dimensional Ricci tensor and the Ricci scalar $R$ is its trace. The stress tensor $S_{i j}$, the momentum density vector $s_{i}$, and the total energy density $\rho$ are obtained as projections of the Maxwell stress-energy tensor $T_{\mu \nu}$ along the normal $n^{\mu}$ by

$$
\begin{equation*}
\rho=T_{\mu \nu} n^{\mu} n^{\nu}, \quad s_{i}=T_{i \mu} n^{\mu}, \quad \text { and } \quad S_{i j}=T_{i j} \tag{8}
\end{equation*}
$$

The mean extrinsic curvature

$$
\begin{equation*}
K:=\gamma_{i j} K^{i j}=-\nabla_{\mu} n^{\mu} \tag{9}
\end{equation*}
$$

measures the amount of "crunch," i.e., the fractional rate of contraction of 3 -volume along a unit normal to the surface.

In the following we want to restrict ourselves to maximal slicing,

$$
\begin{equation*}
K \equiv 0 \tag{10}
\end{equation*}
$$

The reason for its name can be inferred from a variational principle maximizing the volume

$$
\begin{equation*}
\mathcal{V}(\Omega)=\int_{\Omega} \sqrt{\operatorname{det}\left\{\gamma_{m n}\right\}} d^{3} x \tag{11}
\end{equation*}
$$

of a bounded but arbitrary portion $\Omega$ of the Cauchy slice $\Sigma$, where as pointed out by York in Ref. [1] it follows that the trace of the extrinsic curvature has to vanish. Contracting the evolution equation for $K_{i j}$, Eq. (7), in the context of $K \equiv 0$ one obtains the maximality condition

$$
\begin{equation*}
\triangle \alpha:=\nabla^{i} \nabla_{i} \alpha=\alpha[R+4 \pi(S-3 \rho)], \tag{12}
\end{equation*}
$$

which is an elliptic equation for the lapse function.

As in Refs. [3,4,12] the calculations are performed in the radial gauge

$$
\begin{equation*}
d s^{2}=\left(-\alpha^{2}+\frac{\beta^{2}}{\gamma}\right) d \tau^{2}+2 \beta d \tau d r+\gamma d r^{2}+r^{2} d \Omega^{2} \tag{13}
\end{equation*}
$$

with $\alpha, \beta$ and $\gamma$ being functions of $\tau$ and $r$ only. Whereas $\{t, r, \theta, \phi\}$ are the standard Schwarzschild coordinates with the Schwarzschild radius $r$ measuring the circumference divided by $2 \pi$ or the square root of area divided by $4 \pi$ of the 2 -sphere, the function $\tau=\tau(t, r)$ is clearly not.

Note furthermore that for the Maxwell tensor $F_{\mu \nu}$ of a purely radial electrostatic field one can make the ansatz

$$
F_{\mu \nu}=\left(\begin{array}{cccc}
0 & -E_{Q} & 0 & 0  \tag{14}\\
E_{Q} & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0
\end{array}\right),
$$

see, e.g., Chap. 18 of Ref. [14], and one can readily verify that

$$
\begin{equation*}
E_{Q}=\frac{Q \alpha \sqrt{\gamma}}{r^{2}} \tag{15}
\end{equation*}
$$

solves the source-free Maxwell's equation (2). For (static) Schwarzschild coordinates the classical result $E_{Q}=Q / r^{2}$ for the electric field of a point particle with charge $Q$ situated at the origin is recovered. Finally, the stress-energy tensor can be calculated according to Eq. (3) and its projections (8) are

$$
\begin{equation*}
\rho=\frac{Q^{2}}{8 \pi r^{4}}, \quad s_{i}=0, \quad \text { and } \quad S_{i j}=\rho \operatorname{diag}\left[-\gamma, r^{2}, r^{2} \sin ^{2} \theta\right] \tag{16}
\end{equation*}
$$

In addition, we observe that the trace of $S_{i j}$ coincides with $\rho$, $S:=\gamma^{i j} S_{i j}=\rho$.

One can readily show that the equation for the vanishing of the trace of the extrinsic curvature, $K \equiv 0$, can as in Eq. ( $1^{\prime}$ ) of Ref. [3] be written in the form

$$
\begin{equation*}
(\log \gamma)_{, \tau}=\frac{\beta}{\gamma}\left[\log \left(\frac{\beta^{2} r^{4}}{\gamma}\right)\right]^{\prime} \tag{17}
\end{equation*}
$$

which can be used in the following to eliminate derivatives of $\gamma$ with respect to $\tau$. After some rewriting, the Hamiltonian and momentum constraints, Eqs. (4) and (5), yield

$$
\begin{equation*}
r \frac{\gamma^{\prime}}{\gamma}-3 \frac{\beta^{2}}{\alpha^{2} \gamma}+\gamma\left(1-\frac{1}{\gamma}-\frac{Q^{2}}{r^{2}}\right)=0 \tag{18}
\end{equation*}
$$

and

$$
\begin{equation*}
\left(\log \left[\frac{r^{2} \beta}{\alpha \gamma}\right]\right)^{\prime}=0 \tag{19}
\end{equation*}
$$

respectively. Furthermore, the $\theta \theta$-component of the evolution equation of the extrinsic curvature, Eq. (7), is used to-
gether with the maximality condition (12), which for the radial gauge reduces to a condition involving the $r r$ and $\theta \theta$ component of Eq. (7) only, to obtain as further equations

$$
\begin{align*}
\left(\log \frac{\beta}{\alpha}\right)_{, \tau}= & -\left(\frac{\beta}{\gamma}+\frac{\alpha^{2}}{\beta}\right) \frac{\alpha^{\prime}}{\alpha}+\frac{3}{\gamma} \beta^{\prime}+\frac{1}{2}\left(\frac{\alpha^{2}}{\beta}-\frac{4 \beta}{\gamma}\right) \frac{\gamma^{\prime}}{\gamma} \\
& +\left(3 \frac{\beta}{\gamma}+\frac{\alpha^{2} \gamma}{\beta}-\frac{\alpha^{2}}{\beta}\right) \frac{1}{r}-\frac{Q^{2} \alpha^{2} \gamma}{r^{3} \beta} \tag{20}
\end{align*}
$$

and

$$
\begin{equation*}
\frac{\alpha^{\prime \prime}}{\alpha}+\left(\frac{2}{r}-\frac{1}{2} \frac{\gamma^{\prime}}{\gamma}\right) \frac{\alpha^{\prime}}{\alpha}-\frac{2}{r} \frac{\gamma^{\prime}}{\gamma}-\frac{2 \gamma}{r^{2}}\left(1-\frac{1}{\gamma}-\frac{Q^{2}}{2 r^{2}}\right)=0 . \tag{21}
\end{equation*}
$$

Equations (18)-(21) generalize the Schwarzschild black hole present in Eq. ( $\left.2^{\prime}\right)-\left(5^{\prime}\right)$ of Ref. [3] to a black hole carrying electric charge. (Note the correction of two signs in Ref. [3].)

The momentum constraint (19) immediately yields

$$
\begin{equation*}
\beta(\tau, r)=\frac{\alpha(\tau, r) \gamma(\tau, r)}{r^{2}} C(\tau) \tag{22}
\end{equation*}
$$

where $C$ is a function of $\tau$ only. This equation can be used to replace $\beta$ in the remaining equations such that from the Hamiltonian constraint a first-order partial differential equation (PDE) for $\gamma$ arises. Its solution is given by

$$
\begin{equation*}
\gamma(\tau, r)=\frac{1}{1-\frac{2 M}{r}+\frac{Q^{2}}{r^{2}}+\frac{C^{2}(\tau)}{r^{4}}}=\frac{r^{4}}{p_{C}(\tau, r)} \tag{23}
\end{equation*}
$$

where using the function

$$
\begin{equation*}
f(r)=1-\frac{2 M}{r}+\frac{Q^{2}}{r^{2}} \tag{24}
\end{equation*}
$$

for convenience the polynomial

$$
\begin{align*}
p_{C}(\tau, r) & =r^{4} f(r)+C^{2}(\tau) \\
& =r^{4}-2 M r^{3}+Q^{2} r^{2}+C^{2}(\tau) \tag{25}
\end{align*}
$$

has been introduced. Note that $M$, which arises as a constant of integration, could in principle be a function of $\tau$, however as in Ref. [3] it follows from the evolution equation (20) together with Eqs. (17), (22) and (23) that $M$ must be $\tau$-independent. It is worth pointing out that the radial metric function we obtain in Eq. (23) generalizes Eq. (9) of Ref. [3] by the charge, and the same 3-metric for maximal slicing of Reissner-Nordström as found by Duncan in Ref. [12] is obtained.

Finally, making use of $\beta$, Eq. (22), and $\gamma$, Eq. (23), the maximal slicing condition (17) reduces to

$$
\begin{equation*}
(\alpha \sqrt{\gamma})^{\prime}=-\frac{\gamma^{3 / 2}}{r^{2}} \frac{d C}{d \tau} \tag{26}
\end{equation*}
$$

which is the differential equation for the lapse we were looking for. By integration its general solution is found to be

$$
\begin{equation*}
\alpha(\tau, r)=\frac{\sqrt{p_{C}(\tau, r)}}{r^{2}}\left(D(\tau)+\frac{d C}{d \tau} \int_{r}^{\infty} \frac{y^{4} d y}{p_{C}(\tau, y)^{3 / 2}}\right) \tag{27}
\end{equation*}
$$

where $C$ and $D$ are functions of $\tau$ only and one integration limit has been fixed without loss of generality at spatial infinity. Three different boundary conditions leading to an odd, even, and puncture lapse will be discussed next.

## III. ODD LAPSE

## A. Derivation

The simplest special case of the lapse (27) is, because of its underlying antisymmetry with respect to the throat, referred to as odd (in some references also as antisymmetric) and corresponds to the boundary conditions

$$
\begin{equation*}
\lim _{r \rightarrow \infty} \alpha_{o d d}^{ \pm}= \pm 1 \quad \forall \tau_{o d d} \tag{28}
\end{equation*}
$$

To measure proper time at infinity (on the right-hand side of the throat denoted by a superscript " + ") the lapse is unity there and implied by the antisymmetry the lapse is minus 1 at the puncture (on the left-hand side and hence denoted by a "-"). The odd lapse

$$
\begin{equation*}
\alpha_{o d d}^{ \pm}(C, r)= \pm \sqrt{f(r)+\frac{C^{2}}{r^{4}}}= \pm \frac{\sqrt{p_{C}(r)}}{r^{2}} \tag{29}
\end{equation*}
$$

is obtained by setting $D\left(\tau_{o d d}\right)= \pm 1$ and $d C / d \tau_{o d d}=0$. The time-independent slice label $C$ can be chosen independent of the time at infinity $\tau_{o d d}$ and is, as pointed out for Schwarzschild in Appendix A of Ref. [4], purely gauge for ReissnerNordström.

## B. Schwarzschild lapse

The outer event horizon and inner Cauchy horizon at $r_{ \pm}$ $=M \pm \sqrt{M^{2}-Q^{2}}$ are given by the real roots of $f(r)$, which are time independent, while the throat $r_{C}$ is obtained as a real root of $p_{C}(r)$ and therefore depends on the choice of $C$. Hence, starting with the throat in the same location as the event horizon implies $C=0$. In this case one obtains from Eq. (29) the so-called Schwarzschild lapse

$$
\begin{equation*}
\alpha_{o d d}^{ \pm}(C=0, r)= \pm \sqrt{f(r)} \tag{30}
\end{equation*}
$$

from Eq. (23) the radial component of the metric

$$
\begin{equation*}
\gamma(r)=\frac{1}{f(r)}, \tag{31}
\end{equation*}
$$

and from Eq. (22) a vanishing shift. Hence the static Reissner-Nordström metric written in Schwarzschild coordinates,

$$
\begin{equation*}
d s^{2}=-f(r) d t^{2}+\frac{1}{f(r)} d r^{2}+r^{2} d \Omega^{2} \tag{32}
\end{equation*}
$$

is recovered identifying $Q$ with the charge and $M$ with the mass of the black hole $(0 \leqslant|Q|<M)$.

This result was of course expected, since it is well known that with this coordinate choice the spacelike slices given by $t=$ const, being perpendicular to the timelike Killing vector in the exterior regions, are maximal. That one can immediately see from the definition of the extrinsic curvature $K_{i j}$, Eq. (6), which for zero shift reduces to

$$
\begin{equation*}
K_{i j}=-\frac{1}{2 \alpha} \gamma_{i j}^{-} \quad \text { if } \quad \beta \equiv 0 . \tag{33}
\end{equation*}
$$

Since the 3-metric $\gamma_{i j}$ is time independent, each of the components and therefore also the trace of the extrinsic curvature vanishes, hence $K \equiv 0$. Note furthermore that by contraction of Eq. (33) setting $K \equiv 0$ one immediately obtains the statement that for maximal slicing with vanishing shift the determinant of the 3-metric is time independent. Hence the singularity avoiding property comes to light as the variation of the local volume remains fixed [15].

## C. Isotropic lapse

By applying for vanishing shift a purely spatial coordinate transformation $r=r(R)$, the hypersurfaces obviously remain maximal. To obtain isotropic coordinates by writing $d r^{2}$ $=(d r / d R)^{2} d R^{2}$ and by comparing the $d t^{2}, d r^{2}$ and $d \Omega^{2}$ terms the set of equations

$$
\begin{align*}
\alpha_{o d d}^{ \pm 2}(C=0, R) & =f(r(R))  \tag{34}\\
\Psi^{4}(R) & =\frac{1}{f(r(R))}\left(\frac{d r}{d R}\right)^{2},  \tag{35}\\
R^{2} \Psi^{4}(R) & =r(R)^{2} \tag{36}
\end{align*}
$$

is read off. From Eqs. (35) and (36) the ordinary differential equation (ODE)

$$
\begin{equation*}
\frac{d r}{d R}= \pm \sqrt{f(r(R))} \frac{r(R)}{R} \tag{37}
\end{equation*}
$$

can be inferred where $r$ can take values $r \geqslant r_{+}$only. By integration the solution is found to be given by

$$
\begin{align*}
r(R) & =R\left[\left(1+\frac{M}{2 R}\right)^{2}-\frac{Q^{2}}{4 R^{2}}\right] \\
& =R+M+\frac{M^{2}-Q^{2}}{4 R}, \tag{38}
\end{align*}
$$

choosing an arbitrary constant of integration such that $r$ and $R$ coincide at infinity. With $R_{+}=\frac{1}{2} \sqrt{M^{2}-Q^{2}}$ corresponding to $r_{+}$this relation can also be piecewise inverted to yield

$$
R(r)=\left\{\begin{array} { l } 
{ \frac { 1 } { 2 } \{ - M + r [ 1 - \sqrt { f ( r ) } ] \} }  \tag{39}\\
{ \frac { 1 } { 2 } \{ - M + r [ 1 + \sqrt { f ( r ) } ] \} }
\end{array} \quad \text { for } \quad \left\{\begin{array}{c}
0 \leqslant R \leqslant R_{+} \\
R \geqslant R_{+}
\end{array}\right.\right.
$$

From Eq. (34) follows the isotropic lapse

$$
\begin{equation*}
\alpha_{o d d}^{ \pm}(C=0, R)=\frac{(2 R+M)(2 R-M)+Q^{2}}{(2 R+M)^{2}-Q^{2}} \tag{40}
\end{equation*}
$$

and from Eq. (36) one can read off the conformal factor

$$
\begin{equation*}
\Psi^{4}(R)=\left[\left(1+\frac{M}{2 R}\right)^{2}-\frac{Q^{2}}{4 R^{2}}\right]^{2} \tag{41}
\end{equation*}
$$

Hence the Reissner-Nordström metric in isotropic coordinates as found, e.g., in Ref. [16] is recovered which for vanishing charge reduces to the well-known Schwarzschild case.

## D. Isometry

For the case $0 \leqslant|Q|<M$, one can see from the coordinate transformation (38) that there is an isometry present, since the value of $r$ and therefore also the line element (32) remains the same under a mapping

$$
\begin{equation*}
R \leftrightarrow \frac{M^{2}-Q^{2}}{4 R} . \tag{42}
\end{equation*}
$$

These two values of $R$ for every value of $r>r_{+}$result in two isometric parts of the spacetime (in terms of KruskalSzekeres diagrams the regions I and $\mathrm{I}^{\prime}$ in Fig. 3 for Schwarzschild). In particular, $R=0$ is simply a compactified image of infinity in the other universe referred to as puncture. The fixed point set at the event horizon $r_{+}$is a minimal 2 -sphere of an Einstein-Rosen bridge [17] located at $R_{+}$, the so-called throat (see the embedding diagram of Fig. 2).

Note also that the odd lapse in isotropic coordinates, Eq. (40), changes its sign with positive values on the right-hand side of the throat being the original unextended space and negative ones on the left-hand additional region obtained by analytic extension of the spacetime. In particular, the odd lapse vanishes on the throat, i.e., $\alpha^{ \pm}\left(C=0, R_{+}\right)=0$ (cf. the lapse profile as shown for Schwarzschild in the upper plot of Fig. 6).

## IV. EVEN LAPSE

## A. Derivation I (via Einstein-Maxwell equations)

The even lapse is symmetric with respect to the throat and its boundary conditions are usually stated as unit lapse at infinity and a vanishing gradient at the throat. Since by symmetry time has to run equally fast at both spatial ends of the manifold, one can also formulate even boundary conditions as

$$
\begin{equation*}
\lim _{r \rightarrow \infty} \alpha_{\text {even }}^{ \pm}=1 \quad \forall \tau_{\text {even }} . \tag{43}
\end{equation*}
$$

This motivates for the differential equation obtained for the lapse in Eq. (27) the particular choice $D\left(\tau_{\text {even }}\right)=1$ made by Estabrook et al. and generalized here, so

$$
\begin{equation*}
\alpha_{\text {even }}^{ \pm}(C, r)=\frac{\sqrt{p_{C}(r)}}{r^{2}}\left(1+\frac{d C}{d \tau_{\text {even }}} \int_{r}^{\infty} \frac{y^{4} d y}{p_{C}(y)^{3 / 2}}\right) . \tag{44}
\end{equation*}
$$

Since one starts with the 3-geometry of the $t=\tau_{\text {even }}=0$ hypersurface, i.e., with the initial radial component of the 3-metric given by $\gamma=1 / f(r)$, one can infer from Eq. (23) that $C\left(\tau_{\text {even }}=0\right)=0$ initially. The function $C\left(\tau_{\text {even }}\right)$ though is still undetermined as only single sheets of the 3-geometry labeled by $C$ have been looked at so far. As stated in Ref. [3], the $\tau_{\text {even }}$-dependence of $C$ can be fixed by imposing the requirement of smoothness across the Einstein-Rosen bridge by passing to the Reissner-Nordström line element (32) in Schwarzschild coordinates. For the "height function" $t$ $=t\left(C\left(\tau_{\text {even }}\right), r\right)$, comparing $d \tau_{\text {even }}^{2}, d \tau_{\text {even }} d r$ and $d r^{2}$ terms of the metric the following two PDE's:

$$
\begin{gather*}
\frac{\partial t}{\partial \tau_{\text {even }}}=\alpha_{\text {even }}^{ \pm} \frac{r^{2}}{\sqrt{p_{C}(r)}},  \tag{45}\\
\frac{\partial t}{\partial r}=-\frac{C}{f(r) \sqrt{p_{C}(r)}}, \tag{46}
\end{gather*}
$$

are found. Making for Eq. (46) the ansatz

$$
\begin{equation*}
t:=t_{\text {even }}(C, r)=-\int_{s_{C}}^{r} \frac{C d y}{f(y) \sqrt{p_{C}(y)}}, \tag{47}
\end{equation*}
$$

one finds that this equation also satisfies Eqs. (44) and (45) for $s_{C}$ coinciding with $r_{C}$. The latter is the unique (double counting for $C=C_{\text {lim }}$ ) larger real root of the polynomial $p_{C}(r)$ in $\left[r_{C_{l i m}}, r_{+}\right]$and determines the radial coordinate of the throat on a given maximal slice. Hence

$$
\begin{equation*}
t_{\text {even }}(C, r)=H_{C}(r), \tag{48}
\end{equation*}
$$

where we have introduced the integral

$$
\begin{equation*}
H_{C}(r):=-\int_{r_{C}}^{r} \frac{C d y}{f(y) \sqrt{p_{C}(y)}} \tag{49}
\end{equation*}
$$

for $r \geqslant r_{C}$. Note that in Eq. (49) the integration across the pole at $r_{+}$is taken in the sense of the principal value, and by the same arguments as in Ref. [4] the corresponding slices extend smoothly through the event horizon $r_{+}$and throat $r_{C}$.

The procedure of deriving Eqs. (48) with (49) is nontrivial as pointed out in detail in Ref. [3]: The requirement of smoothness across the bridge is $t_{\text {even }} \rightarrow 0$ and $(\partial / \partial r) t_{\text {even }}$ $\rightarrow \infty$ as $r$ approaches its smallest value $r_{C}$ at the center of the bridge, or in terms of Kruskal-Szekeres coordinates $(\partial / \partial X) T=0$ as $X \rightarrow 0$. As mentioned in Ref. [18], this fixes
the value of $C\left(r_{C}\right)$ such that $p_{C}\left(r_{C}\right)=0$ holds. In particular, with $r_{C}$ becoming at infinite times a double counting root $r_{C_{\text {lim }}}$ with the value

$$
\begin{equation*}
r_{C_{l i m}}=\frac{1}{4}\left(3 M+\sqrt{9 M^{2}-8 Q^{2}}\right)>0 \tag{50}
\end{equation*}
$$

corresponding to

$$
\begin{align*}
C_{\text {lim }} & :=C\left(\tau_{\text {even }}=\infty\right) \\
& =\frac{\sqrt{2}}{8} \sqrt{27-36 \frac{Q^{2}}{M^{2}}+8 \frac{Q^{4}}{M^{4}}+\left(9-8 \frac{Q^{2}}{M^{2}}\right)^{3 / 2}} M^{2}, \tag{51}
\end{align*}
$$

the singularity avoidance of the maximal slicing of the extended Reissner-Nordström spacetime as proven in corollary 3.8 in Ref. [5] becomes clear.

Finally, since $t_{\text {even }}(r)$ and $\tau_{\text {even }}$ have to coincide at spatial infinity modulo an arbitrary constant, which can be set to zero, from Eq. (48) in the limit $r \rightarrow \infty$ one can infer

$$
\begin{equation*}
\tau_{\text {even }}(C)=\lim _{r \rightarrow \infty} t_{\text {even }}(C, r)=H_{C}(\infty) \tag{52}
\end{equation*}
$$

We want to stress that in Eq. (47) the particular choice of the larger root of $p_{C}(r)$ has been made since we are interested in the "horizon-horizon" subfamily of maximal slices only, which extend to both spatial infinities. Here the slices start with the initial hypersurface representing the 3 -geometry at the moment of time symmetry when the throat is at the event horizon $r_{+}$and develop inward to approach $r_{C_{\text {lim }}}$ asymptotically and hence avoid the singularity. As pointed out in remark 8 of Ref. [3] and in Sec. III of Ref. [12], a second "singularity-singularity" subfamily of maximal slices can be obtained choosing the unique (double counting for $C$ $=C_{\text {lim }}$ ) minor real root $\hat{r}_{C}$ of $p_{C}(r)$ in $\left[r_{-}, r_{C_{\text {lim }}}\right]$ instead. The initial hypersurface is now the time-symmetric slice with the throat at the Cauchy horizon $r_{-}$and the slices intersecting the singularity at $r=0$ grow outward to the limiting surface $r_{C_{l i m}}$. As discussed in the next subsection, one can compare the situation with the mechanical analogue of a particle of energy $E=C^{2}$ travelling in a repulsive potential $V(r)=-r^{4} f(r)$, where $r_{C}$ and $\hat{r}_{C}$ represent turning points (cf. Fig. 1). Thinking of particles with energies ranging from $E=0$ to $E_{\text {lim }}=V\left(r_{C_{\text {lim }}}\right)=C_{\text {lim }}^{2}$ it is clear that both subfamilies together cover the spacetime with spacelike maximal slices (cf. the Kruskal-Szekeres diagram for Schwarzschild and the Carter-Penrose diagram for Reissner-Nordström in Fig. 1 of Refs. [3] and [12], respectively). For its limited use in numerical relativity, however-as the slices lie always completely inside the event horizon and hit the singularity-we will not investigate the "singularitysingularity" subfamily further.


FIG. 1. For maximal slicing of Schwarzschild the mechanical analogue consisting of a particle of energy $E=C^{2}$ travelling in a repulsive potential $V=-r^{4} f(r)$ is shown. For the energy levels $E$ $=\left\{0,{ }^{0} C_{\text {lim }}^{2} / 2,{ }^{0} C_{\text {lim }}^{2}\right\}$ the innermost and outermost radial distances for unbounded and bounded particles denoted by ${ }^{0} r_{C}$ and ${ }^{0} \hat{r}_{C}$, respectively, can be inferred.

## B. Contact between Refs. [3] and [4] by a mechanical analogue

To make contact between formulas found by Estabrook et al. [3] and those derived by Beig and Ó Murchadha [4], one can apply an energy conservation equation worked out in Appendix B of the latter paper. There two functions $F$ and $J$ are introduced by

$$
\begin{align*}
& F(E, r)=\int_{x_{E}}^{r} \frac{W(y) d y}{\sqrt{E-V(y)}}  \tag{53}\\
& J(E, r)=\int_{x_{E}}^{r} \sqrt{E-V(y)} V(y) W(y) d y \tag{54}
\end{align*}
$$

In the following, $W$ may have a simple pole at $x=\bar{x}$ and $V$ mapping $x_{E}$ to $E$ and $\bar{x}$ to 0 is a smooth function $V:\left[x_{0}\right.$, $\infty\left[\rightarrow R\right.$ satisfying $0<E<V\left(x_{0}\right), V(x)<E$, and $V^{\prime}(x)<0$ for $x>x_{0}$. By differentiating $J$ twice with respect to $E$ the formula

$$
\begin{align*}
4 \frac{\partial^{2}}{\partial E^{2}} J(E, x)= & -\frac{2}{\sqrt{E-V(x)}} \frac{V(x) W(x)}{V^{\prime}(x)} \\
& +\int_{x_{E}}^{x} \frac{2}{\sqrt{E-V(y)}} \frac{d}{d y}\left[\frac{V(y) W(y)}{V^{\prime}(y)}\right] d y \\
= & F(E, x)+2 E \frac{\partial}{\partial E} F(E, x) \tag{55}
\end{align*}
$$

is derived, cf. Eqs. (B7) and (B9) in Ref. [4].
Now, as pointed out in Ref. [19] using proper velocity $d s / d \tau$, i.e., the rate of change of proper time along a maximal hypersurface with proper distance, from

$$
\begin{equation*}
E=C^{2}=C^{2}\left(\frac{d s}{d \tau}\right)^{2}-r^{4} f(r)=T+V \tag{56}
\end{equation*}
$$

an energy conservation equation arises for a particle of total energy $E=C^{2}$ moving in the repulsive potential $V=$ $-r^{4} f(r)$ with a kinetic energy $T=C^{2}(d s / d \tau)^{2}$. By demanding $d s / d \tau=0$ for unbounded particles starting from infinity the closest approach to the singularity-or for bounded ones starting from the singularity the outermost radial distance-is found to be given by the two real roots $r_{C}$ and $\hat{r}_{C}$ of the polynomial $p_{C}(r)$, cf. Fig. 1. Furthermore, Beig and Ó Murchadha [4] point out that for $E>E_{\text {lim }}$ with $E_{\text {lim }}$ $=V\left(r_{C_{\text {lim }}}\right)=C_{\text {lim }}^{2}$ maximal slices hitting the singularity at $r$ $=0$ are obtained [53]. They also argue that $F(E, r)$ can be thought of as the time it takes a particle of energy $E$ to travel from $r_{C}$ to $r$. In particular, in an analysis following in a later paper [20] based on Refs. [4,21] we will be interested in the way this function blows up as $E$ approaches with $C_{l i m}^{2}$ the maximum of the potential in order to study the late time behavior of the slices.

One can readily check that the identifications

$$
\begin{equation*}
W(r)=-\frac{1}{f(r)}, \quad V(r)=-r^{4} f(r), \quad E=C^{2} \tag{57}
\end{equation*}
$$

and

$$
\begin{equation*}
r_{0}=r_{C_{\text {lim }}}, \quad r_{E}=r_{C}, \quad \bar{r}=r_{+} \tag{58}
\end{equation*}
$$

satisfy the conditions on $W, V$, and $E$ as stated above also in the Reissner-Nordström case and lead to

$$
\begin{equation*}
H_{C}(r)=C F\left(C^{2}, r\right) \tag{59}
\end{equation*}
$$

Hence for the derivative of $H_{C}(r)$ with respect to $C$ the important formula

$$
\begin{align*}
\frac{\partial}{\partial C} H_{C}(r) & =F+2 C^{2} \frac{\partial}{\partial C^{2}} F \\
& =\frac{r^{2}}{2\left(r-\frac{3}{2} M+\frac{Q^{2}}{2 r}\right) \sqrt{p_{C}(r)}}-\frac{1}{2} K_{C}(r) \tag{60}
\end{align*}
$$

can be derived by straightforward calculation using Eq. (55), where for $r \geqslant r_{C}$ we have introduced the integral

$$
\begin{equation*}
K_{C}(r):=\int_{r_{C}}^{r} \frac{y\left(y-3 M+\frac{3 Q^{2}}{2 y}\right) d y}{\left(y-\frac{3}{2} M+\frac{Q^{2}}{2 y}\right)^{2} \sqrt{p_{C}(y)}} . \tag{61}
\end{equation*}
$$

Note that $K_{C}(r)$ diverges in the limit $C \rightarrow C_{l i m}$ as $r_{C_{l i m}}$ becomes a double root of $p_{C}(r)$, the square root of which appears in the denominator of the integrand. Note furthermore that from Eq. (60) in the limit $r \rightarrow \infty$ the equation

$$
\begin{equation*}
\frac{d}{d C} H_{C}(\infty)=-\frac{1}{2} K_{C}(\infty) \tag{62}
\end{equation*}
$$

is found, cf. Eq. (B12) in Ref. [4].
In order to write the expression (44) for the even lapse in terms of the integral $K_{C}(r)$, one can readily verify that

$$
\begin{align*}
\frac{\partial}{\partial C}\left[t_{\text {even }}(C, r)-\tau_{\text {even }}(C)\right] & =\frac{\partial}{\partial C}\left[H_{C}(r)-H_{C}(\infty)\right] \\
& =\int_{r}^{\infty} \frac{y^{4} d y}{p_{C}(y)^{3 / 2}} \tag{63}
\end{align*}
$$

holds and hence the even lapse can be written as

$$
\begin{align*}
\alpha_{\text {even }}^{ \pm}(C, r) & =\frac{\sqrt{p_{C}(r)}}{r^{2}} \frac{d C}{d \tau_{\text {even }}} \frac{\partial t_{\text {even }}}{\partial C} \\
& =-\frac{1}{K_{C}(\infty)}\left(\frac{1}{r-\frac{3}{2} M+\frac{Q^{2}}{2 r}}-\frac{\sqrt{p_{C}(r)}}{r^{2}} K_{C}(r)\right), \tag{64}
\end{align*}
$$

which generalizes Eqs. (2.23) and (2.24) in Ref. [4] by the charge. By the same arguments as applied for Schwarzschild in this reference, the term $\left(d C / d \tau_{\text {even }}\right)\left(\partial t_{\text {even }} / \partial C\right)$ in the first line of Eq. (64) blows up at the throat, i.e., for $r \rightarrow r_{C}$, in such a way that the lapse has a smooth limit there. To our knowledge the lapse function formulated in Eq. (44) or (64) for maximal slicing Reissner-Nordström (i.e., with electric charge included) has not appeared in the literature yet.

For Schwarzschild, the even lapse profile in terms of the Schwarzschild radial coordinate $r$ for the times at infinity $\tau_{\text {even }}=\{0,1 M, 2 M, 4 M, 8 M\}$ is shown in Fig. 6.

Recalling that the shift is given by Eq. (22) and the radial component of the metric by Eq. (23), with

$$
\begin{equation*}
\beta_{\text {even }}(C, r)=\frac{\alpha_{\text {even }}(C, r) \gamma_{\text {even }}(C, r)}{r^{2}} C \tag{65}
\end{equation*}
$$

and

$$
\begin{equation*}
\gamma_{\text {even }}(C, r)=\frac{1}{f(r)+\frac{C^{2}}{r^{4}}}=\frac{r^{4}}{p_{C}(r)} \tag{66}
\end{equation*}
$$

the full 4-metric is found.

## C. Derivation II (by a variational principle and/or via construction from Reissner-Nordström metric)

In this subsection we present two alternative derivations of the maximal slices, which the reader may skip without loss of continuity.

Note that the maximal slicing condition $K \equiv 0$ fixes the PDE for $\partial t / \partial r$ as in Eq. (46) only, whereas boundary conditions have to be specified to obtain $t(C, r)$ by integration. The latter can always be written as the sum of the integral $H_{C}(r)$, Eq. (49), and a time translation function of $C$, fixed
initially by demanding that for $C=0$ one starts with the time-symmetric $t=0$ hypersurface, and determined during the evolution by boundary conditions. In particular, for even boundary conditions the throat $r_{C}$ has to stay at $t=0$ because of the symmetry, hence with $H_{C}\left(r_{C}\right)=0$ it follows that this additional function of $C$ is identical zero and Eq. (48) is found. A nontrivial example, namely zgp boundary conditions leading to $t(C, r)$ as in Eq. (97), will be discussed in Sec. V.

To emphasize the importance of the PDE (46) governing the foliation of Reissner-Nordström into maximal slices formulated as level sets of

$$
\begin{equation*}
\sigma=t-t(C, r)=\text { const }, \tag{67}
\end{equation*}
$$

where $C$ is a parameter depending only on the new time coordinate $\tau$, two further ways of re-deriving this equation will be outlined here.

Duncan based on a variational principle shows in Ref. [12] that for Reissner-Nordström maximizing the 3-volume of the line element

$$
\begin{equation*}
{ }^{(3)} d s^{2}=\left[-f(r)\left(\frac{\partial t}{\partial r}\right)^{2}+\frac{1}{f(r)}\right] d r^{2}+r^{2} d \Omega^{2} \tag{68}
\end{equation*}
$$

the Euler-Lagrange equation

$$
\begin{equation*}
\frac{D}{D r}\left[\frac{r^{2} f(r) \frac{\partial t}{\partial r}}{\sqrt{\frac{1}{f(r)}-f(r)\left(\frac{\partial t}{\partial r}\right)^{2}}}\right]=0 \tag{69}
\end{equation*}
$$

using the notation $D Y / D X=\partial Y / \partial X+(\partial t / \partial X)(\partial Y / \partial t)$ $+\left(\partial^{2} t / \partial X^{2}\right)\left(\partial Y / \partial t_{, X}\right)$ is obtained. Equation (69) is satisfied if the expression within the square brackets is a function of $\tau$ only and one may readily check that Eq. (46) is recovered by setting this function to $C(\tau)$.

Another way followed for Schwarzschild in Refs. [4,22] for maximal and in Ref. [19] for constant mean curvature slices is to examine the behavior of the normal

$$
\begin{equation*}
n=n_{t} d t+n_{r} d r=N \nabla[t-t(C, r)]=N\left(d t-\frac{\partial t}{\partial r} d r\right) \tag{70}
\end{equation*}
$$

where with the underlying Reissner-Nordström line element (32) the normalization constant $N$ is fixed by demanding

$$
\begin{equation*}
n_{\mu} n^{\mu}=N^{2}\left[-\frac{1}{f(r)}+f(r)\left(\frac{\partial t}{\partial r}\right)^{2}\right]=-1 . \tag{71}
\end{equation*}
$$

Note that $N$ is also given by

$$
\begin{equation*}
N=-n_{\mu}\left(\frac{\partial}{\partial t}\right)^{\mu} \tag{72}
\end{equation*}
$$

where $\partial / \partial t$ is the static Killing vector. Hence $N$ can be viewed as the boost function [22] of $\partial / \partial t$ relative to $\sigma$ $=$ const. With Eq. (9) it follows that the trace of the extrinsic curvature can be written as

$$
\begin{align*}
K=-\nabla_{\mu} n^{\mu} & =-\frac{1}{r^{2}} \frac{d\left[r^{2} n^{r}\right]}{d r} \\
& =-\frac{1}{r^{2}} \frac{d}{d r}\left[\frac{r^{2} f(r) \frac{\partial t}{\partial r}}{\sqrt{\frac{1}{f(r)}-f(r)\left(\frac{\partial t}{\partial r}\right)^{2}}}\right] \tag{73}
\end{align*}
$$

which for maximal slices, $K \equiv 0$, yields again Eq. (46) by the same argument as for Eq. (69).

One may readily verify that from the normalization (71) it follows that $N$ coincides with the odd lapse, so

$$
\begin{equation*}
N= \pm \frac{\sqrt{p_{C}(r)}}{r^{2}}=\alpha_{o d d}^{ \pm} \tag{74}
\end{equation*}
$$

Furthermore, writing $\partial / \partial t$ as

$$
\begin{equation*}
\left(\frac{\partial}{\partial t}\right)^{\mu}=N n^{\mu}+\xi^{\mu} \quad \text { with } \quad \xi_{\mu} n^{\mu}=0 \tag{75}
\end{equation*}
$$

and using Eq. (72) together with $n_{\mu}=-\alpha \nabla_{\mu} \tau$, one can find

$$
\begin{equation*}
\alpha=N \frac{d t}{d \tau} \tag{76}
\end{equation*}
$$

In the context of even boundary conditions this yields $\alpha_{\text {even }}=\alpha_{\text {odd }}\left(\partial t_{\text {even }} / \partial \tau_{\text {even }}\right)$ as in the first line of Eq. (64). Here $\alpha_{\text {odd }}$ and $\alpha_{\text {even }}$ are linearly independent solutions of Eq. (12) as pointed out in detail in Refs. [4,22].

One should furthermore mention that instead of varying the parameter $C$ with time-which is the choice leading to a foliation, i.e., a "time evolution," made in the latter references and in our paper-one could also as done in Ref. [19] consider adding constant "time translations" to $t(C, r)$ for fixed $C$.

## D. Initial lapse profile

In order to calculate the initial lapse profile note that for $C=0$ the primitive for $K_{C}(r)$ as in Eq. (61) is given analytically by

$$
\begin{equation*}
K_{C=0}(r)=-\frac{2 r\left(2 M r-Q^{2}\right) \sqrt{f(r)}}{\left(M^{2}-Q^{2}\right)\left(2 r^{2}-3 M r+Q^{2}\right)}, \tag{77}
\end{equation*}
$$

and in particular in the limit $r \rightarrow \infty$ by

$$
\begin{equation*}
K_{C=0}(\infty)=\lim _{r \rightarrow \infty} K_{C=0}(r)=-\frac{2 M}{M^{2}-Q^{2}} . \tag{78}
\end{equation*}
$$

With Eq. (64) therefore the initial lapse profile in Schwarzschild coordinates is found to be

$$
\begin{equation*}
\alpha_{\text {even }}^{ \pm}(C=0, r)=1-\frac{Q^{2}}{M r} \tag{79}
\end{equation*}
$$

taken symmetrically across the throat with the value $\alpha_{\text {even }}^{ \pm}\left(C=0, r_{+}\right)=\sqrt{1-Q^{2} / M^{2}}$ there. In terms of the Schwarzschild isotropic coordinates as in Eq. (38) with the isometry (42) present this can be written as

$$
\begin{equation*}
\alpha_{\text {even }}^{ \pm}(C=0, R)=1-\frac{Q^{2}}{M} \frac{4 R}{4 R^{2}+4 M R+M^{2}-Q^{2}} . \tag{80}
\end{equation*}
$$

Obviously, in the Schwarzschild case $\alpha_{\text {even }}^{ \pm}(C=0, r)=1$ is a solution of Eq. (12), while with increasing charge the source term $4 \pi(S-3 \rho)$ in the maximality condition leads to an increasingly collapsed lapse profile.

## V. PUNCTURE LAPSE

## A. Motivation of the zero gradient at the puncture (zgp) boundary condition

As stated in the introduction, the motivation to define and study the zgp boundary condition derives from puncture evolutions of black holes. In any numerical black hole evolution one has to specify how the black hole singularity is treated. In particular, one can excise the black hole from the domain at or inside the event horizon, thereby creating an inner boundary of the numerical grid, one can use the throat as an inner boundary and impose isometry conditions there, and finally one can work on a punctured $R^{3}$, i.e., $R^{3}$ minus one point (the "puncture") for every asymptotically flat end inside a black hole.

Under different names, punctures were studied as early as Refs. [23,24] for Schwarzschild and axisymmetric black hole data. The puncture topology for black hole initial data was revived in Ref. [25] as a simple method to construct multiple black hole initial data with linear momentum and spin (see also Refs. [26,27]). As it turns out, even in the general case of orbiting black holes one can analytically separate the coordinate singularity at the puncture and work on $R^{3}$, both for initial data and evolution [8,11].

Here we concentrate on evolutions of Schwarzschild in the puncture framework. The 3-metric of Schwarzschild in isotropic coordinates at $t=0$ is

$$
\begin{equation*}
{ }^{(3)} d s^{2}=\left(1+\frac{M}{2 x}\right)^{4}\left(d x^{2}+x^{2} d \Omega^{2}\right) \text {, } \tag{81}
\end{equation*}
$$

where the radial grid coordinate $x$ coincides with the isotropic Schwarzschild coordinate $R$ as given in Eq. (39), but differs at later times depending on the shift and the boundary conditions used during evolution. The coordinate singularity at the puncture, $x=0$, corresponds to the inner asymptotically flat infinity of the black hole, i.e., the puncture corresponds to the left-hand $i^{0}$ in the Carter-Penrose diagrams of Sec. VI B.

For evolutions, one can define conformally rescaled metric and extrinsic curvature variables,

$$
\begin{equation*}
g_{i j}={ }^{0} \Psi^{-4} G_{i j}, \quad k_{i j}={ }^{0} \Psi^{-4} K_{i j}, \tag{82}
\end{equation*}
$$

where ${ }^{0} \Psi=1+M / 2 x$ is the time independent conformal factor of Schwarzschild in isotropic coordinates. As argued in Ref. [8] and discussed further in Ref. [11], as a consequence of this rescaling there are no singularities apart from the coordinate singularity in ${ }^{0} \Psi$, in particular the rescaled metric and extrinsic curvature are regular and do not evolve at the puncture. What concerns us here is the regularity of the maximal slicing condition (12). Using the conformal metric $g_{i j}$, one has to solve equations of the type

$$
\begin{equation*}
\Delta^{g} \alpha-O\left(\frac{1}{x}\right) \partial_{k} \alpha=0 \tag{83}
\end{equation*}
$$

As it turns out, standard numerical methods to solve this elliptic equation can find a regular solution for $\alpha$ on $R^{3}$, which has the feature that its gradient vanishes sufficiently rapidly at the puncture such that $O(1 / x) \partial_{k} \alpha$ is zero at the puncture, and the lapse collapses to zero near the puncture. This was noted as an experimental fact in Ref. [6] and analyzed in Refs. [8,11], but there was no rigorous proof that a regular solution to Eq. (83) exists, and while numerically quite robust, it was not clear that the numerics was able to reliably determine this lapse.

The proposal for the zgp lapse is to impose the vanishing of the gradient as a boundary condition on the lapse in coordinates that avoid the coordinate singularity of isotropic coordinates.

## B. Derivation of the zgp lapse

In order to derive boundary conditions for the zgp lapse, note that at infinity and at the puncture the radial grid coordinate $x$ and also the isotropic Schwarzschild coordinate $R$ at $t=0$ given in Eq. (39), is related to the Schwarzschild radius through $r=x$ for $\{r \rightarrow \infty, x \rightarrow \infty\}$ and $r \propto 1 / x$ for $\{r \rightarrow \infty, x$ $\rightarrow 0\}$. As before we demand unit lapse at infinity,

$$
\begin{equation*}
\lim _{x \rightarrow \infty} \alpha_{z g p}^{+}=\lim _{r \rightarrow \infty} \alpha_{z g p}^{+}=1 \forall \tau_{z g p}, \tag{84}
\end{equation*}
$$

such that the slices are labeled by proper time at infinity. At the puncture, we impose the condition of vanishing gradient by

$$
\begin{equation*}
\lim _{x \rightarrow 0} \partial_{x} \alpha_{z g p}^{-} \propto \lim _{r \rightarrow \infty} r^{2} \partial_{r} \alpha_{z g p}^{-}=0 \quad \forall \tau_{z g p} \tag{85}
\end{equation*}
$$

making use of $\partial_{x} \propto r^{2} \partial_{r}$ in this limit.
It turns out to be convenient to derive the zgp lapse by making the ansatz [54]

$$
\begin{equation*}
\alpha_{z g p}^{ \pm}(C, r)=\Phi(C) \cdot \alpha_{\text {even }}^{ \pm}(C, r)+\Psi(C) \cdot \alpha_{\text {odd }}^{ \pm}(C, r) \tag{86}
\end{equation*}
$$

for a time-dependent linear combination of the odd and the even lapse. This form is possible since the maximality condition (12) is linear in the lapse. Furthermore, with $\alpha_{o d d}$ and $\alpha_{\text {even }}$ two linearly independent solutions are known as discussed for Schwarzschild in Appendix A of Ref. [4] and as is
true also for Reissner-Nordström with $0 \leqslant|Q|<M$. This ansatz reveals useful insights in the properties of odd, even, and zgp lapse, leading, e.g., immediately to the conjecture of Sec. V D regarding the lapse at the right-hand event horizon at late times. Also, the smoothness of the lapse (92) and of the height function (97) follow trivially from the smoothness shown for odd and even boundary conditions in Ref. [4]. Equivalently, the puncture lapse can of course be derived starting with the general solution for the lapse, Eq. (27), by applying directly the desired boundary conditions (84) and (85).

Care has to be taken in demanding these boundary conditions analytically since condition (84) is imposed on the right-hand side of the throat (denoted by a superscript "+") while Eq. (85) on the left-hand side (denoted by a " - "). This, however, will be taken into account in the following as the odd lapse is taken in an antisymmetric manner across the throat using the appropriate plus and minus sign in Eq. (29) for the regions extending to infinity and puncture, respectively. The even lapse is symmetric with respect to the throat by construction.

Since both of these two lapses are already one at infinity, the first boundary condition (84),

$$
\begin{equation*}
\Phi(C)+\Psi(C)=1 \quad \forall C \tag{87}
\end{equation*}
$$

simply yields that the sum of the dimensionless multiplicator functions $\Phi$ and $\Psi$ is one for all times, so one can substitute $\Psi(C)=1-\Phi(C) \forall C$. This (trivial) outer boundary condition already allows us to formulate a conjecture regarding the value of the lapse at the right-hand event horizon at late times as stated in Sec. V D.

Continuing in the derivation of the puncture lapse, the gradients of the odd and even lapse at the puncture can be obtained by calculating

$$
\begin{align*}
& \lim _{r \rightarrow \infty} r^{2} \partial_{r} \alpha_{\text {odd }}^{-}=-M \\
& \lim _{r \rightarrow \infty} r^{2} \partial_{r} \alpha_{\text {even }}^{-}=M+\frac{2}{K_{C}(\infty)} . \tag{88}
\end{align*}
$$

Remembering that the integral $K_{C}(\infty)$ carries units of $1 / M$ and diverges for $C \rightarrow C_{\text {lim }}$, it turns out that for late times the gradients at the puncture for $\alpha_{\text {odd }}$ and $\alpha_{\text {even }}$ just differ by their sign. Therefore, in order to produce a vanishing gradient, at late times the average of the two lapse functions has to be taken, i.e.,

$$
\begin{equation*}
\lim _{C \rightarrow C_{l i m}} \Phi(C)=\lim _{C \rightarrow C_{l i m}} \Psi(C)=\frac{1}{2} \tag{89}
\end{equation*}
$$

For arbitrary $C, 0 \leqslant C \leqslant C_{\text {lim }}$, we use Eq. (88) with the second boundary condition (85) to obtain

$$
\begin{equation*}
\Phi(C) \cdot\left(M+\frac{2}{K_{C}(\infty)}\right)-[1-\Phi(C)] \cdot M=0 \quad \forall C . \tag{90}
\end{equation*}
$$

Hence from Eqs. (87) and (90) the multiplicator functions $\Phi$ and $\Psi$ are found to be given by

$$
\begin{equation*}
\Phi(C)=1-\Psi(C)=\frac{1}{2} \frac{K_{C}(\infty)}{K_{C}(\infty)+\frac{1}{M}} \tag{91}
\end{equation*}
$$

where the divergence of $K_{C}(\infty)$ in the limit $C \rightarrow C_{\text {lim }}$ gives the average of the odd and even lapse for late times as formulated already in Eq. (89).

The zgp or puncture lapse now can be written as

$$
\begin{align*}
\alpha_{z g p}^{ \pm}(C, r) & =\frac{\sqrt{p_{C}(r)}}{r^{2}} \frac{d C}{d \tau_{z g p}} \frac{\partial t_{z g p}}{\partial C} \\
& =\Phi(C) \cdot \alpha_{\text {even }}^{ \pm}(C, r)+\Psi(C) \cdot \alpha_{o d d}^{ \pm}(C, r) \\
& =-\frac{1}{2} \frac{1}{K_{C}(\infty)+\frac{1}{M}}\left\{\frac{1}{r-\frac{3}{2} M+\frac{Q^{2}}{2 r}}-\frac{\sqrt{p_{C}(r)}}{r^{2}}\left[K_{C}(r) \pm\left(K_{C}(\infty)+\frac{2}{M}\right)\right]\right\}, \tag{92}
\end{align*}
$$

making use of the ansatz (86). Similar to the even case, the first line is obtained by passing to Schwarzschild coordinates, which leads to Eqs. (45) and (46) with the subfix "zgp" instead of "even."

We show the zgp lapse profile in these coordinates at times at infinity $\tau_{z g p}=\{0,1 M, 2 M, 4 M, 8 M\}$ when we discuss the numerical evolutions, see Fig. 6.

The shift and the radial component of the 3-metric are again given by

$$
\begin{equation*}
\beta_{z g p}(C, r)=\frac{\alpha_{z g p}(C, r) \gamma_{z g p}(C, r)}{r^{2}} C \tag{93}
\end{equation*}
$$

and

$$
\begin{equation*}
\gamma_{z g p}(C, r)=\frac{1}{f(r)+\frac{C^{2}}{r^{4}}}=\frac{r^{4}}{p_{C}(r)} \tag{94}
\end{equation*}
$$

In order to fix the $\tau_{z g p}$ dependence of $C$ one may from Eq. (92) by analogy with Eq. (64) conjecture that

$$
\begin{align*}
\frac{\partial}{\partial C} t_{z g p}^{ \pm}(C, r)= & \frac{r^{2}}{2\left(r-\frac{3}{2} M+\frac{Q^{2}}{2 r}\right) \sqrt{p_{C}(r)}} \\
& -\frac{1}{2}\left[K_{C}(r) \pm\left(K_{C}(\infty)+\frac{2}{M}\right)\right] \tag{95}
\end{align*}
$$

and hence

$$
\begin{equation*}
\frac{d}{d C} \tau_{z g p}(C)=\lim _{r \rightarrow \infty} \frac{\partial}{\partial C} t_{z g p}^{+}(C, r)=-K_{C}(\infty)-\frac{1}{M} \tag{96}
\end{equation*}
$$

By going back to the differential equation for the maximal lapse, Eq. (26), one can readily verify that Eq. (95) and hence Eq. (96) are correct and therefore the time dependence is consistently fixed by the height function

$$
\begin{equation*}
t_{z g p}^{ \pm}(C, r)=H_{C}(r) \pm\left(H_{C}(\infty)-\frac{C}{M}\right) \tag{97}
\end{equation*}
$$

using Eqs. (60) and (62). Furthermore, time is measured at right-hand spatial infinity by

$$
\begin{equation*}
\tau_{z g p}(C)=\lim _{r \rightarrow \infty} t_{z g p}^{+}(C, r)=2 H_{C}(\infty)-\frac{C}{M} \tag{98}
\end{equation*}
$$

Note, however, that the time measured at the puncture approaches the finite value

$$
\begin{equation*}
\lim _{C \rightarrow C_{l i m} r \rightarrow \infty} \lim _{z g p} t_{z}^{-}(C, r)=\frac{C_{l i m}}{M} \tag{99}
\end{equation*}
$$

We are not aware of a physical meaning of this finite time at the puncture.

Finally, we want to point out that using our result for the zgp lapse, Eq. (92), together with $r \propto 1 / x$ for $\{r \rightarrow \infty, x \rightarrow 0\}$, one can readily verify that the first and second derivative of the lapse at the puncture both vanish. So the zgp lapse is at least $\mathcal{C}^{2}$ there. However, when calculating higher derivatives of the lapse, terms of higher order in the relationship between $r$ and $x$ can be of importance, and these terms depend on the chosen shift. For a vanishing shift the transformation $r(C(\tau), x)$ will be derived in Sec. VII C.

## C. Initial lapse profile

For the initial lapse profile with Eq. (78) the multiplicator function $\Phi$ as in Eq. (91) for $C=0$ is found to be

$$
\begin{equation*}
\Phi(C=0)=\frac{M^{2}}{M^{2}+Q^{2}} \tag{100}
\end{equation*}
$$

In particular, for Schwarzschild with ${ }^{0} \Phi(C=0)=1$ one starts with the even lapse only, whereas for Reissner-

Nordström with increasing charge the balance is shifted more and more to the odd lapse to produce a "pre-collapsed" lapse profile.

So the initial puncture lapse profile in terms of the Schwarzschild radial coordinate $r$ using Eq. (92) is found to be given on the right-hand and left-hand side of the throat as

$$
\begin{equation*}
\alpha_{z g p}^{ \pm}(C=0, r)=\frac{M^{2} r-Q^{2} M \pm Q^{2} r \sqrt{f(r)}}{\left(M^{2}+Q^{2}\right) r} . \tag{101}
\end{equation*}
$$

Applying the transformation (38) one can derive this profile also for the Schwarzschild isotropic coordinate $R$,

$$
\begin{equation*}
\alpha_{z g p}^{ \pm}(C=0, R)=1-\frac{2 Q^{2}}{M^{2}+Q^{2}} \frac{4 R+M^{2}-Q^{2}}{4 R^{2}+4 M R+M^{2}-Q^{2}} \tag{102}
\end{equation*}
$$

Note that for the puncture lapse the isometry (42) is no longer present.

## D. Late time limit for the lapse at the right-hand event horizon

Based on the ansatz (86) we want to state a conjecture for the lapse at the right-hand event horizon at late times that is of some importance for black hole excision. Although one can use the apparent horizon as the location for the excision boundary, finding the apparent horizon is usually time consuming, and a simpler prescription for some surface that coincides or is located inside the event horizon can serve the same purpose for excision. For example, one sometimes can define the excision surface by a surface of constant lapse. In numerical simulations with maximal slicing, a lapse between 0.3 [28] and 0.34 [29] turned out to mark the location of the right-hand event horizon. A value in this range can also be inferred from some graphs in the literature showing the lapse as a function of time, cf. Fig. 3(a) in Ref. [30], Fig. 6 in Ref. [31] or Fig. 13 in Ref. [32].

For very general boundary conditions we can state the following conjecture:

For maximal slicing of the nonextremal extended Reissner-Nordström spacetime with the throat of the Einstein-Rosen bridge coinciding initially with the event horizon and with boundary conditions imposed on the lapse other than the odd ones, the lapse at late times at the righthand event horizon is found to approach the value $\left.\alpha\right|_{r_{+}}$ $=C_{\text {lim }} / r_{+}^{2}$ asymptotically. In particular, for the Schwarzschild spacetime with ${ }^{0} C_{\text {lim }}=\frac{3}{4} \sqrt{3} M^{2}$ and ${ }^{0} r_{+}=2 M$ this value turns out to be $\left.{ }^{0} \alpha\right|_{r_{+}}=\frac{3}{16} \sqrt{3} \approx 0.3248$.

Without attempting a complete proof, we can argue as follows. Since for fixed time, i.e., for fixed slice label $C$, the lapse arises from the maximality condition (12), i.e., a second order linear ODE with smooth coefficients, the theory of ODE states that the set of solutions forms a 2-dimensional real linear space, cf. theorem I in Chap. 15 of Ref. [33]. As a consequence, every lapse using the superposition principle can be constructed as a (time-dependent) linear combination of the odd and even lapse, which are evidently linearly inde-
pendent for $0 \leqslant|Q|<M$. From Eqs. (29) and (64) evaluated for $C \rightarrow C_{\text {lim }}$, one can see that odd and even lapse at the right-hand event horizon in this limit are given by

$$
\begin{equation*}
\left.\lim _{C \rightarrow C_{\text {lim }}} \alpha_{\text {odd }}^{+}\right|_{r_{+}}=\left.\lim _{C \rightarrow C_{\text {lim }}} \alpha_{\text {even }}^{+}\right|_{r_{+}}=\frac{C_{\text {lim }}}{r_{+}^{2}} . \tag{103}
\end{equation*}
$$

Furthermore, any other lapse constructed by a linear combination with coefficients adding up to one in order to have unit lapse at infinity has the same limiting value. Finally, we argue that as the slices approach with $r_{C} \rightarrow r_{C_{l i m}}>0$ a limiting surface and hence avoid the singularity [5], the limit $C$ $\rightarrow C_{\text {lim }}$ considered so far carries over to the limit of infinite time, $\tau \rightarrow \infty$. Although reasonable, it is not yet clear to us whether the last step holds without exception.

## VI. COMPARISON OF THE ANALYTICAL ODD, EVEN, AND ZGP MAXIMAL SLICES

## A. Embedding diagrams

Embedding diagrams are useful tools for the visualization of geometric properties of slicings. Following Appendix F of Ref. [34] and Sec. IV of Ref. [35] in suppressing one of the angular coordinates, by embedding a 2-dimensional (2D) Riemannian hypersurface into flat 3D space the intrinsic geometry of this surface is preserved. The embedding of the Reissner-Nordström $\{r, \phi\}$ line element, i.e., the equatorial hypersurface $\theta=\pi / 2$ corresponding to fixed time at infinity $\tau$, in Euclidean space written in cylindrical coordinates $\left\{z, r=\sqrt{x^{2}+y^{2}}, \phi\right\}$ is obtained by demanding

$$
\begin{align*}
&(3) \\
& d s^{2}=d z^{2}+d r^{2}+r^{2} d \phi^{2} \\
&=\left[-f(r)\left(\frac{\partial t}{\partial r}\right)^{2}+\frac{1}{f(r)}\right] d r^{2}+r^{2} d \phi^{2}  \tag{104}\\
&=\frac{r^{4}}{p_{C}(r)} d r^{2}+r^{2} d \phi^{2} .
\end{align*}
$$

For fixed $C(\tau)$ this results in the differential equation

$$
\begin{equation*}
\left.\frac{d z}{d r}\right|_{C=\text { const }}= \pm \sqrt{\frac{r^{4}}{p_{C}(r)}-1} \tag{105}
\end{equation*}
$$

for the embedding function $z(C, r)$. For $0 \leqslant|Q|<M$ and $r$ $\geqslant r_{C}$ its solution is found by integration,

$$
\begin{equation*}
z(C, r)= \pm \int_{r_{C}}^{r} \sqrt{\frac{y^{4}}{p_{C}(y)}-1} d y \tag{106}
\end{equation*}
$$

where without loss of generality symmetry with respect to the $z=0$ plane has been chosen. In particular for the initial Schwarzschild slice, i.e., for $Q=C=0$, the solution [34] is found to be

$$
\begin{equation*}
{ }^{0} z(C=0, r)=2 \sqrt{2} \sqrt{(r-2 M) M} \tag{107}
\end{equation*}
$$

The embedding is a parabola of revolution referred to as Einstein-Rosen bridge [17]. Here in both "universes" the

3-geometry becomes Euclidean far from the throat, which is the minimal 2-sphere of the bridge.

Note, however, that Einstein's field equations fix only the local geometry of the spacetime but not its topology. A geometrically identical—but topologically differentembedding could be found for example by identifying both sheets in order to obtain the "throat of a wormhole" in the sense of Misner and Wheeler [23]. Here in one flat space two distant regions are connected in the limit when the separation of the wormhole mouths is large compared to the circumference of the throat, cf. Fig. 31.5 in Ref. [36].

For the general $0 \leqslant|Q|<M, 0 \leqslant C \leqslant C_{\text {lim }}$ case we evaluated the integral (106) numerically using for the relationship $C(\tau)$ equations (52) and (98) for the even and zgp boundary conditions, respectively. The embeddings of these two cases therefore only differ by their time labeling and are less informative than their corresponding spacetime diagrams shown in Sec. VI B. In particular, information about any underlying symmetry of the slices-like the (anti)symmetry with respect to the throat for (odd) even boundary conditions and the more complicated behavior for zgp conditions-has been lost. The results are shown for Schwarzschild in Fig. 2, which should be compared for the even boundary conditions with Fig. 4.18 in Ref. [34] or Fig. 2 in Ref. [3]. Reflecting the curves at the $z=0$ plane and rotating them around the $z$ axis, a set of throats is obtained starting with a parabola of revolution with the minimal 2 -sphere initially at the event horizon ${ }^{0} r_{+}=2 M$ and degenerating at late times to an infinitely long cylinder with radius $r={ }^{0} r_{C_{l i m}}=3 M / 2$ as the slices approach the maximal hypersurface with this radius asymptotically. The plots for charge in the range $0<|Q|$ $<M$, which are not shown here, are qualitatively very similar.

## B. Kruskal-Szekeres and Carter-Penrose diagrams

Spacetime diagrams such as the Kruskal-Szekeres [37] and Carter-Penrose [38,39] diagrams provide a convenient way of visualizing spacetime properties like causality, see, e.g., Refs. [36,40]. In this paper we want to limit ourselves to the discussion of the Schwarzschild spacetime, the results for the nonextremal Reissner-Nordström spacetime can be found in Ref. [21].

For the Schwarzschild metric (32), radial null geodesics motivate for $r \in\left[{ }^{0} r_{+}=2 M, \infty[\right.$ the introduction of the Regge-Wheeler radial coordinate

$$
\begin{equation*}
\left.r_{*}=\int \frac{d r}{1-\frac{2 M}{r}}=r+2 M \ln \left|\frac{r-2 M}{2 M}\right|, r_{*} \in\right]-\infty, \infty[ \tag{108}
\end{equation*}
$$

As $d\left(t \pm r_{*}\right)=0 \quad$ on radial null geodesics, ingoing Eddington-Finkelstein coordinates $\{v, r, \theta, \phi\}$ with

$$
\begin{equation*}
\left.v=t+r_{*}, \quad v \in\right]-\infty, \infty[ \tag{109}
\end{equation*}
$$

leading to $d s^{2}=-(1-2 M / r) d v^{2}+2 d v d r+r^{2} d \Omega^{2}$ can be defined as in Ref. [41]. Similarly, outgoing EddingtonFinkelstein coordinates $\{u, r, \theta, \phi\}$ given by


FIG. 2. In the embedding diagrams for maximally slicing the Schwarzschild metric using odd, even, and zgp boundary conditions, the Einstein-Rosen bridges are obtained by reflecting the curves corresponding to $\tau=\{0,1 M, 2 M, 4 M, 8 M\}$ displayed from the bottom up at $z=0$ and rotating them around the $z$ axis. They start with the throat at ${ }^{0} r_{+}=2 M$ and degenerate for $\tau \rightarrow \infty$ in the even and zgp case-which just differ by their time labeling-to an infinitely long cylinder with radius ${ }^{0} r_{C_{\text {lim }}}=3 M / 2$.

$$
\begin{equation*}
\left.u=t-r_{*}, \quad u \in\right]-\infty, \infty[ \tag{110}
\end{equation*}
$$

lead to $d s^{2}=-(1-2 M / r) d u^{2}-2 d u d r+r^{2} d \Omega^{2}$. These line elements can now be analytically extended to $r>0$, and the corresponding Eddington-Finkelstein diagrams are shown, e.g., in Ref. [40]. In these coordinates the metric components
are nonsingular at ${ }^{0} r_{+}=2 M$. However, it should be mentioned that the regions $r<2 M$ in ingoing and outgoing Eddington-Finkelstein coordinates do not coincide, since one can readily verify that for all timelike or null worldlines from $d s^{2} \leqslant 0$ it follows that $2 d v d r \leqslant 0$, while $2 d u d r \geqslant 0$. Therefore, the nature of the singularity at $r=0$ is different: An analysis in ingoing Eddington-Finkelstein coordinates shows that no signal can escape back to infinity once it passed the event horizon. The time reverse of a black hole, a white hole, is found by performing a similar analysis in outgoing Eddington-Finkelstein coordinates.

With the exterior region covered by both in- and outgoing Eddington-Finkelstein coordinates, one can write the Schwarzschild metric as

$$
\begin{align*}
d s^{2} & =-\left(1-\frac{2 M}{r}\right) d u d v+r^{2} d \Omega^{2} \\
& =-\frac{32 M^{3}}{r} e^{-r / 2 M} d U d V+r^{2} d \Omega^{2} \tag{111}
\end{align*}
$$

by introducing for $r>2 M$ the Kruskal-Szekeres coordinates [37]

$$
\begin{equation*}
U=-e^{-u / 4 M}<0 \quad \text { and } \quad V=+e^{+v / 4 M}>0, \tag{112}
\end{equation*}
$$

which are analytically extendable to $U>0$ and $V<0$. The Schwarzschild radial coordinate $r$ is now given implicitly as a function of $U$ and $V$ by

$$
\begin{equation*}
U \cdot V=-e^{r_{*} / 2 M}=\left(1-\frac{r}{2 M}\right) e^{r / 2 M} \tag{113}
\end{equation*}
$$

Note that the singularity at $r=0$ corresponds to $U \cdot V=1$ and the event horizon at ${ }^{0} r_{+}=2 M$ to $U \cdot V=0$, i.e., to either $U$ $=0$ or $V=0$. It is convenient to introduce new time and space coordinates by

$$
\begin{equation*}
T=\frac{1}{2}(V+U) \text { and } X=\frac{1}{2}(V-U) \tag{114}
\end{equation*}
$$

in order to produce Kruskal-Szekeres diagrams. Note that with $t$ expressed in terms of $T$ and $X$ by

$$
t=4 M\left\{\begin{array} { r } 
{ \operatorname { a r c t a n h } \frac { T } { X } }  \tag{115}\\
{ \operatorname { a r c t a n h } \frac { X } { T } }
\end{array} \quad \text { in the regions } \quad \left\{\begin{array}{c}
\mathrm{I}, \mathrm{I}^{\prime} \\
\mathrm{II}, \mathrm{II}^{\prime}
\end{array}\right.\right.
$$

the lines of constant $t$ correspond to straight lines through the origin, whereas curves of constant $r$ are hyperbolae with asymptotes $T= \pm X$.

In Fig. 3, we show Kruskal-Szekeres diagrams for odd, even, and zgp lapse. (Note the difference to the hand-drawn Fig. 1 in Ref. [11].) Since the in- and outgoing radial null geodesics are given by lines of constant $U$ and $V$, the light cones are unit light cones appearing at $45^{\circ}$. One can infer from the Kruskal-Szekeres diagram that the Schwarzschild geometry consists of four regions separated by the (dot-



FIG. 3. The Kruskal-Szekeres diagrams for the extended Schwarzschild spacetime show the maximal slices for time at infinity $\tau=\{0,1 M, 2 M, 4 M, 8 M\}$ for the odd, even, and zgp boundary conditions. Note that the puncture corresponds to the spatial infinity of region $I^{\prime}$ located to the left of the plot.
dashed plotted) event horizon at ${ }^{0} r_{+}=2 M$, namely the regions I and I', two identical but distinct asymptotically flat universes, where the isometry ${ }^{0} R \leftrightarrow M^{2} / 4^{0} R$ corresponds to the mapping $(T, X) \leftrightarrow(-T,-X)$, and the regions II and $\mathrm{II}^{\prime}$, two identical but time-reversed regions in which physical singularities (a black hole and a white hole) are present.

As discussed in Sec. III, the maximal slices with odd boundary conditions correspond to surfaces of constant Schwarzschild time coordinate $t$ in the outer regions I and I' since $\partial / \partial t$ generates a Killing vector field there $[4,42]$. In particular, in the upper plot of Fig. 3 the solid black straight lines in regions I and $\mathrm{I}^{\prime}$ are (starting with the horizontal time-symmetric $t=0$ slice) the spacelike maximal hypersurfaces $t=\{0,1 M, 2 M, 4 M, 8 M\}$, whereas the gray timelike lines correspond to $r=\{2.5 M, 3 M, 3.5 M, 4 M\}$. In regions II and II' $^{\prime}$ the spacelike limiting maximal slice $r={ }^{0} r_{C_{\text {lim }}}$ $=3 M / 2$ is plotted as a dashed line, the singularity $r=0$ by a zigzag line.

In the even case, plotting the height function $t_{\text {even }}\left(C\left(\tau_{\text {even }}\right), r\right)$ as in Eq. (48) for the previously stated times at infinity, an observer moves forward in Schwarzschild time $t$ in region and backward in region $\mathrm{I}^{\prime}$ in a symmetric manner in order to reach the limiting maximal slice, cf. the plot in the middle of Fig. 3, and, e.g., Fig. 1 in Ref. [3] or Fig. 3 in both Refs. [7] and [18]. However, in terms of the new time coordinate $\tau_{\text {even }}$, time runs forward (due to the always positive lapse) equally fast (due to the symmetry) in both regions so that the asymptotic values for $t$ at puncture and infinity differ by the amount $2 \tau_{\text {even }}$. Due to the symmetry with respect to the $T$ axis, the throat ${ }^{0} r_{C}$ (plotted as an unfilled box) moving from ${ }^{0} r_{+}=2 M$ to ${ }^{0} r_{C_{l i m}}=3 M / 2$ remains on this axis and the slices penetrate into the left-hand and right-hand event horizon (denoted by downward and upward pointing triangles) symmetrically.

Demanding for zgp boundary conditions neither symmetry nor antisymmetry, the slices are "lopsided" as can be seen by plotting $t_{z g p}\left(C\left(\tau_{z g p}\right), r\right)$, Eq. (97), in the graph on the bottom of Fig. 3. In particular, one can observe that as a function of time the throat ${ }^{0} r_{C}$ moves "to the right" along the shown curve corresponding to $t=H_{C}(\infty)-C / M$. From Eq. (97) one can infer that as in region I at infinity the time measured as $\tau_{z g p}(C)=\lim _{r \rightarrow \infty} t_{z g p}^{+}(C, r)$ goes to infinity in the limit $C \rightarrow{ }^{0} C_{\text {lim }}$, as stated in Eq. (99) in region I' at the puncture the finite time ${ }^{0} C_{\text {lim }} / M=\frac{3}{4} \sqrt{3} M \approx 1.2990 M$ is found. Taking care of the sign as for even boundary conditions, the maximal hypersurfaces approach in region $\mathrm{I}^{\prime}$ the line $t=-{ }^{0} C_{\text {lim }} / M$ asymptotically in the limit $r \rightarrow \infty$ with $C \rightarrow{ }^{0} C_{\text {lim }}$.

In Fig. 4, we show Carter-Penrose diagrams corresponding to Fig. 3. These are obtained by a conformal compactification of the form $d \widetilde{s}^{2}=\Omega^{2}\left(t, x^{i}\right) \cdot d s^{2}$ which-leaving the underlying causal structure unchanged-map points at infinity in the original metric $d s^{2}$ to a finite affine parameter in the compactified metric $d \widetilde{s}^{2}$. See Ref. [40] for further technical conditions on the spacetime and on the (not unique) choice of $\Omega$ to guarantee that this construction will work. As shown in this reference, on the conformal boundary one can


FIG. 4. Carter-Penrose diagrams are obtained by compactifying the Kruskal-Szekeres diagrams of Fig. 3 as stated in the text. Note the behavior of the slices at spatial infinity, the movement of the throat $r_{C}$ and of the left-hand and right-hand event horizon, which are again plotted as unfilled box, downward and upward pointing triangles, respectively.
identify past and future null infinity $\mathcal{J}^{\mp}$, past and future timelike infinity $i^{\mp}$ and spacelike infinity $i^{0}$, i.e., the beginning and end of null, timelike and spacelike geodesics.

For the Schwarzschild metric, compactification can be carried out [42] by introducing as in Eq. (114) new time and space coordinates $\widetilde{T}$ and $\widetilde{X}$ based on

$$
\begin{equation*}
\widetilde{U}=\arctan U \quad \text { and } \quad \widetilde{V}=\arctan V \tag{116}
\end{equation*}
$$

where $\widetilde{U}$ and $\widetilde{V}$ are in the range $-\pi / 2 \leqslant \widetilde{U}, \widetilde{V} \leqslant \pi / 2$.
It is worth pointing out that as radial null geodesics are again unit light cones the maximal slices are obviously spacelike. Furthermore, at the right-hand $i^{0}$, with the lapse being one at infinity for all three boundary conditions, essentially $t=$ const slices are found, whereas in particular for zgp boundary conditions at the puncture, i.e., the left-hand $i^{0}$, the line $t=-{ }^{0} C_{\text {lim }} / M$ is approached at late times. One may
readily verify that for the compactification carried out here these slices arrive at $i^{0}$ with a slope given by

$$
\begin{equation*}
\left|\frac{d \widetilde{T}}{d \widetilde{X}}\right|_{i^{0}}=\tanh \frac{|t|}{4 M} . \tag{117}
\end{equation*}
$$

In our case, starting with the horizontal time-symmetric hypersurface $t=0$ the slices for all three boundary conditions fan out to hug $\mathcal{J}^{+}$asymptotically, while for zgp boundary conditions at the puncture a finite angle given by $\arctan \left[\tanh \left(C_{\text {lim }} / 4 M^{2}\right)\right] \approx 17.4^{\circ}$ is found in the limit of late times.

## VII. COMPARISON WITH NUMERICAL SIMULATIONS

## A. Numerical method

Maximal slicing has been studied numerically for the evolution of a single Schwarzschild black hole already in Ref. [3], and was later on implemented and used as a standard test case in 1D [7], 2D [31] and 3D codes [6,11] based on a Cartesian grid and by using a smooth lattice method [32].

For comparison with the analytical result for the puncture lapse, we have performed simulations with the CACTUS code [43]. We evolved a single Schwarzschild puncture with maximal slicing and vanishing shift with the Baumgarte-Shapiro-Shibata-Nakamura (BSSN) system of evolution equations, see Ref. [11] for details. The maximal slicing lapse is obtained by solving the elliptic equation (12) using the multigrid solver BAM_Elliptic [44,45], without imposing any additional boundary condition at the puncture.

In Fig. 5, we show an example for the numerical grid. The runs are carried out in three dimensions on an octant of $R^{3}$, which is possible for spherically symmetric systems. The puncture is located at the origin, and we choose a staggered Cartesian grid with uniform grid spacing such that the puncture is not part of the grid but rather is located half way between grid points in all three directions.

The outer boundary condition for the lapse is implemented numerically at the edge of the finite numerical grid by employing a Robin condition [46] as described in Ref. [47]. In order to study errors introduced by the Robin boundary condition implemented at the edge of the grid, runs have been carried out using a uniform spacing of $\triangle X=0.05 M$ and (multiplied by a courant factor of $\frac{1}{4}$ ) time steps of $\triangle \tau_{z g p}$ $=\frac{1}{4} \triangle X=0.0125 M$ for a series of $32^{3}, 64^{3}$ and $128^{3}$ grid points to place the outer boundary at $X_{o b} \approx 1.6 M, 3.2 M$ and $6.4 M$, respectively. Similarly, we checked for second order convergence using different numbers of grid points for the outer boundary close in. These numerical tests are described in Ref. [21]. For the resolutions considered here, there are limitations in the numerical convergence near the puncture, and it is known that higher resolution is required to see clean convergence near the puncture, see Ref. [11] for algebraic slicings. For the present purpose of comparison with the analytical results, the goal was only to establish that these runs are approximately in the convergent regime. All the results in the remainder of this section are for $\triangle X=0.05 M, 128^{3}$ grid points, and $X_{o b} \approx 6.4 M$.

$$
\tau_{\mathrm{zgp}}=0
$$




FIG. 5. The Cartesian grid used in numerical solutions is shown (suppressing the $Z$ direction) for $32^{3}$ grid points and a resolution of $\triangle X$ $=\triangle Y=\triangle Z=0.05 M$, which places the outer boundary at $X_{o b} \approx 1.6 M$. The domain is one octant with appropriate boundary conditions for spherical symmetry imposed at the planes $X$ $=0, Y=0$, and $Z=0$. Note that the puncture is staggered at the origin. The numerically found locations of the throat $x_{C}$ and the left-hand and right-hand event horizon, $x_{C}^{-}$and $x_{C}^{+}$, are superimposed as dark solid lines for the times $\tau_{z g p}$ $=0$ and $\tau_{z g p}=8 \mathrm{M}$.

We will show that the numerical evolution obtained in this way agrees nicely (within a certain error) with the analytical result for the puncture lapse. In order to carry out this comparison, we have to establish an explicit mapping between the coordinates used in the numerical simulation and our analytical study.

## B. Schwarzschild radial coordinate

One has to remember that for 3D Cartesian coordinates $\{X, Y, Z\}$ the system has no spherical symmetry from the point of view of the code. However, looking at radial output the radial coordinate $x$ defined as the Euclidean distance from the puncture is readily obtained. Because of the spherical symmetry the expression $r^{2} d \Omega^{2}$ for the angular part of
the metric is also expected in numerical simulations [55]. Hence the Schwarzschild radial coordinate can be obtained by calculating

$$
\begin{equation*}
r(\tau, x)=\Psi^{2}(x) \sqrt{g_{\theta \theta}(\tau, x)}=\Psi^{2}(x) \sqrt{\sin ^{2} \theta g_{\phi \phi}(\tau, x)} . \tag{118}
\end{equation*}
$$

Figure 6 shows the odd, even, and zgp lapse profiles for times $\tau=\{0,1 M, 2 M, 4 M, 8 M\}$ measured at infinity. The solid lines show the analytic results based on the evaluation of Eqs. (29), (64) and (92). For the zgp boundary condition, data points obtained from the largest simulation are plotted as boxes in Fig. 6 and lie virtually on top of the analytical results.

Evaluating the analytic integrals is a nontrivial task due to the late time divergence of the involved integrals $H_{C}(r)$ and


FIG. 6. Shown are the odd, even, and zgp lapse versus the Schwarzschild radial coordinate $r$ for times $\tau=\{0,1 M$, $2 M, 4 M, 8 M\}$ measured at infinity. The solid lines show the analytic results, while the numerical results for the zgp lapse are plotted as solid boxes. The numerical data points lie virtually on top of the analytical result. Note that in the odd case the time-independent lapse is negative on the left-hand side of the throat (denoted by an unfilled box) coinciding with the event horizon, whereas for the even case the collapsing lapse is symmetric in the sense that in particular left-hand and right-hand event horizon (shown as downward and upward pointing triangles) and also infinity and puncture coincide. These symmetries are lost for the zgp lapse with the lapse remaining one at infinity and collapsing at the puncture.
$K_{C}(r)$ as discussed in more detail in Ref. [21] based on Ref. [48]. The value of the lapse at the throat ${ }^{0} r_{C}$ is marked on these slices by an unfilled box and similarly for the left-hand and right-hand event horizon corresponding to ${ }^{0} r_{+}=2 M$ by downward and upward pointing triangles. Being motivated geometrically these "markers" essentially allow one to sketch for a certain time at infinity the corresponding lapse profile and are hence suited for a study of their late time behavior which will be carried out in a later paper [20]. Note, for example, that for the collapsing lapse profiles obtained for even and zgp boundary conditions the radial coordinate of the throat approaches ${ }^{0} r_{C_{\text {lim }}}=3 M / 2$ and that the conjecture of Sec. V D regarding the lapse at the right-hand event horizon holds.

## C. Radial isotropic grid coordinates

From the analytical point of view the task of finding the foliation of the extended Reissner-Nordström metric using maximal slices with zgp boundary conditions has been solved already in Sec. V in the sense that in a well-suited coordinate system, namely the radial gauge (13), the maximal slices arising as level sets $\tau_{z g p}=$ const of the height function $t_{z g p}\left(C\left(\tau_{z g p}\right), r\right)$, Eq. (97), have been found. Keeping in mind the $3+1$ split, the foliations shown previously in Kruskal-Szekeres and Carter-Penrose diagrams are uniquely determined by the lapse function $\alpha_{z g p}^{ \pm}\left(C\left(\tau_{z g p}\right), r\right)$, Eq. (92), telling one how to progress from slice $\Sigma_{\tau}$ to the consecutive one $\Sigma_{\tau+\delta \tau}$. Since for puncture data in CACTUS neither the Schwarzschild coordinates, $\{t, r, \theta, \phi\}$, nor the previously introduced coordinates $\{\tau, r, \theta, \phi\}$, but depending on the shift different "grid coordinates," $\{\tau, x, \theta, \phi\}$, are used, it is for a comparison with numerical results important to find the coordinate transformations relating these gauges. Above all we are now interested in using the freedom of choosing different coordinates $\left(x^{i}\right)$ on these slices in order to construct coordinates such that the 4-metric coincides at all times with output from a numerical evolution of black hole puncture data and hence to prove by construction the existence of an underlying analytical solution. The radial coordinates of this puncture data line element we shall call "isotropic grid coordinates" in the case of a vanishing shift and "isothermal grid coordinates" for a nontrivial shift to emphasize the connection both to the isotropic and isothermal gauge and to the numerical grid. Unless stated otherwise, here and in the following the expressions are valid for arbitrary boundary conditions imposed on the lapse. However, one should note that for odd boundary conditions the time-independent isotropic coordinates of Sec. III are recovered, which are not horizon penetrating. In this paper we concentrate on the case of vanishing shift, $B \equiv 0$, where $B$ denotes the shift for isotropic coordinates to distinguish it from the shift $\beta$ in radial gauge. The more general case of a shift $B \neq 0$ is discussed in Ref. [21] and subject of a later paper.

Independent of the coordinate choice $\left(x^{i}\right)$ on the maximal slices, time at infinity is still measured by $\tau$. So the task is to find a radial coordinate transformation of the form $r$ $=r(C(\tau), x)$ to a line element with zero shift $B$,

$$
\begin{align*}
d s^{2} & =\left(-\alpha^{2}+\frac{\beta^{2}}{\gamma}\right) d \tau^{2}+2 \beta d \tau d r+\gamma d r^{2}+r^{2} d \Omega^{2} \\
& :=-A^{2} d \tau^{2}+G d x^{2}+r^{2} d \Omega^{2} \tag{119}
\end{align*}
$$

Here, $\partial r / \partial \tau=(\partial r / \partial C)(d C / d \tau)$ has been used, and the lapse $A$ and the 3-metric $G_{i j}$ with its radial component $G$ as functions of $\tau$ and $x$ have been introduced and are given by

$$
\begin{align*}
& A(\tau, x)=\alpha(\tau, r(\tau, x)) \\
& G(\tau, x)=\gamma(\tau, r(\tau, x))\left(\frac{\partial r}{\partial x}\right)^{2} \tag{120}
\end{align*}
$$

To allow for a direct comparison with numerical puncture evolutions as produced by CACTUS, the 3-metric is written in the form

$$
\begin{equation*}
{ }^{(3)} d s^{2}=G d x^{2}+r^{2} d \Omega^{2}=\Psi^{4}\left[g d x^{2}+\frac{r^{2}}{\Psi^{4}} d \Omega^{2}\right] \tag{121}
\end{equation*}
$$

obtained by rescaling the 3-metric with the conformal factor

$$
\begin{equation*}
\Psi^{4}(x)=\left[\left(1+\frac{M}{2 x}\right)^{2}-\frac{Q^{2}}{4 x^{2}}\right]^{2} \tag{122}
\end{equation*}
$$

Here the coordinate $x$ of puncture evolutions is given in terms of the 3D Cartesian coordinates $\{X, Y, Z\}$ by $x$ $=\sqrt{X^{2}+Y^{2}+Z^{2}}$, which measures the Euclidean distance to the puncture at the origin, and

$$
\begin{equation*}
g_{i j}(\tau, x):=\frac{G_{i j}(\tau, x)}{\Psi^{4}(x)} \text { with } g(\tau, x):=\frac{G(\tau, x)}{\Psi^{4}(x)} \tag{123}
\end{equation*}
$$

has been introduced.
Again it is worth pointing out that for the initial slice the radial grid coordinate $x$ is identical to the Schwarzschild isotropic coordinate $R$ defined in Eq. (38) and hence related to the Schwarzschild radial coordinate $r$ by

$$
\begin{equation*}
r(\tau=0, x)=x \Psi^{2}(x) \tag{124}
\end{equation*}
$$

as discussed in Sec. III. Note, furthermore, that for black hole puncture initial data the 3-metric $G_{i j}$ is implemented in isotropic coordinates, hence

$$
\begin{equation*}
G(\tau=0, x)=\Psi^{4}(x) \quad \text { and } \quad g(\tau=0, x)=1 \tag{125}
\end{equation*}
$$

has to hold initially.
Notice that as a time-independent, trivial case the odd boundary conditions are included and lead to the isotropic lapse of Sec. III together with the formulas (124) and (125) valid at all times, which yields the static Reissner-Nordström metric in isotropic coordinates. However, due to the negative values of the lapse in the region between the puncture and the throat, with an observer going backward in time, its numerical implementation has been found to be unstable in at least one example [49].

In the following we use the observation that the puncture data line element for zero shift has to have a 3-metric with a time-independent determinant. As remarked in Sec. III, this is a consequence of maximal slicing, $K \equiv 0$, in combination with a vanishing shift, $B \equiv 0$. Considering the ansatz (121), one can see that due to the time independence of the conformal factor the determinant of the rescaled 3-metric $g_{i j}$ $=G_{i j} / \Psi^{4}(x)$ also has to be time independent and hence to be a function of $x$ only. The latter can be determined on the initial slice to be given by $\operatorname{det}\left\{g_{m n}\right\}=x^{4} \sin ^{2} \theta$ using the initial conditions (124) and (125). So it follows that the rescaled radial part of the 3-metric can be written as

$$
\begin{equation*}
g(C(\tau), x)=\frac{x^{4} \Psi^{8}(x)}{r^{4}(C(\tau), x)} \tag{126}
\end{equation*}
$$

It is from $G=\Psi^{4} g=x^{4} \Psi^{12} / r^{4}=\gamma(\partial r / \partial x)^{2}$ now trivial to infer for fixed slice label $C$ the ODE

$$
\begin{equation*}
\frac{\partial r}{\partial x}= \pm \frac{\sqrt{p_{C}(r)}}{r^{4}} x^{2} \Psi^{6}(x) \tag{127}
\end{equation*}
$$

which relates the Schwarzschild radial coordinate $r$ to the radial coordinate $x$ for puncture evolutions. This can be integrated as

$$
\begin{equation*}
\int_{r_{C}}^{r} \frac{y^{4} d y}{\sqrt{p_{C}(y)}}= \pm \int_{x_{C}}^{x} y^{2} \Psi^{6}(y) d y \tag{128}
\end{equation*}
$$

using the throat as lower integration limit. Here $x_{C}$ denotes the location of the throat on the grid as a function of time and the "+" and "-" sign applies for the right-hand or lefthand side of the throat, respectively. One may readily check that for $C=0$ the ODE (127) coincides with the ODE (37) found for Schwarzschild isotropic coordinates leading in that case to $x=R$ with the throat at $r_{C=0}=r_{+}$and $x_{C=0}=x_{+}$ $=R_{+}=\frac{1}{2} \sqrt{M^{2}-Q^{2}}$. For later times, though, $x_{C}$ has to be found from Eq. (128) by demanding that the coordinate transformation $r=r(C(\tau), x)$ is consistent with the requirement of a vanishing shift. See [20] for details and for a discussion of the late time behavior of $x_{C}$ in the case of the even and the "zgp" boundary conditions.

Given these coordinates, we can finally compare the analytically given 4-metric with cactus output for maximal slicing of a Schwarzschild black hole with zgp boundary condition and vanishing shift. The time-dependent profiles, namely the coordinate transformation relating $r$ and $x$, the "outward moving shoulder" obtained for the collapse of the lapse and the growing peak in the radial component of the 3-metric, are plotted in Figs. 7, 8, and 9, respectively. Similar numerical results can also be found in the literature, see, e.g., Fig. 3.16 in Ref. [50] or Figs. 2 and 6 in Ref. [31] and Fig. 2 in Ref. [6], where instead of $x$ in the latter references usually a logarithmic radial coordinate has been used.

For Figs. 7-9 the reader should bear in mind that for odd boundary conditions the time-independent coordinate transformation relating Schwarzschild radial and isotropic coordinates is given by Eq. (38), the isotropic lapse by Eq. (40) and


FIG. 7. The Schwarzschild radial coordinate $r$ as given by Eq. (128) in the context of "zgp" boundary conditions is shown as a function of the isotropic radial coordinate $x$ for maximal slices with times at infinity $\tau_{z g p}=\{0,1 M, 2 M, 4 M, 8 M\}$. The slices are horizon penetrating and approach the limiting slice $r={ }^{0} r_{C_{\text {lim }}}=3 M / 2$ asymptotically. Data points from a CACTUS run have been plotted as filled boxes, which agree well with analytic results. The throat (located as minimum of the radial coordinate and depictured by a box) is found to move to the right-hand side of its initial location ${ }^{0} x_{+}=M / 2$, whereas the left-hand and right-hand event horizon (both now corresponding to $r={ }^{0} r_{+}$ $=2 M$ and denoted by downward and upward pointing triangles) move to the left and right, respectively.
the rescaled radial part of the 3-metric is simply $g=G / \Psi^{4}$ $\equiv 1$. Although both the evaluation of the underlying analytical expressions (as described in Ref. [21]) on the one hand and the numerical simulations (with errors introduced by finite differencing and the outer boundary) on the other hand


FIG. 8. The analytically derived collapse of the lapse is shown for "zgp" boundary conditions as solid lines for the slice again corresponding to $\tau_{z g p}=\{0,1 M, 2 M, 4 M, 8 M\}$. These curves have been obtained by evaluating $\alpha_{z g p}^{ \pm}(C, r)$, Eq. (92), in the context of the coordinate transformation (128) shown in Fig. 7. CACTUS results from the best resolved run are shown as boxes lying almost on top of the analytically found collapsing lapse profile. An "outward moving shoulder" is obtained as the lapse decreases exponentially to zero at the puncture, at the left-hand event horizon, and at the throat, but approaches the finite value ${ }^{0} C_{\text {lim }} /{ }^{0} r_{+}^{2}=\frac{3}{16} \sqrt{3} \approx 0.3248$ at the right-hand event horizon.
contain numerical errors, the CACTUS data points virtually lay on top of the analytic curves.

We want to emphasize that for arbitrary boundary conditions the coordinate transformation $r=r(C, x)$, Eq. (128), holds, with differences in the time dependence of the slice label $C(\tau)$ and the (in general time-dependent) location of the throat $x_{C}$. For this-an exception being the timeindependent odd case discussed previously-e.g., the unbounded growth of the radial metric function $g(C, x)$ $=x^{4} \Psi^{8}(x) / r^{4}(C, x)$, Eq. (126), as shown in Fig. 9 for "zgp" boundary conditions, is not only a feature of the puncture lapse. Even worse, in the context of zero shift this slice stretching effect is a fundamental property of maximal slicings when avoiding singularities as will be discussed further in [20].

The development of the peak in the metric shown in Fig. 9 is the combined effect of local observers falling into the black hole and the collapse of the lapse function shown in Fig. 8. The coordinate points at smaller values of the isotropic coordinate have larger infall speeds, causing the radial metric component $g$ to increase towards smaller $x$. However, at the same time, there is a competing effect due to the use of the singularity avoiding slicing. The motion of the grid points close to the puncture at $x=0$ is frozen as the lapse collapses there. Well inside, the latter effect dominates, and $g$ cannot increase in time. This causes the radial metric function to develop a peak at a place slightly inside the righthand event horizon. At this location, the difference in the infalling speed of the grid points is large, but the lapse has not completely collapsed.

Finally, we want to mention that if one demands a timeindependent 3-metric $G_{i j}$, by looking at the angular part of both $G_{i j}$ and $\gamma_{i j}$ given by $r^{2} d \Omega^{2}$ it is obvious that the coor-


FIG. 9. For the radial component $g$ of the conformally rescaled 3 -metric $g_{i j}$ for the "zgp" Schwarzschild case in the manner of the previous figures, a comparison of the analytical result $g(C, x)$ $=x^{4} \Psi^{8}(x) / r^{4}(C, x)$, Eq. (126), and CACTUS output is made. Note that whereas $g \equiv 1$ holds for the odd case, for other boundary conditions similar slice stretching effects are present in the radial metric component as will be discussed further in [20].
dinate transformation relating $r$ and $x$ has to be time independent and hence to be given by Eq. (124). Therefore this requirement inevitably leads to the isotropic lapse. This observation is relevant for the construction of initial data for black hole punctures on a maximal slice. Such data can satisfy some of the necessary conditions for the existence of helical Killing vectors [51], which is appropriate when looking for binary black holes in a quasiequilibrium orbit. As initial condition on the gauge one may want to impose not only the condition that the lapse is a maximal slicing lapse, but furthermore that it is everywhere positive. But as we have just argued, for Schwarzschild it is only the isotropic lapse for which the metric $G_{i j}$ is time independent, and conversely we conclude that for positive lapse the metric will not be time independent, which conflicts with the quasiequilibrium condition. This was first noted in Refs. [21,51] and independently in Ref. [52].

## VIII. CONCLUSION AND OUTLOOK

We have introduced the "zero gradient at the puncture" boundary condition for maximal slicing of the Schwarzschild and Reissner-Nordström spacetimes. Comparing analytical and numerical results for Schwarzschild, this boundary condition leads to convincing agreement with the numerically computed evolutions for maximal slicing and vanishing shift. As an application of the analytical form for the zgp or puncture lapse, we can derive a late time limit for the lapse at the right-hand event horizon, which is consistent with previous numerical estimates.

Let us mention several directions for further investigations. First of all, in Ref. [20] we will give a detailed late time analysis for the maximal slicing of Reissner-Nordström
puncture data, extending the results for Schwarzschild obtained in Ref. [4]. We will discuss there the late time behavior of the 4-metric at the puncture, the throat and the event horizons. Note that all of our numerical results refer to the Schwarzschild spacetime. Future numerical work could include an electric charge in the range $0<|Q|<M$.

Maximal slicing is a special case of constant mean curvature slicings, see for example Ref. [19]. It would be interesting to see whether constant mean curvature slicing is amenable to a similar analysis as presented here, and whether there is a promising avenue for numerical simulations.

As mentioned in the introduction, maximal slicing has in some cases been replaced with algebraic slicings of the " 1 $+\log$ " type, see Ref. [11] for recent work on puncture evolutions. It may be possible to gain analytic insight into $1+\log$ slicing, which in fact in some regards mimics maximal slicing. For example, one would like to understand the singularity avoidance properties of $1+\log$ slicing better. A first attempt to study this problem has met with technical difficulties, but further work is certainly warranted.

Of particular interest from the point of view of numerical relativity is an analytical study of elliptic shift conditions in Schwarzschild, say the minimal distortion shift condition. A maximal slicing lapse together with a minimal distortion shift have been suggested as a natural coordinate choice for numerical simulations [1]. While the minimal distortion shift has not been successful for puncture evolutions, a closely related shift condition called Gamma freezing or conformal 3-harmonic has to some extent solved the long standing slice stretching problem of maximal slicing for single black hole and head-on collision simulations [11]. In that reference this shift is implemented as an evolution equation for the shift, but it is the elliptic version which is more easily studied analytically. A key feature of the Gamma freezing shift is that when it is combined with maximal or $1+\log$ slicing an approximately time independent metric is obtained for the final, static black hole. While in the present paper we answered the question whether there exists a maximal slicing corresponding to the numerically obtained zgp lapse, we now can ask the question whether for zgp maximal slices there exists a shift condition such that the evolution of the metric in the resulting coordinates is minimized. Some steps in this direction can already be found in Ref. [21].

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[53] We will not discuss these slices further. However, note that similar "singularity-horizon" slices extending from the singularity to infinity can be derived for constant mean curvature slicing, i.e., $K \equiv$ const $\neq 0$, see Ref. [19] for details.
[54] This was suggested to us by R. Beig, whom we would like to thank for very useful conversations and valuable comments.
[55] Furthermore, we observed that $r\left(\tau_{z g p}, x\right)$ obtained independently as square root of the prefactor of the angular metric part and via the cactus thorn "Extract" coincides up to numerical error. The latter thorn is normally used for gravitational wave extraction for observers at some distance from the source that coincides for a Schwarzschild black hole with the Schwarzschild radial coordinate $r$ calculated from an expansion of surface integrals of metric components.

