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Impact of 4D-variational assimilation of WOCE hydrography on the meridional circulation of the Indian Ocean

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Abstract

World Ocean Circulation Experiment (WOCE) hydrographic sections and a sea-surface climatology are combined with a ocean general circulation model through a 4D-variational method to analyze the meridional overturning of the Indian Ocean. The regional model is run with realistic surface forcings over year 1995 for which most of WOCE Indian Ocean sections were made. The assimilation controls the initial temperature and salinity fields, surface forcings and open-boundary velocities, temperature and salinity. When no observations are assimilated, the model shows that the deep (below 1000 m) meridional overturning is weak compared to observation-based estimates. This is a common feature of general circulation models. In contrast, after the assimilation, the model develops a deep overturning of 17×10^6 m³ s⁻¹ at 32°S when a 10×10^6 m³ s⁻¹ Indonesian Throughflow (ITF) is prescribed. The mass flux of bottom waters that moves northward below 3200 m is balanced by a southward mass flux of deep waters between 1000 and 3200 m. The deep overturning carries 10% of the total southward energy flux of 1.2 PW at 32° S. The intensity of this deep overturning changes only by $\pm 2 \times 10^6$ m³ s⁻¹ when the annual mean ITF is zero or 30×10^6 m³ s⁻¹. The upper circulation is less constrained by the assimilation because of the large temporal and spatial variability of this ocean and also because of limitations in the representation of the mixed layer physics during the assimilation process. Limitations in the physics of the model also are thought to be the source of the slow erosion of the deep overturning when the model is run for several years from its optimal state.

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1. Introduction

The meridional overturning circulation (i.e. zonally integrated circulation) of the Indian Ocean is still the subject of a large range of estimates. Such a description of the circulation, although it remains basic, is an important parameter since it gives the overall budget of various properties for a

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given basin, thus ranking the role of the basin in the global balance. Because the Indian Ocean has been less observed than other oceans, there remains large uncertainties concerning the structure and intensity of its meridional overturning. Especially, estimates from hydrographic inversions are not consistent with the picture given by ocean general circulation models. These two approaches particularly differ in their representation of the deep circulation below 1000 m.

On the one hand, inverse models based on hydrographic oceanic transects show that there

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exists a deep overturning in the Indian Ocean. The magnitude of this deep overturning at 32°S is estimated to be $10.1 \times 10^6 \text{ m}^3 \text{ s}^{-1}$ (Bryden and Beal, 2001), $11+4 \times 10^6 \text{ m}^3 \text{ s}^{-1}$ (Ganachaud et al., 2000), $12\pm3\times10^6$ m³ s⁻¹ (Robbins and Toole, 1997), $17\pm5\times10^6$ m³ s⁻¹ (Macdonald, 1998), $23 \pm 3 \times 10^{6} \text{ m}^{3} \text{ s}^{-1}$ (Sloyan and Rintoul, 2001). Older estimates widen the range of possible values (Fu, 1986; Toole and Warren, 1993). Such estimates depend on the choice of hydrographic lines, properties and their conservation equations (constraints), free parameters (control variables), and the weight given to each constraint. These estimate are questionable because most of these studies (i) assume that the circulation is stationary, (ii) combine hydrographic lines that are taken at different seasons and years, and (iii) use simplistic physics.

On the other hand, ocean general circulation models only show weak deep overturning (Wacongne and Pacanowski, 1996; Garternicht and Schott, 1997; Lee and Marotzke, 1997, 1998; Zhang and Marotzke, 1999). These model estimates are also questionable because models (i) suffer from subgrid-scale parameterizations that generate model errors, (ii) are blended with surface forcing errors, and (iii) are started from smoothed climatologies that cannot represent the major boundary currents accurately.

We propose to reconcile the two approaches by using a general circulation model to assimilate the recent WOCE hydrography of the Indian Ocean. We use a 4D-variational method (e.g., Le Dimet and Talagrand, 1986; Thacker and Long, 1988) that exploits the dynamics of an ocean general circulation model to propagate information contained in the observations distributed in time and space. This method naturally links all available observations with each other to produce an estimate in which observations are consistent with the dynamics of the model. This study focuses on the impact produced by the assimilation of WOCE hydrography on the deep meridional overturning circulation. Although some other typical characteristics of the Indian Ocean circulation are given, the detailed description of the circulation is left for a subsequent study.

2. Configuration of the experiment

The 4D-variational approach is an iterative process that uses a forward model and the adjoint of its tangent-linear model. The time integration of the forward non-linear model gives a measure (or cost function) of the cumulated misfits between the data and their model analogues in a least square sense. The data consist of observations and also include the first guess. Model-data misfits are weighted by some error covariances. In this study, all the error covariance matrices are diagonal; that is, there is no correlation between two different data. Model-observations misfits act as constraints on the adjoint model. The backward time integration of the adjoint gives the gradient of the cost function to some independent variables of the model (or control variables). A descent algorithm is then used to calculate the amplitude of the independent variables so that, at the next iteration, the model trajectory is closer to the observations. Iterations are stopped as soon as the model trajectory is consistent with the observations. The estimated trajectory is then optimal with respect to the constraints. For further details about the method, the reader is referred to Le Dimet and Talagrand (1986) and Thacker and Long (1988). Observations are composed of the WOCE hydrography and the monthly Levitus et al. (1994) sea-surface climatology. As the WOCE hydrography was measured nearly over a 1-year time period, the forward and adjoint models are integrated during 1 year at each iteration to respectively produce the cost function and its gradient. Using a 1-year time window is necessary to propagate the information contained in the sparse observations through the assimilation scheme. A shorter time window would contain less observations which would be insufficient to act as a constrain on the model.

2.1. Configuration of the forward and adjoint models

This work uses the M.I.T. ocean general circulation model (Marshall et al., 1997a,b), which is based on the primitive equations under the Boussinesq approximation. The Indian Ocean

domain extends from $(24^{\circ}\text{E}, 35^{\circ}\text{S})$ to $(122^{\circ}\text{E}, 26^{\circ}\text{N})$ (Fig. 1). The horizontal resolution is 1°, with 22 levels in the vertical (10 m resolution near the surface down to 500 m for the last six levels). The model bathymetry is interpolated from ETOPO5 data (1988). Mixing processes are parameterized through a convection algorithm and constant eddy diffusivity coefficients $(K_h^{\text{dyn}} = 2 \times 10^4 \text{ m}^2 \text{ s}^{-1}, K_v^{\text{dyn}} = 2 \times 10^{-3} \text{ m}^2 \text{ s}^{-1}, K_h^{\text{trac}} = K_h^{\text{dyn}}/20, K_v^{\text{trac}} = K_v^{\text{dyn}}/100$ where K_h is the horizontal diffusivity, K_v is the vertical diffusivity, superscript dyn stands dynamics and trac for tracers).

Prescribed open boundaries are set up at 35°S and at 122°E allowing for an Indonesian through-flow to exist. Open-boundary velocities are interpolated from Stammer et al.'s (1997) global ocean circulation estimate. These open-boundary velocities were corrected to have no net mass transport divergence. Temperature and salinity at the open boundary are prescribed from the Levitus et al. (1994) climatology to be consistent with the spin-up that uses restoring towards Levitus's climatology. During a run, open boundaries are linearly

interpolated from monthly velocity and tracer (temperature and salinity) fields. Twice-daily winds and daily heat and freshwater fluxes from re-analyses of the National Center for Environmental Prediction (NCEP) force the ocean surface. Velocities at the open boundaries and surface forcings correspond to year 1995 to be consistent with WOCE hydrography.

The adjoint of the primitive equation model (Marotzke et al., 1999) is generated with the tangent-linear and adjoint model compiler (Giering and Kaminski, 1998). A quasi-Newton method (Gilbert and Lemaréchal, 1989) is used to compute changes in the control variables. Because the cost function is not sensitive to the velocities at the open boundary when observations (CTDs and seasurface properties) are assimilated, the assimilation is split into two steps. The first step assimilate observations to control the initial guess in temperature and salinity, tracers at the open boundary and surface forcings. Changes in the control variables induced by step 1 produces a new first guess in which the interior (away from the open boundaries) circulation is not consistent with

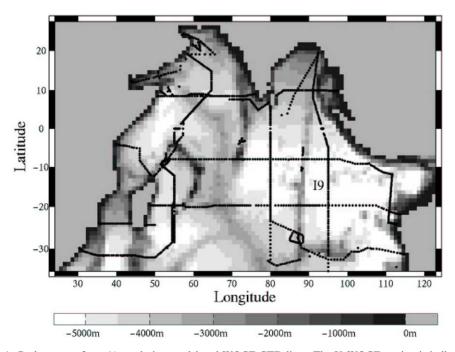


Fig. 1. Bathymetry of our 1° resolution model and WOCE CTD lines. The I9 WOCE section is indicated.

velocities at the open boundaries. Starting from this new first guess, step 2 controls open boundary velocities under the constraint that those velocities must be consistent with the interior flow. Ideally, all constraints should be applied in one step. But, because the assimilation of the hydrography generates large changes in the initial guess stratification in step 1, an adjustment occurs during the first 2 months of time integration. Demanding open boundary velocities to be consistent with the interior flow during the adjustment period (which happens when all constraints are applied simultaneously) produces spurious recirculation near the open boundary. That is why we decided to apply this constraint in a second step, starting from a first guess in which the dynamics is balanced by interior stratification. Note that the development of a multivariate assimilation scheme that produces geostrophically balanced control variables would be a solution to apply all constraints in one step.

2.2. Step 1: Control of the initial guess, tracers at the open boundary, and surface forcings

During the first step, a series of iterations is performed with the WOCE hydrography (Fig. 1) and the monthly Levitus sea-surface temperature and salinity as observations. Most of the CTD lines were occupied during year 1995 except few of them which were done at the beginning of year 1996 (before 22 January). In the assimilation, it has been assumed that the 1996-measurements were made at the same time as the last 1995-measurement (31 December). Hence, in the following, only year 1995 is simulated.

During the first step, the control variables are the initial temperature and salinity 3D-fields, the time varying temperature and salinity at the open boundaries, and the surface forcings. Surface forcings are controlled once every 12 days to limit the size of the problem (note that 12 days is of the order of the decorrelation time of the atmosphere, which is consistent with our simplification that errors are uncorrelated). Linear interpolation is applied between the timesteps where the surface forcings are controlled. Open boundaries are controlled monthly, that is with the same fre-

quency as their forcing. The cost function reads:

$$\begin{split} J_{1} &= X_{T_{0}}^{T} B_{T_{0}}^{-1} X_{T_{0}} + X_{S_{0}}^{T} B_{S_{0}}^{-1} X_{S_{0}} \\ &+ X_{T_{0b}}^{T} B_{T_{0b}}^{-1} X_{T_{0b}} + X_{S_{0b}}^{T} B_{S_{0b}}^{-1} X_{S_{0b}} \\ &+ X_{\tau_{x}}^{T} B_{\tau_{x}}^{-1} X_{\tau_{x}} + X_{\tau_{y}}^{T} B_{\tau_{y}}^{-1} X_{\tau_{y}} \\ &+ X_{hf}^{T} B_{hf}^{-1} X_{hf} + X_{E-P}^{T} B_{E-P}^{-1} X_{E-P} \\ &+ (T_{\text{model}} - T_{\text{CTD}})^{T} R_{T_{\text{CTD}}}^{-1} (T_{\text{model}} - T_{\text{CTD}}) \\ &+ (S_{\text{model}} - S_{\text{CTD}})^{T} R_{S_{\text{CTD}}}^{-1} (S_{\text{model}} - S_{\text{CTD}}) \\ &+ (\overline{SST}_{\text{model}} - SST_{\text{Levitus}})^{T} \\ &\times R_{\overline{SST}_{\text{model}}}^{-1} (\overline{SST}_{\text{model}} - SSS_{\text{Levitus}})^{T} \\ &\times R_{\overline{SSS}_{\text{model}}}^{-1} (\overline{SSS}_{\text{model}} - SSS_{\text{Levitus}}), \end{split}$$

where X is a vector of deviations from control variables, B is the error covariance matrix relative to the control variables, R is the error covariance matrix for the observations, T_0 (S_0) is the first guess 3D-temperature (salinity) field from which the model is initialized, $T_{\rm ob}$ ($S_{\rm ob}$) is the first guess temperature (salinity) at the open boundary, τ_x (τ_y) is the first guess zonal (meridional) wind stress, hf is the first guess net heat flux, E-P is the first guess freshwater flux, $T_{\rm CTD}$ ($S_{\rm CTD}$) are the CTD temperature (salinity) profiles and $T_{\rm model}$ ($S_{\rm model}$) their model counterpart, $SST_{\rm Levitus}$ ($SSS_{\rm Levitus}$) are the monthly sea-surface temperature (salinity) climatology and $\overline{SST}_{\rm model}$ ($\overline{SSS}_{\rm model}$) their model counterpart.

During an iteration, the forward non-linear model is integrated over year 1995. During this integration, the cost function cumulates all modelobservation misfits (last four terms in J_1) up to the last time-step (December 31). Then, the adjoint model is integrated backward from the last day of December back to the first day of January. This adjoint run provides the cost function gradients with respect to the control variables. For instance, if the wind stress on June 6 0h00 is a control variable, model-observation misfits occuring after this date will give an non-zero cost function gradient with respect to this control variable if those misfits are non-zero. Once the adjoint run is achieved, all the gradients are available and a descent algorithm is applied to get the amplitude of the deviation for each control variable. At the next iteration, our 3D wind stress field on June 6 0h00 will be its first guess value plus the corresponding 3D deviation calculated by the descent algorithm. Note that as error covariance matrices are diagonal, properties of the first guess fields are not conserved (like the wind curl for example).

During the first evaluation of the cost function (first iteration), the first eight terms of J_1 , which penalize the deviation (i.e. drift) from the first guess, are 0 since the control variables are 0; Only model-observation misfits force the adjoint equations. In subsequent iterations, the first guess is modified to decrease model-observation misfits. Hence for these iterations, both model-observation misfits and deviations from the first guess force the adjoint equations. The first eight terms of J_1 prevent the assimilation from producing optimized control variables that are unrealistic relatively to our knowledge of uncertainties (contained in the error covariance matrix) on these control variables.

2.3. Step 2: Control of velocities at the open boundary

During the second step, the only control variables are the open boundary velocities. They are controlled under the constraint that vertical velocities along the open boundaries should not exceed generic values found in the interior. The cost function then reads:

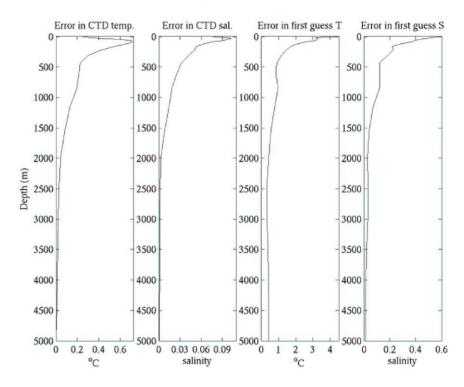
$$J_{2} = X_{U_{ob}}^{T} B_{U_{ob}}^{-1} X_{U_{ob}} + X_{V_{ob}}^{T} B_{V_{ob}}^{-1} X_{V_{ob}} + \overline{W_{ob}}^{T} R_{W_{ob}}^{-1} \overline{W_{ob}},$$
(2)

where $X_{U_{ob}}(X_{V_{ob}})$ are deviations from the zonal (meridional) velocities at the open boundaries, \overline{W}_{ob} are the monthly mean vertical velocities along the open boundaries.

Several sensitivity experiments have shown that the Indonesian Throughflow (ITF) transport is not constrained by the data we assimilate. That is the gradient of the cost function to the throughflow transport is weak so that the assimilation scheme does not change it. Hence, this second step adjusts the open-boundary velocities to the interior flow without controlling the throughflow transport. For this second step to work, a new first guess needs to be built. Indeed, at the end of the first step, initial temperature and salinity fields have been modified so that the initial velocity fields are no more dynamically balanced. The new first guess is built by integrating the model during one year from the estimated parameters of the first step. This time integration is necessary to spin-up the model before launching step two. If this spin-up is not achieved, the initial adjustment that occurs within the first two months enters in the assimilation process of step two, and leads to spurious meridional recirculation along the open boundaries.

2.4. Error covariances

The depth-dependent errors in the CTD temperature and salinity are calculated as follow: For each vertical profile of CTD temperature and salinity, a local standard deviation profile was first calculated from profiles within a distance of two degrees and within a time of 2 weeks. The effect of internal waves was then added as a source of error assuming the internal wave spectra follows the Garrett and Munk (1975) spectra. A minimum error of 10^{-3} psu is prescribed for the salinity. Profiles of the depth-dependent error that finally weights the model-CTD misfits (Figs. 2a and b) are the average of these local standard deviation profiles for the temperature and the salinity. They thus encompass changes due to time and subgridscale variability. These vertical profiles (Figs. 2a) and b) show that errors are the largest below the sea surface for both the temperature and the salinity. This is related to the position of the main thermocline and halocline located below the weak stratification of the first tens of meters. The main halocline is shallower than the main thermocline which explains the difference in maximum error depth. Note that the use of local standard deviation profiles instead of their average prevent the assimilation from converging to a consistent level because those profiles may vary too drastically from one profile too its neighbour. The use of the average of the local profiles produces smoother and more consistent changes in the control variables than when local profiles are used.



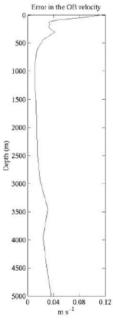


Fig. 2. Vertical profiles of the error in (a) CTD temperature, (b) CTD salinity, (c) first guess temperature, (d) first-guess salinity, and (e) open-boundary (OB) velocity.

Errors in Levitus sea-surface temperature and salinity are assumed spatially constant. They correspond to one-fourth of the standard deviation of the difference between CTDs and their Levitus counterpart. This leads to an error of 0.5°C for the sea-surface temperature and of 0.08 psu for the sea-surface salinity. The factor one-fourth was chosen to prevent sea-surface properties from drifting when the model is started from the optimized state and run for several years.

Errors in the initial temperature and salinity (Figs. 2c and d) are inferred from an average of standard deviations computed from the CTDs and their model counterpart taken from a prognostic run of one year started from the first guess. The depth-dependent profile obtained reflects large errors near the surface both in temperature and salinity. Same errors are taken for the open-boundary temperature and salinity since open boundaries are forced with Levitus climatology, which is also used to construct the first guess.

Atmospheric models produce large relative errors in the heat and freshwater fluxes. For our assimilation, we took an error on those fluxes that is of the order of the standard deviation of the fluxes calculated over year 1995 and averaged over the whole domain. This gives an error in the heat flux of 80 W m⁻² and of 1 m year⁻¹ for the freshwater flux. Errors in the wind stress are calculated as standard deviations from NCEP and ERS over year 1995. They are regional to enforce larger errors in the regions of monsoon.

For the second step, vertical velocities along the open boundaries larger than $10^{-5} \,\mathrm{m \, s^{-1}}$ are penalized. Depth-dependent error profile in the open boundary velocities (Fig. 2e) are equal to the standard deviation calculated from the difference in velocities away from the open boundaries between one-year runs before and after step one.

3. Ocean circulation without assimilation

A 11-year long spin up of the model is obtained from starting the model at rest with the initial temperature and salinity fields taken from Levitus et al. (1994). The model undergoes 11 cycles of slightly modified year 1995 forcings. During the

spin up, temperature and salinity are restored towards Levitus et al. (1994) in the first 12 levels to prevent the model from drifting. The restoring coefficient are set to one day at the surface, 10 days at the second level and 30 days at deeper levels. The ITF is forced to have an annual mean transport of $10 \times 10^6 \text{ m}^3 \text{ s}^{-1}$ with a seasonal variation in the range of $6 \times 10^6 \text{ m}^3 \text{ s}^{-1}$ (February) to 13×10^6 m³ s⁻¹ (June). This throughflow intensity is in the range of values estimated from observations and models. Gordon et al. (1999) reported a transport about 9 to 10×10^6 m³ s⁻¹ for 1997 through the Makassar Strait, which is considered as the main source of Pacific waters that feeds the ITF. Since the interannual variability of the throughflow intensity might be important, the sensitivity of our estimated circulation to this parameter is investigated in Section 5.

Year 11 of the spin up is considered as the reference state of the forward model without assimilation. The model develops a circulation with an annual mean Agulhas Current transport of 75×10^6 , 70×10^6 m³ s⁻¹ during January and $78 \times 10^6 \text{ m}^3 \text{ s}^{-1}$ at the end of September. The Mozambique Channel carries an annual mean southward transport of 22×10^6 m³ s⁻¹, with a minimum of 12×10^6 m³ s⁻¹ during February and a maximum of 39×10^6 m³ s⁻¹ during October. Eddies may contribute to a significant part of the transport through the Mozambique Channel (Biastoch and Krauß, 1999). Although our model is not eddy-permitting, its Mozambique Channel annual mean transport and seasonal variability fit in the range of previous estimates (DiMarco et al., 2001 for a review).

Fig. 3 shows the annual mean meridional overturning (zonally integrated circulation) based on an average of the monthly fields. Like in previous modelling studies, the meridional overturning circulation is mainly intensified in the first 500 m, south of the Equator. The shallow cell connects the Tropics to the Equator and transports $13 \times 10^6 \text{ m}^3 \text{ s}^{-1}$. Below 3000 m, $6 \times 10^6 \text{ m}^3 \text{ s}^{-1}$ moves northward up to 12°S . This deep inflow is compensated by a southward flow around 1000 m. This pattern, though similar to other general circulation models, is not consistent with recent hydrographic inversions. Especially,

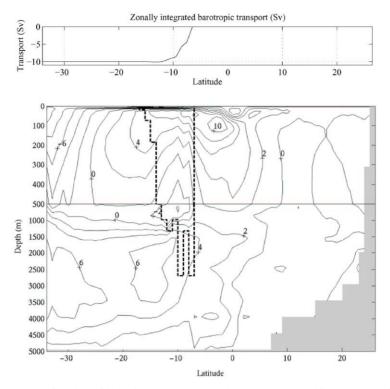


Fig. 3. Meridional transport as a function of latitude (upper panel) and annual mean meridional overturning (lower panel) of the model without assimilation (units \times 10⁶ m³ s⁻¹). Note that in the region of the ITF (area bounded by the dashed line), the flow is divergent and isolines depict constant transport integrated from the bottom.

Ganachaud et al. (2000) still find a northward flow of $10.2\pm3\times10^6$ m³ s⁻¹ at 8°S using a global inversion of the WOCE data, whereas only 4×10^6 m³ s⁻¹ remains at this latitude in our reference circulation. Moreover, as referenced in the introduction, most of the recent hydrographic inversions show that between 11 and 23×10^6 m³ s⁻¹ of deep and bottom waters should propagate northward at 32° S. Our estimate is significantly lower.

In the reference circulation, the southward energy flux across $32^{\circ}S$ is 1.1 PW ($1 \text{ PW} = 10^{15} \text{ W}$). This flux is the sum, scaled to PW, of the product of the temperature referenced to $0^{\circ}C$ by the velocity across the section. At this section, Sloyan and Rintoul (2001) estimate a southward flux of $0.87 \pm 0.06 \text{ PW}$, Ganachaud et al. (2000) find $1.5 \pm 0.2 \text{ PW}$, Macdonald (1998) finds $1.30 \pm 0.28 \text{ PW}$, and Toole and Warren (1993) find 1.67 PW. The reference circulation fits in the broad range of possible values. Our maximal southward

energy flux is 1.3 PW at 14°S and is due to both the presence of the ITF and the heat gained in the northern Indian Ocean. In this simulation, the restoring to Levitus climatology also provides other sources and sinks of heat.

For the throughflow, Ganachaud et al. (2000) reported westward energy flux of 1.36 ± 0.15 PW across the Java Australia Dynamic Experiment section (Fieux et al., 1994). In our reference circulation and for this section located around 115°E, the Indonesian throughflow carries two-fold less energy flux. Our energy flux is smaller because our throughflow transport is 33% smaller than Ganachaud et al. (2000) estimate and also because our transport weighted temperature is weaker. However, from temperature-current meters, Vranes et al. (2001) estimate an westward flux of 0.55 PW within the Makassar Strait from December 1996 to July 1998. Again, the model fits the range of published estimates.

4. Minimization

4.1. Step 1

The minimization starts from the first guess, which is the ending state of the year 10 of the spin up. The forward model and its adjoint undergo several iterations to minimize the cost function of year 11 (Eq. (1)). During this process, no restoring to Levitus fields is activated at any depth since the assimilation of Levitus fields at the sea surface should rectify the drift of the model.

Figs. 4a and b detail the contributions of cost function terms. Each term is normalized so that a value of one (level of consistency) means that the term is consistent with its a priori error. Iteration zero corresponds to the forward model run from the first guess before any changes are made in the control variables. The scale of the *Y*-axis being logarithmic, contributions from the control variables are not plotted at iteration zero.

Initially, the major misfits relate to the CTD temperature and to the Levitus temperature and salinity climatology. The misfit to CTDs is 20-fold less in the salinity than in the temperature. That is, most of the modifications in the interior stratification will be due to the temperature constraint. Misfits to the sea-surface climatology are mainly due to errors in surface forcings and mixed layer physics that generate a drift of the forward model. Misfits to the CTD observations mainly come from errors in the first guess. The assimilation is stopped at iteration 20 to prevent an overfitting of the model to the surface climatology. As Fig. 4a shows, misfits to the CTD observations are still slightly above the consistency level at iteration 20. Ten more iterations bring misfits to CTD observations at a consistency level but results in a overfitting of the model to the sea-surface climatology. Since no significant differences appears between the estimated circulation from iteration twenty and those from iteration 30, step 1 is stopped at iteration 20.

In order to investigate how the misfit to the CTD temperature is distributed in the vertical, Figs. 5a and b show this misfit scaled by its error along the meridional WOCE section 19 (Fig. 1). For reason of clarity, only the absolute value of

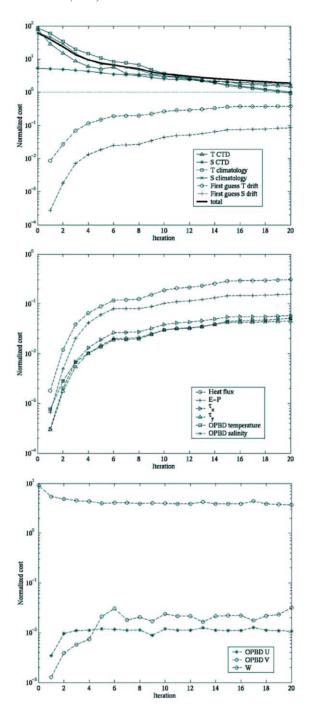


Fig. 4. (a) Total cost for step 1 as a function of iteration number and contributions from misfits to CTD observations and climatology and from first guess control variables, (b) contributions from the other control variables. Each cost is normalized by its number of elements, and (c) same as (a) but for step 2 of the assimilation.

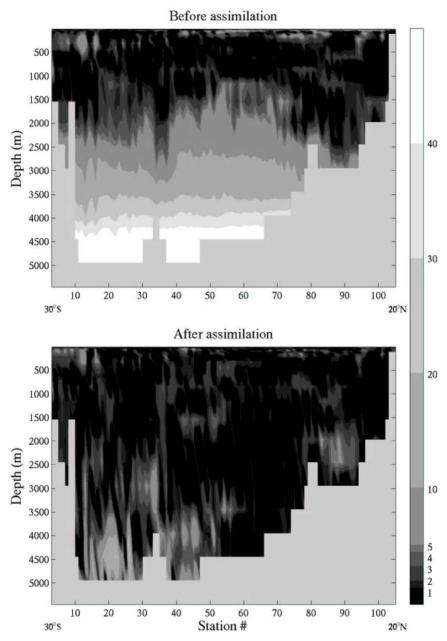


Fig. 5. Absolute value of the model-CTD temperature misfit scaled by the error in the temperature of the CTDs along the I9 WOCE section. Upper panel: state before step 1. Lower panel: state after step 1.

the scaled misfit is represented. Before the assimilation (Fig. 5a), the largest misfit (larger than a factor 40) occurs at depth. This vertical structure reflects those of the error in the CTD temperature, which is the weakest at depth (Fig. 2a). Hence,

because the deep circulation has less spatial and temporal variability (a criteria used for constructing the error on CTDs), CTD data will mostly constrain the deep circulation. After the assimilation (Fig. 5b), most of the misfit has been

significantly reduced. Some regions still exhibit important misfits. Continuing the iterations decrease these local residuals, but again this does not lead to any detectable changes in the meridional overturning circulation.

Figs. 4a and b show that the major changes in the control variables, relative to their error, concern the first-guess temperature field and the surface heat flux and also, in a lesser extent, the surface freshwater flux and the first-guess salinity field. The wind stress is not directly controlled by the set of observations of temperature and salinity used in the assimilation since it redistributes heat and salt through the Ekman velocities. This is probably why it is not as much changed as the other surface forcing fields. This is not a limitation of the method but a limitation of the assimilated observations. Velocity observations would certainly constrain the wind stress more efficiently. At the open boundaries, the level of consistency of the temperature is the same as those of the salinity. We could have expected a larger consistency for the temperature in the same way as the first guess fields. This may be due to the fact that within a year, information from the open boundary do not have the time to influence the interior circulation for such a large basin.

4.2. Step 2

As explained in Section 2, a new first guess is built from step 1. In this first guess, interior velocities are adjusted to the new stratification. These adjusted fields are obtained by running the forward model with the control variables estimated during step 1. The open-boundary velocities are now adjusted by minimizing cost function given in Eq. (2). The constraint on vertical velocities forces the adjoint equations to control velocities at the open boundaries.

At iteration 0 of this second step, the cost concerning the vertical velocities is 10-fold higher than its level of consistency (Fig. 4c). Most of the minimization occurs in the first six iterations. After 20 iterations, this cost is divided by three but remains 3-fold too large. This may indicate either that errors in the model prevent it from reaching the consistency level (in the 4D-variational pro-

blem, the model is considered as perfect) or that errors in the vertical velocities are underestimated.

5. Estimated ocean circulation

5.1. Estimated circulation with a $10 \times 10^6 \text{ m}^3 \text{ s}^{-1}$ Indonesian throughflow

Fig. 6a shows the annual mean meridional overturning obtained after step one of the assimilation. The circulation above 1000 m has not changed compared to the overturning circulation without assimilation (Fig. 3). In contrast, the overturning below 1000 m is intensified. This new deep interior circulation is closed at the southern open boundary by strong vertical velocities. That is, the southern open boundary is not consistent with the interior circulation after step 1.

After step 2, the open-boundary velocities are adjusted to the interior circulation (Fig. 6b). The constraint on the vertical velocity provides open-boundary velocities in geostrophic balance with the density at the open boundary. This adjustment results in an increase by 2×10^6 m³ s⁻¹ of the deep overturning. The adjustment of the open-boundary velocities are thus necessary in our assimilation of WOCE hydrography and our final estimation is those obtained after step 2.

The assimilation of the hydrography produces an increase by 11×10^6 m³ s⁻¹ of the deep overturning (Figs. 6b and 3). 17×10^6 m³ s⁻¹ of deep and bottom waters moves northward up to 10°S below 3200 m. At the Equator, we still find a deep northward flow of $7 \times 10^6 \text{ m}^3 \text{ s}^{-1}$, value that gradually decreases to $1 \times 10^6 \text{ m}^3 \text{ s}^{-1}$ at 10°N . At 32°S, our estimate is larger than both Ganachaud et al. (2000) estimate of $11+4 \times$ 10⁶ m³ s⁻¹. These two estimates that uses WOCE hydrography are consistent at 8°S. Our deep overturning is deeper by 700 m, although this should be taken with caution since Ganachaud et al. (2000) calculate their solution using neutral surfaces. The assimilation does not change significantly the circulation above 1000 m. This was expected since the major constraint brought by CTD data concerns the deep ocean as demonstrated by Fig. 5. The assimilation of the surface

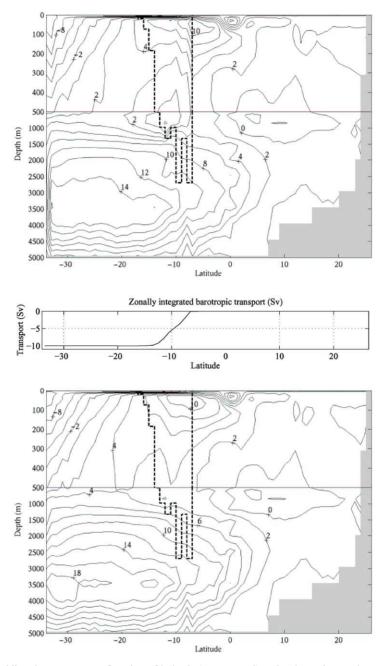


Fig. 6. (a) Estimated meridional transport as a function of latitude (upper panel) and estimated annual mean meridional overturning (lower panel) after step one of the assimilation and (b) same as (a) but after step 2 of the assimilation. Units \times 10⁶ m³ s⁻¹.

climatology has not changed the upper meridional overturning circulation since this climatology also was imbedded in the circulation without assimilation through the restoring terms. A zonal section at 30°S of differences in the meridional velocities between the estimated circulation and the reference circulation is shown in Fig. 7. The assimilation of the WOCE hydrogra-

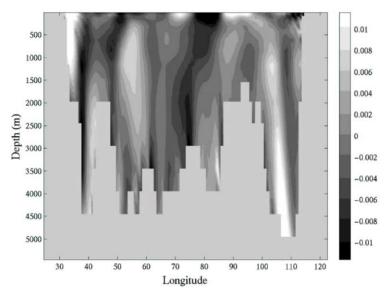


Fig. 7. Difference of meridional velocities (m/s) at 30°S between the estimated circulation and the reference 1.

phy intensifies deep northward boundary currents along Madagascar Plateau (40°E , 4×10^{6} m³ s⁻¹ below 3200 m), Ninety East Ridge (90°E , 4×10^{6} m³ s⁻¹) and east of Broken Plateau in Perth Basin (105°E , 15×10^{6} m³ s⁻¹). Between 1000 and 3200 m, southward currents are intensified along the Australian continental slope, west of Ninety East Ridge, above the Indo-Pacific Ridge, and in the Agulhas current.

Fig. 7 also shows that southward velocities in the core of the Agulhas current decrease. The Agulhas current transports 5×10^6 m³ s⁻¹ less in the estimated circulation than in the reference one. Its seasonal variation has the same amplitude in both circulations. The Mozambique Channel mean transport is increased by 4×10^6 m³ s⁻¹, with a minimum decreased by 3×10^6 m³ s⁻¹ in February and a maximum unchanged.

The southward energy flux at 32°S is slightly increased by 0.1 PW in the estimated circulation compared to the reference circulation (Fig. 8). At 3°N, the estimated circulation transports 0.2 PW less energy southward than in the reference circulation. This is a consequence of the decrease of the surface heat gain by the ocean. Removing the restoring to the sea-surface climatology in the reference circulation would lead to a significant increase in sea-surface temperatures. Hence, the

assimilation decreases the surface heat flux so that the increase in surface temperatures is removed when no restoring is applied. However, the assimilation produces too large a decrease in the surface heat flux since a forward run from the estimated circulation shows that the heat content decreases within the upper 500 m. According to the errors bars set on surface observations (CTD and Levitus) and the constraints applied during the assimilation, it is not possible to get accurate estimates of the upper circulation and heat budget.

In the reference circulation, the deep circulation below 1000 m does not contribute to the southward energy flux. In the estimated circulation and south of 3°S, the deep circulation below 1000 m transports between 0.06 and 0.12 PW and contributes by 5–10% to the total southward flux. Its contribution increases to 30% around 10°N because the southward energy flux of the upper circulation becomes marginal.

5.2. Sensitivity to the ITF transport

Two experiments were made to vary the annual mean ITF while keeping the same seasonal variation as the previous experiment with a $10 \times 10^6 \text{ m}^3 \text{ s}^{-1}$ throughflow. One experiment has no annual mean throughflow and the other a 30×10^{-1}

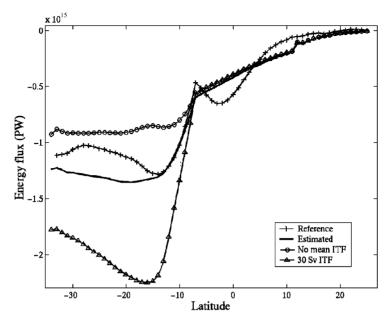


Fig. 8. Energy flux of the circulation as a function of latitude for the reference circulation and the estimated circulation with a 10×10^6 m³ s⁻¹ ITF. Also shown are the estimated fluxes of the estimated circulations with an annual mean ITF of 0×10^6 and 30×10^6 m³ s⁻¹.

 $10^6~\rm m^3~s^{-1}$ throughflow. For both experiments, reference and estimated overturning circulations are shown in Fig. 9. The estimated circulation is produced in the same way as the experiment with a $10\times10^6~\rm m^3~s^{-1}$ throughflow. Whatever the ITF is, the estimated circulation always shows that between 15 and $19\times10^6~\rm m^3~s^{-1}$ move northward below 3200 m at $32^{\circ}\rm S$, of which $7\times10^6~\rm m^3~s^{-1}$ reach the Equator. North of the throughflow and above $1000~\rm m$, the overturning circulation does not change with the throughflow transport. The only change that occurs above $1000~\rm m$ is the southward returning currents south of the Indonesian passages as a response of the throughflow change.

Fig. 8 shows the influence of the throughflow magnitude on the meridional energy flux. The higher the westward transport through the Indonesian passage, the larger the southward energy flux. 60% of the increase in the westward energy flux at the throughflow open boundary is transported to the South Africa–Australia open boundary without changing the heat flux at the surface. The remaining part goes in heat storage change.

This heat storage change, which mostly occurs in the first 500 m, is not large enough to be controlled by the constraints of the assimilation. In contrast, the estimated northward energy flux that originates from the South Africa-Australia open boundary below 3200 m is robust (0.07 PW at 32°S) to our changes in the throughflow transport.

6. Discussion

The main goal of this study was to investigate the presence of a deep meridional overturning in the Indian Ocean from a 4D-variational assimilation of WOCE hydrography and surface climatology within a primitive equation model. The observations were used to constrain the initial state in temperature and salinity, surface forcings, and open boundaries. Because of the lack of sensitivity of the cost function to the velocities at the open boundary, these velocities were constrained in a second step of the assimilation where large vertical velocities are penalized along the open boundaries.

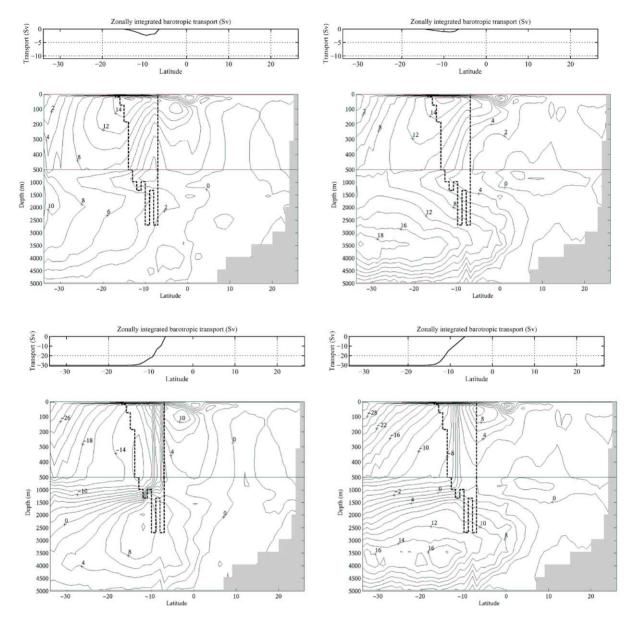


Fig. 9. Upper panels show the reference (left) and estimated (right) meridional overturnings (units \times 10⁶ m³ s⁻¹) with no annual mean ITF. Lower panel same as upper with a throughflow of 30 \times 10⁶ m³ s⁻¹.

Our study brings an answer about the existence of a deep overturning in the Indian ocean. For three values of the Indonesian Throughflow, an estimated circulation dynamically consistent with the observations was found. With a $10 \times 10^6 \text{ m}^3 \text{ s}^{-1}$ ITF, the estimated circulation produces a deep overturning below 1000 m. This over-

turning was weak in the first guess. The northward flow of bottom waters transports $17 \times 10^6 \text{ m}^3 \text{ s}^{-1}$ at 32°S below 3200 m, $7 \times 10^6 \text{ m}^3 \text{ s}^{-1}$ at the Equator, and reaches the latitude of 10°N . Most of this northward flow of bottom waters is balanced by a southward flow of deep waters between 1000 and 3200 m. Consequently, the

energy flux carried by this deep overturning cell is restricted to 0.1 PW at 32°S, which is only 10% of the southward energy flux at this latitude. This deep overturning is also present, with almost the same transport ($\pm 2 \times 10^6 \, \mathrm{m}^3 \, \mathrm{s}^{-1}$) in estimated circulations that have no annual mean ITF and a $30 \times 10^6 \, \mathrm{m}^3 \, \mathrm{s}^{-1}$ annual mean throughflow. Waters that originate from the throughflow are warm and concern the upper circulation, which may explain why the estimated deep overturning circulation is not sensitive to the throughflow transport. It has also been verified that starting from a different first guess (further apart from the hydrography) leads to the same intensification of the deep overturning in the estimated circulation.

Our estimated deep overturning in the Indian Ocean contrast with the usual weak deep circulation found in primitive equation models (Wacongne and Pacanowski, 1996; Garternicht and Schott, 1997; Lee and Marotzke, 1997, 1998; Zhang and Marotzke, 1999). The assimilation generates a deep overturning that fits to the range $(11-23 \times 10^6 \text{ m}^3 \text{ s}^{-1} \text{ at } 32^{\circ}\text{S})$ of recent estimates from hydrographic studies (Robbins and Toole, 1997; Macdonald, 1998; Ganachaud et al., 2000; Sloyan and Rintoul, 2001). Observing the meridional velocities shows that the assimilation of WOCE hydrography is responsible for boundary current reconstructions. Bryden and Beal (2001), Ganachaud et al. (2000), Sloyan and Rintoul (2001) and Macdonald (1998) also found that the deep northward flow is mainly balanced by a southward flow between 1000 and 3000 m. This assimilation is thus able to extract the small scale structures of the hydrography (same scales as those seen by hydrographic studies) to improve the initial state of the primitive equation model.

Running the forward model from its estimated initial state and forcings for 10 years shows a slow but regular decrease of the deep overturning from 17×10^6 to 12×10^6 m³ s⁻¹. The misfit to the CTDs increases with the year, which shows that the model cannot stay consistent with errors on CTD observations at depth. We think that errors in the model physics are the source of the slow drift from its dynamically consistent estimated circulation. For instance, the misrepresentation of some key passages in the bathymetry, the homo-

genous spatial distribution of the vertical mixing, the lack of horizontal resolution may result in the impossibility of maintaining the deep overturning to its estimated level.

If the estimated deep circulation is robust to change in the ITF and first guess, the upper circulation and consequently its associated energy flux are less constrained by the set of data we used. This is best illustrated by the rapid decrease in the heat content within the first 500 m when the estimated initial state is run over several years with the optimal surface forcings. This decrease may occur for two reasons. Firstly, the mixed layer physics is not parameterized adequately with a constant vertical diffusion coefficient and a convective mixing scheme. If the surface heat and freshwater flux are not adequately transferred in the vertical, even perfect surface forcings would not prevent a drift of subsurface properties. An assimilation with an appropriate mixed layer physics and its adjoint would answer to this problem. Such a physics was not included in our assimilation because its adjoint was still under development. Secondly, because of the natural high spatial and temporal variability of the upper circulation, errors in the observations (CTDs and climatology) are too large at the surface to produce accurate estimates of the surface heat and freshwater flux. To overcome the effect of large errors in the observations at the surface, a constraint that penalizes the temporal drift could be added to the cost function. The drift should not exceed what we think the interannual variability is. Such a constrain should control the heat flux divergence of the basin.

Acknowledgements

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