

CONTROL OF HEAD PITCH IN DROSOPHILA DURING REST AND FLIGHT

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Introduction: *Drosophila* holds its body axis close to horizontal when walking on even ground (body pitch BP = 15°) or when flying fast ($v = 1$ m/s, BP = 20°). In hoverflight the body axis is held much steeper ($v = 0$ m/s, BP = 65°; David 1978).

However, under these conditions *Drosophila* pitches its head downwards (head pitch relative to the thorax: HP = $-30.7 \pm 6.6^\circ$ SD, N = 16, n = 160, tethered flight). This behaviour stabilizes a distinct orientation of the fly's head in space, and thus the proper alignment of its eyes with the visual surroundings.

Problem: How is this compensatory head pitch during flight elicited and controlled? Head posture was observed from the side by macro-videography under red illumination in different locomotor states of the flies, under various stimulations, and after surgical manipulation.

Results: (1) The downward head pitch is not due to a latching of the neck joint at rest (e.g. Mittelstaedt 1950) and its relaxation during flight, combined with the action of gravity on the head. In *Drosophila* head pitch is largely the same whether the fly is mounted upside up (HP = $-25.3 \pm 7.3^\circ$ SD, N = 14) or upside down (HP = $-19.9 \pm 9.6^\circ$ SD).

(2) Positive or negative stimulation of the fly's graviceptive system (Horn and Lang 1978) can be effected by holding the fly upside up or upside down while it clings to either a paper confetto of 0.5 x body weight or a styrofoam ball of 2.5 x body weight. None of these stimuli elicits a head pitch comparable to that in flight.

(3) Removal of tarsal contact which suspends a strong flight inhibition (Fraenkel 1932) is not sufficient to elicit the full downward head pitch if *Drosophila* does not actually fly (HP = $-6.9 \pm 5.3^\circ$ SD, N = 16).

(4) Tethering *Calliphora* by its back elicits via the halteres an upward head pitch which vanishes after haltere amputation (G. Nalbach 1991). In contrast, *Drosophila* pitches its head, under similar conditions, in the opposite direction (HP = $-25.3 \pm 7.3^\circ$ SD, N = 14), and the response is largely insensitive to haltere amputation (HP = $-19.5 \pm 9.6^\circ$ SD).

(5) Flies measure air speed by their antennae (Gewecke 1967), and could control their head pitch accordingly. Surprisingly, however, amputation of both antennae (HP = $-31.4 \pm 5.3^\circ$ SD, N = 13) does not prevent the head pitch observed in the same flies before amputation (HP = $-28.3 \pm 5.0^\circ$ SD, N = 13).

(6) Head posture could still be influenced by other wind-sensitive organs (e.g. WeisFogh 1949, Pflüger and Tautz 1982) which, however, have not yet been detected in flies. In resting and walking *Drosophila* laminar wind from ahead does not elicit a downward head pitch at wind speeds up to $v = 1$ m/s. Likewise, in flying *Drosophila* the downward head pitch, observed in still air, is not modified by wind up to $v = 1$ m/s. Apparently, wind has no influence on head posture.

Conclusion: The body axis of *Drosophila* is elevated more steeply during flight than during resting or walking on even ground. The resulting misalignment of the fly's eyes with the visual surroundings is prevented by a corresponding downward head pitch made during flight. This compensatory head movement is initiated endogeneously, and is overlaid by visual motion compensation described previously (Hengstenberg 1991).

SD = standard deviation, N = number of flies, 10 observations per fly.
