# Restoration of four-dimensional diffeomorphism covariance in canonical general relativity 

An intrinsic Hamilton-Jacobi approach

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#### Abstract

Classical background independence is reflected in Lagrangian general relativity through covariance under the full diffeomorphism group. We show how this independence can be maintained in a Hamilton-Jacobi approach that does not accord special privilege to any geometric structure. Intrinsic spacetime curvature based coordinates grant equal status to all geometric backgrounds. They play an essential role as a starting point for inequivalent semi-classical quantizations. The scheme calls into question Wheelers geometrodynamical approach and the associated Wheeler-DeWitt equation in which three-metrics are featured geometrical objects. The formalism deals with variables that are manifestly invariant under the full diffeomorphism group. Yet, perhaps paradoxically, the liberty in selecting intrinsic coordinates is precisely as broad as is the original diffeomorphism freedom. We show how various ideas from the past five decades concerning the true degrees of freedom of general relativity can be interpreted in light of this new constrained Hamiltonian description. In particular, we show how the Kuchař multi-fingered time approach can be understood as a means of introducing full four-dimensional diffeomorphism invariants. Every choice of new phase space variables yields new Einstein-Hamilton-Jacobi constraining relations, and corresponding intrinsic Schrödinger equations. We show how to implement this freedom by canonical transformation of the intrinsic Hamiltonian. We also reinterpret and rectify significant work by B. Dittrich on the construction of 'Dirac observables'.


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## 1 Introduction

Few researchers today believe that an ultimate quantum theory of gravity can or should presuppose any preferred spacetime structure. Geometry must emerge from a background-independent theory. Closely related to this requirement is the foundational property of the general theory of relativity. The classical Einstein equations are covariant under the four-dimensional diffeomorphism group. Yet it is remarkable that even today debate persists on the nature of diffeomorphism covariance of the Hamiltonian formulation of Einstein's theory and the question whether true diffeomorphism invariants (or observables) exist and if so, how does one go about finding them. We need only mention the continuing debate on the "problem of time" as motivation for this contribution. We shall briefly show, in as elementary manner as possible, that the efforts of many historical investigators in this field can be understood and reinterpreted in a wider framework.

Methods for respecting diffeomorphism covariance in a phase space approach to general relativity were first invented in 1930 by Léon Rosenfeld 27, although his significant achievements were largely unknown to the individuals who are now recognized as the creators of constrained Hamiltonian dynamics - Peter Bergmann [3], Paul Dirac [10, 11, Arnowitt-Deser-Misner (ADM) [1, 2], and Karel Kuchař 20. Each of these initiated their research with distinctly different motivations. Only in the case of Bergmann did the underlying diffeomorphism covariance play a central role. Dirac's starting point was actually a flat spacetime model in which arbitrary parameterized spacelike hypersurfaces were introduced by hand. ADM dealt with gauge symmetry essentially in the manner that Arnowitt and Deser had learned from their mentor Julian Schwinger - that is to say they attempted from the beginning to work with a preferred spacetime coordinate choice, identified by them as "intrinsic" coordinates 1 Having made a choice they were not concerned with the relation of the resulting theory to models that would result from different choices. Kuchar continued in the tradition of ADM, showing that at the classical level one could in principle implement a choice of coordinates as a canonical transformation. In this note we intend to show how a suitably improved and reinterpreted version of the Kuchar program links back to the focus of Bergmann and his group. It turns out that the gauge fixing envisioned by Kuchar is a construction of true diffeomorphism invariants that never-the-less undergo nontrivial intrinsic temporal evolution. Our result is a suitably modified realization of the partial observable program of Rovelli [29. Dittrich [12,13 and Thiemann 30 based

[^1]their approach to the construction of diffeomorphism invariants on the Kuchař multi-fingered time program that was in turn based on Dirac's implementation of Hamiltonian constraints. We will show that when properly interpreted from the point of view of the underlying full diffeomorphism symmetry, when sufficient restrictions are placed on the range of permissible partial observables, their constructions can be interpreted as a choice of intrinsic coordinates. We stress that one of our main objectives in this paper is to show how all of these procedures, when suitably implemented and interpreted, can be unified within the framework of the full background-independent diffeomorphism covariance of the original Einstein theory. In addition, we wish to stress that we are not proposing a technical procedure that will necessarily lead to simpler computational techniques. The improvement is one of principle. We are simply elevating diffeomorphism covariance to its original foundational status.

We will begin by comparing and contrasting a somewhat analogous intrinsic Hamilton-Jacobi approach to a simple toy model, the relativistic free particle. This will serve as both an inspiration and a warning of the inadequacy of this model in addressing general relativity. One reason we use this example is that it has spawned what we view as an inappropriate terminology in characterizing the construction of observables in general relativity. Several authors refer to these procedures as introducing a "deparameterization" of general relativity, based on what they view as an analogous procedure in the artificially parameterized relativistic free particle model. Then we will briefly review a recent construction of diffeomorphism invariants that is an outgrowth of Bergmann's Syracuse school. We explain the necessity of choosing spacetime scalars as intrinsic coordinates and show how invariants result from these choices. We then present a geometrical improvement of the Kuchar program in which a link is established between classical actions corresponding to distinct intrinsic coordinate choices. The first step in the program is accomplished through an appropriate choice of canonical phase space transformations, yielding new fully covariant Hamiltonian field equations. For each field variable choice there corresponds a new Einstein-Hamilton-Jacobi equation. Then for each choice there exists a natural intrinsic coordinate gauge choice. It turns out that the freedom of choice coincides with the original diffeomorphism freedom, and we show how one can pass from one choice to another with canonically implemented point transformations. The implications of this freedom are profound. In particular we show that Bergmann's notion of phase space diffeomorphism equivalence classes, presented in 1961 [4, is incorrect. Bergmann's equivalence classes consisted of orbits in the phase space whose variables were the 3 -metric components and their canonical conjugates. We show on the other hand that every distinct solution of Einstein's equations constitutes its own proper equivalence class. That a given 3-metric and conjugate momenta can undergo non-unique evolution is traced to the possibility of making distinct intrinsic coordinate choices. We then consider some semi-classical implications of this program. For every choice of intrinsic canonical variable there exists a corresponding Wheeler-DeWitt equation. But rather than employ this equation it is more efficient to work with an intrinsic Schrödinger equation. We will
conclude by illustrating some of these ideas with a simple mini-superspace model.

## 2 The free relativistic particle

Consider the reparameterization covariant action for a free particle of mass $m$, in units in which $c=1$,

$$
S=-m \int\left(-\dot{q}^{2}\right)^{1 / 2} d \theta=\int L d \theta
$$

where $q^{\mu}(\theta)$ represents the spacetime position, and $\dot{q}^{\mu}:=d q^{\mu} / d \theta$. There exists a technique for employing this action to construct a classical and quantum model that establishes a dynamical correlation between observable variables, recognizing that the parameter $\theta$ is itself not observable. The task is to relate this parameter to a measurable physical quantity.

The standard point of departure for this technique is to consider two independent changes to slightly different solutions of the equations of motion. The first independent variation is characterized by the fact that the new solutions have the same value of configuration variables at a slightly increased final evolution parameter as the original solutions had at the original final evolution time. The second variation simply alters the configuration variables at at the original final evolution time. We put some stress on this method since it appears not to be well appreciated that this procedure can be carried out also for singular systems, as in this model.

In this case of the free particle, the first independent variation, at the original final $\theta$, is denoted by $\delta_{0} q^{\mu}$. The second independent variation gives a variation of $q^{\mu}$ at $\theta$ of $-\dot{q}^{\mu} \delta \theta$. So the net variation is $\delta q^{\mu}=\delta_{0} q^{\mu}-\dot{q}^{\mu} \delta \theta$. These variations are in fact defined for all $\theta$ in the range of integration of $S$. Consequently we have

$$
\delta S=\int_{\theta_{0}}^{\theta}\left(-\frac{d}{d \theta} \frac{\partial L}{\partial \dot{q}^{\mu}}\right) \delta q^{\mu}+\left.\left(\frac{\partial L}{\partial \dot{q}^{\mu}}\left[\delta_{0} q^{\mu}-\dot{q}^{\mu} \delta \theta\right]+L \delta \theta\right)\right|_{\theta} .
$$

The last term on the right comes from the shift in the integration range. We have also assumed that the new solutions have the same initial values, so there is no contribution from $\theta_{0}$. Thus, now letting $\delta_{0} q^{\mu} \rightarrow \delta q^{\mu}$ and recognizing that the original $q^{\mu}$ satisfied the equations of motion, we have

$$
\begin{equation*}
d S=\frac{\partial L}{\partial \dot{q}^{\mu}} d q^{\mu}-\left(\frac{\partial L}{\partial \dot{q}^{\mu}} \dot{q}^{\mu}-L\right) d \theta=: \tilde{p}_{\mu} d q^{\mu}-\tilde{H}(\dot{q}) d \theta . \tag{1}
\end{equation*}
$$

This is of course a singular system; the momenta $\tilde{p}_{\mu}(\dot{q}):=\frac{\partial L}{\partial \dot{q}^{\mu}}=\dot{q}_{\mu}\left(-\dot{q}^{2}\right)^{-1 / 2}$ are not independent. In fact, since the Lagrangian is homogeneous of degree one in the velocities, $\tilde{H}:=\frac{\partial L}{\partial \dot{q}^{\mu}} \dot{q}^{\mu}-L \equiv 0$. The constraint takes the form $H=\frac{1}{2}\left(\tilde{p}^{2}+m^{2}\right) \equiv 0$, and we have $\tilde{H}=\left(-\dot{q}^{2}\right)^{1 / 2}\left(\tilde{p}^{2}+m^{2}\right)$. In Appendix

A we show how one can employ (1) to construct a complete set of Hamilton principal functions $S\left(q^{\mu}, \theta ; \bar{p}\right)$ that satisfy the Hamilton-Jacobi equation

$$
\begin{equation*}
\frac{\partial S}{\partial \theta}+\tilde{H}\left(q, \frac{\partial S}{\partial q} ; \theta\right)=0 \tag{2}
\end{equation*}
$$

And we show that one can in the usual manner employ this principal function to obtain the general solution of the parameterized free particle trajectories.

But rather than regain the parameterized trajectories we will inquire as to how one can gain information from $d S$ on the measurable physical evolution of the single particle system- recognizing that the parameter $\theta$ is ostensibly not a physically measurable quantity. In this case the answer is clear. One could simply choose the reparametrization scalar $q^{0}$ as the evolution time. In doing so a relation is established between the in principle measureable spatial position of the particle and the measurable Minkowski time $q^{0}$. This is a choice of intrinsic time - intrinsic in the sense that the evolution parameter itself is measurable. As we shall see, it is essential that our choice transform as a scalar under the action of the reparameterization group. There is in general a two step procedure for making a choice of intrinsic coordinates.

In this particular case the first step is already accomplished since $q^{0}$ is already a configuration space variable. But in order to stress the fact that the isolation of the $q^{0}(\theta)$ does not automatically imply that one has made an intrinsic coordinate choice we note that this variable does undergo variations under the reparameterizations of the form $\theta^{\prime}=\theta+\delta \theta=\theta-\left(-\dot{q}^{2}\right)^{-1 / 2} \xi(\theta)$. The phase space generator of these variations is $G(\xi)=\frac{\xi}{2} H$. Since the following will play a role in the comparisons with the literature, we display explicitly the action of the reparameterization generator on the variable $q^{0}$. Under this infinitesimal reparameterization the corresponding variation of $q^{0}$ is

$$
\bar{\delta} q^{0}:=q^{\prime 0}-q^{0}=\left\{q^{0}, H \xi\right\}=\xi p^{0}=\dot{q}^{0}\left(-\dot{q}^{2}\right)^{-1 / 2} \xi=-\dot{q}^{0} \delta \theta,
$$

thus recovering precisely the required transformation property of a scalar.
Before turning to the second step, note that since we have not yet made a parameter choice we still have a phase space constraint $H=0$. Then it is natural to ask what would be the consequence of representing the momenta in the constraint as $p_{\mu}=\frac{\partial S}{\partial q^{\mu}}$ and interpreting the constraint as a differential equation to be satisfied by $S$. In other words, look for solutions of

$$
\begin{equation*}
\eta^{\mu \nu} \frac{\partial S}{\partial q^{\mu}} \frac{\partial S}{\partial q^{\nu}}+m^{2}=0 . \tag{3}
\end{equation*}
$$

It is significant that solutions of this equation do not give directly solutions $q^{\mu}(\theta)$ of the reparameterization covariant Euler-Lagrange equations. The parameter $\theta$ does not even appear in this equation! Additional information is required. Given a solution $S$, one can set

$$
\begin{equation*}
p_{\mu}=\frac{\partial S}{\partial q^{\mu}} \tag{4}
\end{equation*}
$$

Then one must appeal to the Hamiltonian equation $\dot{q}^{\mu}=\lambda(\theta) p^{\mu}$ where one picks the function $\lambda$, obtaining the first order differential equation $\dot{q}^{\mu}=\frac{\partial S}{\partial q^{\mu}}$ which can then be integrated. The point is that only when this function has been selected has one made a choice of gauge. In other words, the "HamiltonJacobi equation" (3) continues within this formalism to be a constraint, and we have simply managed to solve the constraint. This is the reason that we have enclosed the expression in quotation marks. It is not a true Hamilton-Jacobi equation.

Of course, what really motivates interest in this example is the means that is available to find $q^{a}$ as a function of $q^{0}$. In other words, one wants to make an explicit intrinsic parameter choice. And there is a natural way of doing this using the "Hamilton-Jacobi equation". It does give us directly $S$ as a function of $q^{a}, q^{0}$ and of three independent constants $\bar{p}^{a}$. And solutions for $q^{a}$ as a function of $q^{0}$ can be obtained in the usual manner in Hamilton-Jacobi theory by taking derivatives $\frac{\partial S}{\partial \alpha^{a}}$. Thus the "Hamilton-Jacobi equation" brings with it a natural choice of intrinsic parameter - due to the fact that this natural choice is one of the configuration variables! As we shall see, this is not true in general relativity, and one of the objectives of this paper is to overcome this difficulty.

It is also possible to make the intrinsic parameter choice directly in the action increment $d S$. We simply interpret $q^{0}$ as the evolution parameter and the momenta as phase space variables - subject of course to the constraint. Thus we can solve for the intrinsic Hamiltonian $H_{i}$, setting $p_{0}=-\left(p^{a} p_{a}+1\right)^{1 / 2}:=$ $-H_{i}$, so that the increment in the action in intrinsic coordinates is

$$
d S=-H_{i} d q^{0}+p_{a} d q^{a} .
$$

From this expression we deduce the true (intrinsic) Hamilton-Jacobi equation

$$
\frac{\partial S}{\partial q^{0}}+\left(\frac{\partial S}{\partial q^{a}} \frac{\partial S}{\partial q_{a}}+m^{2}\right)^{1 / 2}=0
$$

It's complete solution is

$$
S=-\left(\boldsymbol{\alpha}^{2}+m^{2}\right)^{1 / 2} q^{0}+\alpha_{a} q^{a}-f(\boldsymbol{\alpha})
$$

from which one obtains the general classical solution by setting $0=\frac{\partial S}{\partial \alpha_{a}}$. It follows as a consequence of the intrinsic Hamilton-Jacobi equation that the quantum wave function $\Psi\left(q^{0}, \mathbf{q}\right)=\int d^{3} \boldsymbol{\alpha} F(\boldsymbol{\alpha}) e^{-S / \hbar}$ satisfies the Schrödinger equation

$$
\begin{equation*}
H_{i}\left(-i \hbar \frac{\partial}{\partial q^{a}}\right) \Psi=i \hbar \frac{\partial}{\partial q^{0}} \Psi . \tag{5}
\end{equation*}
$$

Furthermore, again as a consequence of the intrinsic Hamilton-Jacobi equation, an appropriately peaked superposition over $\boldsymbol{\alpha}$ will deliver a correct semiclassical wave packet.

Although it is obvious that the intrinsic dynamics does not depend on the parameter $\theta^{\prime}$, and is thus invariant under reparameterizations, it is instructive
to see how this intrinsic choice yields variables expressed in terms of the $q^{\mu}\left(\theta^{\prime}\right)$ in an arbitrary parameterization but which are invariant under reparameterizations. They are the observables. The observables associated with $q^{a}$ are (See [26])

$$
\begin{equation*}
\mathcal{O}_{q^{a}}=q^{a}\left(\theta^{\prime}\right)+\frac{p^{a}}{p^{0}} q^{0}\left(\theta^{\prime}\right)-\frac{p^{a}}{p^{0}} \theta, \tag{6}
\end{equation*}
$$

while $\mathcal{O}_{p^{\mu}}=p^{\mu}$.
The coefficients of each power of $\theta$ are invariant under the active transformations generated by $G(\xi)$. The invariant variables $\mathcal{O}_{q^{a}}$ are in fact the $q^{a}$ in (54), while the $\theta$ that appears on the right in (6) is $q^{0}$. This means that when one goes to the quantum theory and considers wave functions $\psi\left(\mathcal{O}_{q^{a}}, \theta\right)$, these wave functions will satisfy $\hat{H} \psi\left(\mathcal{O}_{q^{a}}, \theta\right)=0$, where $\hat{H}$ is the operator $\hat{p}^{2}+1$ with $\hat{p}_{\mu}=-i \hbar \frac{\partial}{\partial q^{\mu}\left(\theta^{\prime}\right)}$.

Finally, we note that the invariant variables satisfy a modified Poisson bracket algebra. It was shown in general in 25 that this algebra is the Dirac bracket algebra constructed using the gauge fixing constraint. In this case the modified bracket is

$$
\begin{equation*}
\{f, g\}^{*}=\{f, g\}+\left\{f, \frac{1}{2}\left(p^{2}+m^{2}\right)\right\} \frac{1}{p^{0}}\left\{t-q^{0}, g\right\} \tag{7}
\end{equation*}
$$

and it is indeed the case that

$$
\begin{equation*}
\left\{q^{a}, p^{0}\right\}^{*}=\left\{\mathcal{O}_{q^{a}}, \mathcal{O}_{p^{0}}\right\}=\frac{p^{a}}{p^{0}} \tag{8}
\end{equation*}
$$

Canonical quantization would then require a realization of this algebra. This can be achieved in a momentum representation with $p^{0}=\left(\mathbf{p}^{2}+m^{2}\right)^{1 / 2}$. Interestingly, the operator $\hat{q}^{a}$ is in this representation none other than the NewtonWigner position operator [21].

Analogues for all of these constructions can be undertaken in general relativity. But we stress again two significant differences in the treatment of the relativistic particle as compared to general relativity: 1) $q^{0}$ is already a reparameterization scalar. Finding such scalars in general relativity is a non-trivial task that the particle model offers no clues in completing 2) It was not adequately realized that just as was clear in the particle model, after taking the first step in general relativity, one still has a theory that is covariant under the full diffeomorphism group.

## 3 Review of Hamiltonian constrained dynamics, observables, and gauge fixing

We briefly review here the nature of the diffeomorphim-induced canonical transformation group of general relativity, and the manner in which it can
be employed to construct diffeomorphism invariants. 2. The phase-space realizable infinitesimal general coordinate transformations are

$$
\begin{equation*}
x^{\prime \mu}=x^{\mu}-n^{\mu} \xi^{0}(x)-\delta_{a}^{\mu} \xi^{a}(x) \tag{9}
\end{equation*}
$$

where $n^{\mu}=\left(N^{-1},-N^{-1} N^{a}\right)$ is the normal to the $t=$ constant spacelike hypersurface. Thus there is an explicit dependence on the metric lapse $N$ and on the metric shift $N^{a}$, and due to the appearance of the 3 -metric $g_{a b}$ in the commutator algebra the descriptors $\xi$ must also depend on the 3 -metric. Variations of the canonical variables (including the lapse and shift) under these transformations are generated by $3^{3} 4$

$$
\begin{equation*}
G_{\xi}\left(x^{0}\right)=\int d^{3} x\left(P_{\mu} \dot{\xi}^{\mu}+\left(\mathcal{H}_{\mu}+N^{\rho^{\prime}} C_{\mu \rho^{\prime}}^{\nu^{\prime \prime}} P_{\nu^{\prime \prime}}\right) \xi^{\mu}\right), \tag{10}
\end{equation*}
$$

where the $P_{\mu}$ are the vanishing momenta conjugate to $N^{\mu}$, the $\mathcal{H}_{\mu}=0$ are the secondary constraints and the $C_{\mu \rho}^{\nu}$ are the structure coefficients of the Dirac algebra. This generator is to be distinguished from the generator of time evolution,

$$
\begin{equation*}
H=\int d^{3} x\left(N^{\mu} \mathcal{H}_{\mu}+\lambda^{\mu} P_{\mu}\right) \tag{11}
\end{equation*}
$$

The $\lambda^{\mu}$ are almost arbitrary spacetime functions, the only restriction being that $\lambda^{0}>0$.

The generator $G_{\xi}\left(x^{0}\right)$ is deployed to construct diffeomorphism invariants by choosing coordinate conditions. We fix coordinates by employing physical landmarks in spacetime. Specifically, we correlate spacetime events with specific values of the spacetime curvature. Such a coordination is called "intrinsic" since it can be used to establish a correlation between a subset of field variables and the remaining dynamical variables 5 We then actively map within a given arbitrary chart to events that satisfy the chosen intrinsic coordinate conditions. So as not to cause unnecessary confusion in the following we will refer to the coordinates in the fixed chart as "coordinate parameters". These will be distinguished from "intrinsic coordinates". The invariants that we obtain through this procedure are invariant under arbitrary maps of the original coordinate parameter chart.

We give a simple argument why the intrinsic coordinate functionals must be spacetime scalars - as was recognized by Bergmann, Bryce DeWitt, and ADM. We suppose that the parameters $x^{\mu}$ have been fixed by the condition that $x^{\mu}=X^{\mu}(g(x), p(x))$. We investigate how this relation transforms under a change of parameters $x^{\prime \mu}=f^{\mu}(x)$. Then we must have

$$
\begin{equation*}
x^{\prime \mu}=f^{\mu}(x)=f^{\mu}\left(X(g(x), p(x))=f^{\mu}\left(X\left(g^{\prime}\left(x^{\prime}\right), p(x)\right)\right),\right. \tag{12}
\end{equation*}
$$

[^2]where on the right we first perform the coordinate parameter transformations before mapping to intrinsic coordinates. Since the result must not depend on the order in which these operations are performed we deduce from (12) that since $f$ is arbitrary,
\[

$$
\begin{equation*}
X^{\mu}(g(x), p(x))=X^{\mu}\left(g^{\prime}\left(x^{\prime}\right), p^{\prime}\left(x^{\prime}\right)\right) \tag{13}
\end{equation*}
$$

\]

In other words, the $X^{\mu}$ must be spacetime scalar functions ${ }^{6}$ It has been shown that if the scalar condition is satisfied then no physical solutions are eliminated, and if is not satisfied then the fixation of coordinates is not unique. 23] We of course have in mind generic spacetimes with no Killing fields and we recognize that generally one must patch together intrinsic coordinate charts.

In general relativity with material sources we have at our disposal at least fourteen scalars that can be constructed from the Riemann curvature tensor 33. They generally involve quadratic or cubic powers of this tensor.

It was shown in 25 how to construct the observables that correspond to given intrinsic coordinate choices $x^{\mu}=X^{\mu}\left[g_{a b}, p^{c d}\right]$. The outcome is that there corresponds to every phase space variable (including the lapse and shift) a series expansion in powers of the intrinsic coordinates, the coefficients of which are invariant functionals of the metric ${ }^{7}$ These coefficients are invariant in the conventional sense that variations of the metric under changes of the coordinate parameters does not change their values.

One outcome of this construction that has as yet not received attention in the literature is that once one has found an acceptable set of spacetime scalar functionals $X^{\mu}(g(x), p(x))$ then one is in position to solve in any coordinate parameter chart for the coordinate parameters in this chart as functionals of $g_{a b}$ and $p^{c d}$. The solution proceeds as follows: Let us suppose that we are in possession of a particular solution of Einstein's equations expressed in coordinate parameters $x^{\mu}$. To solve for the $x^{\mu}$ as functionals of $g_{a b}$ and $p^{c d}$ we most simply find the coordinate transformation that transforms from the intrinsic coordinates $X^{\mu}\left[g_{a b}(x), p^{c d}(x)\right]$ to the coordinates $x^{\mu}$, i.e. $x^{\mu}=f^{\mu}\left(X\left[g_{a b}(x), p^{c d}(x)\right]\right)$. This expression constitutes the solution we are seeking. We will illustrate this procedure below for a cosmological example.

We now show how the construction of diffeomorphism invariants is related to a completion of Kuchař's scheme for introducing what he calls internal coordinates and a corresponding reduced Hamiltonian.

## 4 Intrinsic Hamiltonians

We will ultimately describe a formalism in which the complete gravitational action will be a functional of $2 \times \infty^{3}$ independent metric variables which are

[^3]functions of intrinsic coordinates, and a corresponding number of constants. The task of constructing such an action is complicated by the fact that the curvature-based spacetime scalars we shall use depend on time derivatives of the metric variables. Because of this the introduction of these scalars directly into the gravitational Lagrangian would result in the appearance of second order time derivatives. It may be the case that no intrinsic Lagrangian exists, as is true for the simple cosmological example we consider below.

Actually, although he did not address this particular issue, Karel Kuchař's pioneering work [20,17] suggests a way to proceed - via the appropriate canonical phase space transformation. We will apply the procedure to the vacuum case. The generalization to the non-vacuum case is straightforward. It is noteworthy that Kuchar viewed his procedure as the selection of a family of dynamical-field dependent embeddings of spatial hypersurfaces into spacetime. In introducing the notion of "bubble time" or "multi-fingered time", he explicitly rejected the idea that the full four-dimensional diffeomorphism group could be realized in the Hamiltonian formulation of the general theory of relativity. We shall show that a reinterpretation of his method does bring the full group back into play.

We begin by writing the increment in the action as

$$
\begin{equation*}
d S_{G R}=\int d^{3} x\left(\tilde{p}^{a b} d g_{a b}+\tilde{P}_{\mu} d N^{\mu}\right)-d t \int d^{3} x\left(N^{\mu} \mathcal{H}_{\mu}+\lambda^{\mu} P_{\mu}\right) \tag{14}
\end{equation*}
$$

where the tilde signifies that the momenta are to be conceived as configurationvelocity functions. It is perhaps not widely recognized that this formula is obtained by beginning with a solution of Einsteins equations, and then undertaking two independent variations to new solutions as exemplified in the point particle example. The first variation is to a new solution with slightly altered values of the metric at the final time. The second assumes that at a fixed final time one computes the action for a slightly different new solution of Einstein's equations where one varies the final time and assumes that the values of the metric components at the new final time coincide with the values at the original end time in some chosen system of coordinates 8 This is the

[^4]standard Hamilton-Jacobi procedure, but now applied to a singular dynamical system. Of course the $\tilde{P}_{\mu}$ vanish identically. And we must satisfy the secondary constraints $\mathcal{H}_{\mu}=0$.

Our first task in extending Kuchar's work is to consider the phase space formulation of the action increment (14), and then to implement a canonical phase space transformation in which we introduce the $X^{\mu}\left[g_{a b}, p^{c d}\right]$ as canonical variables. Contrary to Kuchar we do not permit the $X^{\mu}$ to depend explicitly on the coordinate parameters precisely because we insist that we are always choosing a coordinate system based on measurable curvatures. We can then rewrite the non-vanishing contributions to the action increment in terms of the intrinsic coordinates and their conjugate momenta. Thus we seek a canonical transformation such that

$$
\begin{align*}
d S_{G R} & =\int d^{3} x\left(p^{a b} d g_{a b}+P_{\mu} d N^{\mu}\right)-d t \int d^{3} x\left(N^{\mu} \mathcal{H}_{\mu}\left[g_{a b}, p^{c d}\right]+\lambda^{\mu} P_{\mu}\right) \\
& =\int d^{3} x\left(p^{I} d g_{I}+p^{A} d g_{A}+\frac{\delta G}{\delta g_{I}} d g_{I}+\frac{\delta G}{\delta X^{\mu}} d X^{\mu}+P_{\mu} d N^{\mu}\right) \\
& -d t \int d^{3} x\left(N^{\mu} \mathcal{H}^{\prime}{ }_{\mu}\left[g_{A}, p^{B}, X^{\mu}, \pi_{\mu}\right]+\lambda^{\mu} P_{\mu}\right) \tag{15}
\end{align*}
$$

(The necessity of a transformation of the action with a corresponding generating function $G$ is not mentioned explicitly in Kuchar's work.) We assume that the $X^{\mu}$ commute with each other. The $\pi_{\mu}$ are canonically conjugate to the $X^{\mu}$, and they are obtained through the generating functional as,

$$
\begin{equation*}
\pi_{\mu}=\frac{\delta G}{\delta X^{\mu}} \tag{16}
\end{equation*}
$$

and

$$
\begin{equation*}
p^{I}=-\frac{\delta G}{\delta g_{I}} \tag{17}
\end{equation*}
$$

We let $g_{A}$ represent two of the components of $g_{a b}$, with $g_{I}$ representing the remaining four and similarly for the conjugate momenta. Thus we have the canonical change of variables $\left(g_{I}, p^{J}\right) \rightarrow\left(X^{\mu}, \pi_{\nu}\right)$ and the corresponding inverse. It must be emphasized that the transformed action is still fully covariant under the action of the diffeomorphism-induced symmetry group whose generators (10) are now expressed in terms of the new canonical phase space variables, with corresponding changes in the structure coefficients of the Dirac algebra.

The canonical transformations we have just undertaken are the analogue of the first step in the free particle model. This step was trivial in the particle model since $q^{0}$ was already a configuration variable. The advantage that we have gained through this change of variables is that we can now easily isolate in the non-vanishing contribution to the action increment those variables that will serve as our intrinsic coordinates. We will later, in our second step, let $x^{\mu}=X^{\mu}$. Finally, in order to respect the constraints, we solve the constraints and the intrinsic coordinate conditions $x^{\mu}=X^{\mu}\left(g_{a b}, p^{c d}\right)$ for $g_{I}$ and $p^{J}$ and
substitute this expressions into $\pi_{I}$ whereby the $\pi_{I}$ become explicit functionals of $g_{A}, p^{B}$ and $x^{\mu}$. Then since there is no incremental change in the $X^{a}$ in this gauge, the non-vanishing contribution to the action becomes the intrinsic canonical one-form

$$
\begin{equation*}
\theta_{i}=\int d^{3} x\left(p^{A} d g_{A}+\pi_{0}\left[g_{A}, p^{B}, x^{\mu}\right] d x^{0}\right) \tag{18}
\end{equation*}
$$

Thus we deduce that

$$
\begin{equation*}
H_{i}:=-\pi_{0}\left[g_{A}, p^{B}, x^{\mu}\right] \tag{19}
\end{equation*}
$$

is the intrinsic Hamiltonian ${ }^{9}$, while the $\pi_{a}\left[g_{A}, p^{B}, x^{\mu}\right]$ are canonical generators of spatial displacements.

It is important to notice that even though the lapse and shift have disappeared from this formalism, they are in fact fixed through the condition that the intrinsic coordinate choice be preserved under time evolution. They become fixed functionals of $g_{A}, p^{B}$ and $x^{\mu}$.

## 5 Hamilton-Jacobi formalism

After making the change of canonical variables, but before fixing a gauge by choosing intrinsic coordinates, we are in position to rewrite what has been called the Einstein-Hamilton-Jacobi equation using these new variables. In the transformed Hamiltonian constraint $\mathcal{H}^{\prime}{ }_{\mu}\left[g_{A}, p^{B}, X^{\mu}, \pi_{\mu}\right]=0$, analogously to Peres' original proposal [22], we simply write

$$
\mathcal{H}^{\prime}{ }_{\mu}\left[g_{A}, \frac{\delta S}{\delta g_{B}}, X^{\mu}, \frac{\delta S}{\delta X^{\nu}}\right]=0
$$

As was demonstrated by Gerlach using conventional metric variables [16, from solutions of this equation one can construct solutions of Einstein's equations. However, specific choices for the lapse and shift variables must still be made 10 . On the other hand there are natural choices corresponding to trivial functions; these are namely lapse equal to one and vanishing shift in the conventional case. The trivial choices using the new phase space variables actually yield the intrinsic dynamics. We claim, in other words, that the Einstein-Hamilton-Jacobi constraint equation in the new variables is equivalent to the true Hamilton-Jacobi equation obtained using the intrinsic Hamiltonian (19). We call this the true Hamilton-Jacobi equation since it is obtained in the usual manner by seeking the canonical transformation that produces a vanishing Hamiltonian. Calling the generator of this transformation $\bar{S}$, the condition that the resulting Hamiltonian vanishes is

$$
\begin{equation*}
H_{i}\left[g_{A}, p^{B}, x^{\mu}\right]+\frac{\partial \bar{S}}{\partial t}=0=H_{i}\left[g_{A}, \frac{\delta \bar{S}}{\delta g_{B}}, x^{\mu}\right]+\frac{\partial \bar{S}}{\partial t} \tag{20}
\end{equation*}
$$

9 in the literature also known as the "reduced", "true" or "physical", Hamiltonian; we prefer to call it the intrinsic Hamiltonian in order to stress that it is built with the genuine measurable space-time scalars
10 See for example 9

We will demonstrate the equivalence of this equation with the transformed Einstein-Hamilton-Jacobi equation below for a simple cosmological model.

## 6 Intrinsic coordinate transformations

As we have stressed above, having made a particular choice of intrinsic coordinates we now have the liberty to undertake an arbitrary finite transformation to new intrinsic coordinates $X^{\mu}=f^{\mu}(X)$. This is merely a point transformation, and can therefore be realized in phase space as a canonical transformation. We now derive the corresponding new intrinsic Hamiltonian. We require that

$$
\begin{equation*}
\int d^{3} x X^{\mu} d \pi_{\mu}=-\int d^{3} x \pi_{\mu}^{\prime} d X^{\prime \mu}+\int d^{3} x d F\left[X^{\prime}, \pi\right] \tag{21}
\end{equation*}
$$

It follows that

$$
\begin{equation*}
X^{\mu}=\frac{\partial F}{\partial \pi_{\mu}}=f^{-1 \mu}\left(X^{\prime}\right) \tag{22}
\end{equation*}
$$

and

$$
\begin{equation*}
\pi_{\mu}^{\prime}=\frac{\delta F}{\delta X^{\prime \mu}} \tag{23}
\end{equation*}
$$

and therefore

$$
\begin{equation*}
F=\int d^{3} x f^{-1 \mu}\left(X^{\prime}\right) \pi_{\mu} \tag{24}
\end{equation*}
$$

and the transformed intrinsic Hamiltonian is 11

$$
\begin{equation*}
H_{i}^{\prime}=-\pi_{0}^{\prime}=\frac{\delta F}{\delta X^{\prime 0}} \tag{25}
\end{equation*}
$$

## 7 Diffeomorphism equivalence classes and intrinsic dynamics

It has long been an widespread belief that diffeomorphism equivalence classes of solutions of Einstein's equations can be described exclusively in terms of the phase space variables $\left(g_{a b}, p^{c d}\right)$. This is incorrect. The error stems from a common conflation of two distinct notions in constrained Hamiltonian dynamics for reparameterization covariant systems, namely time evolution on the one hand, and diffeomorphism symmetry on the other. In the Hamiltonian formalism time evolution, i.e., global rigid translation in time is not a canonically realizable symmetry. More precisely, there does not exist a member of the diffeomorphism-induced symmetry group that affects a global rigid time translation on every solution of Einstein's equations. Rather, a group element will perform this feat only on one particular solution. On the other hand the diffeomorphism-induced symmetry group transforms solutions of Einstein's

[^5]equations into new solutions. The difference is particularly evident when discussing the dynamical evolution of the intrinsic variables. In this case the analysis of section 3 shows that corresponding to every acceptable spacetime scalar intrinsic coordinate choice the variables $g_{A}$ and $p^{B}$ can be displayed as manifestly invariant functionals under the action of the full diffeomorphism-induced symmetry group. These manifestly invariant functionals are constructed by performing finite symmetry transformation to that location on symmetry orbits (for each value of the coordinate parameters $x^{\mu}$ ) at which the intrinsic coordinate conditions are satisfied. On the other hand one obviously has a nontrivial time evolution. Indeed, quite contrary to the common belief, not only is it incorrect to claim that phase space equivalence classes are orbits in $\left(g_{a b}, p^{c d}\right)$ super-space, the truth is that a single point in this phase space lies within many different equivalence classes! Equivalence classes are actually in one-to-one correspondence with the choice of intrinsic coordinates, and they are characterized by the fact that in each one the intrinsic dynamics is distinct.

This analysis is distinct from the conventional wisdom whereby one confines one's attention to the $\left(g_{a b}, p^{c d}\right)$ space and imagines that one obtains a physical reduced phase space by quotienting out the orbits generated by the constraints $\mathcal{H}_{\mu}$. This construction conflates the roles of time evolution and symmetry transformations, and claims that any data $\left(g_{a b}, p^{c d}\right)$ obtained under the action of the $\mathcal{H}_{\mu}$ must be physically equivalent. We have shown that on the contrary, not only is such data not necessarily equivalent, the same data will in general lie in different equivalence classes. The cosmological example below will serve to illustrate this point.

As we have seen above, it is now a fairly simple matter to transform from one equivalence class to another. Given that we have found at least one acceptable intrinsic coordinate choice with the phase space functionals $X^{\mu}\left(g_{a b}, p^{c d}\right)$ we are at liberty to undertake any point transformations we wish, namely all of those envisioned within the original general covariance symmetry group. We are assured that since these are point transformations they are canonical, and we can always find the corresponding conjugate momenta.

A remark concerning conventional geometrodynamics is appropriate here. In this program one in effect grants three-dimensional space a preferred geometrical status, and one similarly boosts this status by emphasizing the role of the three-dimensional spatial diffeomorphism group. But as we have seen, it is not possible to assign intrinsic spatial spacetime curvature-based coordinates without making reference to the temporal continuation of the three-metric off the spatial hypersurface - since all curvature scalars depend on the threemomentum.

## 8 Semi-classical quantization

The standard approach to the semi-classical quantization of gravity is via the Wheeler-DeWitt equation where one replaces the 3 -momentum variables in the conventional $\mathcal{H}_{0}$ constraint by the operator $-i \hbar \frac{\delta}{\delta g_{a b}}$. But we now have
at our disposal an infinite multitude of $\mathcal{H}_{0}$ constraints, one for each choice of the $X^{\mu}$. For each selection there is a corresponding Wheeler-DeWitt equation, each of which will yield its own natural choice for intrinsic temporal and spatial coordinates. However, as we shall argue in the cosmological example below in referring to the intrinsic Hamilton-Jacobi equation, the physical content of these Wheeler-DeWitt equations must already be contained within an intrinsic Schrödinger equation obtained by making the canonical operator substitutions in the intrinsic Hamiltonian. Thus we have for each choice of the $X^{\mu}$ an intrinsic Schödinger equation

$$
\begin{equation*}
H_{i}\left[g_{A},-i \hbar \frac{\delta}{\delta g_{B}} ; x^{\mu}\right] \Psi\left[g_{A}, x^{\nu}\right]=i \hbar \frac{\partial}{\partial t} \Psi\left[g_{A}, x^{\nu}\right] \tag{26}
\end{equation*}
$$

We are assured that we can construct the correct semiclassical limit, for each of the choices for $X^{\mu}$, from solutions of the form $\Psi=\sigma e^{i S / \hbar}$ where $S$ is a complete solution of the intrinsic Hamilton-Jacobi equation.

It is remarkable that the independent $g_{A}$ and $p^{B}$ are canonically conjugate and yet they are to be understood as diffeomorphism-induced invariants. However, when one undertakes the construction of invariants in the manner described above, the resulting invariants will satisfy the Dirac bracket algebra. They will generally not be canonically conjugate. It is the case however that non-canonical transformations can be undertaken so that this subset does satisfy the canonical Poisson bracket algebra.

Following up on our critique in the previous section of the geometrodynamical program, one cannot anticipate that appropriate choices of spacetime curvature based intrinsic coordinates can emerge from the conventional Einstein-Hamilton-Jacobi equation, and its associated Wheeler-DeWitt equation. The reason is that in the conventional approach the action is viewed as a functional of the three-metric. And as we have seen, neither spatial nor temporal spacetime scalars can be constructed employing the three-metric alone.

## 9 A cosmological example

We illustrate these ideas with a simple cosmological example, an isotropically expanding universe with vanishing curvature, vanishing cosmological constant, and a scalar source field. The line element is

$$
\begin{equation*}
d s^{2}=-N(t)^{2} d t^{2}+a(t)^{2}\left(d x^{2}+d y^{2}+d z^{2}\right) \tag{27}
\end{equation*}
$$

with Lagrangian

$$
\begin{equation*}
L=\frac{1}{2 N}\left(-\frac{6}{\kappa} a \dot{a}^{2}+a^{3} \dot{\Phi}^{2}\right) . \tag{28}
\end{equation*}
$$

The corresponding canonical Hamiltonian is

$$
\begin{equation*}
H_{c}=N\left(-\kappa \frac{p_{a}^{2}}{12 a}+\frac{p_{\Phi}^{2}}{2 a^{3}}\right) \tag{29}
\end{equation*}
$$

where $\kappa:=8 \pi G$, and we have the secondary constraint

$$
\begin{equation*}
H=-\kappa \frac{p_{a}^{2}}{12 a}+\frac{p_{\Phi}^{2}}{2 a^{3}}=0 \tag{30}
\end{equation*}
$$

We find that the quadratic Riemann scalar 12

$$
\begin{equation*}
R^{1}:=R_{\alpha \alpha^{\prime} \beta \beta^{\prime}} g^{\beta \beta^{\prime} \gamma \gamma^{\prime}} R_{\gamma \gamma^{\prime} \delta \delta^{\prime}} g^{\delta \delta^{\prime} \alpha \alpha^{\prime}} \tag{31}
\end{equation*}
$$

where $g^{\beta \beta^{\prime} \gamma \gamma^{\prime}}:=2 q^{\beta[\gamma} g^{\left.\gamma^{\prime}\right] \beta^{\prime}}$, simplifies to a power of $a^{2} p_{a}^{-1}$ for this highly symmetric solution. ${ }^{13}$ We therefore take $T=\frac{1}{3} \kappa a^{-2} p_{a},{ }^{14}$, as one of our new phase space variables. Note that since $\dot{a}=-\frac{\kappa N}{6 a} p_{a}$, this variable is actually minus twice the Hubble parameter $N^{-1} a^{-1} \dot{a}$. The choice we make here is actually proportional to the extrinsic curvature scalar, and is also known as the York time 32. 15

The variable conjugate to $T$ is $p_{T}=-\frac{1}{\kappa} a^{3}$ so that the corresponding generator in

$$
\begin{equation*}
p_{a} d a=p_{T} d T+\frac{\partial G}{\partial a} d a+\frac{\partial G}{\partial T} d T \tag{32}
\end{equation*}
$$

is

$$
\begin{equation*}
G=\kappa^{-1} a^{3} T . \tag{33}
\end{equation*}
$$

The inverse canonical transformation is $a=\kappa^{1 / 3}\left(-p_{T}\right)^{1 / 3}$ and

$$
p_{a}=3 \kappa^{-1 / 3}\left(-p_{T}\right)^{2 / 3} T
$$

In terms of the new canonical variables the constraint (30) becomes

$$
\begin{equation*}
H^{\prime}=\frac{3}{4} p_{T} T^{2}-\frac{p_{\phi}^{2}}{2 \kappa p_{T}}=0 \tag{34}
\end{equation*}
$$

The generator of the Legendre-projectable reparameterizations $t^{\prime}=t-N(t)^{-1} \xi(t)$ in terms of these new variables is

$$
\begin{equation*}
G_{\xi}^{\prime}(t)=\xi(t) H^{\prime}(t) \tag{35}
\end{equation*}
$$

The equations of motion are

$$
\begin{equation*}
\dot{T} \approx \frac{3}{4} N T^{2}, \quad \dot{p}_{T}=-N \frac{3}{4} p_{T} T \tag{36}
\end{equation*}
$$

and

$$
\begin{equation*}
\dot{\phi}=-N \frac{1}{2} \kappa^{-1} \frac{p_{\phi}}{p_{T}} \approx-\kappa^{-1 / 2} N \frac{1}{2}\left(\frac{3}{2}\right)^{3 / 2}(-T), \quad \dot{p}_{\phi}=0 . \tag{37}
\end{equation*}
$$

[^6]Of course, having managed to write the action in the form

$$
\begin{equation*}
S=p_{T} d T+p_{\phi} d \phi \tag{38}
\end{equation*}
$$

we can immediately implement our choice of intrinsic coordinate by simply letting $T=t$ in this expression and also solving the constraint for the momentum, obtaining

$$
\begin{equation*}
p_{T}=-H_{i}=\frac{1}{(3 \kappa / 2)^{1 / 2}} \frac{p_{\phi}}{(-t)} . \tag{39}
\end{equation*}
$$

Substituting into the action we obtain the intrinsic action

$$
\begin{equation*}
S_{i}=-H_{i} d t+p_{\phi} d \phi . \tag{40}
\end{equation*}
$$

This leads to the simple equation of motion

$$
\begin{equation*}
\dot{\phi}=-\frac{1}{(3 \kappa / 2)^{1 / 2}(-t)}, \tag{41}
\end{equation*}
$$

with solutions

$$
\begin{equation*}
\left.\phi=\phi_{0}+\frac{1}{(3 \kappa / 2)^{1 / 2}} \ln (-t)\right), \tag{42}
\end{equation*}
$$

as $t$ ranges from $-\infty$ to 0 .
Finally, to find the lapse we must return to the original Hamiltonian equations, we set $\dot{T}=1$ in (36), obtaining $N=\frac{2}{3 t^{2}}$.

Note also that the Einstein-Hamilton-Jacobi equation from the constraint (34) is

$$
\begin{equation*}
\frac{3}{2}\left(\frac{\partial S}{\partial T}\right)^{2} T^{2}-\frac{1}{\kappa}\left(\frac{\partial S}{\partial \phi}\right)^{2}=0 \tag{43}
\end{equation*}
$$

The intrinsic Hamilton-Jacobi equation is therefore the square root of the Einstein-Hamilton-Jacobi equation (43),

$$
\begin{equation*}
\frac{\partial S_{i}}{\partial t}+\frac{1}{(3 \kappa / 2)^{1 / 2}} \frac{1}{(t+1)} \frac{\partial S_{i}}{\partial \phi}=0 \tag{44}
\end{equation*}
$$

The complete solution is

$$
\begin{equation*}
S_{i}(\phi, t ; \alpha)=e^{-\alpha \phi_{0}-\frac{\alpha}{(3 \kappa / 2)^{1 / 2}} \ln (-t)+\alpha \phi} \tag{45}
\end{equation*}
$$

One obtains the general classical solution for $\phi$ in the usual manner by setting $0=\frac{\partial S_{i}}{\partial \alpha}$. This ensures that in passing to the quantum theory we obtain a wave packet that follows the classical trajectory by forming an appropriate superposition

$$
\begin{equation*}
\Psi(\phi, t)=\int d \alpha f(\alpha) e^{S_{i}(\phi, t ; \alpha) / \hbar} \tag{46}
\end{equation*}
$$

This wave function satisfies the Schrödinger equation

$$
\begin{equation*}
H_{i}\left(t,-i \hbar \frac{\partial}{\partial \phi}\right) \Psi=i \hbar \frac{\partial}{\partial t} \Psi \tag{47}
\end{equation*}
$$

as a consequence of the intrinsic Hamilton-Jacobi equation.
What if we decided to employ the analogue Wheeler-DeWitt equation, using the transformed constraint, i.e.

$$
\begin{equation*}
\frac{3}{4} p_{T}^{2} T^{2}-\frac{p_{\phi}^{2}}{2 \kappa}=0 \rightarrow\left(-\frac{3}{4} t^{2} \frac{\partial^{2}}{\partial t^{2}}+\frac{1}{2 \kappa} \frac{\partial^{2}}{\partial \phi^{2}}\right) \Psi(\phi, t)=0 . \tag{48}
\end{equation*}
$$

rather than the intrinsic Schrödinger equation?
Then it turns out that if solutions are assumed of the form $\Psi=e^{i S / \hbar}$, then one can show after considerable labor, after expanding $S$ in powers of $\kappa$, that $S$ satisfies the intrinsic Hamilton-Jacobi equation. The lesson to be drawn is that the Schrödinger equation is far more efficient.

### 9.1 Intrinsic canonical coordinate transformations

Let us consider a point transformations of the form $T^{\prime}=f(T)$. Following the general prescription described above, we set

$$
\begin{equation*}
T d \pi=-\pi^{\prime} d T^{\prime}+d F \tag{49}
\end{equation*}
$$

resulting in

$$
\begin{equation*}
F=f^{-1}\left(T^{\prime}\right) \pi \tag{50}
\end{equation*}
$$

and the transformed intrinsic Hamiltonian

$$
\begin{equation*}
H_{i}^{\prime}=H_{i} \frac{\partial f^{-1}\left(T^{\prime}\right)}{\partial T^{\prime}} \tag{51}
\end{equation*}
$$

It must be stressed that the $T$ we have chosen in this example is a spacetime scalar only under first order four-dimensional diffeomorphisms away from the spatially isotropic solutions of Einstein's equations. Higher order variations would require the use of $R^{1}$ in (31) in constructing a spacetime scalar intrinsic time.

The following canonical point transformation transformation transforms from York time to proper time:

$$
T^{\prime}=-T^{-1}=f(T)
$$

Therefore according to our general prescription we can perform a point canonical transformation to obtain the corresponding new intrinsic Hamiltonian,

$$
p_{T^{\prime}}^{\prime}=p_{T} \frac{d f^{-1}\left(T^{\prime}\right)}{d T^{\prime}}=\frac{p_{\phi}}{(3 \kappa / 2)^{1 / 2}} T^{\prime} \frac{d\left(-T^{\prime}\right)^{-1}}{d T^{\prime}}=\frac{p_{\phi}}{(3 \kappa / 2)^{1 / 2}} \frac{1}{T^{\prime}} .
$$

Note that this time ranges from 0 to $\infty$.
But we need not stop here. We can actually imitate any choice of time coordinate by choosing new intrinsic times as $\lambda\left(T^{\prime}\right)$, for arbitrary positive definite functions $\lambda$.

This is actually a substantiation of the general result described earlier. For every choice of coordinate parameters in general relativity there corresponds a choice of intrinsic coordinates.

### 9.2 Explicit invariants

The variables that appear in the intrinsic HJ approach are precisely the invariant variables, which are constructed as follows as power series in the intrinsic time in the chosen gauge. We will display the invariant nature of the coefficients in these series. The algebra is considerably simplified using the variable $\alpha$ defined such that $a=e^{\alpha / \sqrt{6}}$. The canonical Hamiltonian in terms of this new variable is

$$
\begin{equation*}
H_{c}=N e^{-3 \alpha / \sqrt{6}}\left(-\frac{\kappa}{2} p_{\alpha}^{2}+\frac{1}{2} p_{\phi}^{2}\right) . \tag{52}
\end{equation*}
$$

The intrinsic time $T$ will be proper time if the requirement that $\dot{T}=1$ fixes $N$ to be 1 . We will let $T$ range from -1 to $\infty$ so that the general solution for $\phi$ will be analytic at $T=0$. These requirements result in

$$
\begin{equation*}
T=-\frac{1}{\kappa z} e^{z \alpha} p_{\alpha}^{-1}-1 \tag{53}
\end{equation*}
$$

where $z:=3 / \sqrt{6}$.
Following the general scheme outlined above, and presented in detail in [26], the invariant observable associated with $\phi$ is

$$
\begin{align*}
\mathcal{O}_{\phi} & =\phi+(t+h)\{\phi, H\}+(t+h)^{2} \frac{1}{2}\{\{\phi, H\}, H\} \\
& +(t+h)^{3} \frac{1}{3!}\{\{\{\phi, H\}, H\}, H\}+\ldots \tag{54}
\end{align*}
$$

where $h:=\frac{1}{\kappa z} e^{z \alpha} p_{\alpha}^{-1}+1$. The infinite series for the coefficient of each power of $t$ can be summed, and the result is

$$
\begin{equation*}
\mathcal{O}_{\phi}=\phi_{0}-\frac{p_{\phi}}{p_{\alpha} \kappa z}\left(t-\frac{t^{2}}{2}+\frac{t^{3}}{3}-\ldots\right)=\phi_{0}-\frac{p_{\phi}}{p_{\alpha} \kappa z} \ln (1+t) \tag{55}
\end{equation*}
$$

where

$$
\phi_{0}\left(\phi, \alpha, p_{\phi}, p_{\alpha}\right)=\phi-\frac{p_{\phi}}{\kappa p_{\alpha}} \alpha+\frac{p_{\phi}}{z \kappa p_{\alpha}} \ln \left[-z \kappa p_{\alpha}\right]
$$

The momenta are constants, as is $\phi_{0}$ since in an arbitrary parameterization

$$
\begin{equation*}
\frac{d}{d t}\left(\phi-\frac{p_{\phi}}{\kappa p_{\alpha}} \alpha\right)=N e^{-z \alpha} p_{\phi}-\frac{p_{\phi}}{\kappa p_{\alpha}} \kappa N e^{-z \alpha} p_{\alpha}=0 \tag{56}
\end{equation*}
$$

It is now a simple matter to find the corresponding invariant $\mathcal{O}_{\phi}^{\prime}$ for other gauge choices $T^{\prime}=f(T)$ :

$$
\begin{equation*}
\mathcal{O}_{\phi}^{\prime}=\phi_{0}\left(\phi, \alpha, p_{\phi}, p_{\alpha}\right)-\frac{p_{\phi}}{p_{\alpha} \kappa z} \ln \left(1+f^{-1}(t)\right) \tag{57}
\end{equation*}
$$

### 9.3 Equivalence classes

We conclude this example with an observation on the nature of diffeomorphism equivalence classes as exhibited in this model. Every choice of intrinsic coordinates yields dynamical variables that are invariant under the restricted action ( in this example ) of the group of time reparameterizations. As we have seen, the coefficients of powers of $T$ are invariants, as is $T$ itself. The construction we have just reviewed delivers invariants because it establishes a unique relationship between a prescribed function of spacetime curvature and the remaining dynamical variables. Since these intrinsic coordinate function $T\left(a, p_{a}\right)$ are freely prescribeable, subject only to the condition that each of them must be a scalar, we have the liberty to employ this freedom to undertake arbitrary transformations of $T$. As we have seen this fixes a new intrinsic dynamics, with the corresponding intrinsic Hamiltonian obtained through a canonical phase space transformation. The perhaps startling consequence of this analysis is that the same initial values of $\left(a, p_{a}, \phi, p_{\phi}\right)$ can and will generally lead to distinct physical evolutions. We can easily achieve this result in this cosmological model, for example, by taking $T=-\frac{1}{\kappa z} e^{z \alpha} p_{\alpha}^{-1}-1$ for one equivalence class, and for the second equivalence class choosing a new $T^{\prime}=f(T)$ where $f(T)=T$ for $T$ less than some positive constant. In other words, the same data can lie in many different diffeomorphism equivalence classes. The equivalence classes are in fact in one to one correspondence with the original set of solutions in terms of arbitrary coordinate parameters $t$.

## 10 Conclusions

In this work we investigated the fate of background independence in a HamiltonJacobi approach to general relativity. A precondition for freedom from arbitrary presupposed structure must be the preservation of full diffeomorphism symmetry. Whereas general covariance is a basic underlying theme in configurationvelocity space, its role in phase space is still obscure. In many cases this obscurity arose with the abandonment of lapse and shift as canonical variables. As already shown in the (generally not adequately appreciated) work of Bergmann and Komar [7, these variables are needed in realizing the diffeomorphism group in phase space. They also necessarily appear in the construction of spacetime scalars in terms of configuration-velocity variables. Nevertheless, as shown originally by Bergmann and Komar, the explicit dependence on lapse and shift disappears when the spacetime scalars are expressed as phase space functionals. As soon as one has in one's possession an acceptable intrinsic coordinate chart, one is then free to carry out the full diffeomorphism group of intrinsic coordinate transformations. Indeed they are canonical phase space transformations. This was Kuchar's starting point in implementing his reduced Hamiltonian idea. We have split his procedure into two steps. The first is the selection of appropriately behaved spacetime scalar functionals of the three-metric and its canonical momenta. We emphasize that this choice of
new canonical configuration variables and their conjugate momenta leaves the resultant theory still fully covariant under the action of the diffeomorphisminduced canonical transformation group. And for each choice there are corresponding Einstein-Hamilton-Jacobi and Wheeler DeWitt equations. The second step is the choice of these configuration functionals as intrinsic coordinates. This is equivalent to imposing gauge conditions. And as was shown in [26], the generator of diffeomorphism-induced canonical transformations can then be deployed to construct corresponding diffeomorphism invariant variables. The message we wish to communicate here is that our synthetic approach results in the seemingly paradoxical conclusion that a choice of intrinsic coordinates yields a dynamics of diffeomorphism invariants, yet the full diffeomorphism freedom still exists since one can arbitrarily canonically transform from one intrinsic coordinate choice to another.

Thus the full four-dimensional diffeomorphism-induced group is realizeable in phase space as a canonical transformation group. Spacetime curvature-based phase space variables can be found that can serve as intrinsic spacetime event landmarks. The freedom in selecting these spacetime landmarks corresponds to the original diffeomorphism freedom. The dynamics expressed in terms of the intrinsic scalars, their conjugate momenta, and the remaining independent phase space variables is fully covariant under the 4-D diffeomorphism-induced group. For each choice of new phase space variables there exists a corresponding Einstein-Hamilton-Jacobi equation

$$
\mathcal{H}_{0}\left[g_{A}, X^{\mu}, \frac{\delta S}{\delta g_{B}}, \frac{\delta S}{\delta X^{\nu}}\right]=0
$$

In fact, since the intrinsic coordinates must be spacetime scalars, the conventional Einstein-Hamilton-Jacobi equation will generally not be suitable for making the semi-classical transition to the Wheeler-DeWitt quantum gravitational wave equation because spacetime scalars cannot be constructed with the three-metric alone. Therefore one cannot expect a "natural" choice of time to emerge from this equation as it did in the free particle model. Rather, the formalism must at least in a semi-classical regime admit the same full range of diffeomorphism freedom of choice of both intrinsic time and space that we find in the classical domain. Each choice of intrinsic coordinate yields distinct explicitly temporal and spatially dependent classical equations of motion. The diffeomorphism symmetry has been employed to construct diffeomorphism invariants, and in this sense the full diffeomorphism symmetry of Einstein's theory has been taken into account. But the resulting dynamics of these invariant variables is distinct for each choice of intrinsic coordinates. In this sense the original diffeomorphism symmetry has been broken. The quantum mechanical challenge is to construct a theory in which all of these in general unitarily inequivalent diffeomorphism invariant evolutions are taken into account. A full description of reality appears to require the collective use of all possible intrinsic times.

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## Appendix A: The free particle principal function

The true Hamilton-Jacobi equation for the free relativistic particle is obtained from the increment (11). In this case we know the general solution,

$$
\begin{equation*}
x^{\mu}(\theta)=\bar{x}^{\mu}+\bar{p}^{\mu} f(\theta) \tag{58}
\end{equation*}
$$

where the barred quantities are constants, $f(\theta)$ is monotonically increasing but otherwise an arbitrary function. This expression is to be evaluated (following differentiation with respect to $\bar{p}_{\mu}$ ) where $\bar{p}^{2}=-m^{2}$. So we need merely substitute this solution into (1), obtaining

$$
\begin{equation*}
S(q, \theta ; \bar{p})=\bar{p}_{\mu} q^{\mu}-\frac{1}{2}\left(\bar{p}^{2}+m^{2}\right) f(\theta)-C(\bar{p}) . \tag{59}
\end{equation*}
$$

We confirm that the Hamilton-Jacobi equation (2) is satisfied. Furthermore, setting

$$
0=\frac{\partial S}{\partial \bar{p}_{\mu}}=q^{\mu}-f(\theta) \bar{p}^{\mu}-\frac{\partial C}{\partial \bar{p}_{\mu}}
$$

we recover the exact general solution.

## Appendix B: Critique of the Dittrich multi-fingered time approach to Dirac observables

Dittrich has pioneered a technique for constructing in generally covariant theories objects which are invariant under the action of the secondary first class constraints. We learned from her how to Abelianize these constraints so as to be able to easily find the phase space dependent coordinate transformations that yield these invariants. But we approach the problem from a distinctly different conceptual perspective. The essential difference is that she employs passive coordinate transformations to construct her invariants whereas we employ active canonically realized diffeomorphism-induced symmetry transformations. She does not take this route since she apparently does not recognize that the full four-dimensional symmetry group is of relevance in this context. Indeed, in order to be able to implement this group the lapse and shift functions must be retained as canonical phase space variables. Connected with this observation is the fact that the Hamiltonian that generates evolution in time is not to be confused with the generator of diffeomorphism-induced symmetry transformations. As must be demanded of a symmetry, the latter actually transforms solutions of the equations of motion into new solutions. On the other hand, in pursuing the Kuchař multi-fingered time approach Dittrich confines her attention to the Hamiltonian - and thus does not reproduce this fundamental symmetry requirement in her canonical formalism.

The evolution in the Dittrich-Kuchař multi-fingered time approach is understood in general relativity as a "pushing forward in time" described by an embedding mapping from $\Sigma \times \Re \rightarrow \mathcal{M}$, where $\Sigma$ is a three dimensional manifold. Using adapted coordinates, the mapping is $Z_{t}^{\mu}(\mathbf{x})=x^{\mu}$. The basic assumption is that one decompose the "push forward" in terms of lapse and shift as

$$
\delta x^{\mu}=\left(N n^{\mu}+\delta_{a}^{\mu} N^{a}\right) \delta t
$$

where the normal to the hypersurface is $n^{\mu}=N^{-1} \delta_{0}^{\mu}-\delta_{a}^{\mu} N^{-1} N^{a}$. This decomposition of the push forward is simply assumed in the Kuchař formalism. We now know that it is required in order to be able to project configurationvelocity transformations under the Legendre map to phase space [24]. The crucial difference with the fully diffeomorphism covariant Hamiltonian approach that we describe in this paper is that any changes in lapse and shift must be inserted in the multi-fingered time approach "by hand"; they are not canonically generated and in this sense the full four-dimension diffeomorphism covariance is lost.

We will detail these differences using as a simple example the free relativistic particle model. For this purpose, since it corresponds more closely to general relativity, it will be instructive to formulate the model using an auxiliary variable $N$ that actually serves as a lapse function on the parameter space. Thus we take the Lagrangian to be

$$
L=\frac{1}{2 N} \dot{q}^{2}-\frac{1}{2} m^{2} N
$$

Then we have the primary constraint $\pi=0$, where $\pi$ is the momentum conjugate to $N$, and the secondary constraint $C_{\perp}=\frac{1}{2}\left(p^{2}+m^{2}\right)=0$. The Dittrich Hamiltonian would be

$$
H[N]=N C_{\perp}
$$

(The embedding looses dependence on the lapse in this one-dimensional case.) Then given $N(\theta)$ one solves the Hamiltonian equations

$$
\frac{d q^{\mu}}{d \theta}=N(\theta) p^{\mu}
$$

and $\frac{d p^{\mu}}{d s}=0$. The crucial observation here is that $N(\theta)$ does change its form under reparameterizations, but these changes are not generated through canonical transformations. There does however exist a means of performing a passive parameter transformation that will alter $N$. Suppose that $N(\theta)$ is given, then the corresponding particle solution is

$$
q^{\mu}(\theta)=q^{\mu}\left(\theta_{0}\right)+p^{\mu} \int_{\theta_{0}}^{\theta} d \theta^{\prime} N\left(\theta^{\prime}\right)
$$

One can then carry out the Dittrich complete observable program by selecting, for example, to put the partial variable $q^{0}(\theta)$ in correspondence with the partial variables $q^{a}(\theta)$. This correspondence qualifies as an intrinsic parameter choice since $q^{0}$ is a reparamterization scalar. Thus we can conceive of
$\hat{\theta}=f(\theta):=q^{0}(\theta)=q^{0}\left(\theta_{0}\right)+p^{0} \int_{\theta_{0}}^{\theta} d \theta^{\prime} N\left(\theta^{\prime}\right)$ as a reparameterization. Then since $N$ transforms as a scalar density of weight minus one, we can calculate the passively transformed $N$ through the formula

$$
\hat{N}(\hat{\theta})=N(\theta) \frac{d \theta}{d \hat{\theta}} .
$$

The actively transformed $N$ is then

$$
\hat{N}(\theta)=\frac{N\left(f^{-1}(\theta)\right)}{\left.\frac{d f(\theta)}{d \theta}\right|_{f^{-1}(\theta)}}
$$

Dittrich can carry out the passive transformation, but she is not able to produce the active result through a canonical transformation since she does not employ the full parameterization-induced generator. This generator is

$$
G(\xi)=\xi H+\dot{\xi} \pi
$$

It generates infinitesimal canonical transformations that follow from infinitesimal reparameterizations of the form $\hat{\theta}=\theta+\delta \theta=\theta-\frac{\xi(\theta)}{N(\theta)}$. With this generator one can with a finite $\xi(\theta)$ generate a one-parameter family of phase space solutions $q_{s}^{\mu}(\theta), N_{s}(\theta)$ from any given initial set of solutions. In other words, this generator exploits the underlying Lagrangian reparameterization symmetry and does indeed transform solutions of the Euler-Lagrange equations into new solutions. This is an essential feature that is lacking in Kuchař multi-fingered time approach in which one deals only with the lapse and shift in advancing the evolution time. Only in the case of three-dimensional diffeomorphisms is the symmetry fully implemented in the Kuchař embedding procedure as a canonical transformation.

Let us also point out that since we can implement reparameterizations, we can now check explicitly whether reparameterization scalars transform correctly. We find for example that

$$
\bar{\delta} q^{\mu}=\left\{q^{\mu}, G(\xi)\right\}=p^{\mu} \xi=\dot{q}^{\mu} \frac{\xi}{N}=-\dot{q}^{\mu} \delta \theta
$$

We contrast this demand with the Kuchař requirement that a variable transform as a scalar under reparameterizations (or in general relativity as a spacetime scalar). Since the timelike transformations are not implemented as a symmetry, Kuchař was forced to characterize a spacetime scalar $S(\mathbf{x})$ as a variable whose variation satisfied $\left\{S(\mathbf{x}), \int d^{3} x C_{\perp}(\mathbf{x}) N(\mathbf{x})\right\}=0$ when $N\left(\mathbf{x}^{\prime}\right)=0$ 18, 19, 12 Actually this is a necessary condition, but it is not sufficient. The variable $v_{\mu} n^{\mu}$, for example, that Bergmann has termed a "D-invariant" satisfies this requirement, and it is is clearly not a spacetime scalar (5].

One might wonder how the Hamiltonian transforms under reparameterizations. The Dirac Hamiltonian is

$$
H_{D}=N H+\lambda \pi
$$

where $\lambda$ is a positive-definite but otherwise arbitrary function of $\theta$. Since it does not depend on the phase space variables one might wonder how it transforms under the action of $G(\xi)$. It does so because it is explicitly $\theta$-dependent. The transformed Hamiltonian is

$$
\hat{H}=H+\{H, G(\xi)\}+\frac{\partial G}{\partial \theta}=H+\dot{\xi} H+\ddot{\xi} \pi
$$

But under this transformation $\hat{N}=N+\dot{\xi}, \hat{q}^{\mu}=q^{\mu}+\xi p^{\mu}$ while $p^{\mu}$ and $\pi$ are unchanged. Substituting we find

$$
\hat{H}_{D}=\hat{N} \hat{H}+(\lambda+\ddot{\xi}) \hat{\pi}
$$

Thus $\lambda$ has varied correctly so that $\frac{d \hat{N}}{d \theta}=\frac{d N}{d \theta}+\frac{d^{2} \xi}{d \theta^{2}}$.
These results can be easily generalized to any generally covariant theory, including general relativity.

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[^1]:    1 We caution the reader that various notions of "intrinsic" can be found in the literature (very often also characterized by the term "internal"). What we have in mind is the idea presented by Komar and Bergmann [8]. It is not to be confused with intrinsic versus extrinsic geometries, fixed in terms of either the 3-geometry or the extrinsic curvature.

[^2]:    ${ }^{2}$ See [25], and literature cited therein for complete details
    ${ }^{3}$ When there are additional gauge fields there are additional terms
    4 We employ B. DeWitt's compact notation in which repeated indices also represent an integration
    5 This is in the spirit of Einstein's point coincidence argument.

[^3]:    ${ }^{6}$ Kuchař 20 required only that the $X^{\mu}$ be scalars under spatial diffeomorphisms. Dittrich and Tambornino [15,14 discuss technical advantages and disadvantages in employing spacetime scalars as partial variables.
    7 Dittrich derived analogous infinite series, with invariant coefficients, referring only to the three-metric and conjugate momenta [12]. It was shown in [26] how to construct analogous series through active transformations also for the lapse and shift.

[^4]:    8 The field-theoretic Hamilton-Jacobi approach (for electromagnetism) was first formulated in this manner by Paul Weiss [31. The application to vacuum general relativity proceeds as follows. In addition to the metric variations $\delta_{0} g_{\mu \nu}(x)$ at the fixed spacetime coordinate parameter position $x^{\mu}$, we will have as a consequence of the second type of variation a resulting change in the metric $-g_{\mu \nu, \alpha} \delta x^{\alpha}$ with the consequent net variation $\delta g_{\mu \nu}=\delta_{0} g_{\mu \nu}-g_{\mu \nu, \alpha} \delta x^{\alpha}$. The resulting variation in the action, assuming that all the variations are to new solutions of Einstein's equations, is

    $$
    \begin{aligned}
    \delta S_{G R}=\int d^{3} x & {\left[p^{a b} \delta_{0} g_{a b}+P_{\mu} \delta_{0} N^{\mu}-\left(p^{a b} \dot{g}_{a b}-\mathcal{L}_{G R}+\pi_{\mu} \dot{N}^{\mu}\right) \delta t\right.} \\
    & \left.+\left(p_{\mid c}^{a b} g_{a b}+P_{0, c} N+P_{a, c} N^{a}\right) \delta x^{c}\right]
    \end{aligned}
    $$

    But $p^{a b} \dot{g}_{a b}-\mathcal{L}_{G R}=\mathcal{H}_{\mu} N^{\mu}$. The $\dot{N}^{\mu}$ are arbitrary functions $\lambda^{\mu}$. The terms multiplying $\delta x^{a}$ are the generators of 3-D diffeomorphisms. Finally, taking $\delta x^{a}=0$, we obtain (14) where we now represent the variation $\delta_{0} g_{a b}$ by $d g_{a b}$.

[^5]:    11 Kuchař did not address this issue. We have here the rule for canonically transforming his reduced Hamiltonian.

[^6]:    $12 R^{1}$ is not to be confused with $R_{\alpha \beta \gamma \delta} R^{\alpha \beta \gamma \delta}$.
    13 Bergmann and Komar's procedure [8 shows that in general some of the curvature scalars's can be expressed in terms of the 3-metric and conjugate momenta. In particular when expressed in terms of these phase space variables there is no explicit dependence on the lapse and shift
    14 With this choice $T$ will range from $-\infty$ to 0
    15 See [28] for a proposed use of York time for this cosmological model.

