

Plasma shaping and its impact on the pedestal of ASDEX Upgrade: Edge stability and inter-ELM dynamics at varied triangularity

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Abstract. The plasma shape, in particular the triangularity (δ), impacts on the pedestal stability. A scan of δ including a variation of heating power (P_{heat}) and gas puff was performed to study the behaviour of edge localised modes (ELMs) and the pre-ELM pedestal stability for different plasma shapes. Generally, at higher δ the pedestal top electron density (n_e) is enhanced and the ELM repetition frequency (f_{ELM}) is reduced. For all δ , the pedestal top n_e is already fully established to its pre-ELM value during the initial recovery phase of the n_e pedestal, which takes place immediately after the ELM crash. The lowering of the f_{ELM} with increasing δ is related to longer pedestal recovery phases, especially the last pre-ELM phase with clamped pedestal gradients (after the recovery phases of the n_e and electron temperature (T_e) pedestal) is extended. In all investigated discharge intervals, the pre-ELM pedestal profiles are in agreement with peeling-ballooning (PB) theory.

Over the investigated range of δ , two well-separated f_{ELM} bands are observed in several discharge intervals. Their occurrence is linked to the inter-ELM pedestal stability. In both kinds of ELM cycles the pedestal evolves similarly, however, the ‘fast’ ELM cycle occurs before the global plasma stored energy (W_{MHD}) increases, which then provides a stabilising effect on the pedestal, extending the inter-ELM period in the case of the ‘slow’ ELM cycle. At the end of a ‘fast’ ELM cycle the n_e profile is radially shifted inwards relative to the n_e profile at the end of a ‘slow’ ELM cycle, leading to a reduced pressure gradient. The appearance of two f_{ELM} bands suggests that the pedestal becomes more likely PB unstable in certain phases of the inter-ELM evolution. Such a behaviour is possible because the evolution of the global plasma is not rigidly coupled to the evolution of the pedestal structure on the timescales of an ELM cycle.

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1. Introduction

In magnetically confined fusion plasmas the stability of the plasma edge, is of special importance. In the high confinement mode (H-mode), on the one hand high plasma performance can be achieved, on the other hand owing to the large pressure gradients at the edge, named the pedestal, instabilities can occur, so-called edge localised modes (ELMs). These cause large transient heat and particle fluxes towards the wall, which could exceed material limits in a future fusion device [1, 2, 3]. Hence, it will be necessary to keep the pedestal as high as possible (good plasma performance), and well below its stability limit (to avoid ELMs). To optimise pedestals in this sense, understanding of the mechanisms that determine the pedestal structure and its stability is required.

The presented work emphasises the impact of the plasma shape on the pedestal stability and its recovery in between ELM crashes in type-I ELMy H-mode plasmas. Under these plasma conditions it is known from magnetohydrodynamic (MHD) theory, that higher triangularity (δ) and plasma elongation (κ) are beneficial for the plasma edge stability [4, 5, 6], enabling steeper profile gradients and higher pedestal pressure. The positive impact of δ on the pedestal height has also been experimentally confirmed in several tokamak experiments [7, 8, 9]. It has been found that higher δ is connected to an increase of the electron density (n_e) pedestal [10, 11]. However, this dependency could be also biased by changes of the strikepoint positions in the active divertor. These were necessary to vary δ , however, such changes can impact on the neutral pumping efficiency and divertor conditions. For this reason, the presented experiments aimed for a variation of δ without changing the strike- and X-point positions in the active divertor.

Additionally to the changes in the pedestal structure, a variation of δ changes the ELM repetition frequency (f_{ELM}) [12]. In general, Type-I ELM behaviour, respectively f_{ELM} and the duration of the ELM crash, can be influenced by several discharge conditions, e.g. impurity seeding [13, 14, 15, 16, 17] or neutral influx like external gas puff [18, 19, 20, 21, 22, 23]. A special change of ELM behaviour has been observed at ASDEX Upgrade, where two separated f_{ELM} bands occurred [24, 25]. Similar observations have also been reported from the KSTAR experiment [26], here, referred to as secondary ELM peaks, and at TCV [27]. Also within the presented experiments, such an ELM behaviour was observed and the underlying mechanisms that cause two distinct f_{ELM} bands are studied in this work.

In the following, the experimental procedure is introduced that was used to compare H-mode plasma discharges with a variation of δ , heating power (P_{heat}) and gas puff (section 2). In section 3 the general discharge behaviour is described, emphasising on the impact of δ on f_{ELM} , n_e pedestal and plasma stored energy (W_{MHD}). The stabilising effect of δ on the pedestal is discussed in section 4 and the inter-ELM evolution for two cases with low and high δ are compared. The occurrence of two distinct f_{ELM} bands is analysed at low and high δ in section 5. In section 6 the main results are recapped, showing that the increased pedestal top n_e at enlarged δ is already established in the initial inter-ELM recovery phase of the pedestal. At higher δ , f_{ELM} decreases because the

inter-ELM recovery phases are prolonged, especially the pre-ELM phase with clamped pedestal pressure gradients [28] is extended. When two distinct f_{ELM} bands are observed, both types of ELM cycles show a similar pedestal evolution up to the point where the ‘fast’ ELM cycle (higher f_{ELM} band) ends. From this point on W_{MHD} increases providing via the Shafranov shift a stabilising effect on the pedestal and extending the ‘slow’ ELM cycle (lower f_{ELM} band).

2. Conducted experiment

To perform a δ scan without changing the divertor conditions in the active divertor, a lower single null (LSN) plasma scenario was chosen and only the upper triangularity (δ_{up}) was varied. The achievable range of δ is limited by operational boundaries on maximum shaping coil currents in the ASDEX Upgrade standard scenario [29] with 1.0 MA plasma current (I_{p}) and -2.5 T toroidal magnetic field (B_{t}). The negative sign of B_{t} stands for its opposite direction to I_{p} . Further, increasing δ increases the n_{e} pedestal, which can lead to n_{e} above the electron cyclotron emission (ECE) cut-off and therefore, limiting the diagnostic capabilities. For these reasons, a plasma scenario with reduced I_{p} in contrast to the ASDEX Upgrade standard configuration was chosen. The main parameters were $I_{\text{p}}=0.8$ MA and $B_{\text{t}}=-2.5$ T. This gives a higher safety factor (q) at the edge in comparison to the standard configuration, lowers the required coil currents for shaping by roughly 20%, lowers the central plasma n_{e} and extends the achievable discharge length because of less flux consumption of the transformer coil.

2.1. Shape comparison and varied parameters

Usually, changing the shaping coil currents impacts δ and κ when the outer strikepoint location is controlled. Since κ also influences the plasma stability, it was emphasised to adjust the shaping accordingly that only minor variations of κ in the region of $\pm 5\%$ occur. Further, changes of P_{heat} and correspondingly W_{MHD} impact on the Shafranov shift and therefore, modify the plasma shape. To avoid these modifications, the shaping coil currents were adjusted, such that δ and κ remained unchanged, when steps in P_{heat} were performed.

The general experimental procedure was to establish a plasma scenario at fixed δ and then vary P_{heat} and neutral gas puff. Then, δ was varied from discharge to discharge. By this procedure the achieved range of the upper triangularity (δ_{up}) was 0.0 to 0.4 leading to an average δ between 0.21 and 0.41.

Figure 1 presents a comparison of the plasma shapes for low (dark blue), medium (dark red) and high (orange) δ .

At low and medium delta a nice match of X-point and strikepoint locations were achieved, while the location of the plasma top was moved inwards resulting in an increased δ . For the high δ scenario a small change in the strikeline positions of the order of 3 cm had to be accepted. Since the targets in this region are usually well conditioned

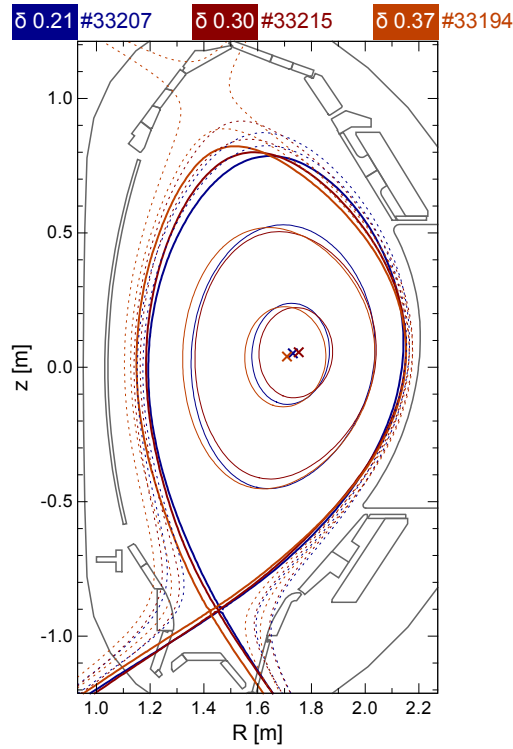


Figure 1: Comparison of separatrix locations with varied δ_{up} : At low (0.21, dark blue) and medium (0.30, dark red) δ the strike- and X-point locations are the same, whereas at high (0.37, orange) δ the strikelines have slightly different locations (shift at the outer target in the region of 3 cm) and the lower triangularity (δ_{low}) is higher.

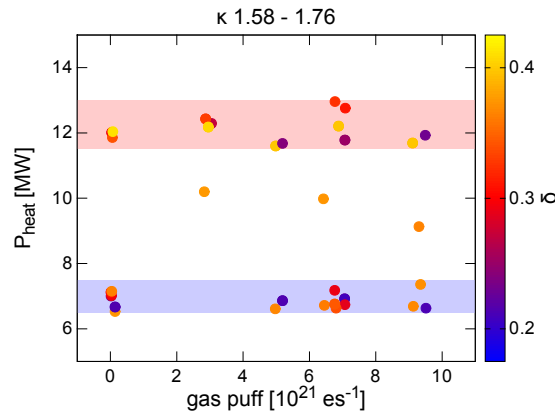


Figure 2: Varied control parameters: At mainly two levels of P_{heat} (6.5 MW to 7.5 MW, blue shaded area and 11.5 MW to 13.0 MW, red shaded area) a scan of the gas puff was performed for the different δ . A variation of κ in the region of $\pm 5\%$ was tolerated.

no impact on the divertor conditions or neutral recycling is expected by this change.

The accessed parameter range of P_{heat} and neutral gas puff is presented in figure 2. In principle two levels of P_{heat} were applied: A lower level between 6.5 MW and 7.5 MW

(blue shaded area) and a higher level in the range from 11.5 MW to 13.0 MW (red shaded area). The gas puff was varied between $0 \cdot 10^{21} \text{ es}^{-1}$ and $10 \cdot 10^{21} \text{ es}^{-1}$ in such a way that it was stepwise reduced throughout and turned off completely towards the end of the discharge.

2.2. Performed data analysis

This study is mainly focused on the investigation of the electron profile structures and especially their inter-ELM dynamics. The n_e and electron temperature (T_e) profiles are evaluated using the integrated data analysis (IDA) approach [30], which combines and evaluates the data of multiple plasma diagnostics. For the presented profiles, the following diagnostics were included in the analysis: The deuterium cyanide laser interferometry diagnostic [31] for the core n_e , the lithium beam diagnostic [32] for the edge n_e and the recently refurbished ECE diagnostic [33] together with an electron cyclotron forward model [34] for the T_e . The relative alignment of the n_e and T_e profiles was determined by cross comparison to the corresponding profiles of the Thomson scattering (TS) diagnostic [35]. If necessary, the T_e profile is slightly shifted ($< 3 \text{ mm}$) such that 100 eV are the separatrix T_e [36]. This minor shift is then also applied to the n_e profile. The quality of the raw data allows a profile evaluation with a temporal resolution of 250 μs .

To reconstruct the plasma equilibria and corresponding quantities, e.g. δ and κ , the integrated data analysis equilibrium (IDE) solver [37] was routinely applied, which implements a constraint on the pedestal pressure profile according to the one evaluated by IDA at the corresponding time. The equilibria are reconstructed at a temporal resolution of 1 ms. Within the presented work, for the first time these ‘IDE equilibria’ have routinely been used to serve as input for linear MHD stability, peeling-ballooning (PB), analyses. Furthermore, an ELM synchronisation technique was implemented to statistically average over multiple equilibria with respect to the corresponding ELM onsets. This allows to determine the uncertainties in average toroidal current density in the pedestal ($\langle j_{\text{tor}} \rangle$) and normalised pressure gradient (α) and furthermore, to display error bars on the operational point. The resulting stability diagrams for low and high δ cases as well as the different types of ELM cycles are presented in the [sections 4.1](#) and [5.3](#).

3. General observations

In the following, the overall discharge behaviour at different δ with respect to the pedestal and ELM behaviour is discussed and compared to previous experimental results. As shown in [figure 3](#), f_{ELM} decreases at higher δ , which is in agreement with previous observations [12]. In this figure only discharge intervals with a single f_{ELM} band are considered. The vertical bars represent the scattering of f_{ELM} . This mainly appears due to varying duration of the last, pre-ELM phase of the inter-ELM pedestal evolution for

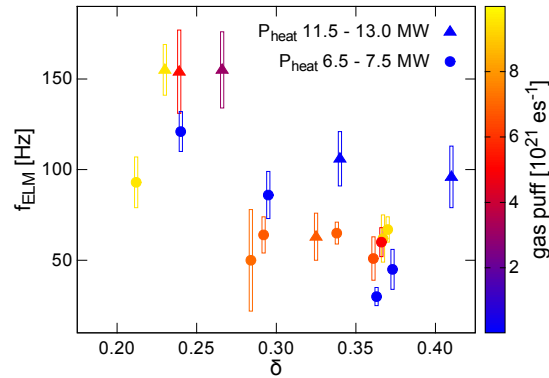


Figure 3: Dependency of f_{ELM} on δ : Only discharge intervals with a single f_{ELM} are considered and the vertical bars correspond to the statistical scattering of f_{ELM} . For high (triangles) and low (circles) P_{heat} , f_{ELM} decreases with δ . Additional scattering in the data might be due to the varying gas puff.

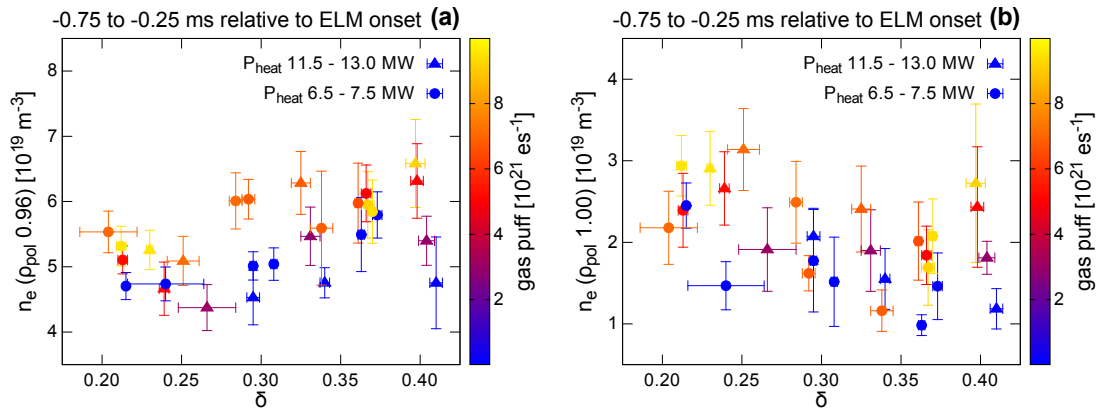


Figure 4: Impact of δ on the n_e pedestal: (a) the pedestal top n_e ($\rho_{\text{pol}} = 0.96$) and (b) the separatrix n_e ($\rho_{\text{pol}} = 1.00$). The pre-ELM pedestal top n_e increases with δ , whereas the separatrix n_e is reduced, indicating a steepening of the pedestal ∇n_e .

the individual ELM cycles. In comparison to the lower level P_{heat} (points) f_{ELM} increases at the higher level of P_{heat} (triangles), which is characteristic for type-I ELMs. For both levels of P_{heat} the anti-correlation of f_{ELM} and δ is observed. Scattering of the data could be related to the applied gas puff, which also impacts on f_{ELM} , however, no clear ordering in terms of gas puff can be seen (compare colour scale). In this comparison it is evident, that the impact of δ on f_{ELM} is much stronger than the one of the gas puff in the investigated parameter range.

Another general trend of previous studies is that n_e increases with δ [10, 38]. This is also reproduced in the conducted experiment at higher gas puff as shown in figure 4 a. Here, the pre-ELM pedestal top n_e , averaged between -0.75 ms and -0.25 ms relative to the ELM onset and measured at $\rho_{\text{pol}} = 0.96$, is plotted in dependency of δ . At

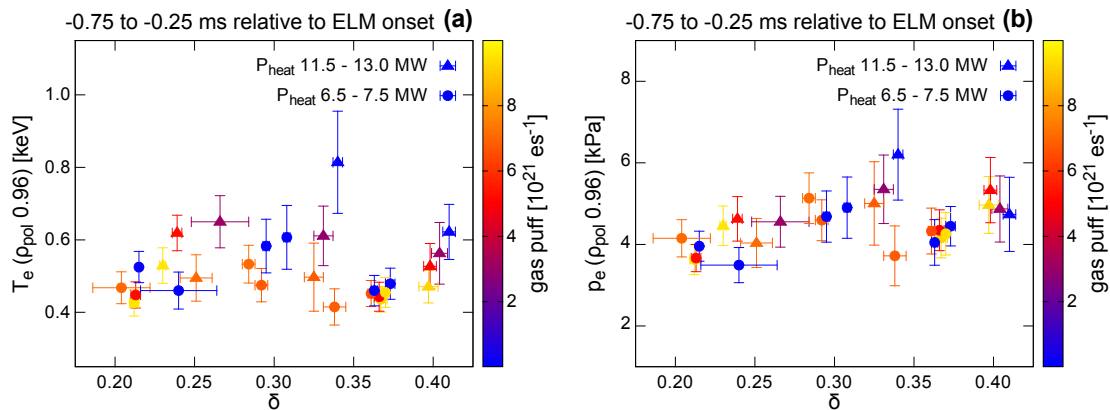


Figure 5: Pedestal temperature and pressure in dependence of δ : (a) the pedestal top T_e and (b) pedestal top p_e ($\rho_{\text{pol}} = 0.96$). The pedestal top T_e shows in average no clear trend for varying δ but an anti-correlation with the gas puff (colour scale) can be seen. In combination with the increasing pedestal top n_e the pedestal top p_e increases for higher δ . At fixed δ the pedestal top p_e is independent of the gas puff.

medium and high gas puff (orange and yellow markers) the trend is visible. Whereas, at low gas puff and high P_{heat} (blue and purple triangles) significantly lower pedestal top n_e are measured at very large δ (> 0.40) than expected from the trend at lower δ . No clear dependence of the pedestal top n_e on the two different P_{heat} (compare points and triangles) can be identified.

The other important contribution to the n_e pedestal structure is the separatrix n_e , which in a simplified approximation together with the pedestal top n_e sets the pedestal ∇n_e (at unchanged pedestal width). The separatrix n_e is presented in figure 4 b and exhibits, as indicated in previous studies [23], a strong dependency on the gas puff. Further, it decreases towards higher δ , especially at low gas puffs (blue and purple markers). Again the discharge intervals for $\delta > 0.40$ mark the exception to the trend, this time in the medium to high gas puff range. Since no obvious reason could be identified for this deviation, the intervals were not excluded from the following analysis. It remains unclear if the observed deviations for the few cases with $\delta > 0.40$ are actually related to δ or simply due to individual discharge conditions. In principle the separatrix n_e is not rigidly coupled to the gas puff, rather, it is impacted by the divertor and scrape-off layer (SOL) conditions, which themselves are dependent on the gas puff. It seems reasonable that when varying δ (at constant gas puff), the SOL conditions are affected and therefore, the separatrix n_e could be varied without a change of the gas puff.

The combination of the increasing pedestal top n_e with the pre-ELM T_e pedestal, forming the electron pressure (p_e) pedestal is presented in figure 5. In average the ‘pedestal top’ T_e , determined at $\rho_{\text{pol}} = 0.96$, does not show a clear dependence on δ and is in the region of 400 eV to 550 eV at low P_{heat} and between 500 eV and 650 eV at high P_{heat} (except for one outlier). The anti-correlation of the pedestal top T_e with the gas

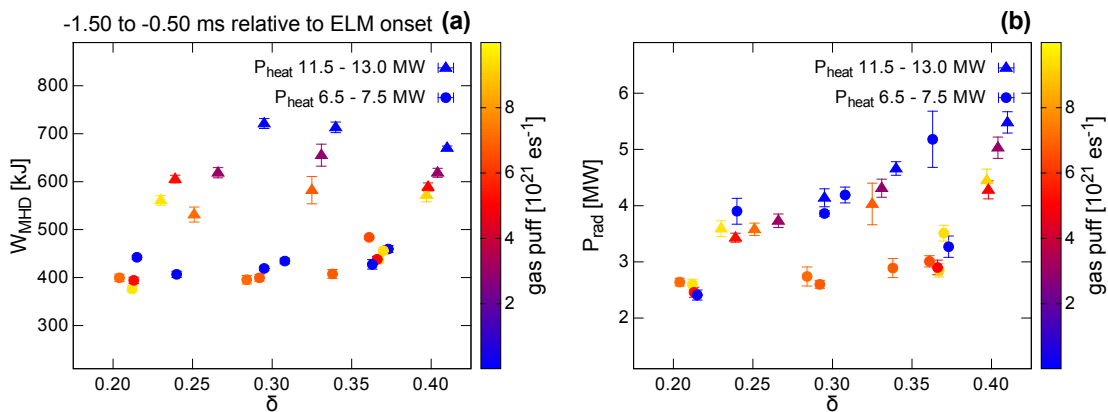


Figure 6: Global plasma properties in relation to δ : (a) W_{MHD} and (b) P_{rad} . As expected a separation of W_{MHD} for the different P_{heat} is observed. At high P_{heat} a clear degradation of W_{MHD} can be seen with increased gas puff (colour scale).

puff can be seen comparing the colour scaling. This can be related to the correlation of the gas puff and the pedestal top n_e , under the condition that the pedestal pressure profile is fixed for a given shape. The pedestal top pressure are compared in figure 5 b. Up to a δ of 0.34 an increase in the pedestal p_e might be seen, which would be consistent with previous results [8, 9]. However, over the full investigated range of δ no clear trend of p_e can be identified.

Further, the global W_{MHD} does not show any strong dependency on δ as presented in figure 6 a. The most dominant impact on W_{MHD} is given by P_{heat} , when comparing points and triangles. By applying approximately two times the P_{heat} , W_{MHD} is increased by roughly 50% in the covered δ range. At the higher level of P_{heat} a separation for the different applied gas puffs can be seen (colour scale). Here, the largest W_{MHD} is achieved at low gas puff. Previously, it has been reported that high gas puff negatively impact on global confinement in H-mode via degradation of the pedestal top pressure [39, 40]. However, this is not the case here, since the pedestal top p_e do not exhibit a clear connection to the gas puff.

The weak relation between pedestal top p_e and W_{MHD} (compare figures 5 b and 6 a) indicate that the pedestal and the core plasma are not rigidly coupled meaning that additional power losses occur from the core region at higher δ . A possible candidate for such a loss is radiation and especially with the tungsten (W) wall at ASDEX Upgrade when reducing the gas puff, impurity accumulation and enlarged radiation losses occur [41, 42]. For this reason the averaged P_{rad} are plotted in figure 6 b for the investigated cases. At constant P_{heat} a clear increase of P_{rad} towards higher δ is observed, which was also seen on JET [43]. Only at selected cases of low P_{heat} and low gas puff (blue circles), significantly higher P_{rad} occurs than at higher gas puffs, similar shape and similar P_{heat} . For these cases of enhanced P_{rad} also an increased W concentration is monitored and the estimated radiation increase due to W is consistent with the measured P_{rad} increase. The overall increase of P_{rad} with δ can not be associated to enhanced W concentrations. It is

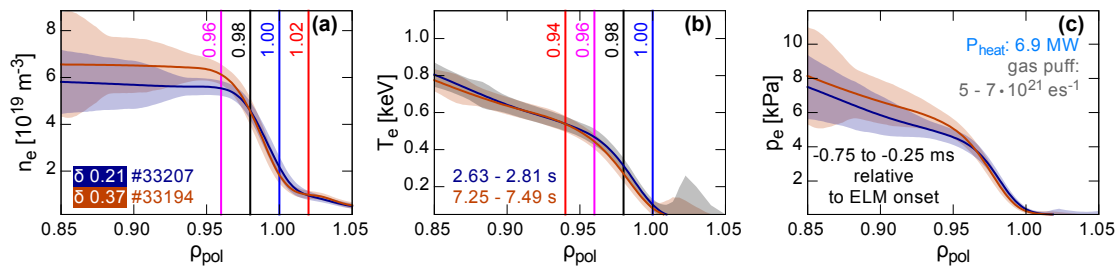


Figure 7: Comparison of the pre-ELM pedestal structure at low (0.21, dark blue) and high (0.37, orange) δ : (a) n_e , (b) T_e and (c) p_e profile. At similar gas puff and P_{heat} the n_e pedestal increases with δ , while T_e pedestal remains similar. In combination, a higher and steeper p_e pedestal is found at higher δ .

more likely that the increased radiation losses at high δ are caused by the combination of a larger plasma volume and a higher averaged plasma density.

The enhanced radiation can partially explain the weaker coupling between the pedestal top p_e and W_{MHD} , however, it can not be the reason for the anti-correlation of W_{MHD} and gas puff at high P_{heat} , since P_{rad} also tends to increase at reduced gas puff. Possible reasons that could explain the degradation of W_{MHD} with gas puff at high P_{heat} are outward shifted deposition profiles of the neutral beam heating power (P_{NBI}) (because higher gas puff increases the density) or changes in core transport and MHD behaviour.

4. Impact of triangularity on the pedestal

As already discussed in [section 3](#) the pedestal top n_e increases at higher δ . In the following the relation between pedestal structure and δ is analysed and compared to PB stability analysis.

4.1. Pedestal structure and stability

To investigate the impact of δ on the pedestal structure and stability, two different discharge intervals, performed at the lower level of P_{heat} , are investigated. These have a similar κ and the applied gas puff only varies between $5 \cdot 10^{21} \text{ es}^{-1}$ and $7 \cdot 10^{21} \text{ es}^{-1}$. The corresponding pre-ELM profiles of n_e , T_e and p_e are compared in [figure 7](#). The two different discharge intervals correspond to the low (0.21, dark blue) and high (0.37, orange) δ . The vertical lines correspond to different radial locations at which layers of n_e and T_e are tracked throughout the ELM cycle in [figure 9](#).

At high δ the pedestal top n_e increases (see [figure 7 a](#)) and the T_e profiles ([figure 7 b](#)) of the low and high δ case are similarly shaped. Maybe at high δ , the T_e profile is slightly shifted inwards, however, this is within the experimental uncertainties. The combined p_e profiles ([figure 7 c](#)) reflect the variation of n_e . At higher δ a higher p_e pedestal is observed, owing to the change of the n_e profile structures in combination with similar

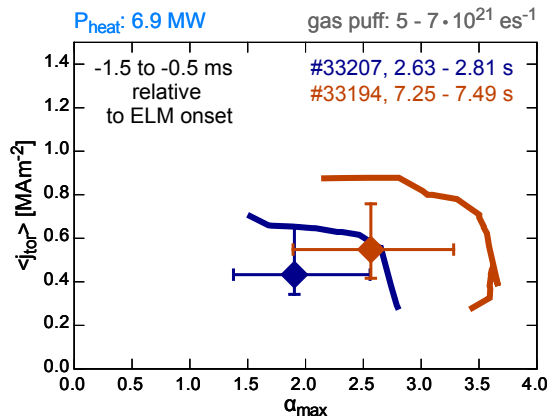


Figure 8: PB stability diagram for low (dark blue) and high (orange) δ : The stability boundary at high δ is shifted towards higher α_{max} and $\langle j_{\text{tor}} \rangle$. The steeper p_e gradient at high δ moves the operational point towards larger α_{max} .

T_e profiles. For the selected discharge intervals of this comparison, W_{MHD} at high δ is also higher according to the increased p_e pedestal.

As theoretically predicted, the steeper pressure gradients are achievable owing to the stabilising effect of higher δ [44, 45]. For the low and high δ pre-ELM equilibria, linear MHD stability analyses were performed using the stability workflow at ASDEX Upgrade [46]. Here, the ELM synchronised equilibria reconstructed with the IDE solver were used as it was introduced in section 2.2. The corresponding operational points and stability boundaries are represented in quantities of $\langle j_{\text{tor}} \rangle$ and maximum normalised pressure gradient (α_{max}). The j - α diagram for the low and high δ case are presented in figure 8. At higher δ the PB boundary is extended towards larger $\langle j_{\text{tor}} \rangle$ and α_{max} . This allows the operational point to shift towards larger α_{max} as also shown in figure 7c. The investigated pre-ELM pedestals are in agreement with PB theory. At high δ the distance between the operational point and the PB boundary increases in comparison to the low δ case, however, this is not a robust observation and usually within the uncertainties in the locations of the operational point and the PB boundary. The uncertainties of the operational point are represented by the standard deviations from the averaged pre-ELM equilibria.

4.2. Inter-ELM evolution

The comparison of the inter-ELM pedestal development for the different δ can give insight into the changes of f_{ELM} and, therefore, the temporal approach of the stability limit. Further, the profile dynamics in between ELMs can be used to test models of the pedestal, as recently done for JET discharges [47]. Figure 9 presents the dynamics of the pedestal n_e and T_e profiles throughout the ELM cycle, in discharge intervals with single f_{ELM} bands, at low (figures 9a and 9b) and high (figures 9c and 9d) δ . The n_e profiles are tracked on four radial locations from the SOL ($\rho_{\text{pol}} = 1.02$) towards the

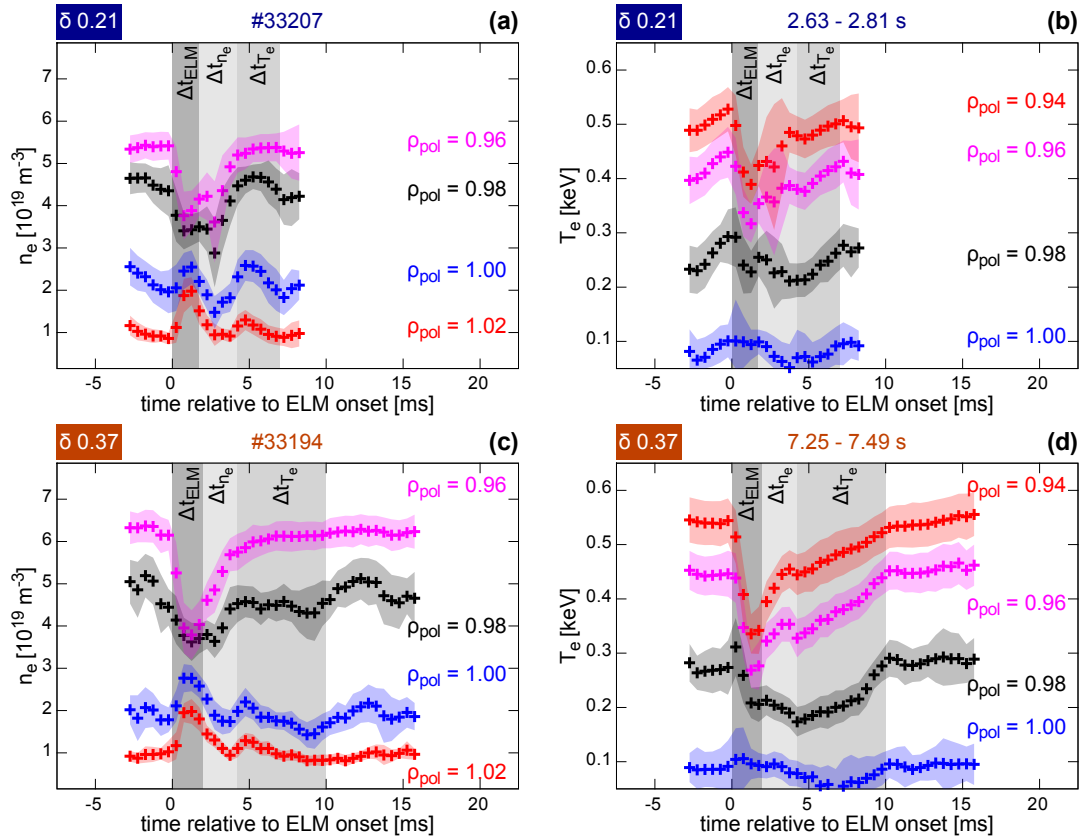


Figure 9: Inter-ELM pedestal evolution: (a,c) n_e and (b,d) T_e at certain radial positions across the pedestal (ρ_{pol}) for (a,b) low and (c,d) high δ . For all cases the n_e pedestal is re-established before the T_e pedestal and the sequence of recovery phases is similar. The T_e pedestal recovery phase (Δt_{T_e}) and the pre-ELM phase increase their duration with increasing δ , which corresponds to a decrease of f_{ELM} .

pedestal top ($\rho_{\text{pol}} = 0.96$) and the T_e profiles are tracked in the confined plasma region from $\rho_{\text{pol}} = 1.00$ to $\rho_{\text{pol}} = 0.94$ (see vertical lines in figure 7).

At all δ the sequence of pedestal recovery phases is similar to the one typical for ASDEX Upgrade, which was previously observed in experiments with a pedestal collisionality variation [28] and in isotope comparison studies [48]. After the ELM crash with duration Δt_{ELM} , the n_e pedestal recovers first (Δt_{n_e}), followed by the recovery of the T_e pedestal (Δt_{T_e}) and the pre-ELM phase in which maximum electron pressure gradient ($\max(-\nabla p_e)$) is clamped [24]. In this phase also high frequency magnetic fluctuations set in, which are associated with an instability with toroidal mode numbers (n) in the region of 10 [49].

The inter-ELM recovery rates can give information on the particle and heat fluxes towards the pedestal. For the n_e pedestal the recovery times are too short to perform a quantitative comparison of electron density recovery rate ($\partial n_e / \partial t$) for the different δ cases. Nevertheless, it is remarkable that the higher pedestal top n_e at high δ (see figure 4 a) is already established in this early phase of the ELM cycle. This suggest that

the n_e pedestal is set first, while the pedestal top T_e is then determined by the maximum achievable pedestal p_e , which is PB limited. The duration of the T_e pedestal recovery phase, Δt_{T_e} , prolongs at higher δ . Nevertheless, the T_e pedestal (positions $\rho_{\text{pol}} = 0.96$ and $\rho_{\text{pol}} = 0.94$) recovers at similar electron temperature recovery rate ($\partial T_e / \partial t$) during Δt_{T_e} for both δ cases, which suggests similar power fluxes to the pedestal. The longer Δt_{T_e} in the high δ case is caused by higher W_{MHD} losses per ELM, which leads to a larger drop of the T_e pedestal.

Most prominently, the duration of the pre-ELM phase with clamped pedestal pressure gradient almost doubles from low to high δ . This is the largest contribution to the observed lower f_{ELM} at higher δ and indicates that at high δ especially this period is more stable and therefore, prolonged.

In summary, the higher pedestal top n_e at high δ is found to be established immediately after the ELM crash in the n_e pedestal recovery phase. The phase of the T_e recovery in the ELM cycle is longer at higher δ and especially the pre-ELM phase with clamped electron pressure gradient (∇p_e). For the T_e pedestal recovery phase this prolongation is caused by higher ELM losses. The extension of the pre-ELM phase might be linked either to enhanced particle and heat fluxes across the pedestal than at low δ , which saturate the stable pedestal structure longer and more reliably. Or at high δ , the pedestal is more stable due to shaping in the sense that small pressure perturbations, which would already cause ELM crashes at low δ , are stabilised and the pre-ELM phase is therefore extended.

5. ELM frequency bands

At all investigated δ , discharge phases with two f_{ELM} bands were observed. Their appearance cannot be related to certain parameter combinations of P_{heat} and gas puff. For each δ it is rather set by an individual parameter combination. At high δ , it is more likely that the two f_{ELM} bands appear at the higher level of P_{heat} .

5.1. Observation of ‘slow’ and ‘fast’ ELM cycles

The two f_{ELM} bands are associated to ELM cycles of different duration. Therefore, according to the observation, it is discriminated between ‘fast’ and ‘slow’ ELM cycles, which are related to the high and low f_{ELM} band. Exemplary time traces of discharge intervals, which contain two f_{ELM} bands, are displayed in [figure 10 a](#) at low δ and in [figure 10 b](#) at high δ . Here, W_{MHD} , pedestal top p_e (tracked at $\rho_{\text{pol}} = 0.96$), f_{ELM} and inner divertor current are shown. The burst in the divertor current is associated to the ELM crash, f_{ELM} is determined by the inversion of the time period from an ELM crash until the following one. A similar P_{heat} is applied in both discharge intervals. In agreement with the data presented in [figure 3](#), both f_{ELM} bands have a higher frequency at low δ . The frequencies, which discriminate the f_{ELM} bands, are indicated by the horizontal, red dashed lines. The higher frequency band, the ‘fast’ ELM cycles, have blue

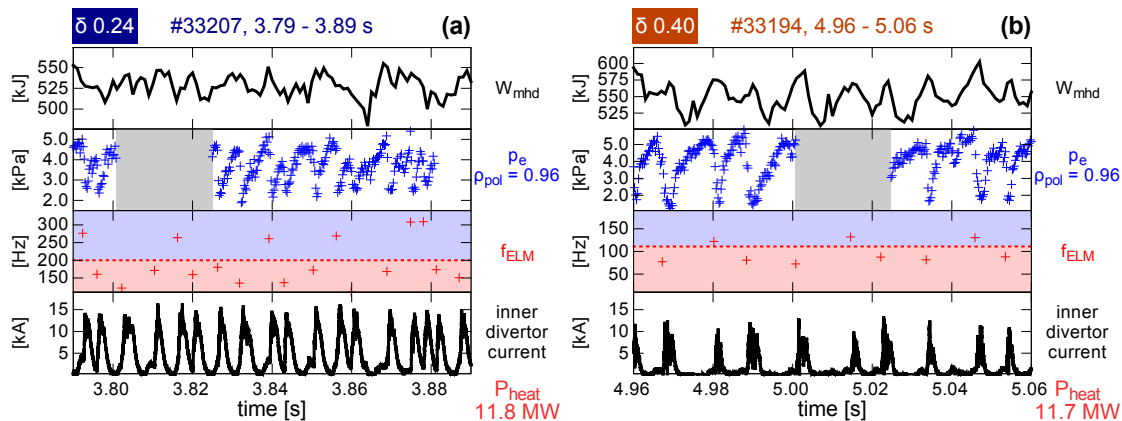


Figure 10: Discharge intervals with two f_{ELM} bands: Time traces of W_{MHD} , pedestal top p_e , f_{ELM} and inner divertor current at (a) low and (b) high δ . The threshold in f_{ELM} discriminating between ‘fast’ (blue background) and ‘slow’ (red background) ELM cycles is indicated by the red dashed line. Both types of ELM cycles appear irregularly.

discharge	δ	P_{heat} [MW]	ELM cycle	f_{ELM} [Hz]	Δt_{n_e} [ms]	Δt_{T_e} [ms]
#33 207	0.21	6.9	single f_{ELM}	93	2.5	2.5
#33 207	0.24	11.8	fast	286		
#33 207	0.24	11.8	slow	148		
#33 194	0.37	6.9	single f_{ELM}	60	2.5	7.5
#33 194	0.40	11.7	fast	134	2.5	3.0
#33 194	0.40	11.7	slow	85	2.5	3.5

Table 1: ELM cycle types and characteristic pedestal recovery timescales: After a fast, initial recovery phase n_e pedestal (Δt_{n_e}), which duration does not show any dependency on P_{heat} or δ , the T_e pedestal builds up (Δt_{T_e}). When two f_{ELM} bands are observed the ‘slow’ ELM cycle relates to the ELM cycle at a single f_{ELM} .

background, while the lower f_{ELM} band, the ‘slow’ ELM cycles have a red background.

In both presented cases of δ , ‘slow’ and ‘fast’ ELM cycles appear irregularly, i.e. there is now systematic relation between them. At low δ it can be seen that the ‘fast’ ELM cycle ends at reduced pedestal top p_e in comparison to the slow ELM cycle. A summary of the recovery timescales of the analysed discharge intervals is presented in [table 1](#) and compared to the interval with a single f_{ELM} . The Δt_{n_e} does not show any dependency on P_{heat} or δ , while at higher δ , Δt_{T_e} becomes longer, because of the larger ELM loss. When comparing f_{ELM} of the ‘fast’ and ‘slow’ ELM cycle to the discharge intervals with a single f_{ELM} , the ‘slow’ ELM cycle relates to the ELM cycle observed at a single f_{ELM} , considering that P_{heat} is higher in the cases with two f_{ELM} bands. This is further supported by the comparison of the pedestal recovery dynamics of the ‘fast’ and ‘slow’ ELM cycles at low and high δ . These are presented in [section 5.2](#) and the detailed pre-ELM pedestal structure of both kinds of ELM cycles is analysed in [section 5.3](#).

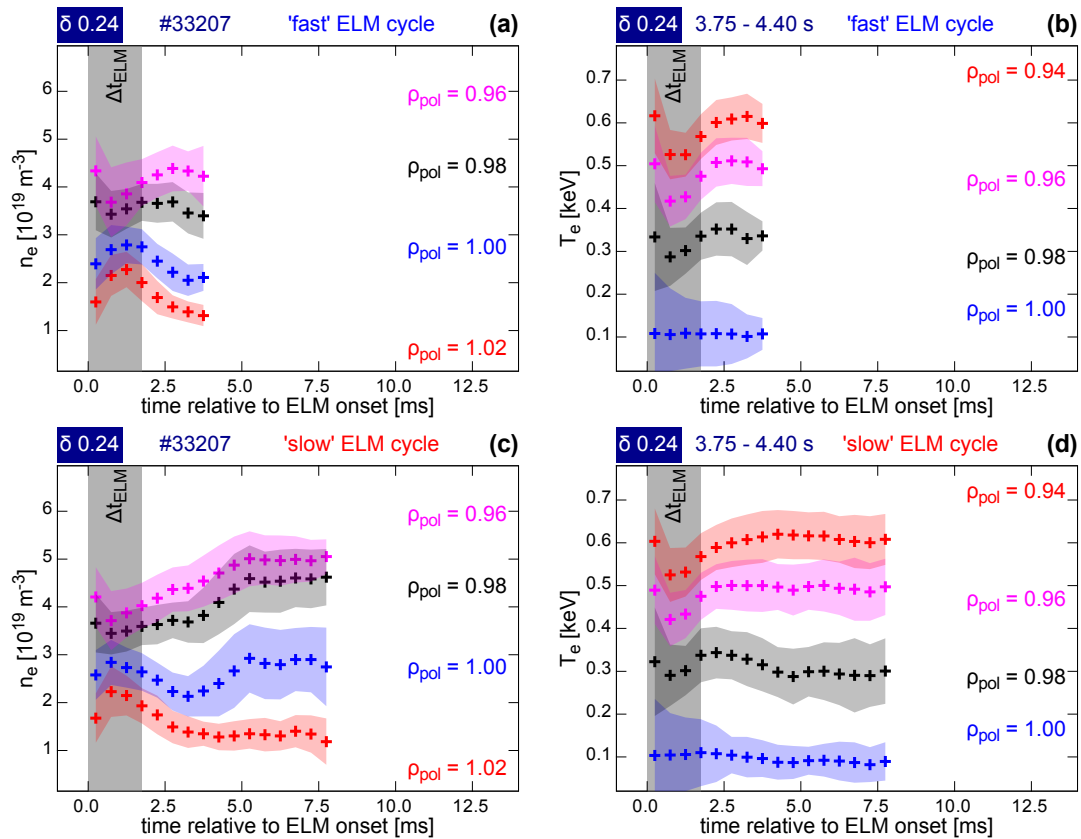


Figure 11: Pedestal evolution at low δ for the two f_{ELM} bands: (a,c) n_e and (b,d) T_e at several radial positions (ρ_{pol}) for the (a,b) ‘fast’ and (c,d) ‘slow’ ELM cycles. Roughly 2.0 ms after the end of the ELM crash (Δt_{ELM}) the ‘fast’ ELM cycle is ended by another ELM crash.

5.2. Pedestal development of ‘slow’ and ‘fast’ ELM cycles

In general, the ‘slow’ ELM cycles show similar recovery behaviour as the ELM cycles at single f_{ELM} (see section 4.2). This means that the pedestal evolves through the typical sequence of recovery phases of n_e , T_e and the pre-ELM clamping of the pressure gradient. At $f_{\text{ELM}} > 200$ Hz the inter-ELM recovery phases become so short, that a clear separation becomes challenging. In the low δ case the higher f_{ELM} is between 250 Hz and 300 Hz. In combination with the duration of the ELM crash (Δt_{ELM}) of approximately 1.5 ms, this gives the pedestal only a short time to recover in a ‘fast’ ELM cycle. In figure 11 the ELM synchronised evolutions of the n_e and T_e pedestal are presented for ‘fast’ (figures 11 a and 11 b) and ‘slow’ (figures 11 c and 11 d) ELM cycles. The n_e and T_e profiles are tracked at equal locations as in figure 9. In comparison to the ‘slow’ ELM cycle, the ‘fast’ ELM cycle immediately ends after a short recovery phase of approximately 2.0 ms. In this case it is not possible to clearly identify the different pedestal recovery phases of n_e and T_e because of the uncertainties of the data (shaded areas).

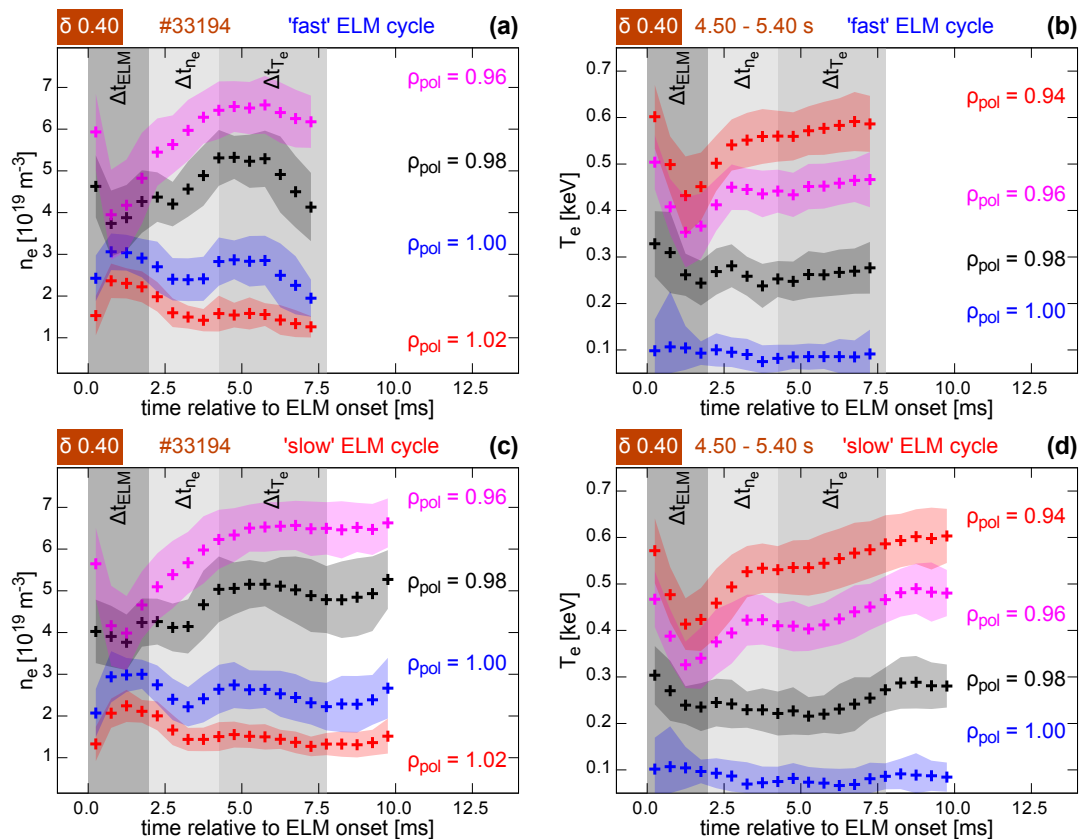


Figure 12: Pedestal evolution at high δ for the two f_{ELM} bands: (a,c) n_e and (b,d) T_e at several radial positions (ρ_{pol}) for the (a,b) ‘fast’ and (c,d) ‘slow’ ELM cycles. At the end of the ‘fast’ ELM cycle, which appears close to the end of the T_e pedestal recovery phase (Δt_{T_e}), a reduction of the n_e from the separatrix inwards is observed, which is not that pronounced in this phase of the ‘slow’ ELM cycle.

At higher δ , the limitation in temporal resolution of the inter-ELM phases relaxes since f_{ELM} is lower. In figure 12 the pedestal development of the high δ case is shown in a similar setup as in figure 11. Here, the pedestal recovery phases are well resolved and indicated by grey shaded areas. The ‘fast’ ELM cycle ends towards the end of the T_e pedestal recovery phase and therefore, the pre-ELM phase with clamped pressure gradients is missing. In both types of ELM cycles the n_e and T_e pedestal recovery behaves similar up to the point when the following ELM crash appears. Towards the end of the ‘fast’ ELM cycle a reduction of the n_e from the separatrix inwards is observed, which corresponds to an inward shift of the n_e profile. This profile movement is not that pronounced in the ‘slow’ ELM cycle.

The appearance of two distinct f_{ELM} bands suggests that during the inter-ELM pedestal development, possibly more pedestal configurations, i.e. pedestal structures combined with core conditions, could become unstable, leading to an ELM crash. Changes in W_{MHD} impact on the PB stability via the Shafranov shift [50, 51, 52, 53, 54]. To investigate the global W_{MHD} dynamics in the ELM cycle, the change of W_{MHD} relative

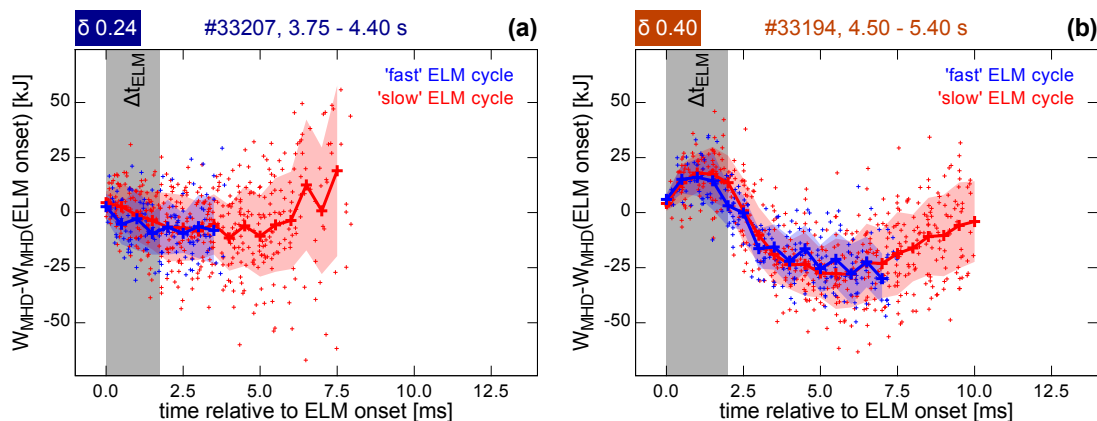


Figure 13: Evolution of W_{MHD} throughout the ELM cycle: The change of W_{MHD} relative to W_{MHD} at the ELM onset for ‘fast’ (blue) and ‘slow’ (red) ELM cycle at (a) low and at (b) high δ . The ‘fast’ ELM cycle ends before the W_{MHD} increases, which then provides a stabilising effect on the pedestal and extends the ‘slow’ ELM cycle.

to the W_{MHD} at the ELM onset for ‘fast’ and ‘slow’ ELM cycle are presented in figure 13. The representation of the ‘relative W_{MHD} ’ was chosen to emphasise the dynamics of W_{MHD} and exclude slower trends of W_{MHD} , which evolve on longer time scales than the ELM cycle and therefore, would lead to additional scatter in the data. At high δ , W_{MHD} increases in the period of the ELM crash (Δt_{ELM}), which is not related to any physical reason but rather demonstrates the challenge to reconstruct a plasma equilibrium during a fast, transient phase like an ELM crash. In the inter-ELM period, W_{MHD} of both types of ELM cycles evolve similarly at low as well as at high δ . It appears that W_{MHD} in the ‘slow’ ELM cycle starts to increase exactly at the point when the ‘fast’ ELM cycle ends. This underlines that the increasing W_{MHD} helps to stabilise the pedestal and for this reason extends the ‘slow’ ELM cycle. Therefore, it can be concluded, that at the end of the ‘fast’ ELM cycle a critical point close to the pedestal stability limit is reached, which can be overcome, when the global W_{MHD} increases, providing a stabilising effect on the pedestal. To investigate the pedestal stability at the end of both ELM cycles, the pedestal structure is analysed.

5.3. Pre-ELM pedestal conditions and stability

Figure 14 compares the pedestal n_e , T_e as well as resulting p_e profiles for ‘fast’ (blue) and ‘slow’ (red) ELM cycle. The profiles, represented with solid lines, are averaged in the time interval between -0.75 ms and -0.25 ms relative to the onset of the following ELM crash, i.e. at the end of the corresponding ELM cycle. The dashed lines indicate the profiles in the ‘slow’ ELM cycle, in the time interval, when typically the ‘fast’ ELM cycle ends. The corresponding time intervals are between 3.25 ms and 3.75 ms relative to the previous ELM onset at low δ and between 6.75 ms and 7.25 ms relative to the previous ELM onset at high δ . For both cases of δ , the T_e profiles (figures 14b and 14e) are

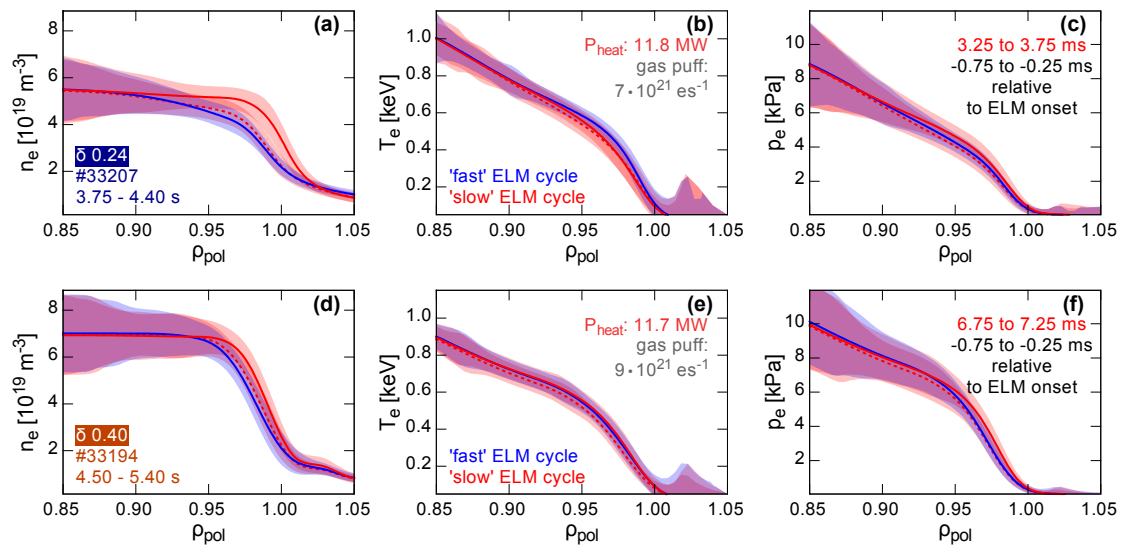


Figure 14: Pre-ELM pedestal profiles at the end of the different ELM cycles: (a,d) n_e , (b,e) T_e and (c,f) p_e for the (a,b,c) low and (d,e,f) high δ cases. The red dashed lines correspond to the profiles in the ‘slow’ ELM cycle, at the relative time interval relative to the ELM onset, when the ‘fast’ ELM cycle ends. At the end of the ‘fast’ ELM cycle the n_e profile (solid blue line) is located further inwards for both δ in comparison to the end of the ‘slow’ ELM cycle (solid red line), resulting in a reduced ∇p_e .

similar at the end of the ‘fast’ and ‘slow’ ELM cycle. The largest difference is observed in the n_e profiles (figures 14 a and 14 d). The pre-ELM n_e profile of the ‘fast’ ELM cycle is located further inwards and also ∇n_e is shallower. In the p_e profiles this is reflected by a reduced ∇p_e . The n_e profiles of the ‘slow’ ELM cycle (red dashed lines) at similar time as the ‘fast’ ELM cycle ends, are shifted slightly outwards in comparison to the pre-ELM profiles of the ‘fast’ ELM cycle (blue solid line) and the T_e profiles are located slightly inwards such that the p_e profiles almost overlay. Although, these shifts occur systematically at low and high δ , they are within the experimental uncertainties.

Stability analyses were performed with the corresponding equilibria at the end of the ‘fast’ and ‘slow’ ELM cycles. In figure 15 the corresponding j- α diagrams are presented. At both investigated δ , the operational points at the end of the ‘fast’ ELM cycles (blue) are located at lower α_{\max} as a result of the inward located n_e profile. The PB stability boundaries are similarly shifted as the operational points. Further, the operational points are close to the PB boundary for both types of ELM cycles, which suggests that it is likely for the pedestal to become unstable.

All in all, the pre-ELM pedestals at the end of the ‘fast’ and ‘slow’ ELM cycles agree with PB stability. This can be interpreted such that the pedestal in between ELMs evolves through configurations which become more likely unstable. Therefore, the occurrence of two f_{ELM} bands is linked to the inter-ELM pedestal stability. The underlying mechanism that leads to this variation of the pedestal stability throughout

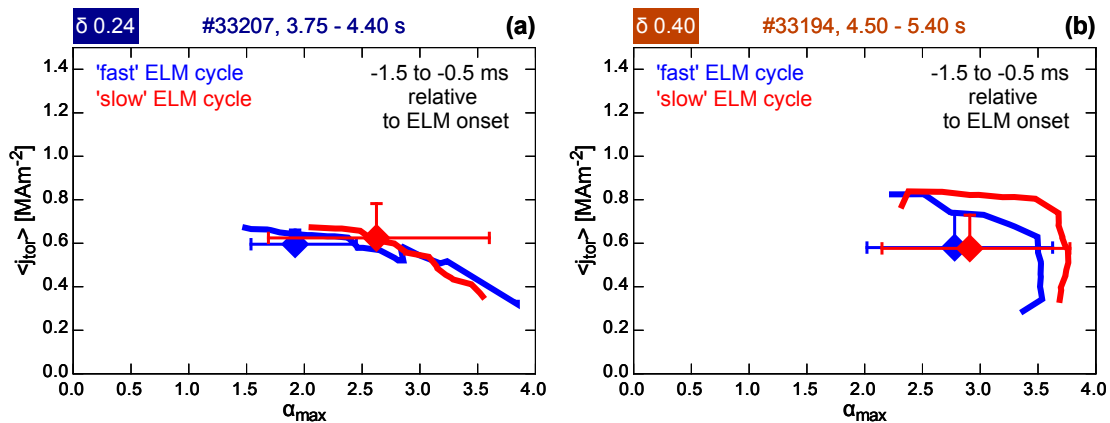


Figure 15: Pre-ELM stability at the end of the ‘fast’ and ‘slow’ ELM cycle: (a) at low and (b) high δ . The operational points are located at higher α_{max} at the end of the ‘slow’ ELM cycle for both δ and the PB boundary is shifted correspondingly.

the ELM cycle is the impact of W_{MHD} . Since the inter-ELM evolution of W_{MHD} is not rigidly coupled to the evolution of the pedestal pressure, there is some degree of freedom which allows the formation of two separated f_{ELM} bands. The ‘fast’ ELM cycle ends, i.e. an ELM crash appears, at a point of relatively low W_{MHD} . When this point is overcome in the slow ELM cycle, W_{MHD} , respectively the Shafranov shift increases, stabilising the pedestal and allowing for its further evolution.

6. Discussion of the main observations and conclusions

The presented results of this work are consistent with previous studies on the impact of δ on the pedestal. It extends these results towards a deeper analysis of the inter-ELM pedestal evolution. A similar sequence of the pedestal recovery phases is identified for all δ . First, the n_e pedestal is immediately established after the ELM crash, then the T_e pedestal builds up and after that a period with clamped pressure gradient appears. The decrease of f_{ELM} with increasing δ is caused by prolongation of the last two inter-ELM pedestal recovery phases. For the T_e pedestal recovery phase, the prolongation is related to the higher ELM loss, since at a constant recovery rate a larger drop in T_e needs longer to recover. Further, the pre-ELM phase with clamped pressure gradient is significantly extended at high δ . This could be either caused by an increased particle and heat flux across the edge or by the beneficial effect of δ on the edge stability.

Higher δ enhances the pedestal top n_e although W_{MHD} is not strongly affected in the presented experiments, which might be partially related to increased radiation. The pre-ELM pedestal structure agrees with PB theory and at higher δ the PB stability boundary is shifted towards larger $\langle j_{\text{tor}} \rangle$ and α_{max} allowing steeper pedestal pressure profiles and higher pedestal top pressures. The enhanced pedestal top n_e at higher δ is already established during the initial recovery phase of the n_e pedestal, immediately after an ELM crash. This indicates that the n_e pedestal structure has an important impact

on the p_e profile, which is set by the PB stability, and the T_e pedestal contributes in between those ‘boundaries’ due to its slower recovery timescale. However, this simple picture does not imply that the temperature has a minor role in forming the pedestal. Throughout this work the evolution of the electron contribution to the pedestal was investigated, however, the ion temperature (T_i) can be decoupled from T_e . Especially, the T_i pedestal exhibits a faster evolution throughout the ELM cycle, which is coupled to the recovery timescale of the n_e pedestal and therefore, faster than the recovery of the T_e pedestal [55]. This becomes relevant, when the temporal dynamics of the PB stability throughout the ELM cycle is analysed since the total pressure as well as the edge current can be affected. With respect to the presented work, the different dynamics of the T_i play a minor role, since the stability was only analysed for a single time slice relative to the ELM onset. T_i measurements with low temporal resolution were used to provide information on the ion contribution to the total pressure, which is sufficient for the ‘static’ stability analysis. To resolve the full dynamics of PB stability throughout the ELM cycle, the T_i profile dynamics need to be taken into account. For this reason, future studies using measurements with high temporally resolved T_i profiles will need to address the main ion contribution to the pressure in the n_e pedestal recovery phase for varying δ .

The occurrence of two f_{ELM} bands has been shown to be connected to the inter-ELM pedestal stability. Both types of ELM cycles evolve through a similar pedestal development. It is important to notice, that the simple picture of a temporally localised stability boundary in j - α space is incomplete. In addition to the operational point of the plasma equilibrium, which moves according to the evolution of α_{max} and $\langle j_{\text{tor}} \rangle$ [56], also the stability boundary changes correspondingly [57]. This can be explained by the evolution of the global plasma parameters such as W_{MHD} . Since the evolution of W_{MHD} is not rigidly coupled to the pedestal pressure, phases in the ELM cycle can appear where W_{MHD} is too low to stabilise the pedestal pressure gradient. For this reason, it is possible that, throughout the inter-ELM evolution of the pedestal, certain pedestal configurations become more likely unstable.

At the end of a ‘fast’ ELM cycle the n_e profile is located radially inwards relative to the n_e profile at the end of a ‘slow’ ELM cycle. At first glance, this might oppose previous studies, where radially inwards shifted n_e profiles tend to lead to more stable conditions [16, 58]. But in the presented cases the shift appears during the dynamics of an ELM cycle, at a reduced W_{MHD} in comparison to the end of the ‘slow’ ELM cycle i.e. the global plasma conditions at the end of ‘fast’ and ‘slow’ ELM cycle differ too. The performed PB stability calculations point into a similar direction. Disregarding the large experimental uncertainties, the operational point and stability boundary tend to be located at lower j - α at the end of the ‘fast’ ELM cycle. Under such a combination of conditions, which are close to the PB stability limit, ELM crashes are more likely to occur. However, when the unstable situation, which appears at the end of the ‘fast’ ELM cycle, can be overcome, W_{MHD} can evolve further up to the point, where another PB unstable configuration is reached, which marks the end of the ‘slow’ ELM cycle.

In summary, the key results of the presented work point out that the sequence of inter-ELM pedestal recovery is not affected by plasma shaping for the examined range. The pedestal top density, which exhibits a dependency on the shaping, is already established in the initial pedestal recovery phase. The appearance of two distinct f_{ELM} bands is associated to the not rigidly coupled evolution of the pedestal and the global plasma. To fully understand and model the interaction of core and edge dynamics, especially, the different timescales of their evolution as well as their coupling need to be considered.

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