

1 Reconstruction of the large multi-aperture beam via 2 IR calorimetry technique and beam emission 3 spectroscopy at the ELISE test facility

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8 **Abstract.** The ELISE test facility with its half ITER size ion source is an important
9 intermediate step in the European development roadmap toward the ITER neutral
10 beam injection system. Of particular interest is the beam characterization at ELISE
11 in terms of homogeneity and divergence. The two main beam diagnostic systems
12 are beam emission spectroscopy (BES), providing beam intensity and divergence and
13 infrared (IR) calorimetry applied to the surface of a diagnostic calorimeter, which
14 provides a spatially resolved 2D map of the beam power density. Beam parameters
15 such as width, intensity, position and accelerated current are retrieved by a fitting
16 routine which is validated using synthetic beam profiles, thus demonstrating that the
17 beam parameters are correctly reproduced. By comparing results of BES and IR
18 calorimetry for several thousand pulses, it is demonstrated that the beam width is, to
19 a large extent, determined by the beam divergence. BES and IR calorimetry are then
20 combined to reconstruct the beam profile and this is the basis to investigate procedures
21 for improving the beam quality in terms of power density homogeneity.

22 1. Introduction

23 The future international fusion experiment ITER ("The Way" in Latin) will be equipped
24 with two 1 MeV D₀ or 870 keV H₀ heating neutral beam injectors (HNBI) for a total
25 power of 33.3 MW and with one 100 keV diagnostic neutral beam (DNB) [1]. In
26 these systems, negative hydrogen or deuterium ions are extracted from a large source
27 (2 m × 1 m) and accelerated in a multi-grid, multi-aperture electrostatic accelerator.
28 The large (about 1.6 m height and 0.8 m width) negative ion beam is then neutralized
29 in a gas neutralizer and the residual charged particles are electrostatically removed
30 from the beamline. To ensure transmission through a 1.08 m high, 0.55 m wide port
31 placed at about 26 m distance from the ion source, the grids are tilted, thus focusing
32 the beam [1][2]. The ITER requirements for the NBI system in terms of extracted
33 current density are 286 A/m² for D⁻ (329 A/m² for H⁻), with an electron-to-ion ratio

1 lower than one, to minimize the power load deposition on beamline components. Source
 2 pressure is restricted to 0.3 Pa to minimize the stripping losses, namely loss of negative
 3 ions neutralized before being fully accelerated, to less than 30%. The pulse length is up
 4 to one hour in deuterium (1000 s in hydrogen) [1][3]. The source is foreseen to deliver
 5 a total accelerated current density of 200 A/m² for D⁻ (230 A/m² for H⁻) before the
 6 neutralization stage. Strict requirements on the beam properties have to be fulfilled
 7 to maximize the beam transmission through the beamline and to minimize the power
 8 loads on the beamline components: the core beamlet divergence, i.e. the width of the
 9 angular velocity distribution of the negative ions, must be less than 7 mrad with a power
 10 homogeneity among beamlets better than 90 % [1][4].

11 In the framework of the European roadmap toward the ITER neutral beam injection
 12 system [5], the ELISE (Extraction from a Large Ion source Experiment) test facility
 13 [6][7] is a fundamental step towards the full size NBI systems. The ELISE ion source
 14 has half of the height and the same width of the ITER NBI source. The testbed aims
 15 to demonstrate the simultaneous achievement of the ITER requirements for the ion
 16 source [3]. The ELISE extraction and acceleration system is made of three grids: the
 17 plasma grid (PG) which directly faces the plasma, the extraction grid (EG), and the
 18 grounded grid (GG). The grids are flat and the apertures are aligned, thus no beam
 19 focusing or beamlet steering is applied. A horizontal magnetic field, called filter field, is
 20 created by a current I_{PG} flowing vertically through the PG. For $I_{PG} = 1$ kA, the filter field
 21 strength is 0.95 mT at 2 cm axial distance from the PG. The filter field is employed to
 22 reduce the electron temperature and density and, combined with pressure gradients and
 23 electric fields, it results in vertical plasma drifts which affect the vertical profile of the
 24 plasma density and of the plasma potential [8]. The filter field is present also within and
 25 downstream of the grid system, thus affecting the beam particle trajectories. Permanent
 26 magnets, called deflection magnets, are embedded in the EG to dump the co-extracted
 27 electrons on the grid itself. The trajectories of the negative ions are also affected by the
 28 deflection magnets. Beamlet compensation, as foreseen for the ITER grid system [1], is
 29 not applied at ELISE. The extraction system is based on the SINGAP design [9], with
 30 a modified design for the grids to maximize the extracted negative ion current density
 31 for an extraction voltage of about 10 kV [10] and to adapt the gap between EG and GG
 32 to the total high voltage available, i.e. up to 60 kV.

33 For a D⁻ extracted current density of 286 A/m² (ITER target), the beamlet divergence,
 34 defined as half width at one e-folding of the angular particle distribution, predicted at
 35 ELISE by the IBSIMU code [11][12] is 14.4 mrad (19.5 mrad for an H⁻ extracted current
 36 density of 329 A/m²). The simulations are performed with a perpendicular particle
 37 velocity of 1 eV [13], 10 kV of extraction voltage, and 50 kV of acceleration voltage.

38 The arrangement of the 640 circular apertures (aperture diameter of 14 mm, total
 39 extraction area of 985 cm²) on the PG is organized in 8 rectangular beamlet groups
 40 of 16 × 5 apertures each [6]. The beamlet group structure is similar to that of the ITER
 41 extraction system. The grids are vertically divided into two segments, each one hosting
 42 four beamlet groups (see figure 1 or 6(a)). The beam portions created by these grid

1 segments are called top and bottom beam segments, respectively. The beam is stopped
 2 by a diagnostic calorimeter placed at 3.5 m distance from the GG [14]. The two main
 3 beam diagnostics used to study the beam divergence and power density profile are beam
 4 emission spectroscopy (BES) and infra-red (IR) calorimetry applied to the diagnostic
 5 calorimeter.

6 The characterization of the beam is of high relevance to determine and study the
 7 homogeneity of the beam power density and this will serve as basis for developing
 8 procedures and recipes to improve the beam homogeneity. In this work BES and IR
 9 calorimetry are described and the data analysis is discussed. For IR calorimetry the
 10 calibration procedure, which allows the retrieval of the absolute beam power deposited,
 11 is introduced and described for the first time. BES and IR calorimetry are crosschecked
 12 and then combined to reconstruct the beam properties.

13 2. Overview of the beam diagnostics

14 In ELISE, the total extracted negative ion current I_{ex} is measured electrically and
 15 the total accelerated current deposited on the diagnostic calorimeter is measured by
 16 IR calorimetry and water calorimetry. The following beam diagnostics are installed
 17 downstream of the grid system, as shown in figure 1: the tungsten wire (W-wires)
 18 calorimeter, the BES diagnostics and the diagnostic calorimeter [15]. The tungsten wire
 19 calorimeter consists of a frame of tungsten wires drawn vertically and horizontally in a
 20 plane perpendicular to the beam direction at 1.8 m axial distance from the GG [15]. This
 21 diagnostic is not absolutely calibrated, thus providing only qualitative monitoring images
 22 of the beam power deposited onto the wires. At about 2.7 m downstream of the GG,
 23 20 BES lines of sight (LOS) [15] measure the beam, providing local but line-integrated
 24 measurements of beam divergence, intensity and stripping losses. The diagnostic is
 25 based on Doppler-shifted H_{α} emission originating from collisions between beam particles
 26 and background gas [8]. The beam is stopped at 3.5 m from the grids by a diagnostic
 27 calorimeter [15] designed to perform calorimetric and thermometric measurements of
 28 the deposited beam power.

29 Since the beam is measured by BES and by the diagnostic calorimeter at large distances
 30 from the GG, single beamlet measurements are not possible due to the large beamlet
 31 overlap occurring at such axial distances. The beam divergence can be considered a fixed
 32 value once space charge compensation [16] occurs, thus preventing the sudden increase
 33 of beamlet divergence due to electrostatic repulsion of the beam particles. Space charge
 34 compensation depends on the background gas density (about 0.01-0.05 Pa at ELISE)
 35 and on the beamlet current density. At ELISE, in case of good beam optics, the beam
 36 divergence measured by BES diagnostics is around 1.5 to 2 degrees (26 to 35 mrad). The
 37 measured value is higher than the predicted one, i.e. between 14.4 and 19.5 mrad, because
 38 the overlap of multiple rows of beamlets, each one horizontally deflected alternately left
 39 or right by the deflection magnets, causes an artificial broadening of the line-integrated
 40 Doppler peak seen by the horizontal LOS. The effect of the beamlet overlapping on

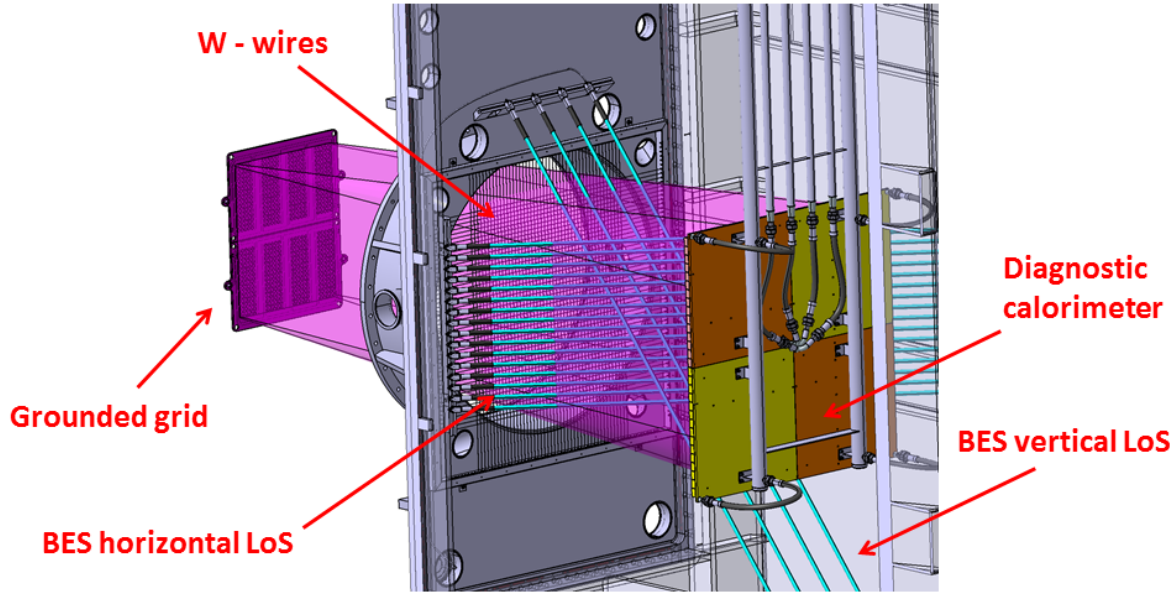
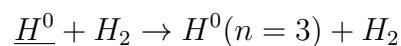
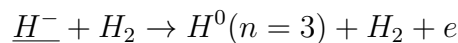


Figure 1: Overview of the beam diagnostic systems at ELISE [15]: the W-wire calorimeter, the two arrays of lines of sight (LoS) of the BES diagnostic and the diagnostic calorimeter on the right. On the leftmost side of the figure, the downstream side of the grounded grid is shown.

1 the broadening of Doppler peak is shown in reference [17] calculated for the Batman
 2 Upgrade test facility [18][19]. The beam position is influenced by the filter field which is
 3 still considerably intense downstream of the GG, e.g. for $I_{PG}=1$ kA at 0.5 m downstream
 4 of the PG the FF is 0.15 mT, thus resulting in a net Lorentz force displacing the beam
 5 downwards in the present configuration. The displacement, being usually between 2 cm
 6 and 10 cm measured at the calorimeter, depends on the strength of the filter field, on
 7 the total high voltage and on the used hydrogen isotope. The beam power profile mimic
 8 the arrangement of the beamlet groups on the GG: the beam is vertically divided in
 9 two segments which usually differ in intensity and width. For each beam segment, the
 10 four beamlet groups can be distinguished or not according to the beam divergence. The
 11 two central beamlet groups can be more intense due to the overlap of the neighboring
 12 groups.

13 3. Beam emission spectroscopy

The BES diagnostic is based on the Doppler shift effect of the H_α or D_α Balmer line produced by impact of the accelerated beam particles with background particles. The most relevant reactions for the production of H_α are [8],



1 where the fast particles are underlined>. The processes are the same in case of deuterium.
 2 The light is collected by 20 optic heads placed inside the vacuum chamber as shown in
 3 figure 1: the light collected by each of them is conveyed through an optical fiber to a
 4 high-resolution Acton spectrometer equipped with a CCD camera (the dispersion is 7
 5 pm/pixel for a spectral interval of 8 nm). The optical head axis has an angle $\zeta = 50^\circ$
 6 with respect to the beam direction and the radiation emitted is Doppler shifted of the
 7 quantity,

$$8 \quad \lambda_{Doppler} = \frac{(1 + \beta \cos \zeta)}{\sqrt{1 - \beta^2}} \lambda_0, \quad (1)$$

9 where $\beta = v/c$ represents the particle velocity and λ_0 is the wavelength for the unshif-
 10 ted H_α or D_α line. The opening angle of the observation cone for the optical head has
 11 been measured to be 0.38° , which is in agreement with the value calculated by taking
 12 into account the geometry of the optical system, the fiber and the lens properties. The
 13 optic heads are positioned at about one meter distance from the geometrical beam cen-
 14 ter and, by assuming a beam width of 1 m, the viewing cone has a diameter of about
 15 20 mm at the entrance and about 32 mm at the exit of the beam region. Therefore, the
 16 signal collected has to be assigned to several rows of beamlets, every row alternately
 17 deflected left or right. For every beamlet, the signal is collected at different distances
 18 from the GG depending on the position of the beamlet along the LOS. These effects
 19 together increase the broadening of the Doppler peak, resulting in an increased value of
 20 measured divergence, which is not representative of the beamlet divergence but rather
 21 of an averaged value over the beam width. The beam divergence is sensitive to changes
 22 of the beam optics.

23 A typical BES spectrum, acquired with an exposure time of 1.5 s, is shown in figure 2(a),
 24 where three main features are distinguishable: the H_α unshifted peak on the left, the
 25 stripping peak caused by negative ions neutralized by collisions with the background gas
 26 before being fully accelerated, and the Doppler shifted H_α peak at higher wavelength.
 27 The Doppler peak integral is proportional to the averaged beam current density and to
 28 the background gas density.

29 The Doppler peak half width at one e-folding $\Delta\lambda$ is determined through a Gaussian fit
 30 applied to the Doppler peak (fit applied to the signal above 30% of the peak) and the
 31 beam divergence ϑ is calculated from $\Delta\lambda$, also taking into account the apparatus profile
 32 of the spectrometer and the opening angle of the lens head. The line broadening of the
 33 Doppler peak $\Delta\lambda$ is determined by the spectrometer instrumental function $\Delta\lambda_N$, by the
 34 opening angle of the observation cone for the optical head ω and by the divergence ϑ
 35 (see equation 2 [21]),

$$36 \quad \Delta\lambda^2 = \Delta\lambda_N^2 + \left(\frac{\lambda_0}{\sqrt{1 - \beta^2}} \beta \sin \zeta \right)^2 (\omega^2 + \vartheta^2). \quad (2)$$

38 In ELISE and for the used spectrometer $\Delta\lambda_N = 0.02522$ nm, $\omega = 0.38^\circ$ [20]. The
 39 apparatus profile of the spectrometer is an order of magnitude lower than the Doppler

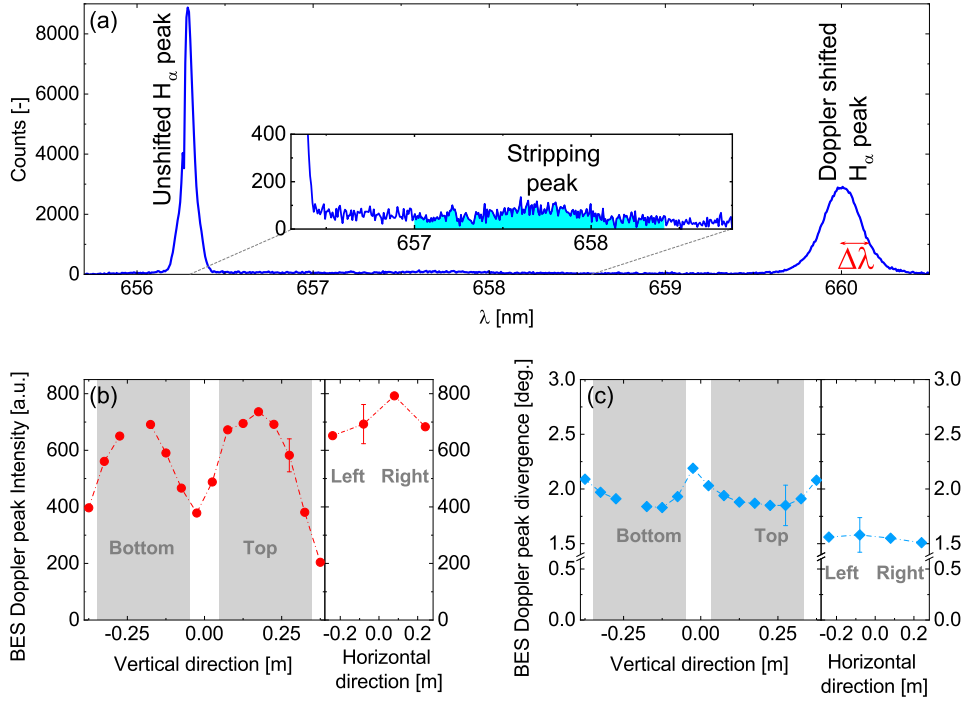


Figure 2: (a) Example spectrum from one LOS (LOS 10 positioned at +7.5 cm from the geometrical center of the beam) of the BES diagnostic: at 656.28 nm the H_{α} unshifted peak is visible while the Doppler shifted peak is placed at a wavelength shift proportional to the total HV applied. Between these two peaks, the stripping peak is visible. Vertical and horizontal profiles of the Doppler peak integral are shown in (b). Vertical and horizontal profiles of the divergence retrieved from the Doppler peak width are shown in (c). In (b) and (c), shaded areas correspond to the vertical projection of the beamlet groups. The LOS positioned at -0.225 m is not available. Shot 27115 performed in hydrogen at 0.3 Pa filling pressure, 180 kW total RF power for an extracted current of $I_{\text{ex}} = 18.7$ A with 6 kV extraction and 30 kV acceleration voltage; $I_{\text{PG}} = 1.6$ kA.

1 peak width typically measured in the experiment. Furthermore, the natural line
 2 broadening is negligible compared to the Doppler broadening. Therefore, the main
 3 contribution to the line is the broadening due to the particle angular distribution. For
 4 the estimation of the errors, the different sources of error as listed in ref. [22] contribute
 5 to an error of about 10% on the LOS-integrated beam divergence value and the main
 6 contribution to the error is the statistical error on the raw signal. The HV ripple,
 7 which can cause variations of the extracted current density and, consequently of the
 8 divergence, is small, i.e. about 100 V over an extraction voltage of 4 kV or more. The
 9 contribution to the Doppler peak broadening of the HV ripple, over which the BES
 10 spectrum is integrated, is negligible.

11 16 LOS are looking along the horizontal direction, thus giving a vertical profile while four
 12 LOS are looking vertically providing a horizontal profile. The horizontal LOS positioned
 13 at -22.5 cm is not available because the fiber coupling to the spectrometer is damaged.
 14 The spacing is 5 cm between the horizontal lens heads and 16 cm between the vertical
 15 ones: a higher resolution is desirable along the vertical direction to identify the effect

1 of the plasma drift [8] on the beam profile. The LOS are relatively calibrated, so it is
2 possible to compare the absolute intensity given by each LOS. In figure 2(b) and 2(c) the
3 vertical and horizontal beam intensity and profile are shown, respectively. The vertical
4 profile of the Doppler peak integral shown in figure 2(b) highlights the presence of two
5 areas with high intensity: these are the vertical projection of the top and bottom beam
6 segments. For LOS measuring an higher current density, a lower divergence is observed
7 as shown in figure 2(c). The LOS between the top and the bottom beam segments, in
8 a portion of volume not directly illuminated by apertures, measure a low intensity with
9 high beam divergence, indicating that the beam in this region is weak and formed by
10 highly divergent particles originating from beamlets located on the beam segments. A
11 better understanding of the origin of the signal measured by such LOS is possible only
12 with codes such as BBCNI [17]. The beam is not centered with respect to the zero of
13 the scale but slightly displaced downwards due to the vertical deflection caused by the
14 filter field. The horizontal divergence (measured by the 16 horizontal LOS) is typically
15 higher than the vertical one (measured by the four vertical LOS) due to broadening of
16 the Doppler peak caused by the overlap of rows of beamlets which are left and right
17 deflected.

18 4. Infra-red calorimetry

19 The calorimeter is made of four inertially cooled copper plates of dimension
20 $60\text{ cm} \times 60\text{ cm} \times 2.5\text{ cm}$. A detailed description is done in reference [15]. The beam
21 power deposited into each plate is measured separately by water calorimetry. 900 copper
22 blocks, each of $3.8\text{ cm} \times 3.8\text{ cm}$ surface area, are brazed onto the water-cooled copper
23 plates. The schematic of the 30×30 blocks is displayed in figure 3(a). A 2 mm gap
24 separates the blocks such that each block can be considered as a single independent
25 heat load measuring element. The power deposited on the blocks passes through an
26 intermediate thermal resistance to the actively cooled plate: in this way the blocks
27 can be considered as inertial calorimeters during the beam-on time. The heat loss
28 due to radiation is negligible at the typical temperature reached by the blocks, and at
29 the maximum temperature that the calorimeter can withstand without damage (about
30 450°C [15]) radiation losses are in the order of a few percent. 48 thermocouples, used to
31 measure the absolute block temperature, are embedded into the same number of blocks
32 as shown with blue squares in figure 3(a).

33 A high resolution (640×480 pixels) FLIR A655sc IR micro-bolometer camera placed
34 outside the vacuum chamber looks at the diagnostic calorimeter through a ZnSe window
35 with anti-reflective coating. To decrease the reflectivity of the beam-facing side of the
36 diagnostic calorimeter, the surface has been covered with a MoS_2 coating [14].

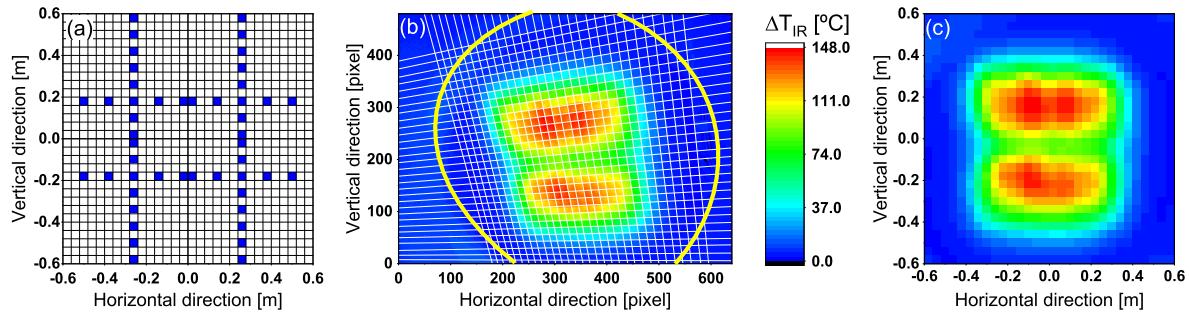


Figure 3: (a) Schematic of the 900 block composing the calorimeter surface. The blocks which 48 thermocouples are embedded are indicated in blue. (b) ΔT image as retrieved from the IR camera. The blocks are defined by the white lines while the yellow thicker lines indicate the limited field of view due to geometrical vignetting. The average temperature values inside each block are shown in (c): a 2D beam profile (resolution: 30×30): the spatial resolution is given by the block dimension of $3.8 \text{ cm} \times 3.8 \text{ cm}$. Data of shot 27115 performed in hydrogen at 0.3 Pa filling pressure, 180 kW total power for an extracted current of $I_{\text{ex}} = 18.7 \text{ A}$ with 6 kV extraction and 30 kV acceleration potential; $I_{\text{PG}} = 1.6 \text{ kA}$.

1 4.1. Camera calibration and temperature evaluation

2 The total radiation seen by the IR camera detector is a function of the power emitted
3 by the calorimeter surface W_{cal} , of the distance between emitting surface and camera,
4 of the emissivity ε of the calorimeter surface and of the transmissivity τ_{opt} of the ZnSe
5 window placed between the IR camera and the calorimeter. The internal calibration
6 coefficient of the micro-bolometer, ε , τ_{opt} and the wavelength response of the chip are
7 used by the processing software to obtain the calorimeter surface temperature T_{cal} from
8 W_{cal} . The problem can be simplified by considering that only the temperature increase
9 ΔT during the beam-on phase is required to evaluate the power density deposited. In
10 figure 3(b) the temperature increase seen by the IR camera is shown: the straight thin
11 lines show the blocks while the thick yellow lines indicate the field of view limited due to
12 vignetting by the pipe. In figure 3(c) the temperature increase for each block is shown:
13 the temperature values are retrieved by averaging over the pixels inside each block.
14 Both the emissivity ε and the transmissivity τ_{opt} can change in time: the emissivity ε
15 is mainly related to the status of the blackening layer, i.e. ε can be reduced locally due
16 to removal of coating by sputtering; the transmissivity τ_{opt} can change due to coating
17 of the ZnSe window by the sputtered material from the calorimeter. It is not possible
18 to monitor these two quantities continuously and without breaking the vacuum of the
19 tank. Therefore, for simplicity, the transmissivity τ_{opt} and the emissivity ε are combined
20 into an effective emissivity $\varepsilon_{\text{eff}} = \varepsilon \tau_{\text{opt}}$, whose value is estimated experimentally by
21 comparing the ΔT measured by the IR camera (ΔT_{IR}) with the value obtained from the
22 thermocouples (ΔT_{TC}). For one block hosting a thermocouple, ε_{eff} is varied within a
23 range of values and ΔT_{IR} is calculated for each case: the value of ε_{eff} which minimizes the
24 quantity $|\Delta T_{\text{IR}} - \Delta T_{\text{TC}}|$ is then the best effective emissivity for the selected block. The
25 evolution of $|\Delta T_{\text{IR}} - \Delta T_{\text{TC}}|$ as a function of ε_{eff} is shown in figure 4(a). This procedure

1 is repeated for the 4 blocks in the center of each calorimeter plate (as displayed in the
 2 schematic on the top right in figure 4(a)). The effective emissivity value for the whole
 3 surface of the calorimeter is an average of these four values. The error on the emissivity
 4 is determined by statistical error propagation taking into account the error of ΔT_{TC} (2.2°
 5 C for the single thermocouple temperature value, 3.1° C for ΔT_{TC}) and the maximum
 6 error of ΔT_{IR} for a fixed ε (footnote ‡, 2° C for the single absolute temperature, 2.8° C
 7 for ΔT_{IR}). The final error on the quantity $|\Delta T_{IR} - \Delta T_{TC}|$ is 4.2° C. The error on ε_{eff} is
 8 ± 0.05 and of ± 0.03 on the averaged emissivity value. For the case shown in figure 4(a),
 9 the averaged value for the effective emissivity is 0.88 ± 0.03 . The emissivity estimation is
 10 performed for each beam pulse. The temporal evolution of the effective emissivity can be
 11 monitored in time for every beam pulse to check possible anomalies in the calorimeter or
 in the IR evaluation. The temperature increase ΔT_{TC} is calculated with respect to the

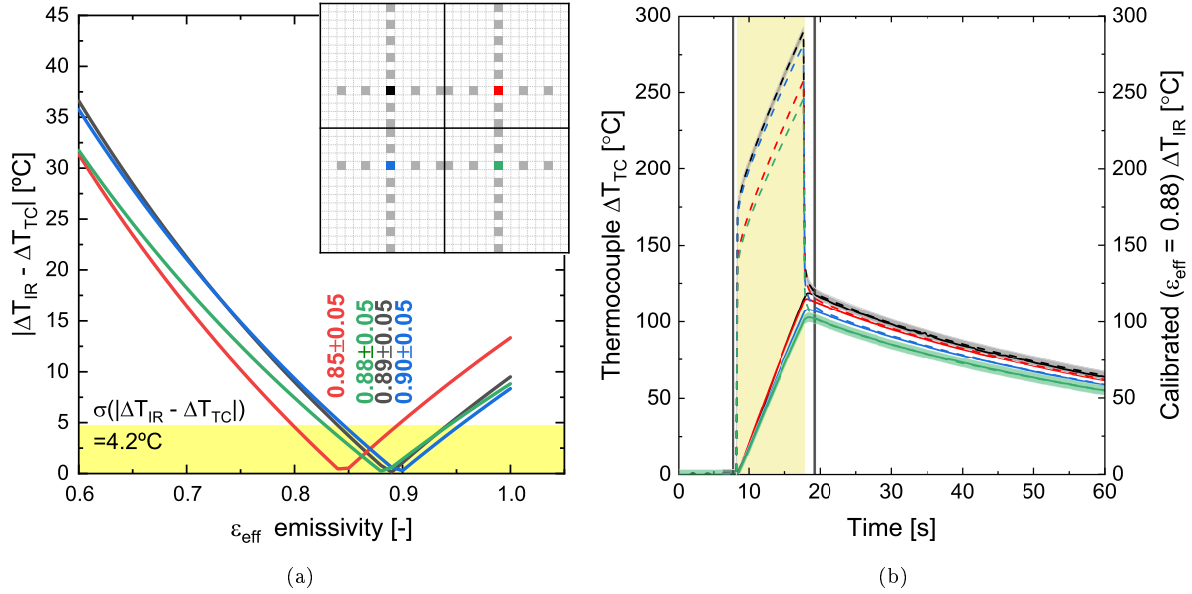


Figure 4: (a) Difference $|\Delta T_{IR} - \Delta T_{TC}|$ as a function of the effective emissivity for four thermocouples. Colors refer to the blocks as shown in the small schematic. The best effective emissivity value for each thermocouple is reported in figure. (b) Temperature difference ΔT evolution in time; measurement from the thermocouples (full line) and from the calibrated IR camera (dashed line) measuring in the same blocks housing the thermocouples. The shaded area highlights the beam-on phase of 9.5s. The vertical black lines show the two times used for determining ΔT_{IR} before and after the extraction phase. The colors refer to the blocks as shown in the small schematic in (a). For two cases the error bar is contouring the data. Shot 27115, the effective emissivity is calculated to be $\varepsilon_{eff} = 0.88$.

12

13 temperature before the beam-on phase and can be monitored in time. The temperature
 14 increase ΔT_{IR} is determined after the end of the pulse as temperature difference between
 15 the end and the beginning of the beam pulse. In figure 4(b) the evolution in time of
 16 ΔT_{TC} measured by the thermocouples (solid lines) installed in four blocks and the

‡ Infrared Camera Accuracy and Uncertainty in Plain Language, <https://www.flir.com/discover/rd-science/infrared-camera-accuracy-and-uncertainty-in-plain-language/>

1 corresponding ΔT_{IR} by IR calorimetry (dashed lines) is shown. The beam-on phase is
 2 shaded while the two points in time for the determination of ΔT_{IR} are shown by vertical
 3 black lines: at these times, once the ε_{eff} calibration is correctly done, IR calorimetry and
 4 thermocouple temperature values superimpose. A significant discrepancy between IR
 5 measurements and thermocouples is observed during the beam-on phase (shown in figure
 6 4). The most likely explanation is that the thin blackening layer heats up considerably
 7 more than the copper substrate due to bad thermal conductivity between the two [14].
 8 This temporary additional increase of the temperature during the beam-on time phase
 9 has no impact on the evaluation of the total temperature increase ΔT and, consequently,
 10 on the beam power estimation because the temperature is measured before the beam
 11 and immediately after this phenomenon vanishes. Although the camera has a high
 12 resolution, the actual experimental spatial resolution for a 2D map of the beam power
 13 deposited onto the calorimeter is given by the 30×30 calorimeter blocks as shown in
 14 3(c). The temperature increase ΔT is proportional to the deposited beam power P ,

$$15 \quad P = \frac{c_{\text{Cu}} m \Delta T}{t_B}, \quad (3)$$

16 where m is the mass of the single copper blocks, c_{Cu} is the heat capacity of copper and
 17 t_B is the beam-on time. For the case shown in figure 3(c), the power deposited in 9.5 s
 18 extraction phase for the block with the highest temperature increase is (1.96 ± 0.06) kW,
 19 the total power deposited onto the calorimeter is 586 kW. From the total HV (36.2 kV)
 20 and the total extraction area (985 cm^2), an accelerated averaged current density of
 21 164 A/m^2 is calculated.

22 A validation of the total power averaged over the calorimeter surface measured by IR
 23 analysis is done through a comparison with the water calorimetry measurement also av-
 24 eraged over the diagnostic calorimeter. The comparison of the total accelerated current
 25 density (obtained dividing the averaged power density by the applied HV) deposited
 26 onto the diagnostic calorimeter measured by IR calorimetry and by water calorimetry
 27 [15] is shown in figure 5 for about five thousand pulses, both in hydrogen and deuterium.
 28 A linear fit of the whole data set is performed: the very good agreement between the two
 29 measurements allows the estimation of j_{acc} retrieved by IR calorimetry to be validated.
 30 The linear fit is not forced to zero to check for the presence of an offset between the
 31 two measurements: the offset is 2.1 A/m^2 , which is very small compared to the typical
 32 value measured ($\leq 5\%$). By considering the error bars of both diagnostics, i.e. $\pm 5\%$ of
 33 the IR calorimetry and $\pm 10\%$ of the water calorimetry, the offset is compatible with the
 34 measurement error. The goodness of the fit is given by Pearson's r coefficient and it is
 35 very good in this case, being the value close to one. For the averaged accelerated current
 36 j_{acc} over the calorimeter surface, IR calorimetry and water calorimetry are equivalent
 37 but, as presented in the next section, IR calorimetry is preferable because it gives a
 38 spatial resolution of 4 cm.

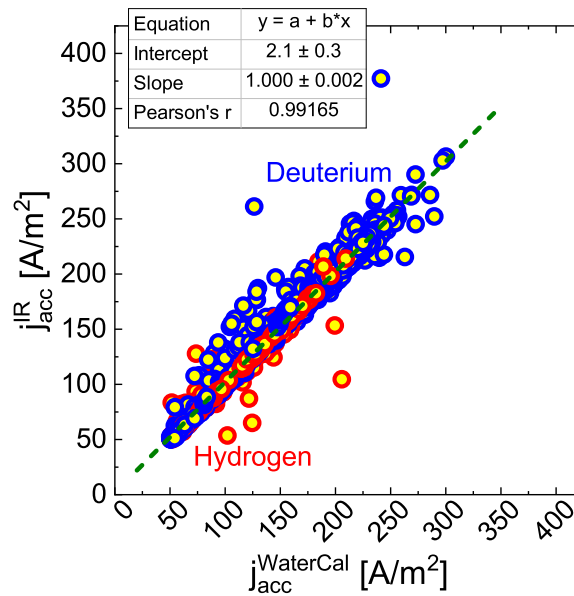


Figure 5: Comparison between the accelerated current density j_{acc} as measured by water calorimetry and by IR calorimetry. The pulses are done between January 2017 and July 2018, both in hydrogen and deuterium. A linear fit is applied to the whole data set: the resulting slope is 1.000 ± 0.002 and the intercept is 2.1 ± 0.3 . The goodness of the fit is given by the Pearson's coefficient. Few cases are outside of the main cloud of data: this is due to an error on the automatic evaluation of the effective emissivity which can not be detected a priori but only at a later time by comparing the value with the water calorimetry measurement.

1 4.2. Fitting procedure

2 The 2D map of the beam power deposited onto the calorimeter provides a qualitative
3 insight on the beam profile: a fitting routine is applied in order to retrieve quantitative
4 information on the beamlet group vertical and horizontal width, intensity and on the
5 vertical position of the beam segments. The fitting formula is a sum of eight bi-
6 dimensional Gaussian functions that represent the eight rectangular beamlet groups.
7 The Gaussian shape assigned to the power density profile was chosen starting from the
8 hypothesis that at high distance from the grid system the overlap of beamlets arranged
9 as the apertures in figure 6(a), gives a Gaussian profile [23]. In equation 4 the fitting
10 function as a function of the vertical and horizontal coordinates (y and x in the equation,
11 respectively) is given. The top and bottom beam segments are treated separately: the
12 subscripts "top" and "bot" refer to the top and bottom beam segment, respectively.
13 The schematic representation of the fitting function superimposed to a power density
14 profile is shown in figure 6(b).

$$15 \quad f(x, y) = \sum_{i=1}^4 A_i e^{-\frac{(x-x_{0,i})^2}{2(\sigma_x^{\text{top}})^2} - \frac{(y-y_{\text{top}})^2}{2(\sigma_y^{\text{top}})^2}} + \sum_{i=5}^8 A_i e^{-\frac{(x-x_{0,i})^2}{2(\sigma_x^{\text{bot}})^2} - \frac{(y-y_{\text{bot}})^2}{2(\sigma_y^{\text{bot}})^2}} \quad (4)$$

16 The horizontal position of the Gaussians $x_{0,i}$ is fixed and it corresponds to the
17 geometrical center of the beamlet groups on the GG. The vertical positions of the
18 top and bottom beam segments (y_{top} and y_{bot}) are free parameters due to the vertical

1 deflection of the beam caused by the filter field. The vertical and horizontal width (σ_y
 2 and σ_x) of the Gaussian are assumed identical for the four beamlet groups in each beam
 3 segment because no inhomogeneity among beamlet groups belonging to the same beam
 4 segment is expected. The amplitude of each Gaussian function is described by the free
 5 parameters A_i , with $i = 1 \dots 8$. The error bar assigned to the fit outputs σ_x , σ_y , y_{top} and
 6 y_{bot} is calculated from the error on the fitting procedure and from the error due to the
 7 dimension of the calorimeter block. The error on the position due to the dimension block
 8 is calculated as $\frac{3.8 \text{ cm}}{\sqrt{12}} = 1.1 \text{ cm}$, where 3.8 cm is the dimension of the block and $\sqrt{12}$
 9 the factor to obtain the standard deviation from the width of the uniform distribution
 10 considered [24], namely the block width in this case. The error due to the dimension of
 11 the block is the dominant contribution to the error on the fit outputs.

In this model, the integral of the the Gaussian function describing one beamlet group

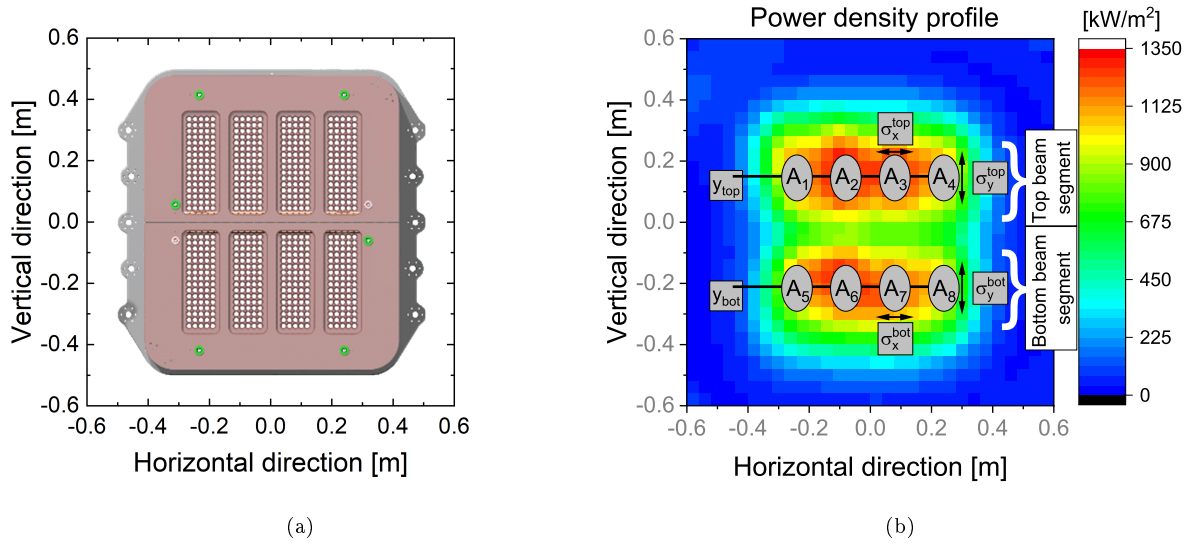


Figure 6: (a) Aperture arrangement on the PG. (b) Schematic of the fitting function applied to the 2D map of the power density on the calorimeter. The parameters of the fitting function are superimposed to power density profile. The top and bottom beam segments enclose the beamlet groups located on the top and on the bottom side of the calorimeter, respectively.

12 is proportional to the accelerated current carried by the beamlets belonging to that
 13 beamlet group. The integral is calculated by integrating each Gaussian function to
 14 infinity, thus including beam losses outside the calorimeter surface ($\leq 10\%$ or negligible
 15 in the majority of the cases) which can occur in case of high beam divergence or high
 16 beam deflection caused by a strong filter field. The accelerated current can be calculated
 17 for each beamlet group and in the case of the top beam segment is

$$19 \quad V_{\text{top}}^{\text{fit}} = \int_{-\infty}^{+\infty} \left(\sum_{i=1}^4 A_i e^{-\frac{(x-x_{0,i})^2}{2(\sigma_x^{\text{top}})^2} - \frac{(y-y_{\text{top}})^2}{2(\sigma_y^{\text{top}})^2}} \right) dx dy = 2\pi \sum_{i=1}^4 A_i \sigma_x^{\text{top}} \sigma_y^{\text{top}} \quad (5)$$

20 and the corresponding case for the bottom is $V_{\text{bot}}^{\text{fit}} = 2\pi \sum_{i=5}^8 A_i \sigma_x^{\text{bot}} \sigma_y^{\text{bot}}$.

21 In order to test the eligibility of the fit, it has been applied to synthetic power profiles.

1 The synthetic profiles are produced by assuming a Gaussian power distribution for each
 2 of the 640 beamlets at the exit of the GG and projecting them up to the calorimeter
 3 distance. No beamlet deflection is foreseen. At the calorimeter each beamlet has a
 4 Gaussian profile and the width δ is calculated as

$$5 \quad \delta = \frac{1}{\sqrt{2}} 3.5 \text{ m} \tan\left(\vartheta_{1/e} \cdot \frac{\pi}{180}\right), \quad (6)$$

6 where $\vartheta_{1/e}$ is the divergence in degrees at one e-folding half width and 3.5 m is the
 7 distance between GG and diagnostic calorimeter. The factor $\frac{1}{\sqrt{2}}$ is the conversion factor
 8 between the width in sigma and the e-folding half width. For every aperture a Gaussian
 9 function $p_i(x, y)$ is used. The total power on the calorimeter $p(x, y)$ is

$$10 \quad p(x, y) = \sum_{i=1}^{640} p_i(x, y) = \sum_{i=1}^{640} \frac{a_i}{2\pi\delta_x\delta_y} e^{-\frac{(x_i-x)^2}{2\delta_x^2} - \frac{(y_i-y)^2}{2\delta_y^2}}, \quad (7)$$

11 where a_i is the peak amplitude of the single Gaussian function describing the beamlet,
 12 x_i and y_i are the horizontal and vertical beamlet coordinates defined in the reference
 13 system of figure 6(a), and δ_x and δ_y are the horizontal and vertical beamlet width. The
 14 following assumptions have been used:

- 15 • All the beamlets are circular ($\delta_x = \delta_y$);
- 16 • The peak intensity a_i is the same for beamlets belonging to the same beamlet group;
- 17 • The divergence is assumed to be the same for apertures belonging to the same beam
 18 segment (top or bottom);

19 The validity of these assumptions are discussed in section 4.3 with a comparison between
 20 simulation and a real pulse performed at ELISE. Fluctuations are simulated by adding
 21 a random noise of $\pm 10\%$ of the absolute values (uniform distribution). The resolution
 22 of the synthetic profile has been reduced to mimic the experimental resolution of the
 23 blocks on the calorimeter.

24 Once the synthetic profiles are produced and the fit is applied, it is possible to correlate
 25 the behavior of the output parameters with the simulation ones, such as the dependence
 26 between beamlet divergence ϑ and beamlet group width σ_x and σ_y as shown in figure
 27 7(a): σ_x and σ_y for the top and bottom beam segments obtained from the fitting routine
 28 are plotted as a function of ϑ . In each simulation shown in figure 7(a), the intensity
 29 and the divergence are the same for all beamlets, thus the beam is horizontally and
 30 vertically symmetric with respect to the zero of the scale. The divergence varies from
 31 $\vartheta = 1$ degree to $\vartheta = 5$ degrees in steps of 0.2 degrees. While increasing the beamlet
 32 divergence, the width of the beamlet groups in the power density profile increases. The
 33 behavior of σ_y is linear above a divergence of about 2.5 degrees, below it σ_y still decreases
 34 with decreasing divergence but not linearly. The beam vertical width is determined by
 35 the divergence and only for small values of divergence by the geometrical arrangement
 36 of the apertures on the grids. The horizontal width σ_x always increases linearly with
 37 increasing divergence. In figure 7(a) on the right axis the adjusted R-square of the fit as
 38 a function of ϑ is shown. The adjusted R-squared is an estimator of the goodness of the

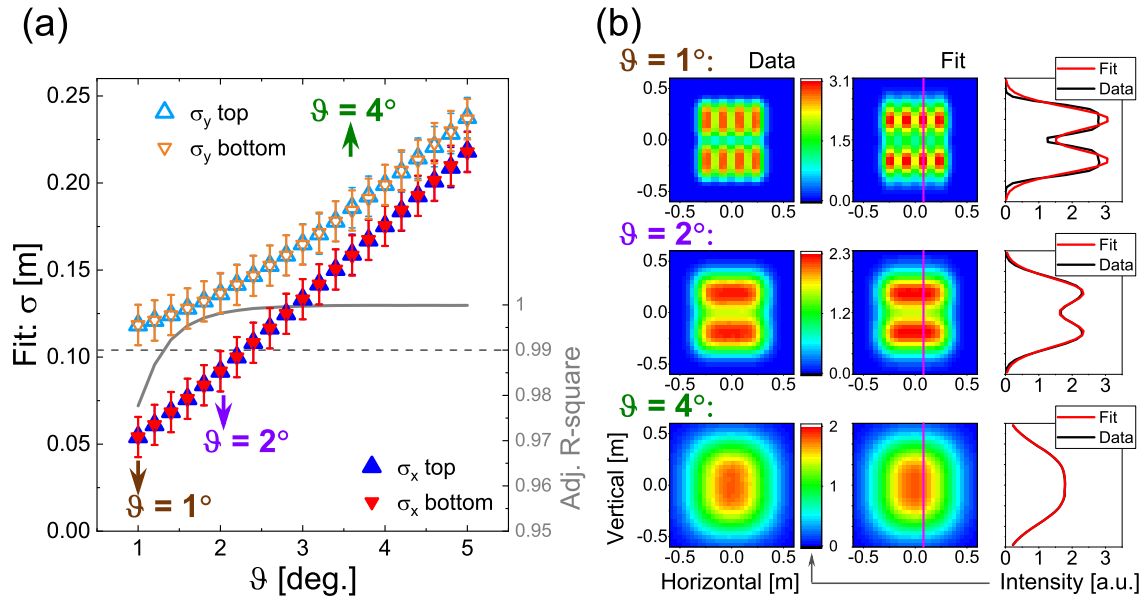


Figure 7: (a) Vertical and horizontal beamlet group width calculated by the fitting routine as a function of the divergence used in the synthetic 2D map; the intensity is the same for all the beamlets. For the cases with 1, 2 and 4 degree divergence a plot of the synthetic data, of the fitted matrix and of the vertical profile is shown in panel (b). In (a), on the right axis, the adjusted R-square calculated is shown: the level of 0.99 indicates the minimum level accepted, below 0.99 the simulated map is not properly reproduced by the fitting routine.

1 fit and the threshold used to accept the result is 0.99. Below it, the fitting function is
 2 not representative of the 2D profile. The lowest value of beamlet divergence ϑ for which
 3 the fitting function properly reproduces the 2D map is 1.5 degrees.
 4 In figure 7(b), the 2D maps and profiles from simulations with 1, 2 and 4 degrees
 5 divergence and the corresponding fits are shown: the synthetic 2D maps is shown in the
 6 first column, the fitted one is shown in the second column and in the third column the
 7 vertical profiles from the synthetic map and from the fitted one are displayed.
 8 The overlap of Gaussian beamlets at the calorimeter plane gives a beamlet group profile
 9 that is not, in general, a Gaussian, especially for low divergences as shown in the
 10 figure 7(b) for the case at 1 degree: in this case, the beamlet group profile becomes flat
 11 in the central part, resulting in a rectangle rather than a bell-shaped curve. At 1 degree
 12 divergence (17.4 mrad which is close to the calculated optimum of 14.4 mrad-19.5 mrad
 13 for ELISE[12]), the fitting procedure does not properly reproduce the synthetic map:
 14 the intensity (i.e. A_i in equation 4) is overestimated and the beam vertical width σ_y is
 15 underestimated. A different type of fitting function, e.g. a box function or a flat-top
 16 Gaussian curve, can also be applied for the cases with divergence lower than 1.5 degrees,
 17 but in such cases the number of points is not sufficient for a robust and reliable automatic
 18 evaluation of the IR 2D profile. The agreement is good at higher divergence as shown
 19 for 2 and 4 degrees divergence in figure 7(b). At 4 degrees, where the beam segments are
 20 indistinguishable because of the large overlap, the fitting routine reproduces the power

1 profile correctly.

2 Up to this point, the test is performed on a homogeneous beam, i.e. all the beamlets
3 have the same divergence and intensity. In the following, the fitting routine is tested on
4 a larger set of simulations, where asymmetries of the beamlet divergence and beamlet
5 intensity between beam segments, but also among beamlet groups, are introduced.

6 *4.2.1. Beam width* The fitting routine is tested on the capability to characterize the
7 two beam segments independently from one other. The test is carried with a set of
8 simulations in which the inputs of the top beam segment are fixed while the bottom
9 ones vary. If the fit outputs for the two beam segments are independent on from each
10 other, the test is then successful.

11 In figure 8 some significant cases are displayed: dots correspond to the simulated pro-
12 file, lines to the fit. In each panel ϑ_{top} is fixed and ϑ_{bot} varies according to the values
13 shown in each panel. In panels (a) and (b) the beamlets in the simulation have the
14 same intensity between top and bottom beam segment while in (c) and (d) the bottom
15 beamlets are three times more intense than the top ones. Such large variations on the
16 input parameters represent scenarios with high inhomogeneity in the current density
17 and in the beam divergence between beam segments. In each panel, the fit correctly
18 reproduces the beam profile in all the cases and σ_y^{top} coincide within the error bars as
19 shown by the overlapping of the black curves. Larger differences on the vertical width
20 σ_y^{top} , but always within the error bars, are observed in (c) and (d) due to the large
21 difference ($3\times$) in intensity between the top and bottom beam segments.

22

23 *4.2.2. Beam integral* The proportionality between beam segment integral in the
24 simulations and calculated from the fit results has been checked under different
25 conditions. This test is fundamental for the correct evaluation of the accelerated current
26 for each beamlet group or beam segment. The beam integral calculated from fit routine
27 outputs (see equation 5) is $V_{\text{top}}^{\text{fit}} = 2\pi \sum_{i=1}^4 A_i \sigma_x^{\text{top}} \sigma_y^{\text{top}}$ and the corresponding case for the
28 bottom is $V_{\text{bot}}^{\text{fit}} = 2\pi \sum_{i=5}^8 A_i \sigma_x^{\text{bot}} \sigma_y^{\text{bot}}$. For the simulation, the top beam segment integral
29 is calculated as

$$30 \quad V_{\text{top}}^{\text{sim}} = \int_{-\infty}^{+\infty} \left(\sum_{i \in \text{top}} \frac{a_i}{2\pi \delta_x \delta_y} e^{-\frac{(x_i-x)^2}{2\delta_x^2} - \frac{(y_i-y)^2}{2\delta_y^2}} \right) dx dy = \sum_{i \in \text{top}} a_i \quad (8)$$

31 and the corresponding case for the bottom is $V_{\text{bot}}^{\text{sim}} = \sum_{i \in \text{bot}} a_i$.

32 In figure 9 the quantity $(V_{\text{top}} - V_{\text{bot}})/V$ where V is the global integral, calculated from
33 the fit outputs as a function of the one retrieved from the simulation inputs is shown. In
34 the simulations, the bottom beam segment intensity is varied while the top one is fixed.
35 In (a) $\vartheta_{\text{top}} = \vartheta_{\text{bot}}$, in (b) $\vartheta_{\text{bot}} = 2$ degrees and in (c) $\vartheta_{\text{bot}} = 4$ degrees. Additionally,
36 ϑ_{top} is varied and the values are shown in each panel of figure 9. The two ratios (of the
37 fitted and of the synthetic profiles) are proportional and all within 10% of the bisector
38 shown as a solid line in each panel and the shaded area around the bisector represents

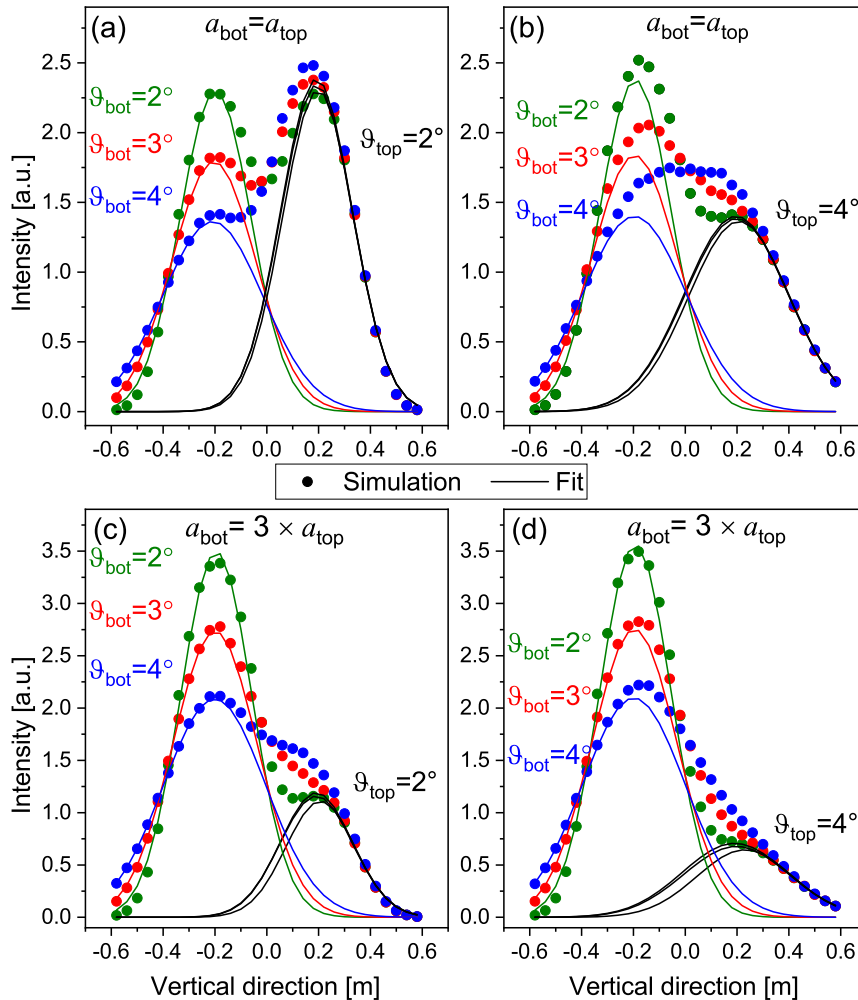


Figure 8: Simulated vertical profiles (dots) for different cases and fitted profiles (lines). The fitted profiles for the top and bottom segments are plotted separately. In each panel the top beamlet divergence is constant while the bottom one is set at 2, 3 and 4 degrees. The top divergence is fixed to 2 degree in (a) and (c) and to 4 degrees in (b) and (d). In panel (a) and (b) the beamlets in the simulated top and bottom beam segments have the same peak intensity while in (c) and (d) the beamlets in the bottom segment are three times more intense that the top ones.

1 $\pm 10\%$ deviation. Thus, the accelerated current carried by each beam segment is reliably
 2 estimated from the fit outputs. Similar tests have been done successfully for varying
 3 the relative intensity of single beamlet groups: the beamlet group integral is always
 4 proportional to the simulated values, confirming the capability of the fitting routine to
 5 correctly estimate the intensity of each beamlet group and, in turn, of the beam segment.

6

7 *4.2.3. Beam position* The vertical positions of the top and bottom beam segment are
 8 free parameters of the fitting routine due to the beam vertical deflection. To simulate
 9 the vertical deflection, the apertures on the grids are vertically displaced keeping the

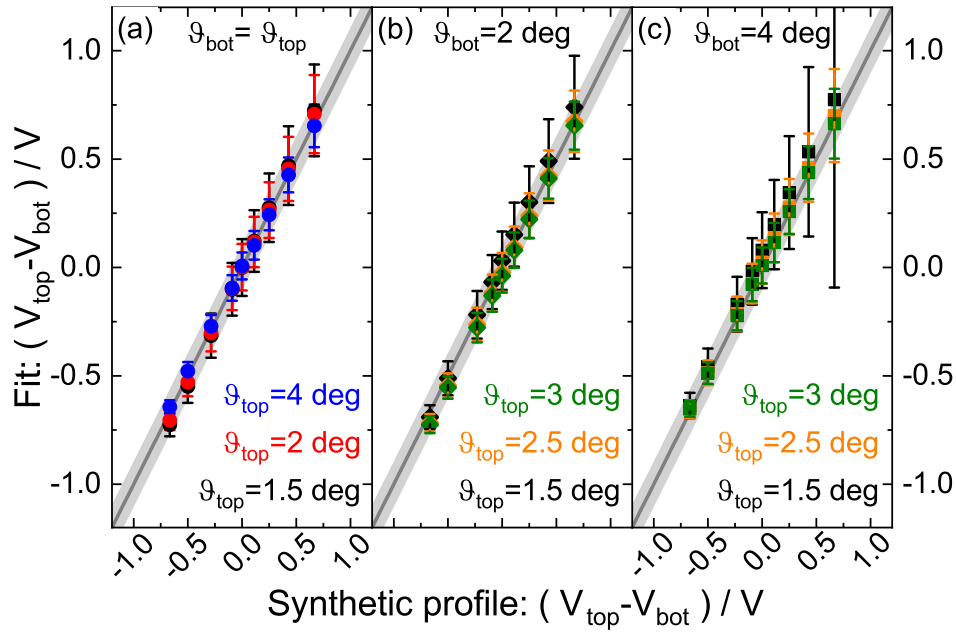


Figure 9: Proportionality between simulation and fit on the ratio of the beam segment integrals. The bottom beamlet intensity was varied with respect to the top one. Three cases are shown: when $\vartheta_{\text{top}} = \vartheta_{\text{bot}}$ in (a), when $\vartheta_{\text{bot}} = 2$ degrees in (b) and when $\vartheta_{\text{bot}} = 4$ degrees in (c). The solid lines identify the bisector in each plot.

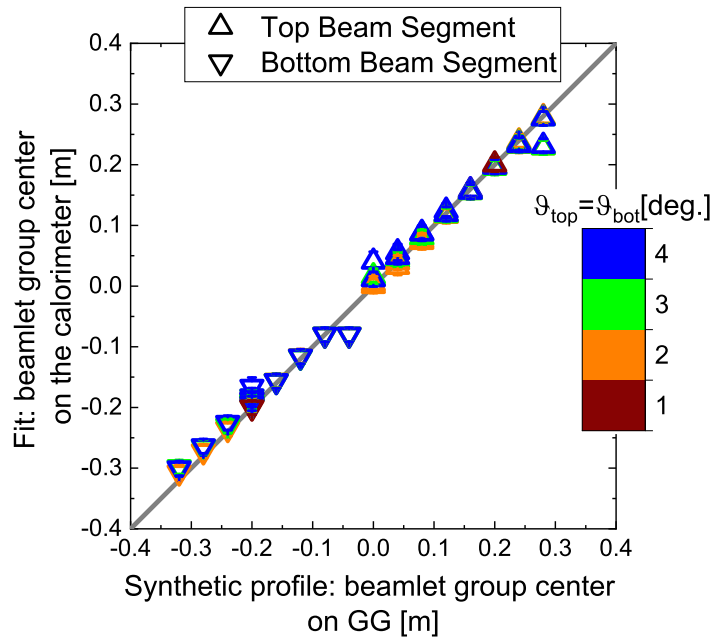


Figure 10: Beam vertical position retrieved by the fit as a function of the beamlet group center position at the GG and for different divergences ($\vartheta_{\text{top}} = \vartheta_{\text{bot}}$) according to the color scale. The solid line identifies the bisector.

1 beamlet group structure. Two different sets of cases have been tested:

- 2 • the position of one beam segment is fixed, the bottom one in this case, while the
3 other one is varying. This case mimics a scenario in which variations of the vertical
4 beam segment homogeneity are detected by variation of σ_y and vertical position.
5 In this case the two beam segments can react independently.
- 6 • the position of both segments is displaced vertically of the same quantity. These
7 cases concern the scenario of different filter field intensity or different HV applied,
8 thus affecting the vertical displacement of both segments in the same way.

9 The fit outputs y_{top} and y_{bot} are shown in figure 10 as a function of the beamlet group
10 center position used for the simulation. Beamlet divergences between 1° and 5° in steps
11 of 0.5° have been considered and some cases are reported in figure. The agreement
12 between the fit and the simulation is very good, also at four degrees divergence when it
13 is qualitatively difficult to distinguish the two beam segments at the calorimeter due to
14 the large overlap as shown in figure 7 for the case at four degrees divergence.

16 4.3. Comparison of simulations with an experimental beam pulse

17 The 2D power density map of the beam shown in figure 3(c) is compared to a simulation
18 in order to check if the assumptions of the simulation are reasonable, especially regarding
19 the uniformity in intensity for all the beamlets belonging to one beam segment. The
20 input values for the simulation are:

- 21 • $\vartheta_{\text{top}} = \vartheta_{\text{bot}} = 1.8$ degrees determined by BES for the horizontal LOS looking at the
22 center of each beam segments (in this case the value is 1.8 degrees for both beam
23 segments).
- 24 • 2.5 cm of vertical displacement downwards taken from the fit on the IR data: the
25 value is 2.5 cm downwards for the top beam segment and 2.9 cm downwards for
26 the bottom beam segment, the value are in agreement within the error bar. For
27 simplicity, only 2.5 cm is chosen.
- 28 • All the beamlets have the same peak intensity since the vertical profile measured
29 by IR calorimetry shows that the two beam segments have a similar intensity (see
30 BES intensity profile in figure 2(b) and 2D map in figure 3(c)).

31 The power density map for the experimental beam pulse and the simulation are shown
32 in figure 11(a) and (b), respectively. In the experimental map, as well as in the
33 simulated one, the beam segments are clearly detached from one another. The inner
34 beamlet groups in the experimental case, especially in the top beam segment, can be
35 distinguished while in the simulation they are barely distinguishable.

36 A more quantitative comparison is carried out by comparing the vertical and horizontal
37 profiles in figure 11(c) and (d), respectively. The vertical profiles are plotted at two
38 positions illustrated in figure 11(a) and (b) with the label "Outer B.G." and "Inner
39 B.G." for the outer and inner beamlet groups, respectively.

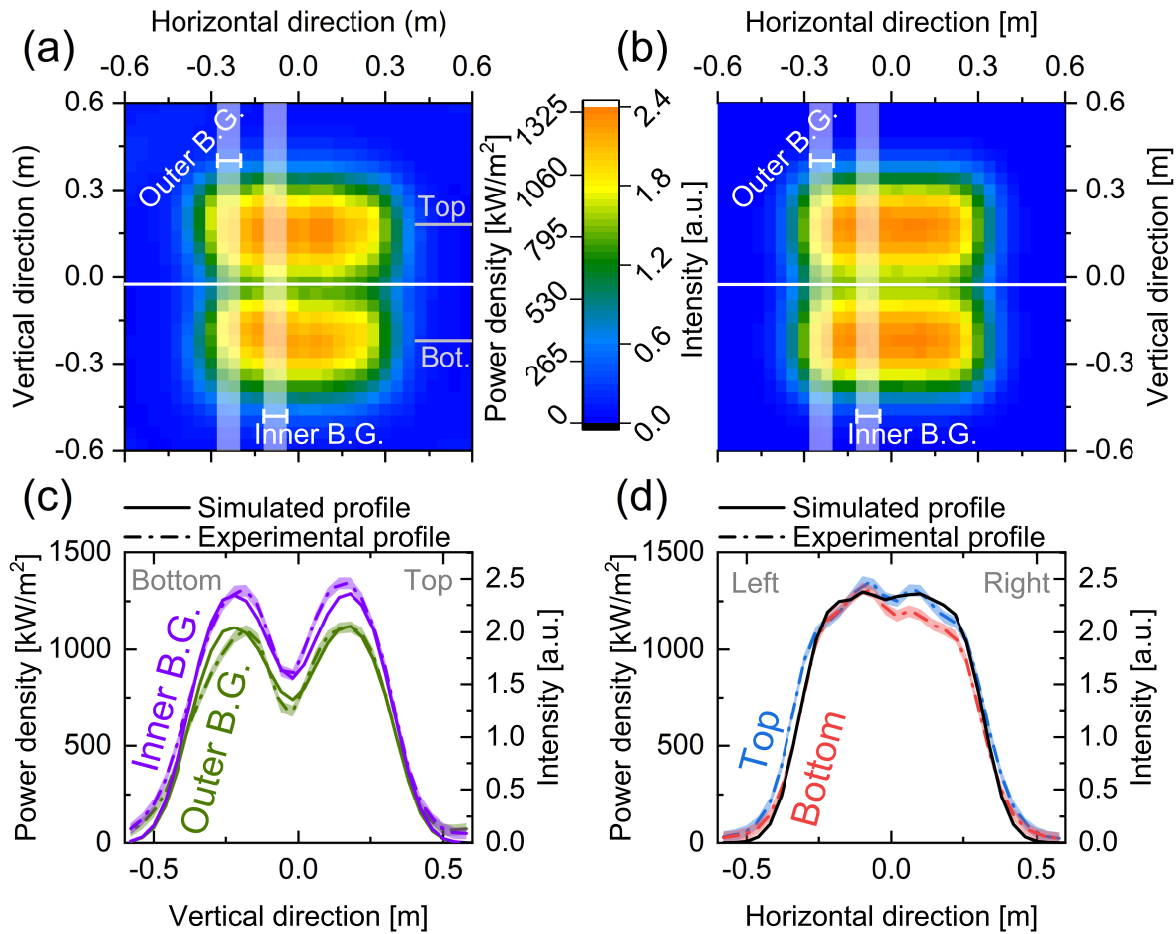


Figure 11: (a) 2D power density map for one ELISE beam pulse, to be compared with the simulated 2D map (input parameters: $\vartheta_{\text{top}} = \vartheta_{\text{bot}} = 1.8^\circ$, uniform intensity for all the beamlets, shift of 2.5 cm downwards retrieved by the fit) shown in (b). The solid white horizontal line depicts the beam center calculated by the IR fit applied to (a) and used as parameter in (b). In panel (c) two measured vertical profiles are compared with the simulation: the vertical profiles are given for the outer beamlet groups (Outer B.G.) and the inner beamlet groups (Inner B.G.) i.e. the leftmost beamlet groups and the second beamlet groups from the left, respectively. In panel (d) the horizontal profiles of the top and bottom beam segments are compared with the simulation: the positions for the comparison are shown in panel (a). The shaded area around the experimental profiles in (c) and (d) is the experimental uncertainty on the power density. In (c) and (d) the experimental profiles refer to the left axis while the simulations to the right axis.

- 1 The horizontal profiles are plotted along the center of the top and bottom beam segment
- 2 as shown in figure 11(a) by the levels labeled with "Top." and "Bot.". The vertical
- 3 profiles are plotted in figure 11(c) for the inner and outer beamlet groups. The inner
- 4 beamlet groups are more intense than the external ones due to the beamlet group
- 5 overlapping that increase the intensity in the center. The shaded area around the
- 6 experimental profiles in fig 11(c) and (d) is the experimental uncertainty on the power
- 7 density.
- 8 The simulation reproduces quite accurately the vertical profile in particular for the
- 9 top beam segment and with minor deviations localized on the bottom beam segment:

1 the maximum of the bottom beam segment is located in a different position and the
 2 intensity profile is different. This discrepancy may indicate that the assumption that all
 3 the beamlets within one segment have the same intensity is not appropriate, especially
 4 for the bottom beam segment where a more appropriate assumption would be a higher
 5 intensity for the upper rows of beamlets and a lower intensity in the remaining ones.
 6 The experimental horizontal profile in figure 11(d) shows that the total beam width is
 7 comparable to the one simulated considering the error bars. The beamlet groups are
 8 more distinguishable in the experimental profile, thus suggesting that the real beamlet
 9 divergence is lower than the one measured by BES and used as input for the simulation
 10 probably due to the left-right beamlet deflection. A priori, the assumption that all
 11 the beamlets carry the same extracted current cannot be verified, but the comparison
 12 of the vertical and horizontal profiles between values measured by IR calorimetry and
 13 a simulation as shown in figure 11(c) and (d) suggests that it is reasonable in a first
 14 approximation.

15 5. Crosscheck of IR calorimetry with BES diagnostic

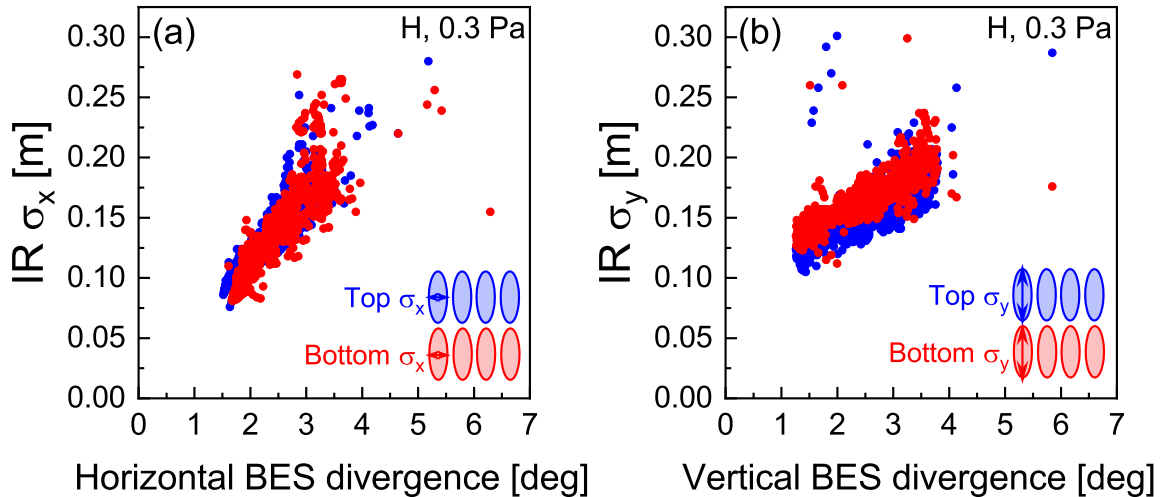


Figure 12: Comparison between IR calorimetry and BES. In (a) the horizontal width σ_x is plotted as a function of the BES horizontal divergence. In (b) the vertical width σ_y is plotted as a function of the BES vertical divergence. About 4000 pulses performed in hydrogen at 0.3Pa between January 2017 and July 2018.

16 Around 4000 hydrogen beam pulses performed at the 0.3 Pa are used to crosscheck
 17 the IR calorimetry technique with the BES diagnostics, particularly regarding the
 18 relation between beam width and BES divergence. The beam segment width σ from
 19 IR calorimetry as a function of the beam divergence from BES is displayed in figure
 20 12, separately for the horizontal σ_x in (a) and the vertical σ_y in (b). The horizontal
 21 divergence from BES is the average of the divergence measured by three LOS looking
 22 at the center of the top and bottom beam segments while the vertical divergence is an

1 average of the values obtained from the two central vertical LOS. The vertical BES LOS
 2 measure the whole beam, so it is not possible to distinguish between the contribution
 3 from the top and the bottom segments.

4 In both directions, there is good overall agreement between the beam width estimated
 5 by IR calorimetry and the beam divergence from BES, thus the beam width is, to a
 6 large extent, determined by the beam divergence. Nevertheless, the data points are
 7 scattered in a range of about 5 cm for the same beam divergence: this can be explained
 8 by a vertical non-homogeneity in beamlet intensity (a_i of equation 7) within the beamlet
 9 groups. The bottom vertical width σ_y (red points in figure 12(b)) is systematically larger
 10 of about 2 cm than the top one for the same BES divergence, thus not within the error
 11 bar. This is a general effect and the reason is attributed to the vertical inhomogeneity
 12 of the source plasma parameters.

13 The combined use of BES diagnostics and IR calorimetry gives additional insight into
 14 the beam properties: BES is sensitive to variations of divergence without any spatial
 15 resolution along the LOS, while IR calorimetry gives the 2D power map at a fixed
 16 position with spatial resolution but without information on the divergence. Thus a
 17 variation in power density cannot be directly attributed to a different divergence or
 18 different power homogeneity.

19 In the following example, the concurrent use of the two diagnostics is applied to study
 20 the evolution of the beam power homogeneity during an RF power variation. In figure 13
 21 the vertical power density profile from IR calorimetry (bottom), beam intensity profile
 22 measured by BES (center) and beam divergence profile from BES (top) are shown. The
 23 beam intensity profiles given by BES (figure 13 center) and by IR calorimetry (figure
 24 13 bottom) show a similar evolution with the RF power and the divergence profile is in
 25 general flatter at higher RF power. The behavior of the beam segments is described in
 26 the following:

- 27 • The top beam segment saturates in intensity and the beam segment width increases
 28 with power from 0.117 cm to 0.128 cm. This increase of the vertical width is
 29 not caused by an increase in the beam divergence, which is only slightly varying
 30 (see figure 13 top), but due to flattening of the beam intensity profile. BES
 31 measurements together with IR calorimetry suggest that the vertical power profile
 32 gets more homogeneous with increasing RF power, as the extracted current within
 33 the beam segment is more homogeneous at 240 kW than at 160 kW.
- 34 • The bottom beam segment shows a different evolution with increasing RF power:
 35 the intensity increases (see figure 13 center and bottom) and the beam divergence
 36 slightly improves from 0.146 m to 0.12 m with the RF power (see figure 13 top). In
 37 this case the vertical width decreases because the beam divergence improves with
 38 RF power. The beam segment intensity increases with RF power being the beamlets
 39 more focused and the extracted current higher. The vertical beam width follows
 40 the variation of the beam divergence thus suggesting that the vertical homogeneity
 41 of the bottom beam segment is not changed.

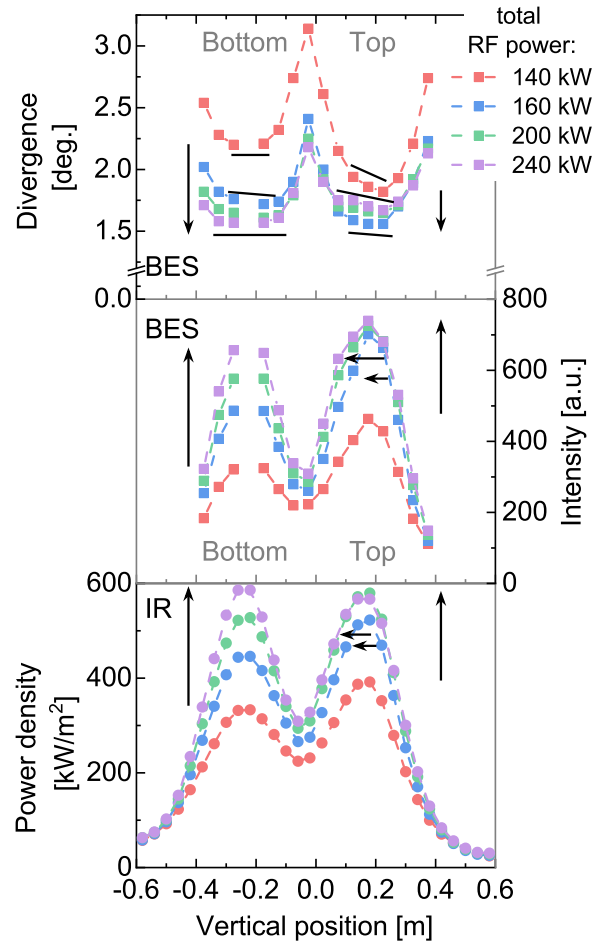


Figure 13: RF power scan performed in deuterium at 0.3 Pa source filling pressure, shot 22617-22624 in the range between 140 kW and 240 kW RF power, $U_{\text{ext}} = 6$ kV, $U_{\text{acc}} = 30$ kV and $I_{PG} = 3.7$ kA. In (a) the vertical beam profile for the divergence (top), beam intensity measured by BES (center) and power profile measured by IR calorimetry (bottom) are shown. The LOS positioned at 22.5 cm is not available. The evolution of the beam divergence and intensity profiles is highlighted with purple arrows.

- 1 The beam segments reach the divergence optimum at different level of RF power. The
- 2 reason behind the asymmetry between top and bottom is generally attributed to the
- 3 vertical non homogeneity of the source plasma parameters. Any further discussion on
- 4 this is beyond the scope of this work.
- 5 As shown in this case, the combined use of BES and IR calorimetry gives additional
- 6 insight into the beam properties: the homogeneity can be monitored and the variation
- 7 in power density observed by IR calorimetry can be addressed to variations of diver-
- 8 gence or extracted current density by combining with BES information. The limiting
- 9 point is the large beamlet overlap at the level of the diagnostic planes that prevent the
- 10 evaluation of current density and divergence at single beamlet level.

6. Conclusions

IR calorimetry and BES diagnostics applied to the large multi-aperture beam at ELISE provide measurements of the beam divergence and accelerated current with an accuracy of 10% on the measured values. The IR calorimetry evaluation technique is developed, described and verified, thus providing measurements of the beamlet group width, beamlet group power density, and vertical beam position with an accuracy of 1.2 cm on the position and 10% on the power density. Due to the large beamlet overlap occurring at the diagnostic planes, the beam properties are averaged over groups of beamlet, thus not representative of the single beamlets.

The calibration procedure applied to determine the effective surface emissivity of the calorimeter is accurate, i.e. 5% error bar, and reliable as demonstrated by the crosscheck of the IR calorimetry results with water calorimetry. A fitting routine which describes the beamlet group profile as Gaussian is applied to the 2D map obtained from the IR calorimetry to retrieve the beamlet group width, beamlet group intensity, vertical beam position and accelerated current. The fit properly describes cases with a simulated beamlet divergence higher than about 1.5 degrees. For cases with lower simulated beamlet divergence the beamlet group profile is not Gaussian, therefore the fitting routine is not applicable. The fitting routine correctly reproduces the power density profile of cases with strong asymmetries between beam segments independently of the beam divergence, thus is a valuable tool to retrieve the beam properties from the IR 2D map.

Results from IR calorimetry and BES are compared over a large set of experimental beam pulses to verify that the beamlet group width is proportional to the beam divergence, thus the beam width at the calorimeter is determined mainly by the beam divergence for cases with BES divergence higher than 1 degree. For certain parameter variations, IR calorimetry and BES diagnostic have to be applied jointly to assess properly if a variation of the power density observed at the calorimeter is due to a change in divergence or a change in power density homogeneity.

To reduce the effect of the beamlet overlapping on the BES results, the LOS should be positioned closer to the grid system and with a smaller volume of observation of the lens head. However this will make the analysis more difficult due to the partial interception of the beamlets with the LOS. A larger number of LOS can improve the spatial resolution. For large beams where beamlet overlapping is inevitable an increase in diagnostic precision will still not be able to give beamlet level information. Therefore, coupling diagnostic measurements with simulation code such as IBSIMU [11] and BBCNI [17] is necessary for a better insight of the single beamlet properties.

On the side of the diagnostic calorimeter a smaller block size would be beneficial for the spatial resolution, but will still not allow single beamlet measurements. Furthermore, having the diagnostic calorimeter closer to the grid will only increase the power density deposited locally and the risk of localized damages on the surface. For the calorimetric study of single beamlets other tools should be used, with the drawback of limiting the

1 power deposition and/or the beam-on time. An example of such tools are tungsten wire
 2 calorimeters [25] or one-dimensional carbon fiber-composite tile [26] placed at a short
 3 distance from the last grid to limit the beamlet overlap.

4 7. Acknowledgements

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 6 studies on the IR technique here presented.

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 8 and has received funding from the Euratom research and training programme 2014-
 9 2018 and 2019-2020 under grant agreement number 633053. The views and opinions
 10 expressed herein do not necessarily reflect those of the European Commission.

11 List of the most relevant symbols

	δ	Single beamlet width
	a_i	peak amplitude of the single Gaussian function describing the beamlets
	ϑ	beamlet divergence
	σ	Beamlet group width
12	y_{top}/y_{bot}	Beam segment position vertical position
	A_i , with $i = 1 \dots 8$	Amplitude of each Gaussian function describing the beamlet groups
	Vol_{top}/Vol_{bot}	Integral to infinity of the top/bottom beam segments
	ε	surface emissivity
13	τ_{opt}	ZnSe window transmissivity

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