

F-Manifolds and geometry of information

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Abstract

The theory of F-manifolds, and more generally, manifolds endowed with commutative and associative multiplication of their tangent fields, was discovered and formalised in various models of quantum field theory involving algebraic and analytic geometry, at least since the 1990s.

The focus of this paper consists in the demonstration that various spaces of probability distributions defined and studied at least since the 1960s also carry natural structures of F-manifolds.

This fact remained somewhat hidden in various domains of the vast territory of models of information storing and transmission that are briefly surveyed here.

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1. Introduction and summary

The structure of Frobenius manifolds and its later weakened versions weak Frobenius manifolds, also called F-manifolds, was discovered in the 1980s and 1990s in the process of development and formalisation of Topological Field Theory, including Mirror Conjecture: see [17, 19], and references therein.

Below, speaking about (super)manifolds M, we understand objects of one of the standard geometric categories: C^{∞} , analytic, algebraic, formal, etc.

According to Dubrovin [17, 26], the main component of a Frobenius structure on M is a (super)commutative, associative and bilinear over constants multiplication $\circ : \mathcal{T}_M \otimes \mathcal{T}_M \to \mathcal{T}_M$ on its tangent sheaf \mathcal{T}_M .

Additional parts of the structure in terms of which further restrictions upon \circ might be given, are listed below.

- A subsheaf of flat vector fields $\mathcal{T}_M^f \subset \mathcal{T}_M$ consisting of tangent vectors flat in a certain affine structure.
 - A metric (nondegenerate symmetric quadratic form) $g: S^2(\mathcal{T}_M) \to \mathcal{O}_M$.

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- An identity e.
- An Euler vector field E.

Relationships between/restrictions on all these structures depend on the context in which they appeared in various research domains. Accordingly, the versions of structures themselves were called by various names: besides Frobenius manifolds and F-manifolds, the reader can find pre-Frobenius, weak Frobenius [26], and most recently, Frobenius-like structures of order (n, k, m) (in the latter, the tangent sheaf is replaced by an external sheaf, [20]). Therefore, we will not be very strict with terminology.

The popularity of Frobenius manifolds among algebraic/analytic geometers was growing after initial discovery of three large classes of them, naturally arising in mathematics and physics.

- (i) A choice of Saito's good primitive form determines a natural Frobenius structure on moduli (unfolding) spaces of germs of isolated singularities of hypersurfaces (topological sector of the Landau–Ginzburg theory for physicists): see [35, 39, 40].
- (ii) The formal moduli spaces of solutions to the Maurer-Cartan equations modulo gauge equivalence have natural formal Frobenius structure, if these Maurer-Cartan equations are stated in the dGBV (differential Gerstenhaber-Batalin-Vilkovisky) framework: see [4, 23].
- (iii) The formal completion at zero of the cohomology (super)space of any smooth projective (or compact symplectic) manifold carries a natural formal Frobenius supermanifold (theory of Gromov–Witten invariants): for early mathematical sources see [5, 6, 22]. Here we add to this list
- (iv) Convex homogeneous cones [7, 44, 45] and the spaces of probability distributions (see [8] and the monographs [2, 3, 12]).

We show that, under some restrictions, these spaces carry structures of F-manifolds.

In fact, on the map of 'Information Geometry Land', there is another domain, connecting this land *not* with rigid structures such as metric geometries (which are in the focus of this paper), but with rather more fluid ones, of homological and especially homotopical algebra. Intuitively, one starts with imagining, say, configurations of neural nets in brain as simplicial complexes, accompanied by highly non-obvious heuristic observation that *complexity of information* that can be successfully treated by such a net grows with *complexity of homotopy class* of its geometric realisation.

For an introduction to this domain aimed to mathematicians, cf. [28, 29].

The contents of our survey are distributed as follows.

Section 2 of this article contains a survey of geometry of Frobenius-like manifolds. In Section 3, we focus on the appearance of this structure on the unfolding spaces of isolated singularities, and stress the role of so-called *potentials* that reappear further in information geometry. Section 4 introduces F-structures on convex homogeneous cones and spaces of probability distributions stressing the environment in which these F-structures look similar to the ones of previous section, but with replacement of framework of complex varieties with the one of real geometry. Finally, Section 5 introduces 'paracomplex' structures bridging complex and real geometry in this context, and revealing paracomplex potentials.

2. Frobenius manifolds and F-manifolds

2.1. Frobenius manifolds

We start, as above, with a family of data

$$(M; \circ: \mathcal{T}_M \otimes \mathcal{T}_M \to \mathcal{T}_M; \quad \mathcal{T}_M^f \subset \mathcal{T}_M; \quad g: S^2(\mathcal{T}_M) \to \mathcal{O}_M),$$
 (1)

mostly omitting identity e and Euler field E.

The main additional structure bridging these data together is a family of (local) potentials Φ (sections of \mathcal{O}_M) such that for any (local) flat tangent fields X, Y, Z we have

$$g(X \circ Y, Z) = g(X, Y \circ Z) = (XYZ)\Phi.$$

If such a structure exists, then (super)commutativity and associativity of \circ follows automatically, and we say that the family (1) defines a Frobenius manifold.

2.2. F-identity

This identity relates multiplication \circ and the Lie (super)commutator that in the theory of Frobenius manifolds follows from the basic definitions, and in the theory of F-manifolds is postulated.

It is convenient to introduce first the auxiliary Poisson tensor $P: \mathcal{T}_M \times \mathcal{T}_M \times \mathcal{T}_M \to \mathcal{T}_M$

$$P_X(Z, W) := [X, Z \circ W] - [X, Z] \circ W - (-1)^{XZ} Z \circ [X, W].$$

Here and further on we write $(-1)^{XZ}$ in place of $(-1)^{|X||Z|}$, where |X| denotes the parity $(\mathbb{Z}_2$ -degree) of X.

About relationship between Poisson tensors and manifolds with Poisson structure, (cf. [26, subsection 5.5, p. 47; 27, Section 5]).

DEFINITION 2.1. Let M be a (super)manifold endowed with (super)commutative and associative multiplication \circ in its tangent sheaf.

M with this structure is called an F-manifold, if it satisfies the F-identity:

$$P_{X \circ Y} = X \circ P_Y(Z, W) + (-1)^{XY} Y \circ P_X(Z, W).$$

2.3. Compatible flat structures

An affine flat structure on a manifold M, by definition, is a local system $\mathcal{T}_M^f \subset \mathcal{T}_M$ of finite-dimensional (over constants) supercommutative Lie algebras of rank $\dim M$ such that $\mathcal{T}_M = \mathcal{O}_M \otimes \mathcal{T}_M^f$.

In the situation of 1.1, but not postulating F-identity, assume that in a neighbourhood of any point of M there exists a vector field C such that the \circ -product of arbitrary local flat fields X, Y defined in this neighbourhood can be written as

$$X \circ Y = [X, [Y, C]].$$

Such C is called a local vector potential for \circ . Then we will call \mathcal{T}_M^f compatible with \circ . If \circ admits a flat identity e, we will call \mathcal{T}_M^f compatible with (\circ, e) .

PROPOSITION 2.2. In the situation of Definition 2.1, if \circ admits a compatible flat structure, then it satisfies the F-identity. Thus, $(M, \mathcal{T}_M, \circ)$ is an F-manifold.

In the context of geometry of statistics/information, the following equivalent descriptions of flat structure might be useful.

- An atlas of local coordinates, whose transition functions are affine linear (over constants).
- A torsionless flat connection $\nabla_0 : \mathcal{T}_M \to \Omega^1_M \otimes_{\mathcal{O}_M} \mathcal{T}_M$.

Indeed, given ∇_0 , we can define \mathcal{T}_M^f as $Ker \nabla_0$.

3. F-manifolds and singularities

3.1. K. Saito's frameworks

We will describe here in considerable detail a class of (pre-)Frobenius structures that was introduced by Saito in the context of unfolding isolated singularities and periods of primitive forms (see [25, 39, 40]). Our choice is motivated by the fact that the central objects of Section 4 coming from a very different environment (convex cones and probability spaces) look strikingly similar to real versions of Saito's frameworks.

Intuitively, Saito's F-structures are canonical data arising on unfolding spaces of isolated singularities, both in analytic and algebraic geometry, in characteristic zero.

More precisely, let $p:N\to M$ be a submersive morphism of complex analytic (or algebraic) varieties (we do not assume them to be compact). Denote by $d_p:\mathcal{O}_M\to\Omega^1_{N/M}$ its relative differential. For a holomorphic function F on M, the equation $d_pF=0$ defines the closed analytic subspace $i_C:C=C_{N/M}(F)\hookrightarrow N$ of fibrewise critical points of F; denote by $p_C:C\to M$ the restriction of p to C. We will need also the invertible sheaf of holomorphic vertical volume forms Ω_N^{\max}/M and its restriction $L:=i_C^*(\Omega_{N/M}^{\max})$ to C. Finally, we will assume given a nowhere vanishing global section ω of $\Omega_{N/M}^{\max}$.

The following definition and proposition (due to Saito) are borrowed from [25, 2.1.1].

DEFINITION 3.1. The family of data $(p: N \to M; F; \omega)$ as above is called Saito's framework if it satisfies the following additional conditions.

- (1) Define the map $s: \mathcal{T}_M \to p_{C*}(\mathcal{O}_C)$ by $X \mapsto \overline{X}F \mod J_F$ where J_F is the ideal defining C. Assume that C is finite and flat over M.
- (2) Now consider the Hessian of function F. In local coordinates $z=(z_a),\ a=1,\ldots,m;$ $t=(t_b)$ such that (t_b) is a maximal set of coordinates constant along fibres of p, the Hessian can be defined as a section of L^2 that can be written as

$$\operatorname{Hess}(F) := i_C^* [\det(\partial^2 F/\partial z_a \partial z_b) (dz_1 \wedge \cdots \wedge dz_n)^2].$$

Make an additional assumption that the subspace G_C of zeroes of $\operatorname{Hess}(F)$ is a divisor, and that p_C is étale outside the divisor $G := i_{C*}(G_C)$ in M.

PROPOSITION 3.2. Let $(p: N \to M; F; \omega)$ be a Saito's framework. Consider a local tangent field X on M over whose definition domain p_{C*} is a disjoint union of isomorphisms. Then we can define an 1-form ϵ on $M \setminus G$ whose value on these disjoint components is given by

$$i_X(\epsilon) := \operatorname{Tr}_{C/M}(p_C i_C^*(\omega^2)/\operatorname{Hess}(F)).$$

Moreover, we can define commutative and associative product \circ by

$$\overline{X \circ Y}F = \overline{X}F \cdot \overline{Y}F \mod J_F.$$

Then the scalar product $g: S^2(\mathcal{T}_M) \to \mathcal{O}_{M \setminus G}$ defined by

$$g(X,Y) := i_{X \circ Y}(\epsilon)$$

is a flat metric, which together with g extends regularly to M.

3.2. Potentiality and associativity

We describe now the axiomatisation of Saito's frameworks due to Dubrovin: cf. [26, Definition 1.3 and further on, p. 19].

DEFINITION 3.3. A pre-Frobenius manifold is a (super)manifold M endowed with an affine flat structure \mathcal{T}_M^f as in 2.3 above; with a compatible metric g (that is, g is constant upon flat fields); and with an even symmetric tensor tensor $A: S^3(\mathcal{T}_M) \to \mathcal{O}_M$.

This pre-Frobenius manifold is called potential one, if everywhere locally there exists an even section Φ of \mathcal{O}_M such that restriction of A on \mathcal{T}_M^f can be written as

$$A(X,Y,Z) = (XYZ)\Phi.$$

Upon flat vector fields of such a manifold, we can introduce an even multiplication \circ bilinear over constants such that

$$A(X, Y, Z) = g(X \circ Y, Z) = g(X, Y \circ Z).$$

It is commutative and associative, and can be extended to an \mathcal{O}_M -bilinear, commutative and associative product $\mathcal{T}_M \otimes_{\mathcal{O}_M} \mathcal{T}_M \to \mathcal{T}_M$ also denoted \circ .

If we choose local flat coordinates (x^a) and respective local basis of tangent fields (∂_a) , we can write

$$(\partial_a \circ \partial_b \circ \partial_c) \Phi = \partial_a \partial_b \partial_c \Phi,$$

and then compatibility of Φ and g will mean that

$$\partial_a \circ \partial_b = \sum_c \Phi^c_{ab} \partial_c, \quad \Phi^c_{ab} := \sum_e (\partial_a \partial_b \partial_c \Phi) g^{ec}, \quad (g^{ab}) := (g_{ab})^{-1}.$$

Note that the last formula should be read as an inverted matrix.

Rewriting the associativity of \circ in the usual way as $(\partial_a \circ \partial_b) \circ \partial_c = \partial_a \circ (\partial_b \circ \partial_c)$, we obtain a non-linear system of Associativity Equations, partial differential equations for Φ :

$$\forall a,b,c,d: \quad \sum_{ef} \Phi_{abe} g^{ef} \Phi_{fcd} = (-1)^{a(b+c)} \sum_{ef} \Phi_{bce} g^{ef} \Phi_{fad}.$$

In the community of physicists, they are known as WDVV (Witten-Dijkgraaf-Verlinde-Verlinde) equations.

3.3. Structure connections, flatness and potentiality

To conclude this section, we describe below important criteria of potentiality and associativity expressed in terms of the structure connection of a pre-Frobenius manifold.

First, introduce the connection $\nabla_0: \mathcal{T}_M \to \Omega^1_M \otimes_{\mathcal{O}_M} \mathcal{T}_M$, uniquely defined by the horizontality of \mathcal{T}_M^f . Of course, it extends to the differential upon $\Omega^*_M \otimes_{\mathcal{O}_M} \mathcal{T}_M$ in the standard way.

One easily sees that ∇_0 can be further extended to a pencil of connections ∇_{λ} depending on an even parameter λ : the respective covariant derivative is

$$\nabla_{\lambda,X}(Y) := \nabla_{0,X}(Y) + \lambda X \circ Y.$$

We will refer to this pencil as the structure connection of our pre-Frobenius manifold.

Here is our final result that can be checked by direct calculations (cf. [26, 1.5 and 1.6]). Put $\nabla_{\lambda}^2 = \lambda^2 R_2 + \lambda R_1$.

PROPOSITION 3.4. (1) Potentiality of (M, g, A) is equivalent to the vanishing of R_1 , that in turn is equivalent to the identity holding for all local tangent fields:

$$\nabla_X (Y \circ Z) - (-1)^{XY} \nabla_Y (X \circ Z) + X \circ \nabla_Y Z - (-1)^{XY} Y \circ \nabla_X Z - [X, Y] \circ Z = 0.$$

(2) Associativity of (M, g, A) is equivalent to the vanishing of R_2 .

4. Convex cones and families of probabilities

4.1. Basic example: probability distributions on finite sets

Consider a finite set X. A probability distribution P_X on X is a map $P_X: X \to \mathbb{R}, x \mapsto p_x \in [0,1]$, such that $\sum_{x \in X} p_x = 1$.

The simplest geometric image of the set of all probability distributions on X is the simplex Δ_X spanned by the end-points of basic coordinate vectors in \mathbb{R}^X . We will also consider its maximal open subset ${}^{\circ}\Delta_X$:

$$^{\circ}\Delta_X := \{(p_x) \mid 0 < p_x < 1 \text{ for all } x \in X\}.$$

The existence of highly non-trivial geometries (in particular, F-geometry) naturally supported by such simplices was one of the first discoveries in the domain of future 'Geometry of Information'. (As we mentioned, another developments led through homological and homotopical algebra.)

The earliest sources here are [10] and [11]; see also the monograph [12, 30–32]. One of the contemporary expositions is given in [29]. In order to avoid set-theoretical difficulties, we will be working in a fixed small universe.

We start with geometry.

4.2. Convex cones, potentiality and F-structures

The union of all oriented half-lines in \mathbb{R}^X starting at $(0, \dots, 0)$ and containing a point of ${}^{\circ}\Delta_X$ is a particular case of the general class of open *convex cones*. We use this terminology here in the sense of [44, Chapter 1, Introduction, Definition 1].

Namely, let R be a finite-dimensional real linear space (former \mathbb{R}^X). By definition, a cone $V \subset R$ is a non-empty subset, closed with respect to addition and multiplication by positive reals. Moreover, the closure of V should not contain a real linear subspace of positive dimension.

Following [44, Ch.1, section 2], we will now introduce the definition and state main properties of *characteristic functions* of general convex cones.

Let again R be an oriented finite-dimensional real affine space, R' its dual space. We will denote the value of $x' \in R'$ upon $x \in R$ as $\langle x, x' \rangle$.

DEFINITION 4.1. Let $V \subset R$ be a convex cone and $vol_{V'}$ be a differential form of maximal degree (a volume form) invariant with respect to translations in R'.

The function $\varphi: V \to \mathbb{R}$ defined by

$$\varphi_{V}(x) := \int_{V'} e^{-\langle x, x' \rangle} vol_{V'}$$

is called a characteristic function of V.

Since translation invariant volume forms are defined up to a positive constant factor, the same is true for characteristic functions.

Consider now the cone V as a smooth manifold, whose tangent space at any point x can (and will) be canonically identified with R, by the parallel transport identifying $x \in V$ with $0 \in R$. Fixing an affine coordinate system (x^i) in R, put

$$g_{ij} := \partial^2 \ln \varphi_V / \partial x^i \partial x^j .$$

The main result from [44], needed here, is the following theorem.

THEOREM 4.2. (1) The symmetric quadratic form $\sum_{i,j} g_{ij} dx^i dx^j$ determines a Riemannian metric on V.

(2) The respective metric defines the torsionless canonical connection on the tangent bundle \mathcal{T}_V whose components in any affine coordinate system are

$$\Gamma^{i}_{jk} = \frac{1}{2} \sum_{l} g^{il} \frac{\partial^{3} \ln \varphi}{\partial x^{j} \partial x^{k} \partial x^{l}},$$

with

$$\sum_{i} g^{ij} g_{jk} = \delta^i_k.$$

(3) Hence the formula

$$\sum_{i} a^{i} \partial_{x_{i}} \circ \sum_{j} b^{j} \partial_{x_{j}} := -\sum_{i,j,k} \Gamma^{i}_{jk} a^{j} b^{k} \partial_{x_{i}}$$

defines on \mathcal{T}_V a commutative \mathbb{R} -bilinear composition.

At this point, the reader should turn back and compare the statement of Theorem 4.2 constructions involving the Hessian in the Definition 3.1, and subsequent treatment of Associativity Equations and potentiality. Clearly, geometry of convex cones (in particular, cones generated by probability distributions upon finite sets) provides strong analogies with theory of unfolding spaces of singularities.

In particular, convex cones admit families of F-structures depending on the choice of an affine coordinate system on R.

4.3. σ -algebras and categories of probability distributions

In order to extend the notion of a probability distribution on possibly infinite sets X, and to pass to categorical constructions, we must recall the definition of a σ -algebra.

Here is a summary of main participants of the game (omitting certain details).

Consider a set X and a collection of its subsets \mathcal{F} satisfying the following restrictions.

 $X \in \mathcal{F}$; if $U, V \in \mathcal{F}$, then $U \setminus V \in \mathcal{F}$, so in particular $\emptyset \in \mathcal{F}$; for any *countable* subcollection of \mathcal{F} , the union of its elements belongs to \mathcal{F} .

Such a pair (X, \mathcal{F}) is called a σ -algebra.

From the definition it follows that:

- (a) intersection of all elements of a countable subcollection of \mathcal{F} belongs to \mathcal{F} ;
- (b) if a collection \mathcal{F} is a countable partition of X, and \mathcal{F}' is the collection formed by all unions of parts of this partition, then (X, \mathcal{F}') is a σ -algebra.

Given a σ -algebra (X, \mathcal{F}) , we will be considering measures and probability measures/distributions on it.

Generally, let (S,+,0) be a commutative semigroup with composition law + and zero element. Then an S-valued measure μ on (X,\mathcal{F}) is a map $\mu:\mathcal{F}\to S$ such that $\mu(\emptyset)=0$, and $\mu(X\cup Y)+\mu(X\cap Y)=\mu(X)+\mu(Y)$.

Such a measure is called a probability distribution p if S is the additive semigroup of non-negative real numbers, and moreover, for any countable subfamily (U_i) , i = 1, 2, 3, ... of elements of \mathcal{F} with empty pairwise intersections, we have $p(\bigcup_{i=1}^{\infty} U_i) = \sum_{i=1}^{\infty} p(U_i)$; and if such a countable subfamily covers X, then the sum of probabilities is 1.

DEFINITION 4.3. Category CAP of probability distributions [11] consists of the following data.

(1) An object of CAP is the set $Cap(X, \mathcal{F})$ of all probability distributions on a σ -algebra (X, \mathcal{F}) .

(2) One (Markov) morphism $\Pi \in Hom_{CAP}(Cap(X_1, \mathcal{F}_1), Cap(X_2, \mathcal{F}_2))$ is given by a 'transition measure', that is a function $\Pi\{*|x'\}$ on $\mathcal{F}_2 \times X_1$ such that for a fixed $U \in \mathcal{F}_2$, $\Pi\{U|x_1\}$ is \mathcal{F}_1 -measurable function on X_1 , and for a fixed $x_1 \in X_1$, $\Pi\{U|x_1\}$ is a probability distribution upon \mathcal{F}_2 .

Explicitly, such Π sends the probability distribution $P_1 \in Cap(X_1, \mathcal{F}_1)$ to the probability distribution $P_2 \in Cap(X_2, \mathcal{F}_2)$ given by

$$P_2(X_2|x_1) := \int_{X_1} \Pi\{*|x_1\} P_1\{dx_1\}.$$

For (more or less evident) description of identical morphisms and composition of morphisms, see [11].

Below, we will return from general convex cones to the ones obtained from Δ_X by passing to the union of all oriented half-lines in \mathbb{R}^X connecting the origin with a point in ${}^{\circ}\Delta_X$. Clearly, the boundary of such a cone is a union of cones of the same type with vertices corresponding to elements of all subsets $\{i_1, \ldots, i_m\} = \{1, \ldots, n\}$. Geodesics of the respective metrics are simply segments of affine lines in R, although the metrics themselves blow up to infinity near each respective face.

This makes it possible to bridge two different paths from the intuitive image 'description of a global space by approximating it with finite subsets of points'.

- (1) Passing from probability distributions on finite subsets to the probability distribution on the whole σ -algebra [15, 6.1.2].
- (2) Passing from a simplicial set to the topology of its geometric realisation [18, I.2, Definition 1, p. 6].

In order to enrich simplicial algebra with information geometry, it is necessary to use the categorical lift of simplicial constructions from the category of finite sets to a category CAP. We hope to return to this challenge later.

5. Statistical manifolds and paracomplex structures

5.1. Paracomplex geometry

The algebra of paracomplex numbers (cf. [16]) is defined as the real vector space $\mathfrak{C} = \mathbb{R} \oplus \mathbb{R}$ with the multiplication

$$(x,y) \cdot (x',y') = (xx' + yy', xy' + yx').$$

Put $\varepsilon := (0,1)$. Then $\varepsilon^2 = 1$, and moreover

$$\mathfrak{C} = \mathbb{R} + \varepsilon \mathbb{R} = \{ z = x + \varepsilon y \, | \, x, y \in \mathbb{R} \}.$$

Given a paracomplex number $z_+ = x + \varepsilon y$, its conjugate is defined by $z_- := x - \varepsilon y$. We denote by $\mathfrak{C}^* = \{x + \varepsilon y \mid x^2 - y^2 \neq 0\}$ the group of invertible elements of \mathfrak{C} .

Let E_{2m} be a 2m-dimensional real affine space. A paracomplex structure on E_{2m} is an endomorphism $\mathfrak{K}: E_{2m} \to E_{2m}$ such that $\mathfrak{K}^2 = I$, and the eigenspaces E_{2m}^+, E_{2m}^- of \mathfrak{K} with eigenvalues 1, -1 respectively, have the same dimension. The pair (E_{2m}, \mathfrak{K}) will be called a paracomplex affine space.

Finally, a paracomplex manifold is a real manifold M endowed with a paracomplex structure \mathfrak{K} that admits an atlas of paraholomorphic coordinates (which are functions with values in the algebra $\mathfrak{C} = \mathbb{R} + \varepsilon \mathbb{R}$ defined above), such that the transition functions are paraholomorphic.

Explicitly, this means the existence of local coordinates $(z_+^{\alpha}, z_-^{\alpha})$, $\alpha = 1..., m$ such that paracomplex decomposition of the local tangent fields is of the form

$$T^+M = \operatorname{span}\left\{\frac{\partial}{\partial z_+^{\alpha}}, \ \alpha = 1, \dots, m\right\},\,$$

$$T^{-}M = \operatorname{span} \left\{ \frac{\partial}{\partial z_{-}^{\alpha}} , \alpha = 1, \dots, m \right\}.$$

Such coordinates are called adapted coordinates for the paracomplex structure \mathfrak{K} .

If E_{2m} is already endowed with a paracomplex structure \mathfrak{K} as above, we define the paracomplexification of E_{2m} as $E_{2m}^{\mathfrak{C}} = E_{2m} \otimes_{\mathbb{R}} \mathfrak{C}$ and we extend \mathfrak{K} to a \mathfrak{C} -linear endomorphism \mathfrak{K} of $E_{2m}^{\mathfrak{C}}$. Then, by setting

$$E_{2m}^{1,0} = \{ v \in V^{\mathfrak{C}} \mid \mathfrak{K}v = \varepsilon v \} = \{ v + \varepsilon \mathfrak{K}v \mid v \in E_{2m} \},$$

$$E_{2m}^{0,1} = \{ v \in V^{\mathfrak{C}} \mid \mathfrak{K}v = -\varepsilon v \} = \{ v - \varepsilon \mathfrak{K}v \mid v \in E_{2m} \},$$

we obtain $E_{2m}^{\mathfrak{C}} = E_{2m}^{1,0} \oplus E_{2m}^{0,1}$.

We associate with any adapted coordinate system $(z_+^{\alpha}, z_-^{\alpha})$ a paraholomorphic coordinate system z^{α} by

$$z^{\alpha} = \frac{z_{+}^{\alpha} + z_{-}^{\alpha}}{2} + \varepsilon \frac{z_{+}^{\alpha} - z_{-}^{\alpha}}{2}, \alpha = 1, \dots, m.$$

We define the paracomplex tangent bundle as the \mathbb{R} -tensor product $T^{\mathfrak{C}}M = TM \otimes \mathfrak{C}$ and we extend the endomorphism \mathfrak{K} to a \mathfrak{C} -linear endomorphism of $T^{\mathfrak{C}}M$. For any $p \in M$, we have the following decomposition of $T_p^{\mathfrak{C}}M$:

$$T_p^{\mathfrak{C}}M=T_p^{1,0}M\oplus T_p^{0,1}M$$

where

$$\begin{split} T_p^{1,0}M &= \{v \in T_p^{\mathfrak{C}}M | \mathfrak{K}v = \varepsilon v\} = \{v + \varepsilon \mathfrak{K}v | v \in E_{2m}\}, \\ T_p^{0,1}M &= \{v \in T_p^{\mathfrak{C}}M | \mathfrak{K}v = -\varepsilon v\} = \{v - \varepsilon \mathfrak{K}v | v \in E_{2m}\} \end{split}$$

are the eigenspaces of \mathfrak{K} with eigenvalues $\pm \varepsilon$. The following paracomplex vectors

$$\frac{\partial}{\partial z_{+}^{\alpha}} = \frac{1}{2} \left(\frac{\partial}{\partial x^{\alpha}} + \varepsilon \frac{\partial}{\partial y^{\alpha}} \right), \quad \frac{\partial}{\partial z_{-}^{\alpha}} = \frac{1}{2} \left(\frac{\partial}{\partial x^{\alpha}} - \varepsilon \frac{\partial}{\partial y^{\alpha}} \right)$$

form a basis of the spaces $T_p^{1,0}M$ and $T_p^{0,1}M$.

Useful constructions from the theory of paracomplex differential forms are collected in [1], as well as [13, 14, 24]). In particular, one can define the Dolbeault paracomplex (see [14] for details).

5.2. Convex cones and paracomplex geometry

Before applying this machinery to the spaces of probability distributions on finite sets (cf. Section 4.1), we should explain why we cannot extend it to the more general setting of (subspaces of) finite-dimensional convex cones.

The main reason is this: in order to establish the connection with F-manifolds, we need to have a paracomplex analogue of Theorem 4.2 in which real differential forms and Riemannian metrics would be replaced by their paracomplex versions. But it turns out that this is possible only for a narrow subclass of convex cones that unmistakably singles out probability distributions on finite sets.

This subclass is the last one in the Vinberg's list of such cones that are irreducible ones with respect to direct sums (cf. [43-45]).

PROPOSITION 5.1. Each irreducible homogeneous self-dual cone belongs to one of the following classes.

- (1) The cone $M_+(n,\mathbb{R})$ of $n \times n$ real positive matrices.
- (2) The cone $M_+(n,\mathbb{C})$ of $n \times n$ complex positive matrices.
- (3) The cone $M_+(n, \mathbb{H})$ of $n \times n$ quaternionic positive matrices.
- (4) The cone $M_+(3,\mathbb{O})$ of 3×3 positive matrices whose elements are in \mathbb{O} , the Cayley algebra (also known as the Octonionic algebra).
 - (5) The cone $M_+(n,\mathfrak{C})$ of $n \times n$ paracomplex positive matrices.

Recall that a matrix is positive if it is self-adjoint and its eigenvalues are positive.

DEFINITION 5.2. The structure of Jordan algebras [21] on a real linear space \mathfrak{M} is determined by two polylinear operations.

- (1) Binary multiplication $(a, b) \rightarrow a \cdot b$.
- (2) Ternary multiplication $(a, b, c) \rightarrow a(bc)$, satisfying the compatibility axiom

$$a \cdot ((a \cdot a) \cdot b) = (a \cdot a) \cdot (a \cdot b).$$

Such an algebra is called formally real if from $\sum_{i=1}^{n} a_i \cdot a_i = 0$ it follows that all $a_i = 0$.

THEOREM 5.3. (1) The list of algebras in Proposition 5.1 coincides with the list of all irreducible finite-dimensional formally real algebras.

(2) The irreducible homogeneous self-dual cone associated with such an algebra \mathfrak{M} is the set of positive elements of a Jordan algebra, that is, elements represented by positive matrices.

Proof. For the proof of this theorem, we refer directly to [43, 45].

From the works studying affine spaces over an algebra of finite rank [9, 34, 36, 37, 42], we have the following statement:

PROPOSITION 5.4. Consider an affine, symmetric space over a Jordan algebra. There exists exactly two affine and flat connections on this space if and only if the algebra is of rank 2, and generated by $\{1, \varepsilon\}$ with $\varepsilon^2 = 1$ or -1.

In the case where $\varepsilon^2=-1$, we have a complex structure. Similarly, if $\varepsilon^2=1$, we have a paracomplex structure.

Proof. (1) Suppose that we are working on an affine space over a Jordan algebra A of rank two, with basis elements $\{e_1, e_2\} = \{1, \epsilon\}$. The affine representation of the algebra, or free module AE_n , admits a real interpretation in the affine space E_{2n} [37, section 2.1.2]. In this interpretation, each vector $\mathbf{x} = (x^i) \in AE_n$ with coordinates $x^i = x^{(i,\alpha)}e_\alpha$, is interpreted as the vector $\mathbf{x} = (x^{(i,\alpha)}) \in E_{2m}$.

Let us introduce a parametrizable curve $x^i = x^i(t) \in E_{2n}$, and a tangent vector **w** to it, at a given point. Our aim is to proceed to the parallel transport of this vector, along that curve in E_{2n} . We have a parallel transport of **w** along the curve $x^i = x^i(t)$ given by

$$d\mathbf{w} + \Gamma \mathbf{w} d\mathbf{x} = 0.$$

and Γ is an affine connection for the A-space. Because of the splitting property, we can write the parallel transport equation in the following way:

$$d(\mathbf{w}^{(1)}\oplus\mathbf{w}^{(2)})+(\boldsymbol{\Gamma}^{(1)}\oplus\boldsymbol{\Gamma}^{(2)})(\mathbf{w}^{(1)}\oplus\mathbf{w}^{(2)})d(\mathbf{x}^{(1)}\oplus\mathbf{x}^{(2)})=0,$$

therefore, giving us

$$d\mathbf{w}^{(\alpha)} + \Gamma^{(\alpha)}\mathbf{w}^{(\alpha)}d\mathbf{x}^{(\alpha)} = 0, \quad \alpha \in \{1, 2\}.$$

Therefore, we can define an affine connection in E_{2n} having two components with respect to the local coordinates $x^{(i,\alpha)}$.

(2) Consider an affine and symmetric space over a Jordan algebra A, and suppose that there are two flat, affine connections on this space. These flat affine connections are constructed from a field of objects, having components:

$$\Gamma^{i}_{jk} = \Gamma^{i\alpha}_{jk} e_{\alpha} \in A.$$

Suppose that $\mathbf{v}^i = \mathbf{v}^{(i,\alpha)} e_{\alpha}$ are quantities from the algebra corresponding to a tangent vector \mathbf{v} . Then, from the following condition

$$d\mathbf{v}^i + \Gamma^i_{jk}\mathbf{v}^j d\mathbf{x}^k = 0,$$

we can define an affine connection in the affine space E^{2n} having the following components

$$\Gamma^{(i,\alpha)}_{(j,\beta)(k,\gamma)} = \Gamma^{is}_{jk} C^{\delta}_{s\beta} C^{\alpha}_{\delta\gamma},$$

where the $C^{\alpha}_{\beta\gamma}$ are structure constants of algebra A, with respect to the local adapted coordinates $x^{(\alpha,i)}$. Now, these objects are indexed by the number of generators of the algebra A. Since there exist two connections, it implies that $s \in \{1,2\}$ and so that the number of generators of the algebra A is 2.

5.3. Projective space and paracomplex structure

Let X_d be a d-dimensional surface of the n-dimensional (real or complex) projective space \mathcal{P}^n with $d \leq n$.

DEFINITION 5.5. The surface X_d is said to be normalized if, at each point $p \in X_d$, are associated the two following hyperplanes.

- (1) Normal of first type, P_I , of dimension n-d, and intersecting the tangent d-plane T_pX_d at a unique point $p \in X_d$.
- (2) Normal of second type, P_{II} , of dimension d-1, and included in the d-plane T_pX_d , not meeting the point p.

This decomposition expresses the duality of projective space. In particular, in the limit case, where d = n, then P_I is reduced to the point p and P_{II} is the (n-1)-surface which does not contain the point p. This property is nothing but the usual duality of projective space. Note that in this case, X_n can be identified with the projective space \mathcal{P}^n .

DEFINITION 5.6. A pair consisting of an m-plane and an (n-m-1)-plane is called an m-pair.

REMARK 5.1. The 0-pair can be identified with the projective space \mathcal{P}^n .

From [33, 41], for normalized surfaces associated to an m-pair space, the following properties holds.

LEMMA 5.7. (1) The space of m-pairs is a projective, differentiable manifold.

(2) For any integer $m \ge 0$, a manifold of m-pairs contains two flat, affine and symmetric connections.

In particular, this leads to the following proposition:

PROPOSITION 5.8. The space of 0-pairs in the projective space \mathcal{P}^n is isometric to the Hermitian projective space over the algebra of paracomplex number.

Proof. See, for example, [37, section 4.4.5].

PROPOSITION 5.9. Suppose that (X, \mathcal{F}) is a finite measurable set where the dimension of X is n+1, and measures vanish only on an ideal \mathcal{I} . Let \mathcal{H}_n be the space of probability distributions on (X, \mathcal{F}) . Then, the space \mathcal{H}_n is a manifold of 0-pairs.

Proof. The *n*-dimensional surface \mathcal{H}_n is the intersection of the hyperplane $\mu(X) = 1$ with the cone \mathcal{C}_{n+1} of strictly positive measures, in the affine space \mathcal{W}_{n+1} of signed bounded measures. It is interpreted as an *n*-dimensional surface (also denoted by \mathcal{H}_n) of the projective space \mathcal{P}^n . Then, the geometrical structure of this surface is inherited from projective geometry. Using the remark in the first paragraph of section 0.4.3 in [37] and the Definition 5.6 of 0-pairs, one deduces that it corresponds to a manifold of 0-pairs.

THEOREM 5.10. Suppose that (X, \mathcal{F}) is a finite measurable set where the dimension of X is n+1, and measures vanish only on an ideal \mathcal{I} . The space \mathcal{H}_n of probability distributions on (X, \mathcal{F}) is isomorphic to the Hermitian projective space over the cone $M_+(2, \mathfrak{C})$.

Proof. This is a consequence of applying Proposition 5.9, Lemma 5.7 and finally Proposition 5.4.

5.4. Paracomplex potentiality of spaces of probability distributions

Now we will describe explicitly the analogues of local potentials φ from Section 4 in the paracomplex geometry. Using this description, we will state the paracomplex version of Theorem 4.2 for cones of probability distributions.

Theorem 5.11 (Paracomplex Dolbeault lemma). Any (local) potential φ on a cone of probability distributions determine the local paracomplex Dolbeault (1,1)-form

$$\widetilde{\omega} := \partial_+ \partial_- \varphi = \varepsilon \partial_- \overline{\partial} \varphi.$$

The potential φ is defined uniquely modulo subspace of local functions $Ker \partial_+ \partial_-$.

Proof. The proof uses an explicit construction of the paracomplex structure encoded in the direct sum $R \oplus R'$ from Section 4.2 above.

Let (V, I, g) be a para-Kähler manifold with para-Kähler form ω . Consider a point p on V, and an open neighbourhood U of p. Let (z_{\pm}^i) be adapted coordinates defined on U and mapping U onto the product of two simply connected open sets $U^{\pm} \subset \mathbb{R}^n$, where $n = \dim_{\mathfrak{C}} V$. Moreover, assume $z_{+}^i(p) = 0$.

Suppose that $\partial_+\theta^+=0$ on $U\cong U^+\times U^-$. The Dolbeault paracomplex technique shows that there exists a function φ^+ on U, given by

$$\varphi^+ := \int_{(0,z_-)}^{(z_+,z_-)} \theta^+.$$

The integration is over any path from $(0, z_{-})$ to (z_{+}, z_{-}) contained in $U^{+} \times \{z_{-}\}$.

From the condition that $\partial_+\theta^+=0$, it follows that the integral is path independent and that the one-form θ^+ restricted to $U^+\times\{z_-\}$ is closed (and thus exact), since U^+ is simply connected.

We now show that there exists a real valued function φ defined in some simply connected open neighbourhood U of p such that $\omega = \partial_- \partial_+ \varphi$ on U. The function φ is unique up to addition of a real-valued function f satisfying the equation $\partial_- \partial_+ f = 0$. Any such function is of the form $f = f_+ + f_-$, where $f_{\pm}: U \to \mathbb{R}$ satisfying the equation $\partial_{\pm} \partial_{\pm} f = 0$.

The first cohomology of U vanishes, so $H^1(U,\mathbb{R}) = 0$. Since ω is closed, there exists a one-form θ such that $\omega = d\theta$. We decompose θ into its homogeneous components: $\theta = \theta^+ + \theta^-$, $\theta^+ \in \Omega^{1,0}(U)$, $\theta^- \in \Omega^{0,1}(U)$. Then

$$d\theta = \partial_{+}\theta^{+} + (\partial_{-}\theta^{+} + \partial_{+}\theta^{-}) + \partial_{-}\theta^{-}.$$

From the fact that ω is of the type (1,1), we obtain the equations:

$$\partial_{\pm}\theta^{\pm} = 0$$
, and $\partial_{-}\theta^{+} + \partial_{+}\theta^{-} = \omega$.

Therefore, there exist two real-valued functions φ^{\pm} such that $\partial_{\pm}\varphi^{\pm} = \theta^{\pm}$. Assuming $\varphi := \varphi^{+} - \varphi^{-}$, we have:

$$\partial_-\partial_+\varphi = \partial_-\partial_+\varphi^+ + \partial_+\partial_-\varphi^- = \partial_-\theta^+ + \partial_+\theta^- = \omega.$$

It is clear that the function φ is unique up to adding a solution of $\partial_-\partial_+ f = 0$ (in fact, any solution is of the form $f = f_+ + f_-$, where $\partial_\pm f_\pm = 0$.). Let us consider $\partial_+ f = \sum f_i^+ dz_+^i$, with $f_i^+ = \frac{\partial f}{\partial z_i^i}$. We get

$$0 = \partial_- \partial_+ f = \sum \frac{\partial f_i^+}{\partial z_-^j} dz_-^j \wedge dz_+^i.$$

Therefore, $\frac{\partial f_i^+}{\partial z_-^j} = 0$ and the functions ∂f_i^+ depend only on the positive coordinates z_+ . So, we obtain

$$f = \sum_{i=0}^{\infty} \int_{0}^{z_{+}} f_{i}^{+}(\xi) d\xi^{i} + f_{-}(0, z_{-}),$$

where $\xi=(\xi^1,\dots,\xi^n)$. The path integral is well defined, U^+ being simply connected. By a change of notation, we have that $f_+=\sum \int_0^{z_+} f_i^+(\xi)d\xi^i$, and thus $f=f_++f_-$. Conversely, let φ be a real-valued function on $U\subset V$ such that $\omega=\partial_-\partial_+\varphi$ is a non-

Conversely, let φ be a real-valued function on $U \subset V$ such that $\omega = \partial_- \partial_+ \varphi$ is a non-degenerate two-form. This two-form is closed and of type (1,1). This is equivalent to $I^*\omega = -\omega$, which implies that $g := \omega(I, \cdot, \cdot)$ is symmetric, that is, g(X, Y) = g(Y, X).

5.5. Projective geometry of statistical manifolds

Returning to the proof of Theorem 5.10 above, we recall that the space of probability distributions over a finite set is endowed with two flat subspaces with flat connections. This property is common to a large class of probability distributions, generalizing the distributions on a finite set.

More precisely, let us consider the positive cone \mathcal{C} of strictly positive measures on a space (X, \mathcal{F}) , vanishing only on an ideal \mathcal{I} of the σ -algebra \mathcal{F} of the n-dimensional real space \mathcal{W} of the signed measures of bounded variations (that is, signed measures whose total variation $\|\mu\| = |\mu|(X)$ is bounded, vanishing only on an ideal \mathcal{I} of the σ -algebra \mathcal{F}).

Let $\mathcal{H} \subset \mathcal{C}$ be the subset of probability distributions defined by the following constraint on measures $\mu \in \mathcal{W}$:

$$\langle 1, \mu \rangle = 1$$
, where $\langle f, \mu \rangle = \int_X f d\mu$.

We associate to any parallel transport h in the covector space \mathcal{W}^* of the space \mathcal{W} of σ -finite measures $f \xrightarrow{h} f + h$, an automorphism of the cone \mathcal{C}

$$\mu \xrightarrow{h} \nu$$
, where $\frac{d\nu}{d\mu} = \exp(h)$,

where $d\nu/d\mu$ is the Radon–Nikodym derivative of the measure ν with respect to the measure μ . This automorphism is a non-degenerate linear map of W which leaves the cone invariant.

Let \mathfrak{G} be the group of all automorphisms h such that $h = \ln \frac{d\nu}{d\mu}$. The commutative subgroup of all 'translations' of the cone \mathcal{C} is a simply transitive Lie group, so the cone is homogeneous. To this group \mathfrak{G} the associated Lie algebra \mathfrak{g} defines the derivation of the cone.

The cone \mathcal{C} is not invariant with respect to the group \mathfrak{G} , but, since $\mathcal{C} \cap h(\mathcal{C}) \neq \emptyset$ for any $h \in \mathfrak{G}$, \mathfrak{G} is the so-called pseudo-group of automorphisms of \mathcal{C} . The subset \mathcal{H} of probability distributions is a hypersurface in \mathcal{C} which can be equipped with an paracomplex algebraic structure (see Proposition 5.8 for information about the algebraic structure).

Lemma 5.12. The manifold of probability distributions \mathcal{H} is torsionless.

Proof. We consider the n-dimensional affine space over an algebra A. By the previous results, we can assume that this algebra is of rank 2. Recall that A is finite-dimensional, unitary, associative. We interpret this as the affine space E_{2n} . One particularity is that we have a representation of the algebra such that to any generator of A corresponds a unique endomorphism E_{2n} (the structural endomorphisms).

We turn our considerations to so-called dyadics, that is, endomorphisms depending on the constant structures of the algebra. Let \mathbf{v} be a vector in E_{2n} , given by $\mathbf{v} = v^{(\alpha,i)} \mathbf{e}_{(\alpha,i)} \in E_{2n}$. There corresponds the element $\mathbf{V} = V^{\alpha} \mathbf{E}_{\alpha} \in M_n(A)$, where $M_n(A)$ is the free unitary A-module with basis \mathbf{E}_{α} .

Now, we consider M_{2n} the differentiable manifold defined by A. This is given by the space of affine connections. The regular structure defined by the algebra A arises on it in the case where on M_{2n} we have a set of two dyadic tensors, with matrices simultaneously reduced to the form

$$\begin{pmatrix} \hat{C}_k & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \hat{C}_k \end{pmatrix}$$

where $\hat{C}_k = (C_{jk}^i)$ is defined in the adapted basis $\mathbf{e}_{(\alpha,i)}$. Each tangent vector space serves as a real model (that is, a representative in the affine space E_{2n}) of the module $M_n(A)$.

On the manifolds M_{2n} defined by A, we have a field of objects $\Gamma^{\alpha}_{\beta\gamma} = \Gamma^{(\alpha,s)}_{\beta\gamma} \mathbf{e}_s \in A$ in local coordinates. Since we have the relation

$$\Gamma_{(\beta,j)(\gamma,k)}^{(\alpha,i)} = \Gamma_{\beta\gamma}^{\alpha,s} C_{sj}^m C_{mk}^i$$

with respect to the local adapted coordinates $x^{(\alpha,i)}$ (see [42, equation (3)]).

From the commutativity relation of the constant structures defining A, we have the $C_{ij}^k = C_{ji}^k$. Therefore, we have $\Gamma_{\beta\gamma}^{\alpha} = \Gamma_{\gamma\beta}^{\alpha}$, which implies that \mathcal{H} is torsionless.

Theorem 5.13. The manifold of probability distributions \mathcal{H} is an F-manifold.

Proof. From Lemma 5.12, the manifold \mathcal{H} is torsionless and from Theorem 5.10, we know that \mathcal{H} has a paracomplex structure.

We have shown in Proposition 5.9 and Theorem 5.10 that the manifold of probability distributions is, geometrically speaking, a projective Euclidean manifold and that it has a Clifford algebra structure (for further information, see as well [12, 31, 32]).

From Section 5.3, it follows that \mathcal{H} contains two distinct real projective flat subspaces (see also the Rozenfeld–Yaglom theorem [38, p. 112]). On the other hand, we already know the potentiality of \mathcal{H} . We can now define respective closed 2-paracomplex form $\tilde{\omega}$.

From the proof of the paracomplex Dolbeault Lemma, it follows that locally there exists a real-valued function φ (potential) such that

$$\tilde{\omega} = \partial_+ \partial_- \varphi = \varepsilon \partial \overline{\partial} \varphi.$$

The potential φ is defined up to addition of a function f satisfying the condition $\partial_+\partial_-f=0$. Going back to the multiplication operation \circ , we see again that for any pair of flat vector fields, X,Y, there exists a vector field C (a potential vector field) such that the multiplication operation is given by $X \circ Y = [X, [Y, C]]$. Therefore \mathcal{H} is an F-manifold.

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