The E₁₀ Wheeler–DeWitt operator at low levels

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Abstract: We consider the Wheeler–DeWitt operator associated with the bosonic part of the Hamiltonian of D=11 supergravity in a formulation with only the spatial components of the three-form and six-form fields, and compare it with the E₁₀ Casimir operator at low levels, to show that these two operators precisely match modulo spatial gradients up to and including \mathfrak{gl}_{10} level $\ell=2$. The uniqueness of the E_{10} Casimir operator eliminates all ordering ambiguities in the quantum Hamiltonian, at least up to the level considered. Beyond $\ell \geq 3$ the two operators are expected to start to differ from each other, as they do so for the classical expressions. We then consider truncations of the E_{10} Wheeler–DeWitt operator for various finite-dimensional subgroups of E₁₀ in order to exhibit the automorphic properties of the associated wave functions and to show that physically sensible wave functions generically vanish at the cosmological singularity, thus providing new and more sophisticated examples of DeWitt's proposed mechanism for singularity resolution in quantum gravity. Our construction provides novel perspectives on several unresolved conceptual issues with the Wheeler–DeWitt equation, such as the question of observables in quantum gravity, or the issue of emergent space and time in a purely algebraic framework. We also highlight remaining open questions of the E_{10} framework.

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1 Introduction

The Wheeler–DeWitt (WDW) equation [1,2] is the central equation of quantum gravity (see [3] for an introduction and many further references). However, notwithstanding the fact that this equation has been around for more than half a century, only comparatively little progress has been achieved with it. This is due to conceptual issues (in particular concerning the proper interpretation of the 'wave function of the universe') as well as to severe mathematical difficulties that have so far thwarted all attempts to properly formulate this equation in a manageable, mathematically well-defined and physically meaningful way. To be sure, one can consider simplified versions of the WDW equation, such as the mini-superspace approximation often invoked in quantum cosmology (see [3]

for examples), or purely topological theories, such as pure gravity in three space-time dimensions (see e.g. [4]), or otherwise exploit the equation for heuristic purposes. However, none of these simplifications addresses the core technical issue, namely the occurrence of short distance singularities which can be viewed as a non-perturbative manifestation of the non-renormalisability of perturbative quantum gravity. Furthermore, for pure gravity no observables in the sense of Dirac are known, that is, quantities commuting with all constraints, including the Hamiltonian constraint, even though these are expected to be a central ingredient in any quantum mechanical setting. In addition, there is the crucial question as to what extent space-time concepts are essential at the most fundamental level: indeed, many approaches to quantum gravity posit that space and time should be emergent, rather than fundamental concepts, in which case field theoretic notions would lose all meaning at the Planck scale.

In this paper we take a new look at these issues and are motivated by unification and the view that a consistent theory of quantum gravity requires the inclusion of very specific matter interactions determined by symmetry considerations. More precisely, our approach is based on the proposal of [5] (see also [6,7] for reviews), according to which the maximal rank hyperbolic Kac–Moody algebra \mathfrak{e}_{10} should play a key role. This proposal builds on an old conjecture [8] according to which this symmetry should appear as an extension of the Geroch group in the reduction of maximal supergravity [9] to one dimension. Although the present realisation takes place in a rather different and, in particular, quantum mechanical context we will see that the one-dimensional reduction fits very well with the WDW approach.

The standard canonical formulation of the bosonic sector of D=11 supergravity [9] is built on the spatial metric and the spatial three-form potential as well as their conjugate momenta as functions of a spatial coordinate \mathbf{x} [10,11]. By contrast, the E_{10} formulation has an infinity of fields, but no spatial dependence, because space is hypothesised to be an emergent concept in this approach [5]. In order to reconcile these two aspects, we strive to reformulate D=11 supergravity in a way that brings in new fields in addition to the usual ones, the first instance being a six-form potential dual to the three-form potential. Remarkably, there is a formulation, due to [12], that uses only the spatial components of these two fields rather than a covariant three-form (see also [13] for related work). This

¹The hyperbolic Kac-Moody algebra relevant for pure (Einstein) gravity with zero cosmological constant in four space-time dimensions is the Feingold–Frenkel algebra AE_3 , while higher rank hyperbolic algebras appear for higher-dimensional (super-)gravities. However, out of these, only \mathfrak{e}_{10} possesses a root lattice with the self-duality properties that we ultimately expect to be required for the quantum consistency of the theory.

formulation breaks manifest Lorentz invariance, but because this symmetry is also broken in the E_{10} approach, such a formulation is much better suited for comparison with the E_{10} model than the standard canonical formulation (which we also review here). More poignantly, we shall argue that this breaking of manifest Lorentz invariance is a necessary prerequisite for quantisation, as this is what allows us to treat the three- and six-form fields as independent degrees of freedom. Being off-shell and not manifestly Lorentz covariant, our approach differs from covariant ones such as the proposal of [14,15] for covariant and E_{11} -invariant equations of motions.

We will use this reformulation to bring the bosonic Hamiltonian constraint of D=11supergravity closer to an ultra-local form, by which we mean that only field values at a point enter but not their derivatives. This is done by considering the quantum analogue of the Belinsky-Khalatnikov-Lifshitz (BKL) limit [16] where now in the operator realisation of the Hamiltonian constraint spatial derivatives of fields become negligible compared to functional derivatives rather than to time derivatives (as there is no pre-defined notion of time in canonical quantum gravity). As we shall explain in more detail in section 2.2, this is related to the way the conjugate momenta (time derivatives) of the fields, including their duals, appear in the Hamiltonian constraint. After dropping the spatial gradients, the Hamiltonian then is ultra-local and depends only on canonical variables evaluated at one given spatial point \mathbf{x} and no longer contains any spatial derivatives that connect neighbouring spatial points. This form makes it possible to relate to the E_{10} context. The proper reinstatement of spatial gradients remains, however, to be clarified. We expect the other kinematic constraints (diffeomorphism and Gauss-type) appearing in field theory to play a crucial role in this. However, their final significance in our present approach is not clear and might necessitate the introduction of extra fields beyond the $E_{10}/K(E_{10})$ symmetric space, in the same way that they appear in exceptional field theory [17–19]. A further indication of the need for extra degrees of freedom is the apparent incompatibility of the full $E_{10}/K(E_{10})$ model with supersymmetry [20, 21]. The parts of the Gauss-type constraints that do not contain explicit spatial derivatives have been investigated in [22,23] where it was found that they have a resemblance to Sugawara-type constructions, a fact that is also compatible with the extra fields of exceptional field theory and tensor hierarchy algebras [24, 19, 25].

The Hamiltonian constraint, to the level checked in this paper and after dropping the spatial gradients, then coincides precisely with the invariant norm, alias the quadratic Casimir operator, appearing in the E_{10} model. By the very definition of the Casimir invariant, this means that we have access to an infinite number of observables, at least in principle! We expect our analysis to be extendable to the linearised dual graviton,

keeping in mind the well known difficulties associated with this field [14, 26, 5, 27, 21]. However, as is evident from our derivation in section 2, a complete analysis of the $\ell=3$ sector is technically even more demanding than the present analysis, because various Dirac brackets between gravitational and matter variables will then no longer vanish.

Using the relation between the Hamiltonian constraint and the E_{10} approach we then proceed to propose a quantisation of D = 11 supergravity that preserves this relation, i.e., is based on maintaining E_{10} symmetry. This hinges on a realisation of the Lie algebra \mathfrak{e}_{10} in terms of differential operators acting on the symmetric space $\mathrm{E}_{10}/K(\mathrm{E}_{10})$. Due to the infinite-dimensionality of the symmetric space and the presence of imaginary roots, the construction of such differential operators is difficult. For this reason we shall content ourselves with a truncated version where we only consider the fields up to the six-form. Identifying the WDW-operator with the Casimir operator of \mathfrak{e}_{10} in this truncation then provides an unambiguous quantisation of the system. A further novel aspect is that, with the restriction to one spatial point, the standard short distance singularities that usually hamper a proper definition of the WDW operator have entirely disappeared; instead, one has to cope with an exponentially growing tower of new degrees of freedom. This situation is reminiscent of the one encountered in string theory: there as well, UV singularities are completely absent, but at each order in string perturbation theory one must invoke a 'division' by a modular group to render physical quantities finite (besides ensuring absence of tachyons). As we shall explain, there are hints of a similar mechanism at work in the present construction, which we shall make more explicit by studying certain truncations of the E_{10} WDW operator to a finite number of degrees of freedom and by exhibiting the automorphic properties of the associated wave functions (see [28] for an introduction to automorphic representation theory with a comprehensive list of references). Such finitedimensional truncations are instructive, but it is not clear to what extent they can capture the full complexity of the E_{10} model because, for the full theory, the relevant 'modular group' is expected to be something vastly larger than the modular groups so far considered in string perturbation theory. Besides there are new subtleties for imaginary roots, to be discussed in section 4.5, that cast doubt on the applicability of standard automorphic theory. The use of a discretised version $E_{10}(\mathbb{Z})$ of $E_{10}(\mathbb{R})$, based on considerations of BPS states, was already suggested in [29], and analysed further in relation to M-theory in [30,31] with a viewpoint somewhat more similar to the one adopted here. Automorphic forms related to E_{10} have been studied in relation to scattering amplitudes in [32].

Given the above reformulation of D = 11 supergravity, the central object of interest is the wave function Φ which is a function on the $E_{10}/K(E_{10})$ coset space. A key question, even independently of the question whether extra fields beyond the coset ones are needed or not, concerns the parametrisation of this wave function. We label the fields appearing in Φ according to all elements that appear in the level decomposition of \mathfrak{e}_{10} with respect to its \mathfrak{gl}_{10} subalgebra, that was also heavily used in [5–7]. We note that there are different and inequivalent definitions of Kac–Moody groups available, see [33, 34] for overviews. The original proposal, now often called the minimal group, consisted of gluing $\mathrm{SL}(2,\mathbb{R})$ subgroups of E_{10} associated to real roots only [35]. In this parametrisation, a group element would consist of 'words' made out of an infinite alphabet of real roots, together with appropriate relations inherited from the Serre relations in the Lie algebra [33, 34]. The parametrisation used in physics [5–7] associates one field component to each positive root generator, for both real and imaginary roots. This picture is much closer to the maximal Kac–Moody group defined in the literature [34]. Which global parametrisation and which choice of group E_{10} is most suitable to physics, and, more specifically, which choice is best suited for explaining the emergence of spatial dependence, is not clear at the moment and deserves further study. In this paper we work in level decomposition.

One of the main outcomes of our analysis is a more detailed understanding of the asymptotic behaviour of the wave function as it approaches what would be a (space-like) classical singularity. Previous work on this [36, 37] based on a quantisation of only the cosmological billiard (BKL) approximation of the classical singularity revealed that the wave function vanishes in this limit, thus realising DeWitt's idea of a quantum-mechanical resolution of classical singularities.² We shall show in section 4 that this result is robust when including more degrees of freedom compared to BKL. Even though our analysis is still in a truncated setting we take this as an indication that the full quantum E_{10} system (with appropriate discrete symmetries) could be a sensible model of quantum gravity. The behaviour of the wave function near the singularity may also have implications for the information paradox. In [39] it is argued that information cannot be lost if it is not crushed in the singularity (although it remains unclear how it would be released again upon Hawking evaporation). However, even if the wave function in a BKL type approximation as in (4.1) vanishes at the singularity, there remains the question as to its behavior when infinitely many degrees of freedom 'open up' at the singularity [40]. The latter possibility is strongly suggested by the fact that classical geodesics on the $E_{10}/K(E_{10})$ manifold are infinitely unstable along directions involving imaginary root spaces [41], although it is an open question whether and how this instability percolates to the quantised theory.

 $^{^2}$ We note that this statement, as well as the chaoticity of the classical cosmological billiard rely on the structure of D=11 supergravity which in particular excludes a cosmological constant. Similar statements hold for pure bosonic D=4 gravity with zero cosmological constant. Therefore our results are not in conflict with the no-boundary proposal of [38] which requires a non-zero cosmological constant.

There remain two major unsolved problems at this point. The first is to understand the emergence of spatial dependence beyond the use of dual fields, and thus to extend the 'dictionary' of [5] beyond first order spatial gradients. Namely, like all previous ones, our calculation systematically ignores spatial gradients other than those obtained via dualisation. A significant observation in this context may be our equation (2.30) which states that the Dirac bracket between the three- and six-form fields only vanishes up to spatial gradients (besides being non-local). Discarding the latter is thus consistent with our level expansion (3.12) and (3.13) for *commuting* fields. However, in the quantised theory these two fields can no longer be treated as commuting (c-number) objects, because

$$\left[\hat{A}_{m_1 m_2 m_3}(\mathbf{x}), \, \hat{A}_{n_1 \cdots n_6}(\mathbf{y})\right] = -i\hbar G_{\mathcal{N}} \, \tilde{\varepsilon}_{m_1 m_2 m_3 n_1 \cdots n_6 p} \partial^p G(\mathbf{x}, \mathbf{y}) \tag{1.1}$$

where $G(\mathbf{x}, \mathbf{y})$ is the scalar propagator. This result, which ties the appearance of spatial gradients to an emergent non-commutativity of the basic variables, may indicate the need for some kind of non-commutative geometry on the $E_{10}/K(E_{10})$ manifold, as well as for third quantisation (in the sense that the wave function Φ in (2.42) may become operator valued). We also notice that the right-hand side of (1.1) brings in both \hbar and the Newton constant G_N , and thus a notion of length which is not present in the dimensionless pregeometrical setting.

The second open problem concerns the proper incorporation of fermions into the $E_{10}/K(E_{10})$ model, in a way that is fully compatible with E_{10} symmetry (or an even larger framework), and that can also capture spatial dependence (there are no known analogs of dual fields for fermions). First steps in this direction were already taken some time ago, by showing that the gravitino components at a fixed spatial point make up a finitedimensional unfaithful spinorial representation of the R-symmetry group $K(E_{10})$ [42–44, 20], and by re-interpreting the D=11 Rarita-Schwinger equation as a $K(E_{10})$ covariant 'Dirac equation' [20]. Fermions have also been included in mini-superspace approaches to N=1 supergravity in D=4 in [45,46] and D=5 [47] where they were found to be compatible with singularity avoidance. Treating fermions in the standard way would modify the WDW equation by fermionic contributions, and thus spoil the identification of the WDW operator with the E_{10} Casimir operator already at the very lowest order (as is evident from the explicit expressions given in [45,46]). Moreover, even neglecting spatial dependence, it would blow up the scalar wave function Φ to an object with 2^{160} components [36, 37]. While fermions are not immediately necessary for arriving at the E₁₀ conjecture, it seems clear that their inclusion will be essential for the consistency of the full theory and for singling out better quantum behaviour, much in the same way that local supersymmetry improves the behaviour of perturbative quantum supergravity, and that fermions are needed in string theory for finiteness via modular invariance and elimination of tachyons. For the present model, the main question is therefore whether it is possible to include fermions in a way that manifestly preserves the E_{10} structure of the WDW Hamiltonian; this may require a novel type of bosonisation, perhaps along the lines of [48]. In any case, we expect the answer to these questions to also have a bearing on other outstanding issues.

The structure of this paper is as follows. We first analyse the bosonic sector of D=11 supergravity canonically, recasting the matter sector in a 'democratic' form, where both a three-form and a six-form appear. The canonical quantisation of the resulting theory is then studied and the Wheeler–DeWitt equation worked out. In section 3, we then consider the functional realisation of E_{10} in terms of differential operators. The formal Casimir operator is then worked out in this language and compared to the WDW operator of D=11 supergravity in section 3.4. We relate our results on full (super-)gravity to previous work on its cosmological billiards truncation in section 4, where we also highlight the different effects of real and imaginary roots on solutions and connections to theory of automorphic forms. Section 5 contains concluding general remarks on properties of the wave function.

Throughout this paper we employ units with c=1. For further reference let us record the dimensions of the various objects. We have $[\hbar] = ML$ (mass×length); with dimensionless fields and coordinates of dimensions L (length), the D=11 Newton constant has dimension $[G_N] = L^8 M^{-1}$, so the Planck length is $\ell_P = (\hbar G_N)^{1/9}$. The conjugate momenta have dimension $[\Pi] = ML^{-9}$. The delta density has dimension $[\delta(\mathbf{x})] = L^{-10}$ which is also the dimension of the functional derivative $[\delta/\delta\phi(\mathbf{x})] = L^{-10}$ for any dimensionless field ϕ .

2 Bosonic Hamiltonian of D=11 supergravity

In this section, we analyse the bosonic sector of D=11 supergravity [9] by first performing the standard Hamiltonian treatment of the metric and the three-form field (see for instance [10]). To bring the resulting expressions closer to the E_{10} model, we then introduce a dual six-form potential and reformulate the canonical theory in a version where only the *spatial* components of the three- and six-form fields are retained, following [12].³ In principle this reformulation can also be applied to the gravitational sector, but we leave this step to future work. The resulting expressions are then quantised canonically as a further preparation for comparison with a functional realisation of E_{10} .

³This formulation is also sometimes called the Henneaux–Teitelboim form because of [49, 50].

2.1 Bunster-Henneaux form of D = 11 supergravity

We start from the bosonic part of the D=11 supergravity Lagrangian in the conventions of [20]

$$G_{N}\mathcal{L} = \frac{E}{4}R - \frac{E}{48}F^{MNPQ}F_{MNPQ} + \frac{2}{(144)^{2}}\tilde{\varepsilon}^{M_{1}...M_{11}}F_{M_{1}...M_{4}}F_{M_{5}...M_{8}}A_{M_{9}M_{10}M_{11}}$$
 (2.1)

with $F_{MNPQ} \equiv 4\partial_{[M}A_{NPQ]}$ and E the determinant of the elfbein $E_M{}^A$. These fields depend on eleven coordinates $x^M \equiv (t, \mathbf{x})$ (with time t, and where \mathbf{x} coordinatises the spatial hypersurface) which we usually do not write out. We have explicitly written an overall factor of the Newton constant G_N to emphasise that all bosonic field are dimensionless, as required for the comparison with the $E_{10}/K(E_{10})$ sigma model where the coset degrees of freedom are likewise dimensionless. In (2.1), $\tilde{\varepsilon}^{M_1...M_{11}}$ is the numerical Levi–Civita symbol, a space-time tensor density for which we use the convention that $\tilde{\varepsilon}^{0\,1...10} = -\tilde{\varepsilon}_{0\,1...10} = +1$. The Levi–Civita tensor with upper and lower indices given by $\epsilon^{M_1...M_{11}} = E^{-1}\tilde{\varepsilon}^{M_1...M_{11}}$ and $\epsilon_{M_1...M_{11}} = E\tilde{\varepsilon}_{M_1...M_{11}}$, with analogous definitions for the purely spatial objects.

For the elfbein we assume the triangular gauge

$$E_M{}^A = \begin{pmatrix} N & e_m{}^a N^m \\ 0 & e_m{}^a \end{pmatrix} \qquad \Rightarrow \qquad E = Ne \tag{2.2}$$

with the lapse function N and the shift N^m , which are, respectively, the Lagrange multipliers associated to the Hamiltonian and diffeomorphism constraints; $e = \det e_m{}^a$ is the volume density of the ten-dimensional spatial slice. We split curved space-time indices as M = (t, m) and flat ones as A = (0, a). The Levi–Civita symbol on a spatial slice is induced from that in space-time by $\tilde{\varepsilon}^{m_1...m_{10}} \equiv \tilde{\varepsilon}^{tm_1...m_{10}}$. A further constraint will be seen to be the Gauss constraint associated to the Lagrange multiplier field A_{tmn} .

For the canonical treatment we first determine the canonical momenta conjugate to g_{mn} and A_{mnp} , respectively, which are given by⁴

$$G_{N} \Pi^{mn} = \frac{1}{2} e e^{am} e^{bn} \left(\Omega_{0(ab)} - \delta_{ab} \Omega_{0cc} \right),$$

$$G_{N} \Pi^{mnp} = -E F^{tmnp} + \frac{1}{216} \tilde{\varepsilon}^{tmnpk_{1}...k_{7}} F_{k_{1}...k_{4}} A_{k_{5}k_{6}k_{7}}$$
(2.3)

where $\Omega_{ABC} \equiv E_A{}^M E_B{}^N (\partial_M E_{NC} - \partial_N E_{MC})$ are the D = 11 coefficients of anholonomy and have only flat indices (see e.g. [51] for further explanations and conventions as well

⁴The conjugate momenta of N, N^m and A_{tmn} vanish as primary constraints. As is usual for p-forms coupled to gravity, the fields serve as Lagrange multipliers for the first-class constraints that generate the corresponding gauge transformations.

as [52, 10, 11, 53] for canonical treatments of supergravity theories). For obtaining the above relations we have used the functional derivatives in the normalisations

$$\frac{\delta g_{mn}(\mathbf{x})}{\delta g_{pq}(\mathbf{y})} = 2\delta_{(m}^p \delta_{n)}^q \delta(\mathbf{x}, \mathbf{y}), \qquad \frac{\delta A_{m_1 \dots m_p}(\mathbf{x})}{\delta A_{n_1 \dots n_p}(\mathbf{y})} = p! \, \delta_{m_1 \dots m_p}^{n_1 \dots n_p} \delta(\mathbf{x}, \mathbf{y})$$
(2.4)

with $\delta_{m_1...m_p}^{n_1...n_p} = \delta_{[m_1}^{[n_1} \cdots \delta_{m_p]}^{n_p]}$ and (anti-)symmetrisations of unit strength. The spatial Dirac deltas $\delta(\mathbf{x}, \mathbf{y})$ appearing on the right-hand sides are densities with respect to spatial diffeomorphisms and satisfy $\int d^{10}\mathbf{y} f(\mathbf{y}) \delta(\mathbf{x}, \mathbf{y}) = f(\mathbf{x})$. The momenta defined in (2.3) are also tensor densities, and likewise for the functional derivative operator $\frac{\delta}{\delta \phi(x)}$ for all fields $\phi(x)$. We also note the appearance of the Newton constant G_N in the relation between the velocities and the canonical momenta. From the way the Newton constant appears in the definition of the canonical momenta (2.3), we see that it is important for relating the canonical momenta to spatial derivatives of the fields.

For notational convenience we also define the part of the three-form canonical momentum due to the Chern–Simons term by

$$\mathcal{P}^{mnp} = \frac{1}{216} \tilde{\varepsilon}^{mnpk_1...k_7} F_{k_1...k_4} A_{k_5k_6k_7} , \qquad (2.5)$$

where the ten-dimensional Levi–Civita symbol is related to the eleven-dimensional one by $\tilde{\varepsilon}^{m_1...m_{10}} \equiv \tilde{\varepsilon}^{tm_1...m_{10}}$. With this definition we have

$$F^{tmnp} = -E^{-1} \left(G_N \Pi^{mnp} - \mathcal{P}^{mnp} \right). \tag{2.6}$$

The standard canonical treatment then leads to the Hamiltonian form of the action

$$\mathcal{L}_{can} = \frac{1}{2} \dot{g}_{mn} \Pi^{mn} + \frac{1}{3!} \dot{A}_{mnp} \Pi^{mnp} - N\mathcal{H} - N^m \mathcal{H}_m - \frac{1}{2} A_{tmn} \mathcal{G}^{mn}, \qquad (2.7)$$

The (first-class) constraints appearing in (2.7) are

$$e\mathcal{H} = G_{N}G_{mn|pq}\Pi^{mn}\Pi^{pq} - \frac{1}{4G_{N}}e^{2}R^{(10)}$$

$$+ \frac{1}{12G_{N}}(G_{N}\Pi^{mnp} - \mathcal{P}^{mnp})g_{mm'}g_{nn'}g_{pp'}(G_{N}\Pi^{m'n'p'} - \mathcal{P}^{m'n'p'})$$

$$+ \frac{1}{48G_{N}}e^{2}F_{m_{1}...m_{4}}g^{m_{1}n_{1}}\cdots g^{m_{4}n_{4}}F_{n_{1}...n_{4}}, \qquad (2.8)$$

and

$$\mathcal{H}_m = -g_{mn}\nabla_p\Pi^{pn} + \frac{1}{6}F_{mnpq}(\Pi^{mnp} - G_N^{-1}\mathcal{P}^{mnp}), \qquad (2.9a)$$

$$\mathcal{G}^{mn} = -\partial_{p} \Pi^{pmn} - \frac{G_{N}^{-1}}{12 \cdot 144} \tilde{\varepsilon}^{mnk_{1}...k_{8}} F_{k_{1}...k_{4}} F_{k_{5}...k_{8}}$$

$$= \partial_{p} \left[-\Pi^{pmn} - \frac{G_{N}^{-1}}{3 \cdot 144} \tilde{\varepsilon}^{mnpk_{1}...k_{7}} A_{k_{1}k_{2}k_{3}} F_{k_{4}...k_{7}} \right], \qquad (2.9b)$$

where ∇_p is the covariant derivative with the Levi-Civita connection for the spatial metric g_{mn} (note that the gradient in (2.9b) is an ordinary derivative because Π^{mnp} transforms as a density). They are, in turn, the Hamiltonian (scalar) constraint, the diffeomorphism (momentum) constraint and the Gauss constraint. These constraints must be imposed at each point \mathbf{x} of the spatial hypersurface, whence we are dealing with a continuous infinitude of constraints. Observe that we have pulled out a factor of e, as a result of which the 'potential terms' appear with a prefactor e^2 . The DeWitt metric for D = 11 space-time dimensions is (here without a density factor)

$$G_{mn|pq} := g_{p(m}g_{n)q} - \frac{1}{9}g_{mn}g_{pq}. \tag{2.10}$$

As is well-known, the equations of motion for the matter field allow the introduction of a dual six-form potential $A_{M_1...M_6}$ on-shell. While it is not possible to write the non-linear theory covariantly in terms of only the six-form potential [54] (or even both covariant potentials at the same time), it was shown in [49, 12] that one can write an off-shell theory without manifest Lorentz and diffeomorphism covariance when using only the spatial components $A_{m_1m_2m_3}$ and $A_{m_1...m_6}$ of both potentials⁵; the remaining manifest symmetry is the SO(10) subgroup of the Lorentz group. We review this formalism in some detail in appendix A where we follow [12]. Such a formulation is desirable because these are exactly the fields that appear in the E₁₀ theory which does not exhibit manifest Lorentz symmetry either. Although the notion of level will be 'officially' introduced only in section 3.1, we already here refer to the metric, three-form, six-form and dual graviton fields as "level- ℓ fields", for resp. $\ell = 0, 1, 2, 3$, see also (3.5).

As derived in appendix A, the action of [12] involving both spatial potentials in our conventions is

$$\mathcal{L}_{can} = \frac{1}{2} \dot{g}_{mn} \Pi^{mn} + \frac{G_{N}^{-1}}{2 \cdot 3! \cdot 7!} \dot{A}_{mnp} \tilde{\varepsilon}^{mnpk_{1}...k_{7}} F_{k_{1}...k_{7}} - \frac{G_{N}^{-1}}{2 \cdot 4! \cdot 6!} F_{mnpq} \tilde{\varepsilon}^{mnpqk_{1}...k_{6}} \dot{A}_{k_{1}...k_{6}} + \frac{G_{N}^{-1}}{3! \cdot 864} \dot{A}_{mnp} \tilde{\varepsilon}^{mnpk_{1}...k_{7}} A_{k_{1}k_{2}k_{3}} F_{k_{4}...k_{7}} - N\mathcal{H} - N^{m} \mathcal{H}_{m},$$
(2.11)

where the terms with time derivatives on the three- and six-form result from the replacement of Π^{mnp} by the solution (A.5) of the Gauss constraint (2.9b) which has therefore disappeared. The Hamiltonian constraint is now given by

$$e\mathcal{H} = G_{N} G_{mn|pq} \Pi^{mn} \Pi^{pq} - \frac{G_{N}^{-1}}{4} e^{2} R^{(10)} + \frac{G_{N}^{-1}}{2 \cdot 4!} e^{2} F_{m_{1}...m_{4}} g^{m_{1}n_{1}} \cdots g^{m_{4}n_{4}} F_{n_{1}...n_{4}}$$
$$+ \frac{G_{N}^{-1}}{2 \cdot 7!} e^{2} F_{m_{1}...m_{7}} g^{m_{1}n_{1}} \cdots g^{m_{7}n_{7}} F_{n_{1}...n_{7}},$$
(2.12)

⁵For a closely related formulation with an extra vector allowing for a general 'axial' gauge see [13].

and where

$$F_{m_1...m_7} = 7\partial_{[m_1}A_{m_2...m_7]} - 35A_{[m_1m_2m_3}F_{m_4...m_7]}$$
(2.13)

is the spatial field strength of the six-form potential, including a coupling to the three-form due to the Chern–Simons term, cf. (A.3). To arrive at this form, the original Gauss constraint (2.9b) has been solved and this is the step that introduces the spatial six-form $A_{m_1...m_6}$. In the form (2.12), the Hamiltonian still depends on the magnetic field strengths $F_{m_1...m_4}$ and $F_{m_1...m_7}$ that contain in particular spatial derivatives. As the E_{10} theory does not directly contain spatial derivatives, we now manipulate the theory further. We note that in the Bunster–Henneaux form (2.11) no temporal components of the gauge fields appear explicitly. To simplify the subsequent canonical analysis of the matter sector we now switch to a flat background geometry in the remainder of this subsection, anticipating that for the final results we can re-convert to general backgrounds by covariantising the relevant expressions. For this reason we will also set $G_N = 1$ until the end of this subsection, but re-instate G_N in the following sections.

The theory (2.11) contains the primary constraints

$$C^{mnp}(\mathbf{x}) := \Pi^{mnp} - \frac{1}{2 \cdot 7!} \tilde{\varepsilon}^{mnpk_1 \dots k_7} F_{k_1 \dots k_7} - \frac{1}{3! \cdot 144} \tilde{\varepsilon}^{mnpk_1 \dots k_7} A_{k_1 k_2 k_3} F_{k_4 \dots k_7} , \quad (2.14a)$$

$$\mathcal{C}^{m_1\cdots m_6}(\mathbf{x}) := \Pi^{m_1\cdots m_6} + \frac{1}{2\cdot 4!}\tilde{\varepsilon}^{m_1\dots m_6k_1\dots k_4}F_{k_1\dots k_4}, \qquad (2.14b)$$

where now the momenta are defined from the Lagrangian density (2.11).

For the further analysis we need the non-vanishing Poisson brackets of the elementary variables which are normalised as

$$\{A_{mnp}(\mathbf{x}), \Pi^{qrs}(\mathbf{y})\}_{PB} = 3! \, \delta_{mnp}^{qrs} \delta(\mathbf{x}, \mathbf{y}),$$

$$\{A_{m_1 \cdots m_6}(\mathbf{x}), \Pi^{n_1 \cdots n_6}(\mathbf{y})\}_{PB} = 6! \, \delta_{m_1 \cdots m_6}^{n_1 \cdots n_6} \delta(\mathbf{x}, \mathbf{y}). \tag{2.15}$$

The Poisson bracket itself carries a dimension of inverse action, i.e., $[\{\cdot,\cdot\}] = M^{-1}L^{-1}$. The same will be true for the Dirac bracket to be written below.

With this one can work out the matrix of Poisson brackets of the constraints (2.14) as

$$\begin{pmatrix}
\left\{\mathcal{C}^{m_1 m_2 m_3}(\mathbf{x}), \mathcal{C}^{n_1 n_2 n_3}(\mathbf{y})\right\}_{PB} & \left\{\mathcal{C}^{m_1 m_2 m_3}(\mathbf{x}), \mathcal{C}^{n_1 \cdots n_6}(\mathbf{y})\right\}_{PB} \\
\left\{\mathcal{C}^{m_1 \cdots m_6}(\mathbf{x}), \mathcal{C}^{n_1 n_2 n_3}(\mathbf{y})\right\}_{PB} & \left\{\mathcal{C}^{m_1 \cdots m_6}(\mathbf{x}), \mathcal{C}^{n_1 \cdots n_6}(\mathbf{y})\right\}_{PB}
\end{pmatrix} (2.16)$$

$$= \begin{pmatrix} \frac{1}{24} \tilde{\varepsilon}^{m_1 m_2 m_3 n_1 n_2 n_3 p_1 \cdots p_4} F_{p_1 \cdots p_4}(\mathbf{x}) \delta(\mathbf{x}, \mathbf{y}) & -\tilde{\varepsilon}^{m_1 m_2 m_3 n_1 \cdots n_6 p} \partial_p \delta(\mathbf{x}, \mathbf{y}) \\ -\tilde{\varepsilon}^{m_1 \cdots m_6 n_1 n_2 n_3 p} \partial_p \delta(\mathbf{x}, \mathbf{y}) & 0 \end{pmatrix},$$

where by convention the derivative on the δ -function always acts on the first argument (the antisymmetry of this matrix under simultaneous interchange of indices and coordinates follows from $\partial_{\mathbf{x}} \delta(\mathbf{x}, \mathbf{y}) = -\partial_{\mathbf{y}} \delta(\mathbf{y}, \mathbf{x})$).

Demanding that the constraints (2.14) be preserved in time leads to conditions on the associated Lagrange multipliers introduced for them in the canonical formalism. The Lagrange multipliers are then fixed up to homogeneous solutions that are independent of the canonical variables. Hence, there are no further (secondary) constraints to be considered.

The following Hamiltonian density generates the same matter dynamics as the Lagrangian (2.11) when taken in flat space

$$\mathcal{H} = \frac{1}{2 \cdot 4!} F_{n_1 \dots n_4} F^{n_1 \dots n_4} + \frac{1}{2 \cdot 7!} F_{n_1 \dots n_7} F^{n_1 \dots n_7} + \frac{1}{3! \cdot 7!} \tilde{\varepsilon}_{n_1 n_2 n_3 m_1 \dots m_7} C^{n_1 n_2 n_3} F^{m_1 \dots m_7} + \frac{1}{6!} C^{n_1 \dots n_6} \left[-\frac{1}{4!} \tilde{\varepsilon}_{n_1 \dots n_6 m_1 \dots m_4} F^{m_1 \dots m_4} + \frac{1}{144} \tilde{\varepsilon}_{n_1 \dots n_6 m_1 \dots m_4} F^{m_1 \dots m_7} A_{m_5 m_6 m_7} \right] + \frac{1}{2} \lambda_{m_1} \mathcal{G}^{m_1} + \frac{1}{5!} \lambda_{n_1 \dots n_5} \mathcal{G}^{n_1 \dots n_5} .$$

$$(2.17)$$

We emphasise that the dynamics are generated using Poisson brackets and that they are weakly equal to the Euler-Lagrange equations deduced from (2.11). In particular, the field dependent coefficients of \mathcal{C}^{\cdots} in (2.17) are chosen in such a way that $\dot{\mathcal{C}}^{\cdots} \approx 0$. The free gauge parameters λ_{mn} and $\lambda_{n_1...n_5}$ can also be viewed as being related to the temporal components of the three- and six-form fields.

As our goal is to quantise the system, we need to follow the Dirac formalism and work with Dirac rather than Poisson brackets. The transition to Dirac brackets in particular removes part of phase space and therefore reduces the number of variables, making the resulting expression closer to the E_{10} approach. The constraints (2.14) represent a mixed system of first- and second-class constraints. This can be deduced from the fact that the matrix (2.16) is degenerate, as one can see by acting with it on the vector⁶

$$\left(v_{n_1 n_2 n_3} \mid v_{n_1 \dots n_6} \right)^T = \left(3 \partial_{[n_1} \lambda_{n_2 n_3]}(\mathbf{y}) \mid 6 \partial_{[n_1} \lambda_{n_2 \dots n_6]}(\mathbf{y}) + 15 F_{[n_1 n_2 n_3 n_4}(\mathbf{y}) \lambda_{n_5 n_6]}(\mathbf{y}) \right)^T.$$
(2.18)

This null vector corresponds to first-class constraints \mathcal{G} according to

$$\mathcal{G} = \int d\mathbf{y} \left[\frac{1}{3!} v_{n_1 n_2 n_3} \mathcal{C}^{n_1 n_2 n_3} + \frac{1}{6!} v_{n_1 \dots n_6} \mathcal{C}^{n_1 \dots n_6} \right] = \int d\mathbf{y} \left[\frac{1}{2} \lambda_{mn} \mathcal{G}^{mn} + \frac{1}{5!} \lambda_{m_1 \dots m_5} \mathcal{G}^{m_1 \dots m_5} \right]$$
(2.19)

⁶This action contains both a contraction of the tensorial indices with the canonical combinatorial factors 1/3! and 1/6! as well as an integral over \mathbf{y} as shown in (2.19).

for any $\lambda_{m_1m_2}(\mathbf{y})$ and $\lambda_{m_1...m_5}(\mathbf{y})$ of dimension L. The integrated generator \mathcal{G} is only non-trivial for $\lambda_{m_1m_2}$ and $\lambda_{m_1...m_5}$ that are non-trivial in de Rham cohomology, i.e., that cannot be written as $\lambda_{m_1m_2} = 2\partial_{[m_1}\sigma_{m_2]}$ in terms of a one-form σ_m (and similarly a four-form $\sigma_{m_1...m_4}$ for $\lambda_{m_1...m_5}$). This well-known gauge-for-gauge structure is equivalent to the reducibility of the gauge constraints. Our analysis will not depend on resolving this reducible structure.

The local generators of gauge transformations associated with (2.19) can be read off as

$$\mathcal{G}^{mn}(\mathbf{x}) := -\partial_p \mathcal{C}^{mnp}(\mathbf{x}) + \frac{1}{24} \mathcal{C}^{mnp_1...p_4}(\mathbf{x}) F_{p_1...p_4}(\mathbf{x}) , \qquad (2.20a)$$

$$\mathcal{G}^{m_1 \cdots m_5}(\mathbf{x}) := -\partial_p \mathcal{C}^{pm_1 \cdots m_5}(\mathbf{x}). \tag{2.20b}$$

In a similar way, one can write a projection to the second-class constraints, that we denote by $S^{...}$, in the form

$$S^{n_1 n_2 n_3}(\mathbf{x}) := C^{n_1 n_2 n_3}(\mathbf{x}) - 3 \int d\mathbf{y} \, \partial^{[n_1} G(\mathbf{x}, \mathbf{y}) \, \partial_p C^{n_2 n_3]p}(\mathbf{y})$$

$$+ A_{p_1 \dots p_3}(\mathbf{x}) \int d\mathbf{y} \, \partial^{[n_1} G(\mathbf{x}, \mathbf{y}) \, \partial_k C^{n_2 n_3 p_1 \dots p_3]k}(\mathbf{y})$$

$$- \frac{1}{2} \int d\mathbf{y} \, \partial^{[n_1} G(\mathbf{x}, \mathbf{y}) \, \partial_k \left(C^{n_2 n_3] p_1 \dots p_3 k} A_{p_1 \dots p_3}(\mathbf{y}) \right) \qquad (2.21a)$$

$$S^{n_1 \dots n_6}(\mathbf{x}) := C^{n_1 \dots n_6}(\mathbf{x}) + 6 \int d\mathbf{y} \, \partial^{[n_1} G(\mathbf{x}, \mathbf{y}) \, \partial_p C^{n_2 \dots n_6]p}(\mathbf{y}) \qquad (2.21b)$$

where $G(\mathbf{x}, \mathbf{y})$ is the spatial (flat) Green function satisfying $\Delta G(\mathbf{x}, \mathbf{y}) = \partial_m \partial^m G(\mathbf{x}, \mathbf{y}) = \delta(\mathbf{x}, \mathbf{y})$. All derivatives act on the first argument of a function unless indicated otherwise. The dimension of the Green function is L^{-8} . The appearance of the scalar propagator in these expressions already points to one extra complication with *curved* backgrounds: because of the implicit dependence of $G(\mathbf{x}, \mathbf{y})$ on the spatial metric the gravitational momenta Π^{mn} then no longer commute with the Green function.

The true second-class generators (2.21) therefore contain non-local terms. Using the convolution product defined by $(f \star g)(\mathbf{x}) \equiv \int d\mathbf{y} f(\mathbf{x}, \mathbf{y}) g(\mathbf{y})$, we can thus separate the

⁷In Cartesian coordinates on ten flat Euclidean dimensions (with vanishing conditions at infinity), the Green function can be written explicitly as $G(\mathbf{x}, \mathbf{y}) = (\text{vol}(S^9))^{-1}|\mathbf{x} - \mathbf{y}|^{-8}$, but we shall not rely on this expression. The properties of it that we use are its defining Laplace equation together with $G(\mathbf{x}, \mathbf{y}) = G(\mathbf{y}, \mathbf{x})$ and $\partial_{\mathbf{x}} G(\mathbf{x}, \mathbf{y}) = -\partial_{\mathbf{y}} G(\mathbf{x}, \mathbf{y})$.

original constraints (2.14a) and (2.14b) into first- and second-class constrains as

$$\mathcal{C}^{n_1 n_2 n_3} = \mathcal{S}^{n_1 n_2 n_3} - 3 \,\partial^{[n_1} G \star \mathcal{G}^{n_2 n_3]} - A_{p_1 p_2 p_3} \left(\partial^{[n_1} G \star \mathcal{G}^{n_2 n_3 p_1 p_2 p_3]} \right)
+ \frac{1}{2} \partial^{[n_1} G \star \left(\mathcal{G}^{n_2 n_3] p_1 p_2 p_3} A_{p_1 p_2 p_3} \right) ,$$
(2.22a)

$$\mathcal{C}^{n_1\dots n_6} = \mathcal{S}^{n_1\dots n_6} - 6\,\partial^{[n_1}G \star \mathcal{G}^{n_2\dots n_6]},\tag{2.22b}$$

where we have also expressed the non-local terms through the Gauss constraints (2.20) in order to exhibit that the second-class constraints differ from the full constraints by terms proportional to the first-class constraints.

We note some properties of the first- and second-class constraint that are important for the further development of the Dirac formalism. First, and by construction of the null vector, the first-class generators \mathcal{G}^{\cdots} Poisson commute with all constraints (2.14) in the strong sense, viz.

$$\left\{ \mathcal{C}^{mnp}(\mathbf{x}), \, \mathcal{G}^{q_1 q_2}(\mathbf{y}) \right\}_{PB} = \left\{ \mathcal{C}^{mnp}(\mathbf{x}), \, \mathcal{G}^{q_1 \cdots q_5}(\mathbf{y}) \right\}_{PB} = 0,
\left\{ \mathcal{C}^{m_1 \cdots m_5}(\mathbf{x}), \, \mathcal{G}^{q_1 q_2}(\mathbf{y}) \right\}_{PB} = \left\{ \mathcal{C}^{m_1 \cdots m_5}(\mathbf{x}), \, \mathcal{G}^{q_1 \cdots q_5}(\mathbf{y}) \right\}_{PB} = 0.$$
(2.23)

In particular, the first-class constraints all (strongly) commute with one another. We also note that the second Gauss-type constraint $\mathcal{G}^{m_1...m_5}$ is automatically divergence-free while \mathcal{G}^{mn} satisfies

$$\partial_m \mathcal{G}^{mn} = \frac{1}{24} \partial_m \mathcal{C}^{mnp_1 \dots p_4} F_{p_1 \dots p_4} = -\frac{1}{24} \mathcal{G}^{np_1 \dots p_4} F_{p_1 \dots p_4}. \tag{2.24}$$

The gauge transformations generated by the first-class combinations (2.20) are

$$\delta A_{n_1 n_2 n_3} = 3 \partial_{[n_1} \lambda_{n_2 n_3]}, \qquad \delta A_{n_1 \dots n_6} = 6 \partial_{[n_1} \lambda_{n_2 \dots n_6]} + 15 F_{[n_1 \dots n_4} \lambda_{n_5 n_6]}$$
 (2.25)

and one can check that they leave the field strengths $F_{n_1...n_4}$ and $F_{n_1...n_7}$ (defined in (2.13)) appearing in the Hamiltonian (2.12) invariant. The appearance of the gauge-invariant field strength $F_{m_1...m_4}$ means that in this basis the gauge algebra is abelian. This corresponds to the fact that the first-class constraints $\mathcal{G}^{...}$ strongly Poisson commute with all constraints and therefore also $\{\mathcal{G}^{n_1n_2}, \mathcal{G}^{n_3n_4}\}_{PB} = 0$ strongly.⁸

The second-class constraints (2.21) satisfy the relations

$$-\partial_p S^{pmn} + \frac{1}{24} S^{mnp_1...p_4} F_{p_1...p_4} = 0, \qquad (2.26a)$$

$$-\partial_p \mathcal{S}^{pm_1\dots m_5} = 0, \qquad (2.26b)$$

⁸Alternatively, one could also choose a basis where this commutator only vanishes weakly modulo $\mathcal{G}^{n_1 \dots n_5}$ by taking $\mathcal{G}^{n_1 n_2} \to \mathcal{G}^{n_1 n_2} + (*)A_{m_1 m_2 m_3} \mathcal{G}^{n_1 n_2 m_1 m_2 m_3}$, leading to a non-abelian gauge algebra.

so that inserting them into the projection (2.20) to the first-class constraints gives zero. In fact, this property is what was used to determine the expressions (2.21). Since the second-class constraints differ from the full constraints \mathcal{C}^{\cdots} by first-class constraints and the first-class constraints strongly Poisson commute with all constraints according to (2.23), we deduce that the matrix of Poisson brackets of the second-class constraints is identical to (2.16). However, it is now to be thought of as acting on the space of second-class functions, *i.e.*, those satisfying (2.26).

To determine the Dirac brackets, we shall now invert the matrix (2.16) on this function space. We repeat that we work on flat space-time in order to render the expressions more tractable, as the following discussion only concerns the gauge structure in the matter sector. With the full gravitational couplings, the analysis of the second-class constraints and the determination of the Dirac brackets become substantially more complicated due to their dependence on the spatial metric and the resultant non-commutativity with the gravitational momenta. Nevertheless, we shall see that the relevant expressions can be covariantised in a straight-forward manner and thus extended to curved space, but we leave a detailed analysis of the associated subtleties to future work.

The inverse of the matrix (2.16) on the space of second-class functions is given by

$$\begin{pmatrix} 0 & -\tilde{\varepsilon}_{m_1 m_2 m_3 n_1 \cdots n_6 p} \partial^p G(\mathbf{x}, \mathbf{y}) \\ -\tilde{\varepsilon}_{m_1 \cdots m_6 n_1 n_2 n_3 p} \partial^p G(\mathbf{x}, \mathbf{y}) & X_{m_1 \cdots m_6 n_1 \cdots n_6}(\mathbf{x}, \mathbf{y}) \end{pmatrix}, \qquad (2.27)$$

where

$$X_{m_1...m_6 n_1...n_6}(\mathbf{x}, \mathbf{y}) = -20 \,\tilde{\varepsilon}_{km_1...m_6[n_1n_2n_3} A_{n_4n_5n_6]}(\mathbf{y}) \partial^k G(\mathbf{x}, \mathbf{y})$$

$$-20 \,\tilde{\varepsilon}_{kn_1...n_6[m_1m_2m_3} A_{m_4m_5m_6]}(\mathbf{x}) \partial^k G(\mathbf{x}, \mathbf{y})$$

$$(2.28)$$

satisfies
$$X_{m_1...m_6 n_1...n_6}(\mathbf{x}, \mathbf{y}) = -X_{n_1...n_6 m_1...m_6}(\mathbf{y}, \mathbf{x}).^9$$

With these preparations one can now work out the Dirac brackets. These become quite long and they also contain non-local terms that are due to the separation into first-and second-class constraints we have chosen in (2.22). We shall only give a few salient ones for the elementary variables and then focus on the gauge-invariant objects whose Dirac brackets are free of these non-local terms [50]. We have for instance the following

⁹The matrix operator (2.27) is the inverse of (2.16) on the space of second-class constraints, i.e., its composition with (2.16) in the sense of footnote 6 acts as the identity on functions ($\mathcal{S}^{n_1 n_2 n_3}$, $\mathcal{S}^{n_1 \dots n_6}$) satisfying the relation (2.26). It is *not* the inverse on the space of all functions ($\mathcal{C}^{n_1 n_2 n_3}$, $\mathcal{C}^{n_1 \dots n_6}$) where an inverse does not exist due to the degeneracy of (2.16). Therefore the product of the matrices (2.16) and (2.27) is not the identity matrix but it acts as the identity on the relevant space.

Dirac brackets among position and momentum variables

$$\left\{ A_{mnp}(\mathbf{x}), \Pi^{qrs}(\mathbf{y}) \right\}_{\mathrm{DB}} = \frac{1}{2} \cdot 3! \left(\delta_{mnp}^{qrs} \delta(\mathbf{x}, \mathbf{y}) + 3 \delta_{[mn}^{[qr} \partial_{p]} \partial^{s]} G(\mathbf{x}, \mathbf{y}) \right)
\left\{ A_{mnp}(\mathbf{x}), \Pi^{q_1 \cdots q_6}(\mathbf{y}) \right\}_{\mathrm{DB}} = 0$$

$$\left\{ A_{m_1 \cdots m_6}(\mathbf{x}), \Pi^{n_1 \cdots n_6}(\mathbf{y}) \right\}_{\mathrm{DB}} = \frac{1}{2} \cdot 6! \left(\delta_{m_1 \cdots m_6}^{n_1 \cdots n_6} \delta(\mathbf{x}, \mathbf{y}) + 6 \delta_{[m_1 \cdots m_5}^{[n_1 \cdots n_5} \partial_{m_6]} \partial^{n_6]} G(\mathbf{x}, \mathbf{y}) \right)$$

as well as non-trivial relations among only position and only momentum variables

$$\left\{ A_{m_1 m_2 m_3}(\mathbf{x}), A_{n_1 \cdots n_6}(\mathbf{y}) \right\}_{\mathrm{DB}} = -\tilde{\varepsilon}_{m_1 m_2 m_3 n_1 \cdots n_6 p} \partial^p G(\mathbf{x}, \mathbf{y}), \qquad (2.30)$$

$$\left\{ \Pi^{m_1 m_2 m_3}(\mathbf{x}), \Pi^{n_1 \cdots n_6}(\mathbf{y}) \right\}_{\mathrm{DB}} = \tilde{\varepsilon}^{m_1 m_2 m_3 n_1 \cdots n_6 p} \partial_p G(\mathbf{x}, \mathbf{y}).$$

These Dirac brackets agree with those one would obtain in the free theory without the Chern–Simons coupling. The other brackets, such as $\{A_{m_1\cdots m_6}(\mathbf{x}), \Pi^{qrs}(\mathbf{y})\}_{\mathrm{DB}}$, are non-vanishing only for non-zero Chern–Simons coupling. As an example we have

$$\left\{\Pi^{m_1 m_2 m_3}(\mathbf{x}), \ \Pi^{n_1 n_2 n_3}(\mathbf{y})\right\}_{\mathrm{DB}} = \frac{1}{4 \cdot 6! \cdot 6!} \tilde{\varepsilon}^{m_1 m_2 m_3 p_1 \dots p_7} \tilde{\varepsilon}^{n_1 n_2 n_3 s_1 \dots s_7} \partial_{p_7}^x \partial_{s_7}^y X_{p_1 \dots p_6 s_1 \dots s_6}(\mathbf{x}, \mathbf{y}).$$
(2.31)

Turning to the Dirac brackets involving the gauge-invariant field strengths $F_{m_1...m_4} = 4\partial_{[m_1}A_{m_2m_3m_4]}$ and $F_{m_1...m_7}$ defined in (2.13), we find

$$\left\{ A_{m_1 m_2 m_3}(\mathbf{x}), F_{n_1 \cdots n_7}(\mathbf{y}) \right\}_{\mathrm{DB}} = +\tilde{\varepsilon}_{m_1 m_2 m_3 n_1 \cdots n_7} \delta(\mathbf{x}, \mathbf{y}) - 3\tilde{\varepsilon}_{p n_1 \cdots n_7 [m_1 m_2} \partial_{m_3]} \partial^p G(\mathbf{x}, \mathbf{y})
(2.32)$$

$$\left\{ A_{m_1 \cdots m_6}(\mathbf{x}), F_{n_1 \cdots n_4}(\mathbf{y}) \right\}_{\mathrm{DB}} = -\tilde{\varepsilon}_{m_1 \cdots m_6 n_1 \cdots n_4} \delta(\mathbf{x}, \mathbf{y}) - 6\tilde{\varepsilon}_{p n_1 \cdots n_4 [m_1 \cdots m_5} \partial_{m_6]} \partial^p G(\mathbf{x}, \mathbf{y}).$$

The Dirac bracket $\{A_{m_1...m_6}(\mathbf{x}), F_{n_1...n_7}(\mathbf{x})\}_{DB}$ is also non-zero in the interacting theory with Chern–Simons term. However, most important for our analysis are the Dirac brackets among the gauge-invariant field strengths which take a simpler form, viz.

$$\left\{ F_{m_1 \cdots m_4}(\mathbf{x}), F_{n_1 \cdots n_4}(\mathbf{y}) \right\}_{\mathrm{DB}} = 0,
\left\{ F_{m_1 \cdots m_4}(\mathbf{x}), F_{n_1 \cdots n_7}(\mathbf{y}) \right\}_{\mathrm{DB}} = -7 \,\tilde{\varepsilon}_{m_1 \cdots m_4 [n_1 \cdots n_6} \partial_{n_7]} \delta(\mathbf{x}, \mathbf{y}) \tag{2.33a}$$

and

$$\left\{ F_{m_1 \cdots m_7}(\mathbf{x}) , F_{n_1 \cdots n_7}(\mathbf{y}) \right\}_{\mathrm{DB}} = -\frac{1}{432} \tilde{\varepsilon}_{m_1 \cdots m_7 p_1 p_2 p_3} \tilde{\varepsilon}_{n_1 \cdots n_7 p_4 p_5 p_6} \tilde{\varepsilon}^{p_1 \cdots p_6 q_1 \cdots q_4} F_{q_1 \cdots q_4}(\mathbf{x}) \delta(\mathbf{x}, \mathbf{y}) .$$

$$(2.33b)$$

In particular they are local, in the sense that they contain only δ -functions or derivatives of δ -functions, but no Green functions. Furthermore, these brackets are straightforward to convert into generally covariant form since the right-hand sides of the brackets do not depend on the metric and are tensorial.

We can now rewrite the dynamics by using the Dirac brackets. Referring back to the Hamiltonian (2.17), we know that it generates the correct dynamics (weakly) when using Dirac brackets that also allow us to set to zero the second-class constraints in the Hamiltonian. Since the terms involving the constraints \mathcal{C}^{\cdots} in (2.17) decompose according to (2.22) into first- and second-class pieces, we see that the first-class Lagrange multiplier terms in (2.17) acquire additional field-dependent and non-local contributions. As these are, however, pure gauge transformations, we can absorb their effect in a redefinition of the Lagrange multipliers. Working out the dynamics in the Dirac formalism up to gauge transformations, we only need to consider the Hamiltonian density

$$\mathcal{H}_{\text{mat}} = \frac{1}{2 \cdot 4!} F_{n_1 \dots n_4} F^{n_1 \dots n_4} + \frac{1}{2 \cdot 7!} F_{n_1 \dots n_7} F^{n_1 \dots n_7}. \tag{2.34}$$

If one were to also substitute the second-class constraints into this expression, one would obtain terms involving Π^2 but also non-local terms, and for this reason we keep the expression above.

Given these Dirac brackets and the Hamiltonian (2.34), we can now check that the Hamiltonian equations of motion

$$\dot{A}_{mnp}(\mathbf{x}) \approx \int d\mathbf{y} \left\{ A_{mnp}(\mathbf{x}), \, \mathcal{H}_{mat}(\mathbf{y}) \right\}_{DB} + 3 \, \partial_{[m} A_{np]t}(\mathbf{x})$$

$$\dot{A}_{m_1 \cdots m_6}(\mathbf{x}) \approx \int d\mathbf{y} \left\{ A_{m_1 \cdots m_6}(\mathbf{x}), \, \mathcal{H}_{mat}(\mathbf{y}) \right\}_{DB} - 6 \, \partial_{[m_1} A_{m_2 \cdots m_6]t}(\mathbf{x})$$

$$+ 35 \, A_{[tm_1 m_2} F_{m_3 \cdots m_6]}(\mathbf{x})$$
(2.35)

reproduce the duality relation (A.2). Here, we have absorbed all gauge terms in the definition of the temporal component of the matter potentials. Furthermore, the second relation is consistent with the result for A_{tmn} from the first line.

Our analysis above was restricted to the matter sector and we worked in flat space for simplicity. For the comparison with E_{10} beyond level $\ell=2$ one will need to treat gravity in a similar way, by introducing the dual graviton field $A_{m_0|m_1\cdots m_8}$. At the linearised level, it is possible to perform a similar replacement of the spatial derivatives of the metric by the momentum conjugate to the dual graviton [14, 26, 55, 56]. As this extension involves substantial technical complications we leave the inclusion of this field to future work.

As a final remark we note that is tempting to substitute the *full* constraints $\mathcal{C}^{\cdots} = 0$ from (2.14) into the Hamiltonian (2.17). This would lead directly to a form of the Hamiltonian that is quadratic in the momenta Π and moreover ultra-local in that it only depends on canonical variables at one spatial point and is free of derivatives (except for the gauge transformations). This procedure, however, is inconsistent with the Dirac algorithm.

2.2 Canonical quantisation: a new perspective

Given the Dirac brackets (2.29) and (2.33) we can now proceed to canonical quantisation, replacing the canonical variables by functional derivative or multiplication operators in the standard way. For the metric we have the usual substitutions

$$\hat{g}_{mn}(\mathbf{x}) = g_{mn}(\mathbf{x}) , \quad \hat{\Pi}^{mn}(\mathbf{x}) = i\hbar \frac{\delta}{\delta g_{mn}(\mathbf{x})}$$
 (2.36)

where operators are indicated with hats.

For the three- and six-form fields the rules must be adapted in order to account for the non-vanishing commutators (2.30) and similar non-vanishing Dirac brackets among the momenta. As these brackets depend on the split of the constraints into first- and second-class constraints and contain non-local term, we focus rather on the Dirac brackets (2.33) among the gauge-invariant field strengths. For obtaining a quantisation of the Hamiltonian (2.34), this is sufficient. Operators that realise the algebra (2.33) are

$$\hat{F}_{m_1...m_4}(\mathbf{x}) = -\frac{2}{6!} i\hbar G_N \,\tilde{\varepsilon}_{m_1...m_4n_1...n_6} \frac{\delta}{\delta A_{n_1...n_6}(\mathbf{x})} + \frac{10}{3} \,\partial_{[m_1} A_{m_2m_3m_4]}(\mathbf{x})$$

$$\hat{F}_{m_1...m_7}(\mathbf{x}) = -\frac{2}{3!} i\hbar G_N \,\tilde{\varepsilon}_{m_1...m_7n_1n_2n_3} \left(\frac{\delta}{\delta A_{n_1n_2n_3}(\mathbf{x})} + \frac{1}{12} A_{s_1s_2s_3}(\mathbf{x}) \frac{\delta}{\delta A_{s_1s_2s_3n_1n_2n_3}(\mathbf{x})} \right)$$

$$-\frac{7}{3} \partial_{[m_1} A_{m_2...m_7]}(\mathbf{x}) + \frac{140}{3} A_{[m_1m_2m_3} \partial_{m_4} A_{m_5m_6m_7]}(\mathbf{x}) . \tag{2.37}$$

We see that these operator realisations involve a mix of functional derivatives and multiplicative operators. These expressions are tensorial and hold also on curved spaces. The Dirac brackets of the non-gauge invariant fields and momenta can be similarly worked out, but contain non-local contributions. We shall not give the explicit expressions here as they are not needed.

After replacement of the classical quantities by the above operators the quantum Hamiltonian can be presented in the simple operatorial form

$$\hat{\mathcal{H}}(\mathbf{x}) = \hat{\mathcal{H}}_0(\mathbf{x}) - \frac{1}{4} e R^{(10)}(\mathbf{x}) \tag{2.38}$$

where

$$e\hat{\mathcal{H}}_{0}(\mathbf{x}) = -\hbar^{2}G_{N}G_{mn|pq}(\mathbf{x})\frac{\delta}{\delta g_{mn}(\mathbf{x})}\frac{\delta}{\delta g_{pq}(\mathbf{x})}$$

$$+ \frac{G_{N}^{-1}}{2\cdot 4!}e^{2}\hat{F}_{n_{1}...n_{4}}(\mathbf{x})g^{n_{1}m_{1}}(\mathbf{x})\cdots g^{n_{4}m_{4}}(\mathbf{x})\hat{F}_{m_{1}...m_{4}}(\mathbf{x})$$

$$+ \frac{G_{N}^{-1}}{2\cdot 7!}e^{2}\hat{F}_{n_{1}...n_{7}}(\mathbf{x})g^{n_{1}m_{1}}(\mathbf{x})\cdots g^{n_{7}m_{7}}(\mathbf{x})\hat{F}_{m_{1}...m_{7}}(\mathbf{x}).$$

$$(2.39)$$

and where we have separated off the potential term involving the Ricci scalar in (2.38) because at this point the gravitational sector is described solely in terms of the metric. If a full non-linear dualisation of gravity were employed one would expect to also distribute the dynamics more democratically between the metric and its dual field. At the linearised level, the dual field to the D=11 metric has tensor structure $A_{m_0|m_1...m_8}$ [14, 26] and is well-known to appear in the \mathfrak{gl}_{10} level decomposition of \mathfrak{e}_{10} [5, 57] as we shall review in section 3. The ordering of operators in (2.39) is still arbitrary at this point. We take it to be the one written and this will be seen to agree with the ordering which is uniquely fixed by the E_{10} Casimir operator in the next section.

The above differential operators are then supposed to act on the 'wave function of the universe' Ψ , which for the theory (2.11) in question is a functional of the variables $g_{mn}(\mathbf{x})$, $A_{mnp}(\mathbf{x})$ and $A_{m_1\cdots m_6}(\mathbf{x})$ (and eventually also the dual graviton $A_{m_0|m_1\cdots m_8}(\mathbf{x})$). Upon making the requisite operator replacements in the Hamiltonian constraint and assuming that $\mathcal{H}(\mathbf{x})$ can be properly defined as a quantum operator we end up with the WDW equation

$$\hat{\mathcal{H}}(\mathbf{x})\Psi = 0. \tag{2.40}$$

In addition, the wave functional Ψ must satisfy the kinematic constraints

$$\hat{\mathcal{H}}_m(\mathbf{x})\Psi = \hat{\mathcal{G}}^{mn}(\mathbf{x})\Psi = \hat{\mathcal{G}}^{m_1\cdots m_5}(\mathbf{x})\Psi = 0.$$
 (2.41)

These constraints must be imposed for all spatial points labelled by \mathbf{x} . Extending the procedure of the foregoing section also to the gravitational sector would result in another constraint, supplementing the kinematic constraints (2.41) by a 'dual' spatial diffeomorphism constraint (corresponding to the Bianchi identity on the spatial curvature tensor).

As we already mentioned there has been only scant progress with these equations due to conceptual and mathematical problems, such as the 'clash' of functional differential operators at coincident points in (2.39). As we will now see, the present reformulation offers an entirely new perspective on these problems. Namely, we propose to replace the wave functional Ψ above by a wave function Φ depending on infinitely many variables

corresponding to the degrees of freedom in the coset space $E_{10}/K(E_{10})$, that is

$$\Psi\left[g_{mn}(\mathbf{x}), A_{mnp}(\mathbf{x}), \dots\right] \longrightarrow \Phi\left(g_{mn}, A_{mnp}, A_{mnpqrs}, A_{m_0|m_1\cdots m_8}, \dots\right)$$
 (2.42)

The main step is thus to replace a set of field variables depending on the spatial coordinates \mathbf{x} by an infinite tower of new variables corresponding to the degrees of freedom present in the $E_{10}/K(E_{10})$ coset space, and which depend no longer on \mathbf{x} ; the dots in the argument of Ψ are included in order to allow for further dual and auxiliary field variables (which, however, cannot change the on-shell content of the theory). At least in principle, the arguments in the new wave function Φ are supposed to correspond to the values of $g_{mn}(\mathbf{x})$ and $A_{mnp}(\mathbf{x})$, and their duals at one fixed spatial point $\mathbf{x} = \mathbf{x}_0$, as well as possibly other degrees of freedom. This identification is accompanied by the replacement of functional differential operators by ordinary partial derivatives according to the rule

$$\frac{\delta}{\delta\phi(\mathbf{x}_0)} \to \ell_{\mathrm{P}}^{-10} \frac{\partial}{\partial\phi} \qquad \text{for } \phi = g_{mn}, A_{mnp}, \cdots$$
 (2.43)

where $\ell_{\rm P} \equiv (\hbar G_{\rm N})^{1/9}$ is the (eleven-dimensional) Planck length. Observe that this is not a discretisation in any standard sense as there is no underlying space lattice here: rather the spatial dependence is supposed to get encoded into the infinite tower of dual variables on which Φ depends.¹⁰ This effective reduction to one spatial point is in accord with the $E_{10}/K(E_{10})$ sigma model proposal of [5], where the D=11 theory is reduced to one dimension, and the (first order) spatial gradients of the basic fields are regarded and treated as independent degrees of freedom. In other words, spatial dependence has been traded for an infinity of variables at a fixed spatial point, but these can be associated directly with spatial gradients only in lowest order of the level expansion [5,6].

Neglecting spatial gradients is usually associated with the BKL limit in the classical theory, where the Einstein equations are supposed to be dominated by time derivatives near the cosmological singularity [16]. When extending such considerations to the quantised theory, it is important to keep in mind that in the WDW approach there is no a priori 'time', unlike for a Schrödinger wave function, and hence also no hidden time dependence in any of the canonical expressions. Rather, time is supposed to emerge operationally by picking a 'clock variable' and by approximating the WDW equation in a semi-classical expansion by an effective Schrödinger equation, as for instance explained

 $^{^{10}}$ This is also suggested by the reduction of maximal supergravity to two space-time dimensions, where E_9 takes the place of E_{10} . There, at least at the level of the equations of motion, the coordinate dependence of the basic fields can be encoded into an *infinite* tower of dual potentials, which in principle allows us to extract the information on spatial dependence from the dependence on the spectral parameter at a given spatial point (see [58] and references therein).

in [3]. With regard to (2.37), we therefore take the BKL limit as being equivalent to neglecting spatial gradients in comparison with the functional differential operators, since the latter originate from canonical momenta, which themselves are related to velocities. This limit does not involve the Planck length.

The expression that will be related to E_{10} in the next section is then (2.37) with the spatial gradients dropped. Before going into the technical details, we sketch what the correspondence will be. As a first step, and keeping in mind the caveats mentioned above and in the introduction, we propose that the standard WDW equation (2.40) should be replaced by a new constraint equation

$$\Omega \Phi = 0 \tag{2.44}$$

where the original Hamiltonian $\hat{\mathcal{H}}(\mathbf{x})$ is replaced by the E_{10} Casimir operator Ω , up to overall factors, see (3.28) below. This operator, whose differential operator realisation will be discussed in detail in the following sections, acts on the $E_{10}/K(E_{10})$ coset space degrees of freedom which appear as arguments of Φ . Importantly, in this version of the theory any reference to 'space' has disappeared! Likewise there are no short distance singularities any more, thanks to the replacement of functional derivative operators by ordinary derivatives with respect to the coset variables, cf. (2.43). Another key feature is that the E_{10} Casimir operator is unique [59,60], and therefore the proper operator ordering is pre-ordained by E_{10} symmetry.¹¹ Our main result in (3.28) below then is that the operators $\hat{\mathcal{H}}_0(\mathbf{x}_0)$ for fixed \mathbf{x}_0 and Ω match precisely up to and including level $\ell=2$. This non-trivial agreement extends partially to level $\ell=3$ if one replaces the spin connection by the 'dual graviton' variable $A_{m_0|m_1\cdots m_8}$ (where however the trace ω_{bba} of the spin connection is missing due to the constraint $A_{[m_0|m_1\cdots m_8]}=0$) and the spatial curvature term in \mathcal{H} by yet another kinetic term. In the same way that the six-form arose from solving locally the Gauss constraint (2.9b), the linearised dual graviton will arise from solving locally the linearised diffeomorphism constraint (2.9a).

Of course, many questions remain, even disregarding the issue of fermions. One is the fact that the matching between \mathcal{H}_0 and Ω fails starting from level $\ell=3$, reflecting the incompleteness of the 'dictionary' presented in [5]. This incompleteness is also evident from the fact that the spatial Ricci scalar can assume both positive and negative values, whereas the E_{10} Casimir is a positive operator away from the Cartan subalgebra. Furthermore, it seems doubtful that the discrepancies arising at levels $|\ell| \geq 3$ can be resolved purely within the framework of E_{10} alone, as already suggested by the absence of the trace

 $^{^{11}}$ In contrast to finite-dimensional Lie algebras, E_{10} admits no polynomial Casimir operators other than the quadratic one [60].

of the spin connection. It has been argued from the point of view of exceptional field theory and the tensor hierarchy algebra that an appropriate extension of the E_{10} coset will involve an indecomposable structure where E_{10} is augmented by highest weight representations where the first one is triggered by the trace of the spin connection [24, 19, 25], a fact that is also suggested by compatibility with supersymmetry [20, 61].

The present approach thus suggests that the notion of 'space' must be extracted in a similarly 'operational' way as the notion of 'time'. For this we would need to incorporate the kinematical constraints also into the E_{10} framework by endowing them with a group theoretical realisation. First steps in this direction were taken in [22] where an attempt was made to assign these constraints to a representation of E_{10} (which however cannot be a highest or lowest weight representation). If this could be done, we would re-interpret the group theoretical version of the diffeomorphism constraint operator \mathcal{H}_m as a generator of spatial coordinate dependence, simply by conjugation with the operator $\exp(\xi^m \mathcal{H}_m)^{12}$, where ξ^m is some coordinate parametrising the motion away from $\mathbf{x}_0 \equiv \mathbf{x}(0)$. Although such formulas are familiar from quantum field theory, the crucial difference is that the operator \mathcal{H}_m would here be defined entirely group theoretically, and without reference to a pre-existing space-time structure, unlike the standard momentum operator in quantum field theory.

We end this section by observing that in the full theory, the dimensionful constants G_N and \hbar appear explicitly in the operator realisations (2.37) in between the functional derivatives and multiplication parts of the operators. As we shall in the next section consider the operators at one fixed spatial point and drop all spatial derivatives, the operators become homogeneous in the dimensionful constant that thus can be eliminated from the WDW equation (2.40). This is in agreement with the fact that the E_{10} model does not contain any dimensionful constants.

3 Functional realisation of E_{10} at low levels

In this section, we first explain some basic features related to the level expansion of the hyperbolic Kac-Moody algebra \mathfrak{e}_{10} , see [60, 67, 5, 57, 6] for more information. Then we proceed to realise the beginnings of this algebra formally in terms of differential operators on an infinite-dimensional function space by considering its action on the symmetric space $E_{10}/K(E_{10})$. Of course, this is still very far from providing a proper understanding of \mathfrak{e}_{10} : continuing with the construction one quickly runs into the very same difficulties as with

¹²It has been observed that the gauge parameters $(\xi^m, \xi_{mn}, \xi_{m_1 \cdots m_5}, \cdots)$ associated to the kinematic constraints (2.41) constitute the beginning of the Λ_1 representation of E_{10} [62–66]

more traditional realisations, because the full differential operators are unmanageable infinite sums whose summands contain an exponentially growing number of terms.

3.1 \mathbf{E}_{10} commutation relations at levels $|\ell| \leq 3$

There is no known explicit representation of the E_{10} Lie algebra (this remains the key unsolved problem in the theory of indefinite Kac-Moody algebras since its inception more than 50 years ago [68, 59, 60]). Some insight can be gained by decomposing it in terms of representations of a 'manageable' subalgebra. This is achieved by making a level decomposition, which is a \mathbb{Z} -graded decomposition of the infinite-dimensional Lie algebra

$$\mathfrak{e}_{10} = \bigoplus_{\ell = -\infty}^{\infty} \mathfrak{e}_{10}^{(\ell)} \tag{3.1}$$

There are different choices for the $\ell = 0$ subalgebra, but here we pick the one best adapted to the problem at hand, namely

$$\mathfrak{e}_{10}^{(0)} = \mathfrak{gl}_{10} \tag{3.2}$$

see [5,57,6] for further details and explanations; we mostly follow notation and conventions of [6]. Other possible choices for the level-0 subalgebra $\mathfrak{e}_{10}^{(0)}$ are $\mathfrak{so}(9,9) \oplus \mathfrak{gl}_1$ and $\mathfrak{gl}_9 \oplus \mathfrak{sl}_2$ and, respectively, correspond to type IIA and type IIB supergravity [69,70].

The \mathfrak{gl}_{10} generators $K^m{}_n$ obey the standard commutation relations

$$[K^{m}_{n}, K^{p}_{q}] = \delta^{p}_{n} K^{m}_{q} - \delta^{m}_{q} K^{p}_{n}$$
(3.3)

The associated standard bilinear form $\langle \cdot | \cdot \rangle$ reads

$$\langle K^m{}_n | K^p{}_q \rangle = \delta^m_q \delta^p_n - \delta^m_n \delta^p_q \,, \tag{3.4}$$

where the trace term proportional to $\delta_n^m \delta_q^p$ is left undetermined by \mathfrak{gl}_{10} and gets fixed only after embedding $\mathfrak{gl}_{10} \subset \mathfrak{e}_{10}$. At levels $\ell = 1, 2, 3$ the subspaces $\mathfrak{e}_{10}^{(\ell)}$ are, respectively, spanned by a three-form, a six-form and mixed Young tableau representation, to wit,

$$E^{m_1 m_2 m_3}$$
, $E^{m_1 \cdots m_6}$, $E^{m_0 | m_1 \cdots m_8}$ (3.5)

The corresponding negative level generators for $\ell = -1, -2, -3$ are

$$F_{m_1m_2m_3}$$
, $F_{m_1\cdots m_6}$, $F_{m_0|m_1\cdots m_8}$ (3.6)

with $E^{[m|n_1\cdots n_8]} = F_{[m|n_1\cdots n_8]} = 0$. We note that these representations are in one-to-one correspondence with the ones encountered in the Hamiltonian analysis of the foregoing

section. Yet higher level generators in (3.1) can be determined analogously, but the analysis becomes rapidly more complicated, and actually unmanageable beyond the very lowest levels, see e.g. [57] for a table of representations up to $|\ell| \leq 28$. For $|\ell| \leq 3$ the commutation relations between positive and negative level generators read

$$\begin{bmatrix} E^{mnp}, E^{qrs} \end{bmatrix} = E^{mnpqrs}, \quad \begin{bmatrix} E^{mnp}, E^{q_1 \cdots q_6} \end{bmatrix} = 3E^{[m|np]q_1 \cdots q_6}
\begin{bmatrix} F_{mnp}, F_{qrs} \end{bmatrix} = -F_{mnpqrs}, \quad \begin{bmatrix} F_{mnp}, F_{q_1 \cdots q_6} \end{bmatrix} = -3F_{[m|np]q_1 \cdots q_6}$$
(3.7)

Note that the normalisation of the $\ell = 3$ generator differs from [6] by a factor of 3. The minus sign in the definition of F_{mnpqrs} and $F_{m|n_1\cdots n_8}$ ensures that (formally) the E's and F's are each other's hermitean conjugates: $E^{\dagger} = F$. These generators transform in the standard tensorial way under GL(10):

$$[K^m_n, E^{qrs}] = 3 \, \delta_n^{[q} E^{rs]m} , \quad [K^m_n, F_{qrs}] = -3 \, \delta_{[q}^m F_{rs]n} , \quad \text{etc.}$$
 (3.8)

For the commutators mixing positive and negative levels we have

$$[F_{mnp}, E^{qrs}] = -18 \, \delta^{[qr}_{[mn} K^{s]}_{p]} + 2 \, \delta^{qrs}_{mnp} K,$$
 (3.9)

where $K \equiv K^m{}_m$, and

$$[F_{m_1m_2m_3}, E^{n_1\cdots n_6}] = 5! \, \delta_{m_1m_2m_3}^{[n_1n_2n_3} E^{n_4n_5n_6}]$$

$$[F_{m_1\cdots m_6}, E^{n_1n_2n_3}] = 5! \, \delta_{[m_1m_2m_3}^{n_1n_2n_3} F_{m_4m_5m_6}]$$

$$[F_{m_1\cdots m_6}, E^{n_1\cdots n_6}] = -6 \cdot 6! \, \delta_{[m_1\cdots m_5}^{[n_1\cdots n_5} K^{n_6}]_{m_6}] + \frac{2}{3} \cdot 6! \, \delta_{m_1\cdots m_6}^{n_1\cdots n_6} K$$

$$[F_{m_1m_2m_3}, E^{n_0|n_1\cdots n_8}] = 7 \cdot 16 \, \left(\delta_{m_1m_2m_3}^{n_0|[n_1n_2} E^{n_3\cdots n_8}] - \delta_{m_1m_2m_3}^{[n_1n_2n_3} E^{n_4\cdots n_8]n_0}\right)$$

$$[F_{m_1\cdots m_6}, E^{n_0|n_1\cdots n_8}] = \frac{1}{3} \cdot 8! \, \left(\delta_{m_1\cdots m_6}^{n_0[n_1\cdots n_5} E^{n_6n_7n_8}] - \delta_{m_1\cdots m_6}^{[n_1\cdots n_6} E^{n_7n_8]n_0}\right)$$

$$[E^{m_0|m_1\dots m_8}, F_{n_0|n_1\dots n_8}] = -\frac{8 \cdot 8!}{9} \left\{\left(\delta_{n_0}^{m_0} \delta_{n_1\dots n_8}^{m_1\dots m_8} + \delta_{n_0}^{[m_1} \delta_{n_2\dots m_8}^{m_2\dots m_8}]\delta_{n_1}^{m_0}\right)K$$

$$-\delta_{n_1\dots n_8}^{m_1\dots m_8} K^{m_0}{}_{n_0} - \delta_{n_0[n_2\dots m_8}^{m_1} K^{m_0}{}_{n_1}] - \delta_{n_1n_2\dots n_8}^{m_0[m_2\dots m_8} K^{m_1}{}_{n_0}$$

$$-8\delta_{n_0}^{m_0} \delta_{[n_1\dots n_7}^{[m_1\dots m_7} K^{m_8}]_{n_8}] - 7\delta_{n_0}^{m_1} \delta_{n_1n_2\dots n_7}^{m_0m_2\dots m_7} K^{m_8}{}_{n_8} \right\}.$$

$$(3.10)$$

¹³Corresponding tables for $\mathfrak{e}_{10}^{(0)} = \mathfrak{so}(9,9) \oplus \mathfrak{gl}_1$ can be found in [69] and for the type IIB case $\mathfrak{e}_{10}^{(0)} = \mathfrak{gl}_9 \oplus \mathfrak{sl}_2$ in [70].

The normalisations with respect to the standard bilinear form imply

$$\langle F_{m_1 m_2 m_3} | E^{n_1 n_2 n_3} \rangle = 3! \, \delta_{m_1 m_2 m_3}^{n_1 n_2 n_3}$$

$$\langle F_{m_1 \cdots m_6} | E^{n_1 \cdots n_6} \rangle = 6! \, \delta_{m_1 \cdots m_6}^{n_1 \cdots n_6}$$

$$\langle F_{m_0 | m_1 \cdots m_8} | E^{n_0 | n_1 \cdots n_8} \rangle = \frac{8}{9} \cdot 8! \left(\delta_{m_0}^{n_0} \delta_{m_1 \cdots m_8}^{n_1 \cdots n_8} - \delta_{m_0}^{[n_1} \delta_{m_1 \cdots m_8}^{n_2 \cdots n_8] n_0} \right)$$
(3.11)

where the latter normalisation implies unit normalisation for real root generators (for which two of the indices coincide), e.g. $\langle F_{1|12345678}|E^{1|12345678}\rangle=1$.

We also recall that the finite-dimensional exceptional algebras \mathfrak{e}_6 , \mathfrak{e}_7 and \mathfrak{e}_8 (which are of course all contained in \mathfrak{e}_{10}) can be obtained by restricting the indices m, n, ... to the ranges $\{1, ..., 6\}$, $\{1, ..., 7\}$ and $\{1, ..., 8\}$, respectively [71]. The level expansions for \mathfrak{e}_6 and \mathfrak{e}_7 terminate at $|\ell| = 2$, while the one for \mathfrak{e}_8 extends up to $|\ell| = 3$. These truncations to finite-dimensional subalgebras of \mathfrak{e}_{10} provide useful checks on our formulas, especially when terms must cancel among themselves that would otherwise be cancelled by higher level contributions that are absent for the finite-dimensional algebras.

3.2 Induced Actions

We parametrise the $E_{10}/K(E_{10})$ coset element formally as

$$\mathcal{V} = \mathcal{V}_0 \mathcal{N} \tag{3.12}$$

where $\mathcal{V}_0 \equiv \exp(h^m{}_n K^n{}_m) \in GL(10)$ corresponds to the standard zehnbein $e_m{}^a$, see (2.2), (but as an E_{10} 'matrix vielbein'), and \mathcal{N} to the unipotent part:

$$\mathcal{N} = \exp\left(\frac{1}{3!}A_{mnp}E^{mnp} + \frac{1}{6!}A_{mnpqrs}E^{mnpqrs} + \frac{1}{8!}A_{n_0|n_1\cdots n_8}E^{n_0|n_1\cdots n_8} + \cdots\right)$$
(3.13)

Here m, n, p, ... are curved (= GL(10)) indices, while a, b, c, ... are flat (= SO(10)) indices. We can use the zehnbein $e_m{}^a$ and its inverse to convert curved to flat indices on the fields and on the E_{10} generators (recall that the fundamental form fields A_{mnp} , etc. are the ones with curved indices). When dealing with $K(E_{10})$ it is sometimes convenient to switch to flat indices on the generators, so as to be able to form linear combinations of type E - F.

For the induced action we note that the above expression corresponds to a parabolic ('almost triangular') gauge where the factor \mathcal{V}_0 corresponds to the Levi subgroup GL(10), which gets completed with the unipotent part \mathcal{N} to a parabolic subgroup of E_{10} . Note that with triangular $e_m{}^a$, the factor \mathcal{V}_0 , and with it the parabolic gauge become fully triangular. For simplicity, and to facilitate the comparison with the standard WDW approach we thus trade the triangular zehnbein by the metric g_{mn} and its inverse.

For any wave function $\Phi = \Phi(\mathcal{V}) \equiv \Phi(g_{mn}, A_{mnp}, \cdots)$ we have the induced action

$$(g \circ \Phi)(\mathcal{V}) \equiv \Phi(g^{-1}\mathcal{V}k) \tag{3.14}$$

where the compensating $K(E_{10})$ transformation $k = k(g, \mathcal{V})$ is only needed for lower triangular g to restore the parabolic gauge. To identify the differential operators realizing the Lie algebra \mathfrak{e}_{10} we evaluate this formula for infinitesimal transformations. So we set $g_{\epsilon} = \exp(\epsilon X)$ to compute

$$(g_{\epsilon} \circ \Phi)(\mathcal{V}) = \Phi\left(\mathcal{V}(\mathbf{1} - \epsilon \mathcal{V}^{-1}X\mathcal{V} + \epsilon \delta k)\right) + \mathcal{O}(\epsilon^{2})$$
(3.15)

Here we can restrict attention to the strictly upper or strictly lower triangular transformations, as the GL(10) part is straightforward, see (3.19) below. The differential operator realisation $\mathcal{O}(X)$ of the relevant transformation is then obtained in the usual way as

$$\mathcal{O}(X)\Phi(\mathcal{V}) := \lim_{\epsilon \to 0} \frac{1}{\epsilon} \Big((g_{\epsilon} \circ \Phi)(\mathcal{V}) - \Phi(\mathcal{V}) \Big)$$
(3.16)

Therefore, schematically, the procedure works as follows, where for illustrative purposes we set the GL(10) submatrix to unity, that is $\mathcal{V}_0 = \mathbf{1}$, and as an example consider a parabolic transformation that does not require compensators. For instance, with $\epsilon * X \equiv \frac{1}{3!} \epsilon_{mnp} E^{mnp}$, we have

$$\Phi(\mathcal{N}) \equiv \Phi(A_3, A_6, A_{1,8}, \cdots) \rightarrow
\rightarrow \Phi(A_3 + \epsilon_3, A_6 + \epsilon_3 A_3, A_{1,8} + \epsilon_3 A_6 + \epsilon_3 A_3 A_3, \cdots)$$
(3.17)

with appropriate (anti-)symmetrisations which we do not write out. From this formula one can directly read off the formulas (3.21) below. For the strictly upper triangular part the calculation of the commutators is thus straightforward, at least in principle, and leads to the low level results given in the following section. Observe that the resulting differential operators in principle contain infinitely many terms.

The computation for the lower triangular part is more involved. Taking as an example $X = \frac{1}{3!} \epsilon^{mnp} F_{mnp}$, we need an infinitesimal compensator

$$\epsilon * \delta k = \frac{1}{3!} \epsilon^{mnp} \mathcal{V}^{-1} \left(F_{mnp} - g_{mq} g_{nr} g_{ps} E^{qrs} \right) \mathcal{V}$$
(3.18)

in (3.15), and analogously for all $\ell \leq -2$ generators. While upper triangular transformations push the level only up, the compensating transformations require levels to go up and down, though down only by finitely many levels at order $\mathcal{O}(\epsilon)$, depending on the level of the F transformation under consideration. Again this computation results in an infinite number of terms, independently of the level.

3.3 Differential Operators

Applying the above procedure by including for the non-negative level differential operators the fields up to $A_{m_0|m_1...m_8}$ on $\ell=3$, one gets the following \mathfrak{gl}_{10} generators from the induced action

$$K^{m}{}_{n} = -g_{np} \frac{\partial}{\partial g_{mp}} - \frac{1}{2} A_{np_{1}p_{2}} \frac{\partial}{\partial A_{mp_{1}p_{2}}} - \frac{1}{5!} A_{np_{1}\dots p_{5}} \frac{\partial}{\partial A_{mp_{1}\dots p_{5}}} - \frac{1}{8!} A_{n|p_{1}\dots p_{8}} \frac{\partial}{\partial A_{m|p_{1}\dots p_{8}}} - \frac{1}{7!} A_{p_{0}|p_{1}\dots p_{7}n} \frac{\partial}{\partial A_{p_{0}|p_{1}\dots p_{7}m}} + \dots$$
(3.19)

which implements the standard action of \mathfrak{gl}_{10} on tensors. Differentiation for the mixed symmetry field is normalised in the same way as the generators in (3.11), i.e.

$$\frac{\partial A_{m_0|m_1...m_8}}{\partial A_{n_0|n_1...n_8}} = \frac{8}{9} \cdot 8! \left(\delta_{m_0}^{n_0} \delta_{m_1...m_8}^{n_1...n_8} - \delta_{m_0}^{[n_1} \delta_{m_1...m_8}^{n_2...n_8]n_0} \right). \tag{3.20}$$

For the positive level generators up to $\ell = 3$ we obtain

$$E^{n_{1}n_{2}n_{3}} = -\frac{\partial}{\partial A_{n_{1}n_{2}n_{3}}} + \frac{1}{12} A_{p_{1}p_{2}p_{3}} \frac{\partial}{\partial A_{p_{1}p_{2}p_{3}n_{1}n_{2}n_{3}}} + \frac{1}{180} A_{p_{1}\dots p_{6}} \frac{\partial}{\partial A_{p_{1}|p_{2}\dots p_{6}n_{1}n_{2}n_{3}}} - \frac{1}{48} A_{p_{1}p_{2}p_{3}} A_{p_{4}p_{5}p_{6}} \frac{\partial}{\partial A_{p_{1}|p_{2}\dots p_{6}n_{1}n_{2}n_{3}}} + \dots$$

$$E^{n_{1}\dots n_{6}} = -\frac{\partial}{\partial A_{n_{1}\dots n_{6}}} + \frac{1}{12} A_{p_{1}p_{2}p_{3}} \frac{\partial}{\partial A_{p_{1}|p_{2}p_{3}n_{1}\dots n_{6}}} + \dots$$

$$E^{n_{0}|n_{1}\dots n_{8}} = -\frac{\partial}{\partial A_{n_{0}|n_{1}\dots n_{8}}} + \dots$$
(3.21)

For the negative level generators we only give the generators at levels $\ell = -1, -2$ and only include the contributions from the coordinates up to $A_{n_1...n_6}$ since the expressions become very unwieldy for $\ell < -2$. Since we have not performed the dualisation of gravity in D = 11 supergravity, the expressions are sufficient for the results of this paper. We get

$$F_{n_{1}n_{2}n_{3}} = 3g_{p[n_{1}}A_{n_{2}n_{3}]q} \frac{\partial}{\partial g_{pq}} - \frac{1}{3}A_{n_{1}n_{2}n_{3}}g_{pq} \frac{\partial}{\partial g_{pq}}$$

$$- g_{n_{1}p_{1}}g_{n_{2}p_{2}}g_{n_{3}p_{3}} \frac{\partial}{\partial A_{p_{1}p_{2}p_{3}}} - \frac{1}{6}A_{n_{1}n_{2}n_{3}p_{1}p_{2}p_{3}} \frac{\partial}{\partial A_{p_{1}p_{2}p_{3}}}$$

$$- \frac{1}{12}A_{n_{1}n_{2}n_{3}}A_{p_{1}p_{2}p_{3}} \frac{\partial}{\partial A_{p_{1}p_{2}p_{3}}} + \frac{3}{4}A_{p_{1}[n_{1}n_{2}}A_{n_{3}]p_{2}p_{3}} \frac{\partial}{\partial A_{p_{1}p_{2}p_{3}}}$$

$$+ \frac{1}{12}g_{n_{1}p_{1}}g_{n_{2}p_{2}}g_{n_{3}p_{3}}A_{p_{4}p_{5}p_{6}} \frac{\partial}{\partial A_{p_{1}\dots p_{6}}} - \frac{1}{720}A_{n_{1}n_{2}n_{3}}A_{p_{1}\dots p_{6}} \frac{\partial}{\partial A_{p_{1}\dots p_{6}}}$$

$$+ \frac{1}{80}A_{p_{1}\dots p_{5}[n_{1}}A_{n_{2}n_{3}]p_{6}} \frac{\partial}{\partial A_{p_{1}\dots p_{6}}} + \frac{1}{48}A_{p_{1}p_{2}p_{3}}A_{p_{4}p_{5}[n_{1}}A_{n_{2}n_{3}]p_{6}} \frac{\partial}{\partial A_{p_{1}\dots p_{6}}}$$

$$+ \cdots$$

$$F_{n_{1}...n_{6}} = -6g_{p[n_{1}}A_{n_{2}...n_{6}]q} \frac{\partial}{\partial g_{pq}} - \frac{2}{3}A_{n_{1}...n_{6}}g_{pq} \frac{\partial}{\partial g_{pq}} - 30g_{p[n_{1}}A_{n_{2}n_{3}n_{4}}A_{n_{5}n_{6}]q} \frac{\partial}{\partial g_{pq}}$$

$$- \frac{5}{3}A_{s_{1}s_{2}s_{3}[n_{1}n_{2}n_{3}}A_{n_{4}n_{5}n_{6}]} \frac{\partial}{\partial A_{s_{1}s_{2}s_{3}}} - \frac{3}{2}A_{s_{1}s_{2}[n_{1}}A_{n_{2}...n_{6}]s_{3}} \frac{\partial}{\partial A_{s_{1}s_{2}s_{3}}}$$

$$- \frac{1}{6}A_{s_{1}s_{2}s_{3}}A_{n_{1}...n_{6}} \frac{\partial}{\partial A_{s_{1}s_{2}s_{3}}} - 5A_{s_{1}s_{2}[n_{1}}A_{n_{2}n_{3}n_{4}}A_{n_{5}n_{6}]s_{3}} \frac{\partial}{\partial A_{s_{1}s_{2}s_{3}}}$$

$$- 20A_{n_{1}n_{2}n_{3}}g_{n_{4}s_{1}}g_{n_{5}s_{2}}g_{n_{6}s_{3}} \frac{\partial}{\partial A_{s_{1}s_{2}s_{3}}}$$

$$- \frac{3}{5!}A_{n_{1}s_{1}...s_{5}}A_{s_{6}n_{2}...n_{6}} \frac{\partial}{\partial A_{s_{1}...s_{6}}} - \frac{1}{3 \cdot 5!}A_{n_{1}...n_{6}}A_{s_{1}...s_{6}} \frac{\partial}{\partial A_{s_{1}...s_{6}}}$$

$$+ \frac{1}{12}A_{n_{1}s_{1}...s_{5}}A_{s_{6}n_{2}n_{3}}A_{n_{4}n_{5}n_{6}} \frac{\partial}{\partial A_{s_{1}...s_{6}}} - \frac{5}{108}A_{s_{1}s_{2}s_{3}}A_{s_{4}s_{5}s_{1}n_{2}n_{3}}A_{n_{4}n_{5}n_{6}} \frac{\partial}{\partial A_{s_{1}...s_{6}}}$$

$$+ \frac{5}{24}A_{s_{1}s_{2}s_{3}}A_{s_{4}n_{1}...n_{5}}A_{n_{6}s_{5}s_{6}} \frac{\partial}{\partial A_{s_{1}...s_{6}}} - \frac{5}{24}A_{s_{1}s_{2}s_{3}}A_{s_{4}s_{5}n_{1}}A_{n_{2}n_{3}n_{4}}A_{n_{5}n_{6}s_{6}} \frac{\partial}{\partial A_{s_{1}...s_{6}}}$$

$$- g_{n_{1}s_{1}} \cdots g_{n_{6}s_{6}} \frac{\partial}{\partial A_{s_{1}...s_{6}}} - \frac{5}{3}A_{s_{1}s_{2}s_{3}}A_{n_{1}n_{2}n_{3}}g_{n_{4}s_{4}}g_{n_{5}s_{5}}g_{n_{6}s_{6}} \frac{\partial}{\partial A_{s_{1}...s_{6}}}$$

$$+ \cdots$$

$$(3.23)$$

Even when not writing out antisymmetrisations explicitly, all terms on the right-hand sides are understood to be antisymmetrised properly in the n_i indices.

Up to \mathfrak{e}_7 for which the indices assume only the values $m, n, \ldots \in \{1, \ldots, 7\}$, the level decomposition stops at this level and one can check using Schouten identities that all commutators close correctly. For higher rank \mathfrak{e}_n this requires contributions from yet higher levels that we have not worked out.

We also note that the property that E and F are each other's Hermitian conjugates is not manifest in this functional realisation. In principle, this requires an appropriate measure on the function space that the differential operators are acting on. To the best of our knowledge, such a measure is not known for the symmetric space $E_{10}/K(E_{10})$, but does exist for the finite-dimensional truncations. In section 4 below, we shall investigate the measure for finite-dimensional subspaces.

3.4 WDW Hamiltonian and the E_{10} Casimir operator

As is well known [60], one can define a normal ordered Casimir operator for E_{10} when acting on integrable modules with a highest weight element. The E_{10} Casimir with parabolic normal ordering adapted to the GL(10) decomposition is

$$\Omega = \frac{1}{2}K^{m}{}_{n}K^{n}{}_{m} - \frac{1}{18}KK + \frac{23}{6}K + \frac{1}{3!}F_{mnp}E^{mnp} + \frac{1}{6!}F_{m_{1}...m_{6}}E^{m_{1}...m_{6}} + \cdots$$
 (3.24)

The term linear in K is fixed by requiring the Casimir to commute with E_{10} . To determine its coefficient it is enough to check that Ω commutes with E^{mnp} and F_{mnp} , as all the higher level generators are given by multi-commutators of the ones at $\ell = \pm 1$; the remaining terms are uniquely given by the general expression (B.1). The above expression differs from the standard one [60] only in its level zero contribution, where instead there appears a contribution depending on the \mathfrak{e}_{10} Weyl vector ϖ . This difference is the result of a partial reordering of the $\ell = 0$ generators, since the \mathfrak{gl}_{10} generators on level $\ell = 0$ are not normal ordered, unlike the $\ell \neq 0$ terms. Taking this difference into account we have complete agreement with the standard formula, as we will demonstrate in appendix \mathbf{B} .

Now let us work out the Casimir up to $\ell=2$ with our explicit expressions for the E_{10} generators. As it turns out there are numerous cancellations, and after some algebra we are left with¹⁴

$$\Omega = \frac{1}{2} \left[g_{mp} \frac{\partial}{\partial g_{np}} g_{nq} \frac{\partial}{\partial g_{mq}} - \frac{1}{9} \left(g_{mn} \frac{\partial}{\partial g_{mn}} \right)^2 \right] - \frac{23}{6} g_{mn} \frac{\partial}{\partial g_{mn}}$$

$$+ \frac{1}{3!} g_{mq} g_{nr} g_{ps} \frac{\partial}{\partial A_{mnp}} \frac{\partial}{\partial A_{qrs}} + \frac{1}{6!} g_{m_1 n_1} \cdots g_{m_6 n_6} \frac{\partial}{\partial A_{m_1 \cdots m_6}} \frac{\partial}{\partial A_{n_1 \cdots n_6}}$$

$$- \frac{1}{36} g_{mq_1} g_{nq_2} g_{pq_3} A_{q_4 q_5 q_6} \frac{\partial}{\partial A_{q_1 \cdots q_6}} \frac{\partial}{\partial A_{mnp}}$$

$$+ \frac{1}{3!} \cdot \frac{1}{144} g_{k_1 p_1} g_{k_2 p_2} g_{k_3 p_3} A_{m_1 m_2 m_3} A_{n_1 n_2 n_3} \frac{\partial}{\partial A_{m_1 m_2 m_3 k_1 k_2 k_3}} \frac{\partial}{\partial A_{n_1 n_2 n_3 p_1 p_2 p_3}} + \dots$$

Remarkably many cross terms cancel, in particular the ones $\propto \delta/\delta g \cdot \delta/\delta A$, and it is an interesting question whether such cancellations still persist beyond level $\ell=2$. We also notice that the terms involving the three- and six-form variables can be written more simply and more suggestively as

$$\Omega \Big|_{|\ell|=1,2} = \frac{e^2}{4!} g^{m_1 n_1} \cdots g^{m_4 n_4} \mathcal{F}_{m_1 \cdots m_4} \mathcal{F}_{n_1 \cdots n_4} + \frac{e^2}{7!} g^{m_1 n_1} \cdots g^{m_7 n_7} \mathcal{F}_{m_1 \cdots m_7} \mathcal{F}_{n_1 \cdots n_7}$$
 (3.26)

where

$$\mathcal{F}_{m_{1}...m_{4}} = -\frac{1}{6!} \tilde{\varepsilon}_{m_{1}...m_{4}n_{1}...n_{6}} \frac{\partial}{\partial A_{n_{1}...n_{6}}},$$

$$\mathcal{F}_{m_{1}...m_{7}} = -\frac{1}{3!} \tilde{\varepsilon}_{m_{1}...m_{7}n_{1}...n_{3}} \left(\frac{\partial}{\partial A_{n_{1}...n_{3}}} + \frac{1}{12} A_{s_{1}s_{2}s_{3}} \frac{\partial}{\partial A_{s_{1}s_{2}s_{3}n_{1}n_{2}n_{3}}} \right). \tag{3.27}$$

Comparison of (3.26) with (2.38) now immediately shows that, up to and including level $\ell = 2$, this structure coincides with the bosonic Hamiltonian of D = 11 supergravity.

The E_n Casimir for $n \leq 8$ was already worked out in [72] in the same truncation.

That is, at a given spatial point, we have the equality

$$e\hat{\mathcal{H}}_0 = -\frac{2\hbar^2 G_N}{\ell_P^{20}} \Omega \Big|_{|\ell| \le 2}$$
(3.28)

provided we convert the functional differential operators into ordinary partial derivatives according to the rule (2.43). We also note that formula (3.28) is consistent with the fact that $\hat{\mathcal{H}}_0$ has dimension $M \cdot L^{-10}$ (= energy density) while Ω is dimensionless. We recall that $\ell_P = (\hbar G_N)^{1/9}$ and so only two independent fundamental constants appear in (3.28).

We can no longer expect complete matching between the E_{10} Casimir and the D=11 Hamiltonian beyond $\ell=2$ without a proper dualisation of gravity. This is already clear from the absence of the trace of the spin connection ω_{bba} on the E_{10} side, and from the fact that the positivity of the E_{10} Casimir away from the Cartan subalgebra is in conflict with the fact that the spatial curvature contribution $\propto R^{(10)}$ in the WDW Hamiltonian (2.38) can have either sign. There are further mismatches at $\ell=3$ which were already exposed in [6,20]. At yet higher levels, the known correspondence ('dictionary') breaks down altogether.

Nevertheless, disregarding the remaining discrepancies, we note that (3.25) has a fixed ordering of the differential operators which is uniquely prescribed by the form of the E_{10} Casimir, with all differential operators to the right, except for standard WDW term in the first line (in cancelling contributions proportional to $A_3 \partial/\partial A_3$ and $A_6 \partial/\partial A_6$ the term $\frac{23}{6}K$ again plays a crucial role). We also note that by the very definition of the Casimir operator we have an infinite number of E_{10} 'charges' that commute with the Casimir, namely all operators corresponding to the E_{10} generators. Whether these admit a space-time interpretation as 'observables' remains to be explored.

With the identification (3.28) the WDW operator acquires a 'dimensionless' form since all terms in (2.37) are homogeneous in dimensionful constants after dropping the terms involving spatial gradients. In this form the semi-classical limit $\hbar \to 0$ evidently cannot be meaningfully discussed, as \hbar appears only as an overall factor. The issue of the semi-classical limit is thus intimately connected to the question of space emergence; the requisite dimensionful parameters only appear after inclusion of the spatial derivative terms.

Let us also comment on the remaining constraints. As emphasised in section 2, these involve spatial derivatives, see for instance (2.9a) and (2.20). Applying the same substitutions of magnetic field strengths (2.14) (or more properly their second-class version) to the terms not involving explicit spatial derivatives, the first Gauss constraint (2.20)

becomes for example

$$\mathcal{G}^{mn} = \partial_p \Pi^{mnp} + \frac{1}{864} \tilde{\varepsilon}^{mnq_1...q_8} F_{q_1...q_4} F_{q_5...q_8}$$

$$\rightarrow \partial_p \frac{\delta}{\delta A_{mnp}} - \frac{1}{36 \cdot 6!} \tilde{\varepsilon}_{q_1...q_{10}} \frac{\delta}{\delta A_{mnq_1...q_4}} \frac{\delta}{\delta A_{q_5...q_{10}}} + \dots$$
(3.29)

where we have applied our quantisation from section 2.2 and so converted the constraint into a functional differential operator in field space up to the explicit spatial derivative. The ellipses include terms involving spatial gradients of the fields and non-local terms that are due to solving the second-class constraints. We expect that similar manipulations can be applied to the diffeomorphism constraint after dualising gravity at the linearised level. These differential operators have to be applied to the WDW wave functional Ψ . In the comparison to E_{10} we drop the explicit spatial derivatives and non-local terms and arrive at an ultra-local expression that can also be interpreted as a constraint on the E_{10} wave function Φ if one transitions according to (2.42). This represents the quantum version of the classical constraints studied in [22, 23] that can be imposed consistently on the classical E_{10} model. We note that, when determining the \mathfrak{e}_{10} weight of the components of the constraints, there seems to be a relation to the indecomposable extension of \mathfrak{e}_{10} studied in [19].

4 Comparison with quantum BKL analysis

In this section, we consider the solutions of the E_{10} WDW equation $\Omega\Phi = 0$ and their relation to previous work on the quantisation of the BKL/cosmological billiards approximation to D = 11 supergravity in the vicinity of a space-like singularity [16, 73–75]. The quantisation of the cosmological billiards picture was found to lead to a normalisable wave function of the Universe that tends to zero when approaching the singularity [36], thus realising DeWitt's original idea of the quantum mechanical resolution of classical singularities [1], see also [76, 77, 45, 39]. We shall review this result that uses only the Cartan subalgebra of \mathfrak{e}_{10} together with the input of the walls locations from cosmological billiard. We then generalise the analysis to include also root generators but we restrict mainly to the case of a single root generator for simplicity. This does not alter the physical conclusions and also connects to the idea of discrete symmetries in string theory.

In group theoretical terms, the BKL approximation corresponds to the restriction of \mathfrak{e}_{10} to its Cartan subalgebra \mathfrak{h} . Here we shall generalise this setting to larger finite-dimensional subalgebras of \mathfrak{e}_{10}

$$\mathfrak{h}_{\perp} \oplus \mathfrak{g}_{(r)} \subset \mathfrak{e}_{10} , \quad \langle \mathfrak{h}_{\perp} | \mathfrak{g}_{(r)} \rangle = 0 , \quad d \equiv \dim \mathfrak{h}_{\perp} = 10 - r$$
 (4.1)

corresponding to a compactification from D=11 down to D=d+1 space-time dimensions. Here, the subalgebra $\mathfrak{g}_{(r)}$ is of rank r, and the dimension d of the restricted Cartan subalgebra $\mathfrak{h}_{\perp} \subset \mathfrak{h}$ coincides with the dimension of the singular spatial hypersurface. The relevant modular group is then $\mathcal{W}_{\perp} \times G_{(r)}(\mathbb{Z})$, where \mathcal{W}_{\perp} is the even subgroup of the Weyl group associated to the billiard defined by the remaining walls for \mathfrak{h}_{\perp} , and $G_{(r)}(\mathbb{Z})$ the appropriate discrete U-duality group for the matter sector. Below we will in particular consider the cases $\mathfrak{g}_{(1)} \equiv \mathfrak{g}_{\alpha} = \mathfrak{sl}_2$ for arbitrary real and timelike imaginary roots α , as well as higher rank examples such as $\mathfrak{g}_{(7)} = \mathfrak{e}_7$ and $\mathfrak{g}_{(8)} = \mathfrak{e}_8$.

4.1 Review of quantum cosmological billiards

In [36, 37], the quantisation of the E_{10} cosmological billiard was studied. The analysis is based on the mini-superspace approximation where only the diagonal components of the spatial metric are retained and their free motion is constrained by hard walls that are the only remnant of the other components and the matter fields. The ten diagonal components of the metric are associated with the Cartan subalgebra generators K^m_m for m = 1, ..., 10 (no sum). As the DeWitt metric (2.10) reduces to a Lorentzian metric η_{mn} of signature (1,9) on diagonal metrics, a convenient set of coordinates for the diagonal components $g_{mm} = \exp(-2\beta^m)$ is given by [74]

$$\beta^m = \rho \gamma^m$$
, with $\rho > 0$ and $\gamma^n \eta_{mn} \gamma^n = -1$ (4.2)

with the logarithmic scale factors β^m , and coordinates γ^m on the unit hyperboloid and ρ representing the effective time parameter for the approach to the singularity which is at $\rho \to \infty$ in these coordinates. Together, ρ and γ^m parametrise the interior of the forward light-cone in the space of diagonal spatial metrics. The hard 'billiard' walls constrain the motion in the forward light-cone to a fundamental chamber of the E₁₀ Weyl group [73]. Quantum-mechanically, one has to solve the wave equation on this Lorentzian space with Dirichlet boundary conditions corresponding to the hard walls.¹⁵

The wave operator is invariant under the E_{10} Weyl group and given by

$$\frac{1}{2} \sum_{m=1}^{10} (K^m{}_m)^2 - \frac{1}{18} \left(\sum_{m=1}^{10} K^m{}_m \right)^2 = -\rho^{-9} \partial_\rho (\rho^9 \partial_\rho) + \rho^{-2} \Delta_{\rm LB} , \qquad (4.3)$$

where we now suspend the summation convention by writing out sums explicitly. Here Δ_{LB} is the Laplace–Beltrami operator on the unit hyperboloid of dimension nine. These

¹⁵For a discussion of other boundary conditions and related ideas see [76–78].

terms are recognised as the restriction of the E_{10} Casimir (3.24) to the Cartan generators, except for the normal-ordering term $\frac{23}{6}K$. The latter breaks E_{10} Weyl symmetry on its own. However, together with all root generators in (3.24) (full, continuous) E_{10} symmetry is restored. The restriction of the full wave equation $\Omega\Phi = 0$ to dependence only on diagonal metric components therefore differs from the wave equation coming from the cosmological billiard (with boundary conditions given by the hard walls) by the normal-ordering term. One may wonder whether the addition of this term will modify the conclusion of [36] regarding the vanishing of the wave function at the singularity.

In order to investigate this we recall from [36] that the spectrum of the Laplace-Beltrami operator on the unit hyperboloid in d = 10 dimensions (with Dirichlet boundary conditions) is bounded by

$$-\Delta_{\rm LB} \ge 16\,,\tag{4.4}$$

which, together with a separation ansatz $\Phi(\rho, \gamma^m) = \mathcal{R}(\rho)\Phi_0(\gamma^m)$ for the wave function leads to the result that

$$\Phi(\rho, \gamma^m) \sim \rho^{-4} e^{i\mu \log \rho} \Phi_0(\gamma^m), \qquad (4.5)$$

where $(-\Delta_{LB} - 16)\Phi_0 = \mu^2\Phi_0$ and the reality of μ is guaranteed by (4.4). Therefore the full wave function vanishes (and oscillates) for $\rho \to \infty$.

For later reference we recall that for singular spatial hypersurfaces of dimension d, the relevant operator is $-\rho^{1-d}\partial_{\rho}(\rho^{d-1}\partial_{\rho}) + \rho^{-2}\Delta_{LB}$. Then the bound in (4.4) becomes

$$-\Delta_{\rm LB} \ge \frac{1}{4}(d-2)^2 \tag{4.6}$$

and the wave function decays as $\rho^{-(d-2)/2}$ [36]. The conserved invariant measure for the quantum cosmological billiards is just given by the standard Klein–Gordon inner product

$$(f|g) = i \int d\Sigma^a f^* \stackrel{\leftrightarrow}{\partial_a} g \tag{4.7}$$

where the integral is over the unit hyperboloid inside the forward light-cone in β -space. We stress that these statements are true for D=11 supergravity, but similar results hold for other gravitational theories such as pure D=4 gravity without a cosmological constant.

4.2 Extension with a single root

Since considering the full E_{10} system is too complicated (and possibly hard to define properly), we consider the case when only a single positive root generator E_{α} is active

along with its associated negative root generator in addition to the Cartan subalgebra. This means that the algebra we are considering is

$$\mathfrak{h}_{\perp} \oplus \mathfrak{g}_{\alpha} \subset \mathfrak{e}_{10}, \qquad \mathfrak{g}_{(1)} \equiv \mathfrak{g}_{\alpha} = \{ E_{\alpha}, F_{\alpha}, H_{\alpha} \equiv \alpha^{i} H_{i} \}, \qquad \langle \mathfrak{h}_{\perp} | \mathfrak{g}_{\alpha} \rangle = 0.$$
 (4.8)

whence the \mathfrak{e}_{10} symmetry is broken to $\mathfrak{h}_{\perp} \oplus \mathfrak{g}_{\alpha}$. Physically, this truncation corresponds to a situation with one compactified dimension, where the dimension of the singular spatial hypersurface is reduced by one.

The three-dimensional algebra \mathfrak{g}_{α} is isomorphic (over \mathbb{R}) to $\mathfrak{sl}_{2}(\mathbb{R})$ if $\alpha^{2} \neq 0^{16}$ and isomorphic to a Heisenberg algebra if α is a null root. The direct sum in the Lie algebra (4.8) is one of Lie algebras. We use the normalisation

$$\langle E_{\alpha}|F_{\alpha}\rangle = 1$$
, $\langle H_{\alpha}|H_{\alpha}\rangle = \alpha^2$. (4.9)

This bilinear form is invariant under the commutation relations

$$[H_{\alpha}, E_{\alpha}] = \alpha^2 E_{\alpha}, \quad [H_{\alpha}, F_{\alpha}] = -\alpha^2 F_{\alpha}, \quad [E_{\alpha}, F_{\alpha}] = H_{\alpha}. \tag{4.10}$$

Classical cosmological solutions to the E_{10} sigma model in such a set-up have been studied in [79], but we are here interested in the quantisation.

The Casimir operator for the algebra (4.8) is likewise a truncation of the full E_{10} Casimir operator to a finite-dimensional differential operator, and decomposes as

$$\Omega_1 = \Omega_\perp + \Omega_\alpha \,, \tag{4.11}$$

where Ω_{\perp} is the part along \mathfrak{h}_{\perp} and Ω_{α} along \mathfrak{g}_{α} . From now on we only consider the case $\alpha^2 \neq 0$ such that the bilinear form (4.9) is non-degenerate and the Casimir reads

$$\Omega_{\alpha} = \frac{1}{2} E_{\alpha} F_{\alpha} + \frac{1}{2} F_{\alpha} E_{\alpha} + \frac{1}{2\alpha^2} H_{\alpha} H_{\alpha} = F_{\alpha} E_{\alpha} + \frac{1}{2} H_{\alpha} + \frac{1}{2\alpha^2} H_{\alpha} H_{\alpha}. \tag{4.12}$$

Choosing coordinates χ and ϕ on an Iwasawa patch of the symmetric space associated with \mathfrak{g}_{α} with representative $\mathcal{V}_{\alpha}=e^{\chi E_{\alpha}}e^{\phi H_{\alpha}}$ we have the differential operators

$$E_{\alpha} = -\partial_{\chi}, \quad H_{\alpha} = -\partial_{\phi} - \alpha^{2} \chi \partial_{\chi},$$

$$F_{\alpha} = \chi \partial_{\phi} + \left(\frac{1}{2} \alpha^{2} \chi^{2} - e^{2\alpha^{2} \phi}\right) \partial_{\chi}$$
(4.13)

and therefore

$$\Omega_{\alpha} = \frac{1}{2}\alpha^{-2}\partial_{\phi}^{2} - \frac{1}{2}\partial_{\phi} + e^{2\alpha^{2}\phi}\partial_{\chi}^{2} = \frac{1}{2}\alpha^{2}y^{2}\partial_{y}^{2} + y^{2}\partial_{\chi}^{2}, \tag{4.14}$$

 $^{^{16}}$ The induced bilinear form has non-standard signature for time-like $\alpha.$

where we have defined $y = e^{\alpha^2 \phi}$ in the last step to make the expression coincide with the usual $SL(2,\mathbb{R})$ Laplace operator on the upper half-plane for real roots ($\alpha^2 = 2$).

In order to solve the WDW equation

$$\Omega_1 \Phi_1(\beta_\perp, \phi, \chi) = 0 \tag{4.15}$$

we use separation of variables, with $\Phi(\beta_{\perp}, \phi, \chi) = \Phi_{\perp}(\rho, \gamma) \mathcal{F}(\phi, \chi)$ as well as $\Phi_{\perp}(\rho, \gamma) = \mathcal{R}(\rho)\Phi_0(\gamma)$. If $\Omega_{\alpha}\mathcal{F}(\phi, \chi) = -\mathcal{E}\mathcal{F}(\phi, \chi)$ we are left with

$$\Omega_{\perp}\Phi_{\perp}(\beta_{\perp}) = \mathcal{E}\Phi_{\perp}(\beta_{\perp}). \tag{4.16}$$

We analyse the case of real roots and time-like imaginary roots separately.

We note that for all $\alpha^2 \neq 0$ the integration measure on the homogeneous space associated with \mathfrak{g}_{α} the integration measure is given by

$$(f|g) = \sqrt{\frac{2}{|\alpha^2|}} \int \frac{d\chi dy}{y^2} f(\chi, y) g(\chi, y)$$
 (4.17)

and the operators (4.13) all satisfy $X^{\dagger} = -X$ with respect to this integration measure. The constant overall normalisation factor is conventional and could be dropped. This measure supplements the billiard measure (4.7) to provide a measure for the full wave function $\Phi_1(\beta_{\perp}, \phi, \chi)$. What is important is that the patch where the coordinates $\chi \in \mathbb{R}$ and y > 0 are defined is of infinite volume in the measure (4.17). This can be remedied by considering a quotient of the homogeneous space by a discrete subgroup such that quotient has finite volume. A standard example for this is the modular group $SL(2,\mathbb{Z})$ acting on the upper half-plane which makes contact of the present set-up to the theory of automorphic forms. As mentioned in the introduction, such discrete symmetries arise naturally in an M-theory context, and here we see a different need for them in quantum gravity.

4.3 The case of a real root

If α is a real root, the associated symmetric space is $SL(2,\mathbb{R})/SO(2)$, the two-dimensional hyperbolic plane. The orthogonal space \mathfrak{h}_{\perp} is a Lorentzian space of dimension 9 and we can choose coordinates $\beta_{\perp} = \rho \gamma_{\perp}$ similar to (4.2). Separating the equation (4.16), we find a total elementary solution to (4.15) of the form

$$\Phi_1(\rho, \gamma_\perp, \phi, \chi) = \rho^{-\frac{7}{2}} \mathcal{R}(\rho) \Phi_0(\gamma_\perp) \mathcal{F}(\phi, \chi)$$
(4.18)

with $\Delta_{LB}\Phi_0(\gamma_\perp) = -E\Phi_0(\gamma_\perp)$ on the eight-dimensional unit hyperboloid inside \mathfrak{h}_\perp and $\mathcal{R}(\rho)$ a bounded function of ρ that is given by the solution to an (ordinary) Bessel differential equation. More precisely, $\mathcal{R}(\rho)$ satisfies the equation

$$\rho^2 \partial_\rho^2 \mathcal{R} + \rho \partial_\rho \mathcal{R} + \left(\mathcal{E} \rho^2 + E - \frac{49}{4} \right) \mathcal{R} = 0, \qquad (4.19)$$

where the contribution $\frac{49}{4}$ corresponds to d=9 in (4.6). After rescaling $\mathcal{E}\rho^2 \to \rho^2$ this becomes the standard Bessel equation, but with *imaginary* index. An explicit solution is provided by the formula [80]

$$\mathcal{R}(\rho) = J_{\nu}(\mathcal{E}^{-1/2}\rho) = \frac{2(\frac{1}{2}\mathcal{E}^{-1/2}\rho)^{\nu}}{\sqrt{\pi}\Gamma(\nu + \frac{1}{2})} \int_{0}^{1} (1 - t^{2})^{\nu - \frac{1}{2}} \cos(\mathcal{E}^{-1/2}\rho t) dt$$
(4.20)

valid for $Re(\nu) > -\frac{1}{2}$. The index

$$\nu = i\sqrt{E - \frac{49}{4}} \,. \tag{4.21}$$

is purely imaginary because $E \geq \frac{49}{4}$, which is the appropriate bound for the spectrum of the Laplacian $-\Delta_{LB}$ for d=9 by (4.6), under the assumption that there is a restricted cosmological billiard with Dirichlet boundary conditions. Moreover, we have that $\mathcal{E} \geq \frac{1}{4}$ under the assumption of a duality symmetry acting on $SL(2,\mathbb{R})/SO(2)$ with Dirichlet boundary conditions for normalisable solutions $\mathcal{F}(\phi,\chi)$. This bound makes the rescaling of the variable real. In the range

$$E \ge \frac{49}{4}$$
 and $\mathcal{E} \ge \frac{1}{4}$ (4.22)

we then have that Φ_1 is normalisable. In addition, the Bessel function $\mathcal{R}(\rho)$ is complex, oscillating and decays as $\rho^{-1/2}$ for $\rho \to \infty$ in the same range of parameters. Therefore, the full wave function Φ_1 retains the property that it vanishes in an oscillating manner for $\rho \to \infty$ when one simple real root is turned on.

The variable ρ used in (4.18) is the one associated only to the space \mathfrak{h}_{\perp} rather than to all of \mathfrak{h} as in (4.5). The reason for this change is that turning on the root generator E_{α} and the associated variable χ removes one hard billiard wall and the BKL geometry is therefore changed, with a singular spatial hypersurface of dimension d=9.

Let us also recall that there are *infinitely* many real roots for E_{10} (like for other hyperbolic Kac-Moody algebras), whose associated root generators can be used to build what is often referred to as the 'minimal group', corresponding to a special prescription for exponentiating the Lie algebra \mathfrak{e}_{10} [35]. While we have no general statement about the behavior of the full E_{10} wave function, this observation already takes us some way towards establishing the generic vanishing of the wave function at the space-like singularity.

4.4 Automorphic aspects with several real roots

For deriving the range (4.22), we used that there are discrete symmetries acting on the variables. On the space \mathfrak{h}_{\perp} the discrete symmetry was the remnant of the E_{10} Weyl symmetry. This is an infinite order symmetry since the stabiliser of any real root inside the infinite E_{10} Weyl group is of finite order.

For the $SL(2,\mathbb{R})/SO(2)$ symmetric space associated with the real root α we assumed a discrete symmetry such as $SL(2,\mathbb{Z})$ with a fundamental domain of finite volume, together with Dirichlet conditions.¹⁷ The mathematical reason is that under these assumptions the derivation of the bound on \mathcal{E} is straight-forward [82] while without this assumption the bound is only almost always satisfied [83]. More importantly, the physical reason for this assumption is that in string theory and supergravity, maximal supersymmetry together with Dirac charge quantisation implies the existence of such discrete U-duality groups [29] that are associated with space-time, at least for $D = d + 1 \ge 4$.

The arguments above can be extended to the case when \mathfrak{g}_{α} is replaced by any finite-dimensional subalgebra $\mathfrak{h}_{\perp} \oplus \mathfrak{g} \subset \mathfrak{e}_{10}$, e.g. $\mathfrak{g} = \mathfrak{e}_7$ in which case \mathfrak{h}_{\perp} would be of dimension three. For finite-dimensional $\mathfrak{g} \equiv \mathfrak{g}_{(r)}$ semi-simple of rank r such that dim $\mathfrak{h}_{\perp} = 10 - r$, the same separation ansatz

$$\Omega_r = \Omega_\perp + \Omega_{\mathfrak{a}} \tag{4.23}$$

applies, and we can first solve $\Omega_{\mathfrak{g}}\mathcal{F} = -\mathcal{E}\mathcal{F}$. The appropriate generalisation of the measure (4.17) exists on the finite-dimensional symmetric space associated with \mathfrak{g} by standard results, i.e., computing the invariant metric and taking its determinant. For the unipotent part associated with the positive roots this is given by the usual Haar measure.

For instance, for $\mathfrak{g} = \mathfrak{e}_7$ this corresponds to a situation with a singular spatial hypersurface of dimension three, and seven compactified dimensions. For doing this, we assume again the existence of discrete U-duality and require the square integrable functions on a locally symmetric space. Although the precise general bound on the Laplace spectrum is not known for $E_7(\mathbb{Z})$ to the best of our knowledge, one can still show that $\mathcal{E} \geq 0$. One instance of a such a function \mathcal{F} for E_7 or E_8 is provided by the automorphic realisation of the minimal unitary representation [84–86, 28].

For $\mathcal{E} > 0$ we are then led again to solutions of the type (4.18) where the difference is that $\rho^{-7/2}$ is replaced by $\rho^{-(8-r)/2}$ and the solution to the Bessel equation provides an additional falloff, still ensuring that the wave function of the Universe vanishes when

¹⁷Under these conditions, the bound $\mathcal{E} \geq \frac{1}{4}$ can actually be strengthened [81], but we do not require this here. In fact, all that we require is that \mathcal{E} is non-negative.

approaching the singularity as a stable property of the solution. Here, we assume implicitly that $r \leq 8$ to have a meaningful geometric picture of the singularity when using the dictionary.

4.5 The case of an imaginary root

For (time-like) imaginary roots α (which obey $\alpha^2 < 0$) new subtleties arise. A first difficulty is that the 'dictionary' of [5,6] does not work for imaginary roots, hence there does not exist an obvious geometric interpretation for this situation, unlike for cosmological billiards. While for real roots the geometry of the coset is that of $SL(2,\mathbb{R})/SO(2)$, the symmetric space associated with an imaginary root is $SL(2,\mathbb{R})/SO(1,1)$, which is now of Lorentzian signature. For $\alpha^2 = -2$ (or any time-like root after a suitable rescaling of the coordinates), the metric reads

$$ds^{2} = y^{-2} \left(-dy^{2} + d\chi^{2} \right) \tag{4.24}$$

and represents a Poincaré patch of Lorentzian AdS_2 space that was computed using one Iwawasa patch where y > 0 and $\chi \in \mathbb{R}$. As is well-known, this is not a global coordinate system of AdS_2 and, in particular, the action of the AdS_2 isometry group $SL(2,\mathbb{R})$ does not preserve this patch, unlike for the Euclidean case, see below. By thinking of the embedding in the ambient space $\mathbb{R}^{1,2}$, we can think of all of AdS_2 as the above Poincaré patch, also allowing values y < 0. This still misses the (light-like in $\mathbb{R}^{1,2}$) hyperplane y = 0 where the metric becomes singular, but this will be of no relevance in our discussion.

The spectral problem of Ω_{α} for $\alpha^2=-2$ is then recognised as being related to the scalar d'Alembertian on AdS₂ where it is known that normalisable solutions

$$\Omega_{\alpha}H(\chi,y) = -\mathcal{E}H(\chi,y) \tag{4.25}$$

exist for $\mathcal{E} < \frac{1}{4}$ by the Breitenlohner–Freedman bound [87]. This is the other side of the bound for real roots α . Since the space associated with α now is Lorentzian, the orthogonal space is Euclidean and therefore the corresponding operator $-\Omega_{\perp}$ becomes elliptic. The remaining equation $\Omega_{\perp}F = \mathcal{E}F$ then has oscillating solutions. However, in this case it is not clear what variable now plays the role of ρ that is the variable 'towards the singularity' as the geometric interpretation of the solutions involving purely imaginary roots is already unclear at the classical level [79]. This is due to the lack of a dictionary beyond level $\ell = 3$.

There are also mathematical subtleties, related to the ones already discussed in [88], that cast doubt on the existence of a proper automorphic theory for this case. Namely, the

action of $SL(2,\mathbb{R})$ in the coordinate system (4.24) can be worked out from the ambient space and gives

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \cdot y = \frac{y}{(c\chi + d)^2 - (cy)^2}, \quad \begin{pmatrix} a & b \\ c & d \end{pmatrix} \cdot \chi = \frac{ac(\chi^2 - y^2) + (ad + bc)\chi + bd}{(c\chi + d)^2 - (cy)^2},$$

This formula resembles the one for Möbius transformations, except for a 'Wick rotation' of the y variable, as a consequence of which the coordinate range y > 0 is no longer preserved. Independently of the non-preservation of the Poincaré patch, we see that for the generators T and S of the discrete subgroup $SL(2,\mathbb{Z})$, this formula implies

$$T = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} : (\chi, y) \to (\chi + 1, y)$$

$$S = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} : \chi \pm y \to -\frac{1}{\chi \pm y}$$

$$(4.26)$$

Hence T and S act as in the Euclidean case, but separately on the real null coordinates $\chi \pm y$, as already noted in [88]. As explained there, one can compactify the space by considering $\chi \pm y \in \mathbb{R} \cup \{\infty\}$ so that the space has the topology a two-torus $S^1 \times S^1$. Now it is known that the action of $SL(2,\mathbb{Z})$ on the real axis with the point at infinity added is dense (any rational number can be mapped to any other by means of a discrete Möbius transformation). Because the action on the two defining circles is dense there is therefore no sensible fundamental region, unlike for real roots. We are not aware of a discussion of the consequences of this fact for the theory of automorphic forms on such a space, nor its implications for the proper definition of the hypothetical discrete duality group $E_{10}(\mathbb{Z})$.

5 General comments on E_{10} wave function

In the previous section we have presented several examples of truncations of the E_{10} WDW equation to *finitely* many variables. In this final section we want to return to the general case and collect some more general statements. More specifically, the E_{10} wave function Φ being part of a functional representation of E_{10} , one can ask the question what type of representation component it belongs to if it solves $\Omega \Phi = 0$. As we will see, all indications point towards the necessity of an enlargement of the E_{10} framework.

The first observation is that if Φ belonged to an irreducible highest or lowest weight representation of E_{10} , then $\Omega\Phi = 0$ would imply that $\Phi = 1$ is the trivial representation (a statement that is, of course, familiar from standard group and representation theory).

This is actually in agreement with our findings for the finite-dimensional truncations studied in the previous sections, as already for the simplest case of \mathfrak{sl}_2 the relevant eigenfunctions belong to unitary representations which are neither of highest or lowest weight type.

More generally, this can be seen by recalling that for such representations we have [60]

$$\Omega \Phi = \frac{1}{2} \Big((\Lambda | \Lambda) + 2(\varpi | \Lambda) \Big) \Phi \tag{5.1}$$

where Λ is the relevant highest or lowest weight, and ϖ the Weyl vector. Now for the fundamental \mathfrak{e}_{10} weights Λ_i , which obey $(\Lambda_i|\alpha_j) = \delta_{ij}$ we have (see e.g. [67])

$$(\Lambda_i | \Lambda_j) \le 0 \tag{5.2}$$

with equality if and only if $\Lambda_i = \Lambda_j = \Lambda_1 = -\delta$, the fundamental weight of the 'hyperbolic' node. Furthermore, for any non-trivial weight $\Lambda = \sum_j p^j \Lambda_j$ we have $(\Lambda | \varpi) < 0$ and thus

$$(\Lambda|\Lambda) + 2(\varpi|\Lambda) < 0 \tag{5.3}$$

This argument shows that for any non-trivial such representation we have $\Omega \Phi \neq 0$, hence the WDW equation cannot be satisfied. This conclusion is also in accord with indefiniteness of WDW operator (which here appears with peculiar and unique ordering prescribed by (3.24)): highest (or lowest) weight representations are unitarisable [60], whereas for standard WDW equation we have the usual indefinite metric Hilbert space, just like for the Klein–Gordon wave function. This again leads to the conclusion that Φ cannot belong to a highest or lowest weight representation of E_{10} .

In the foregoing section, we have considered differential operators that only depend on the E_{10} coordinates up to \mathfrak{gl}_{10} level $\ell \leq 2$. Such a truncation breaks E_{10} symmetry, but it is possible to solve the equation $\Omega \Phi = 0$ in such a truncation consistently. This statement is analogous to the statement for the classical E_{10} coset model that one can truncate the geodesic equation such that only finitely many coset velocity components are non-zero but this provides a solution to the full geodesic equation [6]. At the level of induced representations and automorphic forms it corresponds to considering restricted Fourier coefficients, i.e., to perform the Fourier integral over all variables of $\ell > 2$ [28].

Although such truncations are thus all consistent, it is another question whether they are also stable in the full configuration space w.r.t. small perturbations along the truncated directions. A relevant fact here is that, as shown in [41], classical geodesics on the $E_{10}/K(E_{10})$ coset manifold are infinitely unstable. We recall that the geodesic deviation equations governing the relative evolution of two neighbouring geodesics are determined

by the sectional curvatures (see e.g. [89]). Consequently, for a geodesic with tangent vector $v \in \mathfrak{h}$ in the Cartan subalgebra, and a deviation in the direction of the generator $E_{\alpha}^{+} \equiv E_{\alpha} + F_{\alpha}$ for an arbitrary root α , the deviation of the two geodesics is determined by (see appendix of [41])

$$\mathcal{R}(v, E_{\alpha}^+, v, E_{\alpha}^+) = -(\alpha(v))^2 < 0$$
 (5.4)

This expression decreases without bound for imaginary roots. This is because for every imaginary root α , any integer multiple $n\alpha$ is also a root. Hence, replacing α by $n\alpha$ on the r.h.s., (5.4) can be made arbitrarily negative by taking $n \to \infty$, with an exponentially increasing number of unstable directions (labeled by the multiplicity index of the root $n\alpha$) for time-like imaginary roots. It is not clear how this instability is reflected in the E₁₀ WDW operator, although the usual formal path integral representation of the 'wave function of the universe' (see e.g. [90]) would suggest that the instability should manifest itself via the saddle point approximation. It is also unclear how the inclusion of fermions and third quantisation might affect these conclusions.

Finally, we should point out that the picture here with a wave function that vanishes at the singularity is very different from the one suggested by the no boundary proposal of [38] (see also [40] and [39] for related discussions). The latter hypothesises a creation of the universe 'out of nothing' in terms of a Euclidean instanton, where in particular the BKL analysis and chaotic oscillations play no role. The absence of an initial singularity hinges on the presence of a positive cosmological constant (which is known to suppress chaotic oscillations [74]). By contrast, D = 11 supergravity does not admit a non-vanishing cosmological constant. While a cosmological constant is almost always generated by spontaneous compactification, it generically turns out to be negative. By contrast, the (classical) $E_{10}/K(E_{10})$ model has been shown to not admit static solutions, but rather gives rise to a time-dependent cosmological evolution of quintessence type [79].

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A Theory with both three-form and six-form

In the covariant theory (2.1), the matter equation of motion

$$\partial_S(EF^{SMNP}) = -\frac{1}{576}\tilde{\varepsilon}^{MNPK_1...K_8}F_{K_1...K_4}F_{K_5...K_8} \tag{A.1}$$

allows for the introduction of a dual seven-form field strength according to

$$F_{M_1...M_7} = \frac{1}{4!} \epsilon_{M_1...M_7 N_1...N_4} F^{N_1...N_4} \quad \Leftrightarrow \quad F_{M_1...M_4} = -\frac{1}{7!} \epsilon_{M_1...M_4 N_1...N_7} F^{N_1...N_7} , \quad (A.2)$$

where the seven-form field strength is given by

$$F_{M_1...M_7} = 7\partial_{[M_1}A_{M_2...M_7}] - 35A_{[M_1M_2M_3}F_{M_4...M_7}$$
(A.3)

and satisfies the modified Bianchi identity

$$8\partial_{[M_1}F_{M_2...M_8]} = -70F_{[M_1...M_4}F_{M_5...M_8]}$$
(A.4)

As usual, the duality relation exchanges Bianchi identities and equations of motion and the extra term in the definition of the seven-form field strength is chosen such that duality is compatible with the three-form equation of motion above.

It was shown in [49, 13, 12] that such a six-form potential can already be introduced at the level of the action by breaking manifest space-time covariance.¹⁸ As a six-form potential appears in the E_{10} theory (which does not exhibit manifest Lorentz symmetry either), we now switch to this formulation, following [12]. We focus solely on the matter sector and will leave the gravitational sector untouched in this appendix.

The first step is to explicitly solve the Gauss constraint (2.9b) in terms of the differential of a dual six-form¹⁹

$$\Pi^{mnp} + \frac{1}{3 \cdot 144} \tilde{\varepsilon}^{mnpk_1...k_7} A_{k_1 k_2 k_3} F_{k_4...k_7} = \frac{1}{6!} \tilde{\varepsilon}^{mnpk_1...k_7} \partial_{k_1} A_{k_2...k_7}, \tag{A.5}$$

which is similar to the duality relation (A.3). Inserting this solution leads to the canonical action

$$\mathcal{L}_{can} = \frac{1}{2} \dot{g}_{mn} \Pi^{mn} + \frac{1}{3!} \dot{A}_{mnp} \tilde{\varepsilon}^{mnpk_1...k_7} \left(\frac{1}{6!} \partial_{k_1} A_{k_2...k_7} - \frac{1}{3 \cdot 144} A_{k_1 k_2 k_3} F_{k_4...k_7} \right) - N \mathcal{H} - N^m \mathcal{H}_m$$
(A.6)

¹⁸Writing the non-linear theory solely in terms of the six-form is not possible [54].

¹⁹Here, we work locally and thus there are no topological obstructions to this application of the Poincaré lemma.

that depends only on the spatial components of the three-form A_{mnp} and its dual six-form $A_{m_1...m_6}$. The matter Hamiltonian $e\mathcal{H}^{(\text{mat})}$ from (2.8) can now be written as

$$\frac{1}{12} \left(\Pi^{mnp} - \mathcal{P}^{mnp} \right) g_{mm'} g_{nn'} g_{pp'} \left(\Pi^{m'n'p'} - \mathcal{P}^{m'n'p'} \right) + \frac{1}{48} e^2 F_{m_1 \dots m_4} g^{m_1 n_1} \cdots g^{m_4 n_4} F_{n_1 \dots n_4}
= \frac{1}{2 \cdot 7!} e^2 F_{m_1 \dots m_7} g^{m_1 n_1} \cdots g^{m_7 n_7} F_{n_1 \dots n_7} + \frac{1}{2 \cdot 4!} e^2 F_{m_1 \dots m_4} g^{m_1 n_1} \cdots g^{m_4 n_4} F_{n_1 \dots n_4} ,$$
(A.7)

where

$$F_{m_1...m_7} = -\frac{1}{3!} \tilde{\varepsilon}_{m_1...m_7 n_1 n_2 n_3} \left(\Pi^{n_1 n_2 n_3} - \mathcal{P}^{n_1 n_2 n_3} \right)$$

= $7 \partial_{[m_1} A_{m_2...m_7]} - 35 A_{[m_1 m_2 m_3} F_{m_4...m_7]},$ (A.8)

and where we used (A.5) on the solution of the Gauss constraint, an answer that is consistent with the spatial components of (A.3). Note that $F_{m_1...m_7}$ is tensorial.

The variation of the matter part of the action (A.6) with respect to A_{mnp} and $A_{m_1...m_6}$ gives the equations of motion

$$0 = -\frac{1}{3! \cdot 6!} \tilde{\varepsilon}^{mnpk_1...k_7} \partial_{k_1} \left(\partial_t A_{k_2...k_7} - 20 A_{k_2k_3k_4} \partial_t A_{k_5k_6k_7} + \frac{E}{4!} \tilde{\varepsilon}_{k_2...k_7n_1...n_4} F^{n_1...n_4} \right)$$
(A.9a)

$$+ \frac{1}{216} \tilde{\varepsilon}^{mnpk_1...k_7} A_{k_1k_2k_3} \partial_{k_4} \partial_t A_{k_5k_6k_7} + \frac{E}{72} F^{mnpk_1...k_4} F_{k_1...k_4}$$
$$- \frac{1}{36} \partial_s (EF^{smnpk_1k_2k_3}) A_{k_1k_2k_3} ,$$

$$0 = \partial_m \left(\frac{1}{3!} \tilde{\varepsilon}^{k_1 \dots k_6 m n_1 \dots n_3} \dot{A}_{n_1 n_2 n_3} + E F^{m k_1 \dots k_6} \right). \tag{A.9b}$$

We reiterate that we focus on the matter sector only here and we also work in flat spacetime for simplicity. The second equation is solved locally by

$$EF^{mk_1...k_6} + \frac{1}{3!}\tilde{\varepsilon}^{k_1...k_6mn_1...n_3}\dot{A}_{n_1n_2n_3} = \frac{1}{2}\tilde{\varepsilon}^{k_1...k_6mn_1n_2n_3}\partial_{n_1}A_{tn_2n_3}$$
(A.10)

for some function $A_{tn_2n_3}$. Rewriting this formula leads to

$$EF^{k_1...k_7} = -\frac{1}{3!} \tilde{\varepsilon}^{k_1...k_7 n_1 n_2 n_3} F_{tn_1 n_2 n_3} \quad \Leftrightarrow \quad F_{tn_1 n_2 n_3} = -\frac{1}{7!} \epsilon_{tn_1 n_2 n_3 k_1...k_7} F^{k_1...k_7}, \quad (A.11)$$

where we have reintroduced the time index on the Levi-Civita symbol and turned it into the Levi-Civita tensor by absorbing E in order to recognise this equation as the time component of the second way of writing the duality equation (A.2).

Using (A.9b) and its solution (A.10) in the first equation of motion (A.9a) we get an exterior derivative

$$0 = -\frac{1}{3! \cdot 6!} \tilde{\varepsilon}^{mnpk_1...k_7} \partial_{k_1} \left(\partial_t A_{k_2...k_7} - 35 A_{[tk_2k_3} \partial_{k_4} A_{k_5k_6k_7]} + \frac{E}{4!} \tilde{\varepsilon}_{k_2...k_7n_1...n_4} F^{n_1...n_4} \right),$$
(A.12)

where in particular the term with the bare $A_{tk_2k_3}$ inside the derivative comes from using (A.10). The above equation can be solved locally by

$$\partial_t A_{k_2...k_7} - 35 A_{[tk_2k_3]} \partial_{k_4} A_{k_5k_6k_7]} + \frac{E}{4!} \tilde{\varepsilon}_{k_2...k_7n_1...n_4} F^{n_1...n_4} = -6 \partial_{[k_2} A_{k_3...k_7]t}$$
(A.13)

introducing a function that plays the role of the time component of the six-form potential. Rewriting the equation we then find

$$F_{tn_1...n_6} = \frac{1}{4!} \epsilon_{tn_1...n_6 k_1...k_4} F^{k_1...k_4} , \qquad (A.14)$$

where we have introduced the time index and turned the Levi–Civita symbol into its tensor form. This agrees perfectly with the time component of the first way of writing the duality equation (A.2).

The kinetic term can be brought into a slightly more symmetric form by using integration by parts

$$\frac{1}{3!}\dot{A}_{mnp}\tilde{\varepsilon}^{mnpk_{1}...k_{7}}\left(\frac{1}{6!}\partial_{k_{1}}A_{k_{2}...k_{7}} - \frac{1}{3\cdot144}A_{k_{1}k_{2}k_{3}}F_{k_{4}...k_{7}}\right)
= \frac{1}{2\cdot3!\cdot7!}\dot{A}_{mnp}\tilde{\varepsilon}^{mnpk_{1}...k_{7}}F_{k_{1}...k_{7}} - \frac{1}{2\cdot4!\cdot6!}F_{mnpq}\tilde{\varepsilon}^{mnpqk_{1}...k_{6}}\dot{A}_{k_{1}...k_{6}}
+ \frac{1}{3!\cdot3!\cdot144}\dot{A}_{mnp}\tilde{\varepsilon}^{mnpk_{1}...k_{7}}A_{k_{1}k_{2}k_{3}}F_{k_{4}...k_{7}}$$
(A.15)

In this form both fields appear with time derivatives and have non-vanishing canonical momenta.

Starting then from the action

$$\mathcal{L} = \frac{1}{2 \cdot 3! \cdot 7!} \dot{A}_{mnp} \tilde{\varepsilon}^{mnpk_1...k_7} F_{k_1...k_7} - \frac{1}{2 \cdot 4! \cdot 6!} F_{mnpq} \tilde{\varepsilon}^{mnpqk_1...k_6} \dot{A}_{k_1...k_6}
+ \frac{1}{3! \cdot 3! \cdot 144} \dot{A}_{mnp} \tilde{\varepsilon}^{mnpk_1...k_7} A_{k_1k_2k_3} F_{k_4...k_7}
- N \left[\frac{1}{2 \cdot 7!} e F_{m_1...m_7} g^{m_1n_1} \cdots g^{m_7n_7} F_{n_1...n_7} + \frac{1}{2 \cdot 4!} e F_{m_1...m_4} g^{m_1n_1} \cdots g^{m_4n_4} F_{n_1...n_4} \right]$$
(A.16)

we get the canonical momenta

$$\Pi^{mnp} = \frac{1}{2 \cdot 7!} \tilde{\varepsilon}^{mnpk_1...k_7} F_{k_1...k_7} + \frac{1}{3! \cdot 144} \tilde{\varepsilon}^{mnpk_1...k_7} A_{k_1k_2k_3} F_{k_4...k_7}
\Pi^{m_1...m_6} = -\frac{1}{2 \cdot 4!} \tilde{\varepsilon}^{m_1...m_6k_1...k_4} F_{k_1...k_4} .$$
(A.17)

They represent primary constraints of the theory and are analysed in detail in section 2.

B More details on the E_{10} Casimir

The E_{10} Casimir with parabolic normal ordering was given in (3.24). The terms involving the GL(10) generators $K^m{}_n$ were not fully normal-ordered there, and therefore the coefficient of the linear term is not the same as for the standard expressions for the Casimir operator. Up to normalisation, when acting on integrable highest weight modules, the latter is generally given by the fully normal ordered expression [60]

$$\Omega = \frac{1}{2}G^{ab}H_aH_b + G^{ab}\varpi_aH_b + \sum_{\alpha>0} \sum_{s=1}^{\text{mult}(\alpha)} E^s_{-\alpha}E^s_{\alpha}$$
(B.1)

where ϖ is the Weyl vector, and the sum on the r.h.s. runs over all positive roots together with their multiplicities. In this appendix we show that for E_{10} the two expressions (3.24) and (B.1) are, in fact, the same.

Normal-ordering the GL(10) terms in (3.24) yields

$$\frac{1}{2}K^{m}{}_{n}K^{n}{}_{m} - \frac{1}{18}KK + \frac{23}{6}K$$

$$= \sum_{m>n} K^{m}{}_{n}K^{n}{}_{m} + \frac{1}{2}\sum_{m

$$= \sum_{m>n} K^{m}{}_{n}K^{n}{}_{m} + \frac{1}{2}\sum_{m
(B.2)$$$$

Now we use

$$\frac{1}{2} \sum_{m < n} (K^m_m - K^n_n) + \frac{23}{6} K = \frac{1}{2} (9K^1_1 + 7K^2_2 \dots - 9K^{10}_{10}) + \frac{23}{6} K$$

$$= \frac{1}{3} (25K^1_1 + 22K^2_2 + \dots + K^9_9 - 2K^{10}_{10})$$

$$= G^{ab} \varpi_a H_b \tag{B.3}$$

where in the last expression we have used the E_{10} Weyl vector in the wall basis

$$\varpi = (-30, -31, \dots, -39). \tag{B.4}$$

together with [6]

$$H_1 = K_2^2 - K_1^1, \dots, H_9 = K_{10}^{10} - K_9^9, H_{10} = K_8^8 + K_9^9 + K_{10}^{10} - \frac{1}{3}K$$
 (B.5)

The quadratic terms are as they should be for the fully normal ordered E_{10} Casimir. In conclusion, after normal ordering the GL(10) contribution, our expressions for the Casimir precisely coincide.

The coefficient $\frac{23}{6}$ multiplying K in (3.24) can be generally understood as follows. We explain the calculation for any E_D decomposed with respect to its obvious GL(D) subgroup. The linear term arises from normal-ordering all terms with roots on GL(D) levels $\ell > 0$, therefore it equals

$$\beta \equiv \frac{1}{2} \sum_{\substack{\alpha > 0 \\ \ell > 0}} \alpha = \frac{1}{2} \sum_{\substack{\alpha > 0 \\ \ell = 0}} \alpha - \frac{1}{2} \sum_{\substack{\alpha > 0 \\ \ell = 0}} \alpha = \varpi_{E_D} - \frac{1}{2} \sum_{\substack{\alpha > 0 \\ \ell = 0}} \alpha \tag{B.6}$$

For Kac–Moody E_D , the sums are divergent over infinitely many positive roots are ill-defined but the Weyl vector is well-defined, so β is a well-defined element. The sum over the positive roots on level $\ell=0$ gives the GL(D) Weyl vector whose form in a simple root basis is

$$\frac{1}{2} \sum_{\substack{\alpha > 0 \\ \ell = 0}} \alpha = \frac{1}{2} (D - 1, 2(D - 2), 3(D - 3), \dots, 2(D - 2), D - 1, 0).$$
 (B.7)

The inner product of β with all simple roots can be computed as

$$\beta \cdot \alpha_D = 1 + \frac{1}{2}3(D - 3) = \frac{3D - 7}{2}, \qquad \beta \cdot \alpha_i = 0 \quad \text{for } i \neq D$$
 (B.8)

since the exceptional node attaches three nodes from the end of the GL(D) line. These inner products identify $\beta = \frac{3D-7}{2}\Lambda_D$ in the basis of fundamental weights. Using moreover that $K = 3\Lambda_D^{\vee}$ we deduce that the linear term is $\frac{3D-7}{6}K$ that for D = 10 gives the claimed value.

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