# Bias and synergy in the self-consistent approach of data analysis of ion beam techniques

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#### Abstract

Using multiple ion beam analysis measurements, or techniques, combined with self-consistent data processing, generally allows extracting more (or more accurate) information from the measurements than processing separately data from single measurements. Solving ambiguities, improving the final depth resolution, defining constraints and extending applicability are the main strengths of the data-fusion approach. It basically consists in formulating a multi-objective minimization problem that can be tackled by the adoption of the weighted-sum method. A simulation study is reported in order to evaluate the systematic error inserted in the analysis by the choice of a specific objective function, or even by the weights or normalization adopted in the weighted-sum method. We demonstrate that the bias of the analyzed objective functions asymptotically converges to the true value for better statistics. We also demonstrate that the joint analysis inherits the

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accuracy of the most accurate measurement, establishing a rank of information content, where some combinations of measurements are more valuable than others, i.e. when processed together they provide more information by means of a better constraint for the multi-objective optimization. *Keywords:* Self-consistent analysis, Ion beam analysis, Systematic errors,

Objective function, Data fusion

# 1 1. Introduction

A data-fusion approach for data analysis of spectrometry information obtained using Ion Beam Analysis (IBA) techniques is a powerful tool for an improved material characterization, providing more reliability and increasing the quality of information extracted from these measurements [1]. It basically consists in applying as many IBA measurements as necessary on the same sample and then combining all the information in a common model of the sample that is able to describe all experimental data given some level of statistical significance.

Usually, this model is found by an optimization algorithm in a computer 10 program, given some combined objective function. Currently, only two GUI-11 based computer programs enable a data-fusion approach to process IBA data. 12 The first to provide this features was NDF [2]. Created in the 90s, this code 13 can handle different techniques, including Rutherford Backscattering Spec-14 trometry (RBS), Nuclear Reaction Analysis (NRA), Elastic Recoil Detection 15 (ERD), Elastic Backscattering Spectrometry (EBS), Particle Induced X-ray 16 Emission (PIXE), among others [1]. The second to provide this feature is 17 MultiSIMNRA [3, 4] whose first release occurred in 2015. Despite being new, 18

<sup>19</sup> MultiSIMNRA already offers many interesting features, conveniently orga-<sup>20</sup> nized into a user-friendly environment. It relies on the physical simulations <sup>21</sup> provided by the widely adopted SIMNRA software [5, 6], being currently <sup>22</sup> able to handle data from RBS, NRA, EBS, and ERD, Medium Energy Ion <sup>23</sup> Scattering (MEIS). SIMNRA also provides calculations for Particle Induced <sup>24</sup> Gama-ray Emission(PIGE), which is not yet supported by MultiSIMNRA.

The strength of the joint processing of IBA data lies in the synergy that 25 occurs when combining the individual information contained in the differ-26 ent measurements. Butler [7] introduced the concept of using chemical or 27 thermodynamic information in the analysis, as an alternative to additional 28 measurements, in an attempt to constrain the solution of an ambiguous RBS 29 measurement. In this sense, either the combination of measurements or the 30 use of prior information are, in principle, two possible ways to improve the 31 material characterization by means of a combined processing of the data [4]. 32 More recently, Jeynes [8, 9] has shown the potential of RBS as a primary 33 method for thin film characterization showing a distinct advantages of the 34 IBA techniques over most of its competitors with respect to accuracy and 35 traceability. It was also Jeynes [1] who argued that the data-fusion approach 36 inherits the accuracy of the most accurate measurement in the system, ren-37 dering RBS a good candidate to improve the accuracy of any analysis that 38 takes advantage of the joint processing of the data [10]. This is indeed rea-39 sonable if one thinks that an accurate measurement constraints better the 40 solution space during the optimization process, being the major constraint 41 also in the calculation of statistically acceptable solutions in the uncertainty 42 evaluation. In this sense, this assumption seems to be correct.

However, one important consequence of this assumption is that, given 44 a certain set of measurements, possibly there are some other new measure-45 ments that can be performed and added in the analysis, which can improve 46 the final accuracy. On the other side, there are other measurements that can-47 not succeed in this task of improving the final accuracy significantly, thus, 48 are not worth to be performed. This is simply because adding a measure-49 ment in joint data processing can be considered as adding new constraints 50 to the optimization algorithm, and there are measurements that constraint 51 the parameters more strongly, and others that do not. Thus, we can say that 52 some measurements combine synergistically, and others do not. 53

On top of that discussion, there is also the problem of bias which may be 54 introduced by the choice of the likelihood function or by deficiencies of the 55 forward model. On first glance the choice of the likelihood function appears 56 to be straightforward for most of the ion-beam based methods: Individual 57 events are being registered and the underlying physics (rare, independent 58 scattering events) thus implies a Poissonian likelihood with a expected num-50 ber of events  $\lambda$  which depends on the analysed sample (with sample pa-60 rameters  $\theta_s$ ) and the diagnostic settings (experimental parameters like beam 61 energy, projectile species, detector solid angle, sensitivity, energy resolution 62 etc.), here summarized by  $\theta_d$ . Then the probability to observe c counts is 63 given by 64

$$p_P(c \mid \theta, I) = \frac{\lambda(\theta)^c}{c!} \exp\left(-\lambda(\theta)\right), \qquad (1)$$

with  $\theta$  denoting the union of sample and diagnostic parameters:  $\theta = \{\theta_s, \theta_d\}$ . For this likelihood it can be shown [11] that the estimation of the parameters <sup>67</sup> is unbiased, i.e. the estimation converges to the correct parameter values
<sup>68</sup> with increasing number of data and that the theoretical optimum of the
<sup>69</sup> estimation accuracy, the Cramer-Rao bound is achieved.

However, the likelihoods which are actually used are different and involve several intermediate approximations for a number of reasons. In an almost generic first step the Poissonian likelihood is approximated by a Gaussian likelihood, which holds with good accuracy for a sufficiently large number of counts. In a second approximation step the variance of the Gaussian likelihood is set c, i.e. based on the actual observed number of counts

$$p_G(c \mid \theta, I) = N\left(\lambda\left(\theta\right), \sqrt{c}\right) = = \frac{1}{\sqrt{2\pi c}} \exp\left(-\frac{1}{2}\left(\frac{c - \lambda\left(\theta\right)}{\sqrt{c}}\right)^2\right), \quad (2)$$

instead of the mathematically correct  $N\left(\lambda\left(\theta\right),\sqrt{\lambda\left(\theta\right)}\right)$ . The justification 76 for this second approximation rests on the improved numerical stability of 77 the optimization. In the early stages of the optimization the model may 78 yield values which are significantly different from the observed data and this 79 discrepency is magnified by the simultaneously deviating value of the un-80 certainty, resulting in numerical overflow or convergence failure. In practice 81 there is a second complication: Most measurements are affected by some 82 background signal which needs to be accounted for. A proper statistical 83 handling of this matter turns out to be surprisingly challenging because the 84 difference of two Poisson distributed random variables is not longer described 85 by a Poisson distribution but instead follows a Skellam distribution [12]. This 86 is quite different from Gaussian random variables where their sum and their 87 difference are again described by a Gaussian probability distribution. Also 88

a Bayesian approach for a proper handling of the background subtraction
yields a non-standard likelihood [13].

In addition there is a third reason why likelihoods used in data-fusion 91 approaches are adjusted. The arguments about being asymptotically unbi-92 ased do hold only under the assumption that the forward model, i.e. the 93 model relating the parameters  $\theta$  and the expected number of counts  $\lambda(\theta)$ 94 is perfect. Unfortunately, although the models used in NDF and SIMNRA 95 are continously improved there are inevitible approximations of the under-96 lying scattering and detection process. These small deviations are often of 97 no concern, especially if only a single diagnostic is being used. The problem 98 commonly becomes apparent when diagnostics of very different count rates 90 are jointly evaluated. Then a small model inaccuracy in one diagnostic can 100 completely dominate another diagnostic. The prototypical example is the 101 combination of data from a forward scattering experiment with conventional 102 RBS-data. Tiny inaccuracies of the multiple-scattering modelling in the for-103 ward direction together with a large number of counts in this experiment 104 vield a most likely result from the joint evaluation which are incompatible 105 with information of the RBS measurement alone: the RBS contribution has 106 been overwhelmed. For that reason sometimes the statistical weight of the 107 individual measurements is being 'adjusted' - which may allow an otherwise 108 impossible joint fit of different diagnostics but can also introduce a bias of 109 unknown extend. 110

Therefore, this paper deals with these two important aspects of the datafusion approach of processing IBA data: bias and synergy. Both issues have a direct impact on the final accuracy of the result: while bias introduces systematic errors, the synergy obtained by the combination of different measurements constraint the result more strongly, thus reducing the uncertainties. Therefore, in this study, we aimed at a better understanding of the uncertainties associated with the simultaneous processing of multiple data, and on the influence of the choice in the objective function on the final accuracy.

# <sup>119</sup> 2. Methods

We designed a simulation exercise in order to evaluate both, the sys-120 tematic errors introduced on the final result by the bias of the objective 121 functions, and the final accuracy when combining different measurements. 122 Performing this study through simulations is justified because we aim at the 123 evaluation of systematic errors induced only by the objective functions, while 124 the analysis of experimental data is affected by systematic errors originating 125 from different sources, such as the physics models [14, 15, 16, 17] or the fun-126 damental databases (e.g. stopping forces [18] and cross-sections databases 127 [19]). Another reason is: since we want to evaluate systematic errors and 128 their uncertainties, we need to compare the optimum values of the objective 129 function with true values, and this is only possible in simulations. 130

# 131 2.1. The simulation exercise

For the simulation exercise, we defined a sample consisting of 130 nm thin film of SiO<sub>2</sub> with 10% H content deposited on top of an amorphous Silicon substrate. Then, using simulations provided by SIMNRA for different analysis conditions with Poisson noise added, we generated spectral data that played the role of experimental data.

2.1 shows the idealized setup to perform the calculations. Fig. Two 137 detectors were assumed: one in a backscattering geometry located at  $170^{\circ}$ 138 scattering angle (referred to the incident beam direction); and another detec-139 tor placed in a forward geometry located at 30° scattering angle. The solid 140 angles of both detectors were assumed to be 1 msr. No electronics effects 141 other than energy resolution of 12 keV (such as pile-up or dead-time) was 142 added into the simulations. 143



Figure 1: Idealized setup to perform calculations.

Thus, in this geometrical configuration, the detector placed at forward 144 geometry was used to measure the H content of our hypothetical sample by 145 ERD using He ions as a probe, and the detector placed at backscattering 146 geometry was used to measure Si and O content on it. For the latter, three 147 configurations for ion and energy were adopted: one for He RBS with 1.5 MeV 148 beam (the same energy as adopted for ERD, thus performed simultaneously), 149 one for EBS with 3.04 MeV He beam (to take advantage of the resonant cross-150 section for O to enhance its signal in the spectra), and a last experiment for 151

RBS with 1.0 MeV Li beam. This beam was assumed to provide an improved depth resolution due to its higher stopping force. In a real measurement this effect would be somewhat smaller than in our simulations (where we used identical detector energy resolutions for He and Li) due to the deterioration of the detector energy resolution for Li compared to He. In this sense, three virtual experiments were performed and are summarized in table 1.

We also aim to study the bias introduced by the objective function in 158 the full analysis and uncertainties estimates of the RBS+ERD experiment. 159 Each measurement has some level of bias given by its level of noise, and the 160 bias of the combined result is what we want to evaluate here. Therefore, we 161 want to assess the role of the integrated charge (statistical significance of the 162 spectra) on that bias. After that, we want to study which measurement adds 163 more information to the analysis, whether it is the EBS measurement by the 164 enhanced oxygen signal or the Li-RBS with better depth-resolution, given a 165 fixed integrated charge. 166

	Table 1: Summary of experiments.			
	Incident	Integrated	Scattering	
Technique	beam	charge	angle	Goal
RBS+ERD	$1.5 { m MeV He}$	5, 10, 20 $\mu\mathrm{C}$	$170^\circ,30^\circ$	Full characterization
EBS	$3.04 { m MeV}$ He	$10~\mu\mathrm{C}$	$170^{\circ}$	Enhance O signal
Li-RBS	$1.0~{\rm MeV}$ Li	$10 \ \mu C$	$170^{\circ}$	Improve depth-resolution

# 167 2.2. Tested objective functions

We considered three objective functions in our tests. The simplest form on the list was the sum of the  $\chi^2$  for the different spectra.

$$F_{\chi^2} = \sum_{\text{Spectra}} \left[ \sum_{\text{Channels}} \left( \frac{c_m - c_i}{\sigma_i} \right)^2 \right]$$
(3)

where  $c_m$  is the number of counts in each channel calculated using the forward model (simulation) and the  $c_i$  is the number of counts on each channel for the experimental spectra.  $\sigma_i$  is the estimated uncertainty of  $c_i$  (assuming Poisson distribution it is equal to  $c_i^{1/2}$  or equal to one in case  $c_i = 0$ ).

The second function was the MultiSIMNRA objective function, which is based on the weighted-sum method for multi-objective optimization [3, 4]. It scales the individual  $\chi^2$  spectrum by its expected value so they have the same expected minimum value, therefore the same relative importance for the optimization algorithm [20].

$$F_{MS} = \frac{1}{S} \sum_{\text{Spectra}} \left[ \frac{1}{DoF} \sum_{\text{Channels}} \left( \frac{c_m - c_i}{\sigma_i} \right)^2 \right]$$
(4)

where DoF is the number of degrees-of-freedom of the fit and S is the total
number of spectra.

The third tested objective function was the NDF objective function. This is not based on the standard  $\chi^2$ , but it is based on the sum of squared differences of the simulated and experimental spectra. The normalization factor, in this case, is the area of each spectrum to the 1.5 power.

$$F_{NDF} = \sum_{\text{Spectra}} \left[ \frac{1}{A_j^{1.5}} \sum_{\text{Channels}} (c_m - c_i)^2 \right]$$
(5)

In fact, the area of the spectra is the expected value for the sum of squared differences (assuming Poisson distribution). However, according to the authors, the 1.5 power on the normalization is inserted ad-hoc for performance purposes [21]. The original NDF objective function also has a term that penalizes the optimization algorithm in case it increases the number of parameters in the fit [2]. But this term was not inserted here since we kept the number of fitting parameters always fixed.

Other objective functions may be available in NDF, mainly for the Bayesian inference method of uncertainty estimation [22]. We refer to eq. 5 as an alternative example, and as the only version published until now for the NDF's objective function.

# <sup>196</sup> 3. Results

#### <sup>197</sup> 3.1. Influence of the counting statistics

The major influence of the counting statistics is constraining the bias of 198 the objective function. Increasing the integrated charge of the spectra makes 199 the objective functions less susceptible to the effects of the Poisson noise. It 200 can be observed comparing Figs. 2-4 that all the minima of the objective 201 functions converge asymptotically to the true value with increasing integrated 202 charge. The effects on the bias introduced by the noise are apparently more 203 critical for NDF-like objective functions, since the optimal value predicted 204 by this function lies outside of the confidence interval for the lowest tested 205 value of the integrated charge, as can be observed in Fig. 2. 206

It is worth to mention that the positions of functions minima changes from one simulation to another. The only point that does not change its position is the true value (yellow dots). All others are noise dependent, thus each time random noise is added, the position of the minimum changes. Results shown here are representative to many consecutive simulations, and illustrate theauthor's arguments.



Figure 2: Heat-map (in log scale) for the  $\chi^2$  objective function and the optimum points of the three different objective functions for the simulated case of 5  $\mu$ C integrated charge. Axis units are  $1 \times 10^{15}$  at./cm<sup>2</sup>. The true value used to generate the data is also shown to illustrate the bias introduced by the noisy data into the objective functions. The continuous curve denotes one standard deviation defined by the  $\chi^2$  distribution.



Figure 3: Heat-map (in log scale) for the  $\chi^2$  objective function and the optimum points of the three different objective functions for the simulated case of 10  $\mu$ C integrated charge. Axis units are  $1 \times 10^{15}$  at./cm<sup>2</sup>. The true value used to generate the data is also shown to illustrate the bias introduced by the noisy data into the objective functions. The continuous curve denotes the one standard deviation defined by the  $\chi^2$  distribution.



Figure 4: Heat-map (in log scale) for the  $\chi^2$  and the optimum points of the three different objective functions for the simulated case of 20  $\mu$ C integrated charge. Axis units are  $1 \times 10^{15}$  at./cm<sup>2</sup>. The true value used to generate the data is also shown to illustrate the bias introduced by the noisy data into the objective functions. The continuous curve denotes one standard deviation defined by the  $\chi^2$  distribution.

# 213 3.2. Combination with EBS

In principle, the EBS measurement is intended to take advantage of the resonant cross-section that occurs at 3.038 MeV for the  ${}^{16}O(\alpha,\alpha){}^{16}O$  reaction [23]. The resonance enhances the  ${}^{16}O$  signal in the spectra, thus increasing the counting statistics in the oxygen peak. However, increasing the energy also reduces the effective stopping power and as a consequence reduces the depth-resolution.

The simulations indicate that, instead of providing steeper constraints to the objective function, it contributes very little to the final result since the individual contribution to the objective function is broader in the case of EBS. This apparently is a direct consequence of the loss of depth-resolution. This is observed by no relevant difference between Fig. 3 and Fig. 5.



Figure 5: Heat-map (in log scale) for the  $\chi^2$  objective function and the optimum points of the three different objective functions for the simulated case of 10  $\mu$ C integrated charge and EBS measurements combined. Axis units are  $1 \times 10^{15}$  at./cm<sup>2</sup>. The true value used to generate the data is also shown to illustrate the bias introduced by the noisy data into the objective functions. The continuous curve denotes one standard deviation defined by the  $\chi^2$  distribution.

#### 225 3.3. Combination with Li-RBS

Since the worst depth-resolution resulted in a broader objective function, 226 the Li-RBS measurement is intended to improve this situation by taking 227 advantage of a higher stopping forces for the heavier ion. It is worth to point 228 out that these simulation exercises were performed despite the less accurate 229 database of stopping forces to Li. In fact, in an actual analysis, this should 230 be included as a source of systematic error in the uncertainty budget. Here, 231 however, the database is assumed as accurate since we want to study the 232 effects of the insertion of a measurement with a better depth resolution as a 233 constraint to the objective function. 234

Indeed, all resulting objective functions including the Li-RBS measurement are steeper and resulted in a more constrained fit. This is observed comparing Fig. 3 and Fig. 6.



Figure 6: Heat-map (in log scale) for the  $\chi^2$  objective function and the optimum points of the three different objective functions for the simulated case of 10  $\mu$ C integrated charge and Li-RBS measurements combined. Axis units are  $1 \times 10^{15}$  at./cm<sup>2</sup>. The true value used to generate the data is also shown to illustrate the bias introduced by the noisy data into the objective functions. The continuous curve denotes one standard deviation defined by the  $\chi^2$  distribution.

#### 238 4. Discussion

With the simulated data, the gain of information was clearly observed 239 when inserting the Li-RBS into the optimizations by the shrinkage of the 240 confidence region, which is the region delimited by the uncertainty ellipse. 241 On the other hand, no gain was observed when inserting the EBS analysis 242 into the optimization due to the apparent sameness of the confidence region. 243 A possible explanation for this can be obtained in the Bayesian framework 244 [24, 12]. The Bayes theorem states a relationship between the probability 245 distribution function (pdf) for the parameters ( $\theta$ ) prior the inclusion of a 246 new experiment  $p(\theta|I)$ , with the final state of the pdf in the light of a new 247 experiment  $p(\theta|D, I)$ . This relationship depends on the likelihood function 248 of the new measurement  $p(D|\theta, I)$ , and a normalization term called evidence, 249 p(D|I) [25]: 250

$$p(\theta|D,I) = \frac{p(\theta|I) \cdot p(D|\theta,I)}{p(D|I)}$$
(6)

We can visualize what happens with the pdf when updated with new experimental data by assuming the evidence as a constant, and calculating the product of the prior pdf (the likelihood function of the previous experiment) with the likelihood function of the new measurement, i.e. the nominator in Bayes' theorem. The heat maps presented in fig. 7 show this. For practical reasons, we show data only for Si and O parameters, however, similar maps can be produced using any combination of Si or O with the H parameter.

The upper left figure in the panel of fig. 7 shows the Si and O pdf given 258 the RBS measurement. The upper middle figure shows the same but for the 259 ERD measurement. Note that the ERD measurement only contains direct 260 information for the H, and indirect information on the total amount of Si 261 plus O, roughly given by the width of the H peak. The product of both pdfs 262 results in the upper right figure, being the pdf in the light of the combination 263 of the data contained in the RBS and the ERD data together. Finally, the 264 pdf for the EBS measurement is presented in the lower middle figure, and the 265 pdf in the light of the combination of the three measurements is presented 266 in the lower right figure. 267

Figure 8 tells a different story. While the EBS measurement presents a likelihood function that is broader than the prior (the pdf obtained with the combination of RBS and ERD), the likelihood function of the Li-RBS measurement is narrower (see the figure in the lower middle in the panel of fig. 8). In this sense, the Bayes theorem results is a more restricted pdf, indicating the gain of information.



Figure 7: Probability density functions resulting from the combination of RBS+ERD+EBS. In light of the Bayes theorem, the EBS measurement does not provide additional information since the pdf is broader than the prior given by the RBS and ERD combined. Axis units are  $1 \times 10^{15}$  at./cm<sup>2</sup>.

Concerning the bias of the objective functions. This can also be analyzed in the Bayesian framework. Since the new pdf in light of the new experiment gets less broad, the solution space gets more restricted, thus the optimal prediction deviates less from the true value, therefore converging to the region of maximum probability. This is an important result that demonstrates the synergy as a method to control the bias of the objective functions.

280 4.1. Gain of information

The shrinkage of the pdf observed in the figs. 7 and 8 is a direct consequence of the gain of information provided by the IBA techniques. A narrow



Figure 8: Probability density functions resulting from the combination of RBS+ERD+Li-RBS. In light of the Bayes theorem, the Li-RBS measurement provides additional information since the pdf is narrower than the prior given by the RBS and ERD combined. Axis units are  $1 \times 10^{15}$  at./cm<sup>2</sup>.

distribution reflects less uncertainty on the parameters, thus a state of moreinformation.

The theory provides a quantitative scale for the information gain by the Kullback-Leibler divergence  $(D_{\text{KL}})$  that measures the relative entropy between two pdfs. Here it expresses the difference in the state of information if the pdf in light of the new data is used instead of the prior pdf. A standard unit for information gain is the *bits*.

$$D_{\text{KL}}(P|Q) = \int p(\theta|D, I) \log_2\left(\frac{p(\theta|D, I)}{p(\theta|I)}\right) d\theta \tag{7}$$

The table 4.1 expresses the information gained for the specific case of this sample of each technique alone and when combined. The estimates for the techniques alone take as a reference a neutral prior (representation of ignorance), represented by a uniform pdf that extends from zero up to twice the true value in the three-axis variables (Si, O, and H).

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Prior	Posterior	Information gain $(bits)$
Neutral	RBS	12.8
Neutral	ERD	16.8
Neutral	LiRBS	15.0
Neutral	EBS	11.5
RBS	RBS+ERD	6.5
RBS+ERD	RBS+ERD+LiRBS	0.6
RBS+ERD	RBS+ERD+EBS	0.1

Table 2: Information gained on different stages of the joint approach of data analysis.Values calculated using the Kullback-Leibler divergence.

One can observe the technique alone that presents the highest information gain starting at the neutral prior is the ERD, followed by RBS with lithium probe, while the one with a minor gain is EBS. However, it is essential to notice that this value accounts not just for the increment in oxygen sensitivity enabled by the resonant cross-section but also considers the reduced depth resolution due to the higher energy of the helium probe.

The ERD case is interesting since it increases mutual information, i.e., how much one variable tells us about another. It happens because the width of the H peak introduces a strong constraint between the Si and O amounts. Additionally, the information gained when combining ERD (posterior) with RBS (prior) is lower than the direct sum of the information gain of the separate techniques, indicating information does not add linearly in this case. It happens because part of the information on both measurements is redundant.

Finally, combining Li-RBS (posterior) with the RBS+ERD information state (prior) results in a six-fold information gain compared to the case of combining EBS (posterior) with the same RBS+ERD information state (prior). This is a quantitative measurement of what was observed in figs. 7 and 8.

# 314 5. Conclusions

In the self-consistent approach of analysis of multiple measurements, the forward model takes certain parameters, like the description of the sample proposed by the optimization algorithm, and computes a simulated spectrum that can be compared to the experimental observations. The optimization algorithm uses an objective function as a measure of the goodness of the fit, providing information to the algorithm to adjust the parameters in the search for the optimal parameters.

This search consists in exploring the solution space looking for the minimum of the objective function, which is considered as the optimal estimate to the true value. Deviations on that estimate are expected due to the susceptibility of the objective functions to noise. Here, we demonstrated that, even in conditions of low statistics, the objective function adopted in MultiSIMNRA is robust, presenting a low susceptibility to noise. The objective function adopted by NDF displayed a wider scatter around the true value for consecutive runs of the code, indicating some persistent sensitivity to noise even at
higher values of integrated charge or in combination to other measurements.
Another result is that all objective functions tested converged asymptotically
to the true value as higher the counting statistics (or integrated charge).

Besides that, we also demonstrated that incorporating multiple measure-333 ments by the adoption of the weighted-sum method can result in a gain of 334 information. This depends on the likelihood function of the new measurement 335 when compared to the pdf prior to the new measurement. If the likelihood 336 function of the new measurement is broader than the pdf representing the 337 current status of information, then no significant gain of information is ob-338 served. Alternatively, if the likelihood function is narrower than the prior 339 pdf, then gain of information occurs. 340

In fact, this can be interpreted as a confirmation that the consistent datafusion approach inherits the accuracy of the most accurate measurement since this offers the most stringent constraint to the optimization algorithm. However, this also establishes that some possible measurements, when added to a pool of measurements processed self-consistently, may not result in a relevant gain of information, depending if their likelihood functions combine synergistically or not.

Besides, the preceding results clearly demonstrate that different measurements result in different probability distributions of the parameters. Typically more localized pdfs are preferred, i.e., the ones with lower entropy. It indicates that the expected entropy reduction caused by a measurement (or a sequence of measurements) can provide guidance to assess the value of another measurement or experimental technique. It thus opens the pathway towards quantitative experimental design [26, 25]. For ion beam applications, a case study on deuterium depth profiling focusing on NRA and optimal selection of beam energies has been given in [27]. It appears that a systematic study of the gains achievable by combining different diagnostic tools holds great promise and can result in significant efficiency gains.

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