KÄHLER METRICS AND TORIC LAGRANGIAN FIBRATIONS

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ABSTRACT. We extend the Abreu-Guillemin theory of invariant Kähler metrics from toric symplectic manifolds to any symplectic manifold admitting a toric action of a symplectic torus bundle. We show that these are precisely the symplectic manifolds admitting a Lagrangian fibration with elliptic singularities. The base of such a toric Lagrangian fibration is a codimension 0 submanifold with corners of an integral affine manifold, called a Delzant subspace. This concept generalizes the Delzant polytope associated with a compact symplectic toric manifold. Given a Delzant subspace of finite type, we provide a Delzanttype construction of a Lagrangian fibration with the moment image being the specified Delzant subspace. We establish a 1:1 correspondence between invariant Kähler metrics and a pair consisting of an elliptic connection on the total space of the fibration and a hybrid b-metric on the base Delzant subspace, both with specified residues over the facets. Finally, we characterize extremal invariant Kähler metrics as those whose scalar curvature descends to an affine function on the base integral affine manifold. We show that this provides a method for finding and constructing extremal Kähler metrics.

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1. Introduction

In the late 1990s, Guillemin [24] and Abreu [1] described all invariant, compatible Kähler metrics for a compact symplectic toric manifold, in terms of singular Hessian metrics in the associated Delzant polytope. Abreu's work also encompasses a fourth-order nonlinear PDE expressing the condition for an invariant Kähler metric to be extremal in the sense of Calabi. Subsequently, Donaldson [16] developed the analysis of Abreu's equation and formulated K-stability for polytopes, sparking a series of subsequent research works in the search for extremal Kähler metrics (see, e.g., the recent survey [27]). The main aim of this work is to extend the Abreu-Guillemin theory to a wider class of symplectic manifolds.

The class of symplectic manifolds we consider here have a type of symmetry which is described by an action of a symplectic torus bundle (\mathcal{T}, Ω) . This type of action includes as a special case the ordinary Hamiltonian torus actions but

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also, e.g., torus actions with cylinder valued moment maps or even examples with no globally defined Hamiltonian torus action. More precisely, we consider *toric* actions of symplectic torus bundles (\mathcal{T}, Ω) (see Definition 4.1). These can be characterized in terms of their moment maps as *toric Lagrangian fibrations*, i.e., singular Lagrangian fibrations admitting only elliptic-type singularities (see Theorem 4.4):

Theorem. Every toric Hamiltonian \mathcal{T} -space is a toric Lagrangian fibration. Conversely, every toric Lagrangian fibration admits a toric Hamiltonian action of a symplectic torus bundle (\mathcal{T}, Ω) .

We picture a toric Hamiltonian \mathcal{T} -space as in the following diagram



where M is an integral affine manifold, $p:(\mathcal{T},\Omega)\to M$ is the corresponding symplectic torus bundle, (S,ω) is a symplectic manifold and \mathcal{T} acts on S along the moment map μ .

Delzant's classification of toric symplectic manifolds [15] has been extended to a classification of toric \mathcal{T} -spaces in terms of their moment map image $\Delta = \mu(S)$ [28] (see also Section 4). The space Δ is now a codimension 0 submanifold with corners of the integral affine manifold M, called a *Delzant subspace*. A particular case of these are the principal Hamiltonian \mathcal{T} -spaces, which correspond to Lagrangian fibrations without singularities, where the classification reduces to Duistermaat's result in [19] (see also Section 3). The classical symplectic toric manifolds, both compact and non-compact (see [26]), also fit into this framework and can be characterized as the toric \mathcal{T} -spaces whose associated Delzant space has trivial affine holonomy (see Theorem 4.16). This last result is one instance of the fact that the integral affine geometry of M plays a crucial role in the theory of toric \mathcal{T} -spaces. This is also a well-known feature of the theory of integrable systems (see, e.g., [20, 32]).

Given an integral affine manifold M and a Delzant subspace $\Delta \subset M$, the classification mentioned above requires the construction of a toric \mathcal{T} -space

$$\mu:(S,\omega)\to M$$

with $\mu(S) = \Delta$. This is done for general Delzant subspaces in [28]. Here, for a large class of Delzant subspaces, we give another construction in the spirit of Delzant's original construction. This is the content of the following theorem (see Section 5 for details).

Theorem. Let $\Delta \subset M$ be a finite type Delzant subspace with d facets. Every toric \mathcal{T} -space with moment map image Δ can be realized as a symplectic quotient

$$((P \times \mathbb{C}^d) / (\Gamma \ltimes \mathbb{T}^d), \omega_{\text{red}}),$$
 (1.1)

with P a principal Hamiltonian $p^*\mathcal{T}$ -space, where $p: \tilde{M} \to M$ is the universal covering space. When the Lagrangian-Chern class vanishes one can take $P = p^*\mathcal{T}$.

As we explain in Section 2, in spite of the fact that an element of a symplectic torus bundle only acts on a single fiber of the moment map, one can still make sense of \mathcal{T} -invariant objects. In particular, one can consider \mathcal{T} -invariant metrics and complex structures. Using this we extend the Abreu-Guillemin theory to toric \mathcal{T} -spaces. Our main result is the following (see Section 7).

Theorem. Let $\mu:(S,\omega)\to M$ be a toric \mathcal{T} -space, with Delzant subspace $\Delta:=\mu(S)\subset M$. There is a 1-1 correspondence between invariant Kähler metrics on S compatible with ω and the following data.

- (i) A flat Lagrangian elliptic connection for $\mu: S \to M$ with zero radial residue over the open facets of Δ .
- (ii) A Hessian hybrid b-metric on Δ with residues at the open facets given by the primitive outward-pointing normals multiplied by $\frac{1}{4\pi}$.

Moreover, an invariant Kähler metric G is extremal if and only if its scalar curvature S_G , viewed as function on Δ , is affine.

Elliptic connections and hybrid b-metrics are tensors with specified singularities over the boundary of Δ , introduced in Sections 4.5 and 7.1, respectively. These are defined in a coordinate-free way using the elliptic tangent bundle of μ [9, 10, 11, 12] and the b-tangent bundle of Δ [29].

When $\Delta \subset M$ is a finite type Delzant subspace and M carries a Hessian metric, our Delzant type construction above allows one to apply Kähler reduction, leading to the following result (see Section 7).

Corollary. Let (M,g) be a connected integral affine Hessian manifold and $\Delta \subset M$ a Delzant subspace of finite type with primitive boundary defining functions ℓ_1, \ldots, ℓ_d . The reduced Kähler metric on the symplectic quotient (1.1) induces the Hessian hybrid b-metric on Δ given by

$$g_{\Delta} = g + \operatorname{Hess}_{\Lambda}(\phi),$$

where ϕ is the smooth function on $\mathring{\Delta}$ given by

$$\phi = -\frac{1}{4\pi} \sum_{i=1}^{d} \ell_i \log |\ell_i|. \tag{1.2}$$

The relationship between our Delzant type construction and the standard Delzant construction will be explained in the main body of the paper. Here, we only point out that the metrics obtained by Kähler reduction via the two constructions do not quite coincide.

Our main theorem above provides an effective way of constructing (extremal) Kähler metrics in many examples, some of which have been obtained through much more elaborate means. In this paper, we only discuss a few illustrative examples, although we do show how to recover, by our techniques, the extremal Kähler metrics for a complex ruled surface over an elliptic curve that appears in the work of Apostolov et al. [2] – see Example 7.12. More elaborate examples will appear in an upcoming joint paper with Miguel Abreu. We are further working on extensions of the theory developed here to contact structures, generalized complex structures and the non-commutative setting, i.e., multiplicity-free actions of proper symplectic groupoids.

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Conventions and notations. In this paper, for manifolds with corners we follow the conventions and terminology from [28]. For further background on manifolds with corners see, e.g., [30].

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2. Hamiltonian \mathcal{T} -spaces

In this sections we introduce Hamiltonian actions of symplectic torus bundles and discuss some basic properties.

- 2.1. Symplectic torus bundles. In this paper, by a torus bundle we mean a fiber bundle $p: \mathcal{T} \to M$ where:
 - each fiber is a Lie group isomorphic to a torus;
 - the fiberwise multiplication $m: \mathcal{T} \times_M \mathcal{T} \to \mathcal{T}$, inversion $i: \mathcal{T} \to \mathcal{T}$ and unit $u: M \to \mathcal{T}$ are smooth maps.

On the other hand, an equivalence of torus bundles is a diffeomorphism

$$\begin{array}{ccc}
\mathcal{T}_1 & \xrightarrow{\Psi} & \mathcal{T}_2 \\
\downarrow^{p_1} & & \downarrow^{p_2} \\
M & \xrightarrow{\text{Id}} & M
\end{array}$$

which restricts to a Lie group homomorphism on each fiber.

We will be specially interested in torus bundles carrying a symplectic form:

Definition 2.1. A symplectic torus bundle is a torus bundle $p: \mathcal{T} \to M$ with a symplectic form $\Omega \in \Omega^2(\mathcal{T})$ which is multiplicative, i.e., such that

$$m^*\Omega = \operatorname{pr}_1^*\Omega + \operatorname{pr}_2^*\Omega,$$

where $m, \operatorname{pr}_1, \operatorname{pr}_2 : \mathcal{T} \times_M \mathcal{T} \to \mathcal{T}$ are the fiberwise multiplication and the projections onto each factor, respectively. An **equivalence** of symplectic torus bundles is an equivalence of torus bundles preserving the symplectic forms.

The multiplicative condition forces the fibers of $p: \mathcal{T} \to M$ and the unit section $u: M \to \mathcal{T}$ to be Lagrangian submanifolds, so dim $\mathcal{T} = 2 \dim M$.

Example 2.2. The simplest example of a symplectic torus bundle is

$$\operatorname{pr}: \mathbb{T}^n \times \mathbb{R}^n \to \mathbb{R}^n, \qquad \Omega = \sum_{i=1}^n d\theta_i \wedge dx^i,$$

where $(\theta_1, \ldots, \theta_n)$ denote the angle coordinates on $\mathbb{T}^n := \mathbb{R}^n/\mathbb{Z}^n$.

Remark 2.3 (Symplectic groupoids). The reader familiar with the groupoid language will recognize that a (symplectic) torus bundle is just a source-connected (symplectic) groupoid where the source and target maps coincide and multiplication is abelian.

Many of our results extend to the more general setting of symplectic groupoids. We will discuss this in future work. For now, we will sometimes use the language of symplectic groupoids in an auxiliary manner, but keeping the exposition self-contained. The curious reader can consult [13] for the basics of (symplectic) groupoids.

Given a symplectic torus bundle $p:(\mathcal{T},\Omega)\to M$, the symplectic form allows to identify the Lie algebras of the fibers with the fibers of T^*M . Using this identification, the fiberwise exponential maps assembles to a surjective, symplectic, submersion

$$\exp: T^*M \to \mathcal{T}, \quad \exp^* \Omega = \Omega_{\operatorname{can}}.$$

Since the identity section is Lagrangian, it follows that its preimage

$$\Lambda := \exp^{-1}(M) \subset T^*M$$
,

satisfies the two properties in the following definition.

Definition 2.4. A integral affine structure on a manifold M is a closed submanifold $\Lambda \subset T^*M$ satisfying:

- (i) Λ is a Lagrangian submanifold of (T^*M, Ω_{can}) ;
- (ii) $\Lambda_x := \Lambda \cap T_x^*M$ is a full rank lattice for all $x \in M$.

Remark 2.5. One usually defines an integrable affine structure on a manifold M as a maximal atlas for which the coordinate changes are (restrictions of) maps of the form

$$x \mapsto Ax + b$$
, $A \in GL_m(\mathbb{Z})$, $b \in \mathbb{R}$.

Such atlas are in bijective correspondence with submanifolds $\Lambda \subset T^*M$ as in Definition 2.4. Given Λ one defines the integral affine charts to be any chart (U, x^1, \dots, x^n) such that

$$\Lambda|_U = \mathbb{Z} dx^1 + \dots + \mathbb{Z} dx^n.$$

Conversely, given such an integrable affine atlas the last expression defines Λ . Henceforth, we shall make use of this correspondence with no further notice. We refer to [14, 4, 23] for details on integral affine structures.

Hence, a symplectic torus bundle $p:(\mathcal{T},\Omega)\to M$ determines a canonical integral affine structure Λ on M and the exponential map induces an equivalence

$$T^*M/\Lambda \xrightarrow{\sim} \mathcal{T}$$
.

This diffeomorphism pulls back Ω to the unique symplectic form $\Omega_{\Lambda} \in \Omega^2(T^*M/\Lambda)$ such that

$$q^*\Omega_{\Lambda} = \Omega_{\rm can},$$

where $q: T^*M \to T^*M/\Lambda$ is the projection.

Conversely, given any integral affine structure Λ on a manifold M, we obtain a symplectic torus bundle $(\mathcal{T}_{\Lambda}, \Omega_{\Lambda})$ where

$$\mathcal{T}_{\Lambda} := T^* M / \Lambda, \quad q^* \Omega_{\Lambda} = \Omega_{\operatorname{can}},$$

and the projection $q:T^*M\to\mathcal{T}_\Lambda$ becomes the exponential map. It follows that there is a 1:1 correspondence:

$$\left\{ \begin{array}{c} \text{symplectic torus bundles} \\ \text{over } M \\ \text{up to equivalence} \end{array} \right\} \quad \stackrel{\tilde{}}{\longleftrightarrow} \quad \left\{ \begin{array}{c} \text{integral affine structures} \\ \Lambda \subset T^*M \end{array} \right\}$$

Example 2.6. On \mathbb{R}^n we have the standard integral affine structure

$$\Lambda_{\rm st} = \mathbb{Z}\{\mathrm{d}x^1, \dots, \mathrm{d}x^n\},\,$$

which corresponds to the trivial symplectic torus bundle

$$\operatorname{pr}_2: \mathbb{T}^n \times \mathbb{R}^n \to \mathbb{R}^n, \quad \Omega_{\operatorname{st}} = \sum_{i=1}^n \mathrm{d}\theta_i \wedge \mathrm{d}x^i.$$

Similarly, on the torus $\mathbb{T}^n = \mathbb{R}^n/\mathbb{Z}^n$ we have the integral affine structure

$$\Lambda_{\rm st} := \mathbb{Z}\{\mathrm{d}x^1, \dots, \mathrm{d}x^n\},\$$

where now x^i are standard coordinates on the torus (so defined mod \mathbb{Z}). The corresponding symplectic torus bundle is

$$\operatorname{pr}_2: \mathbb{T}^n \times \mathbb{T}^n \to \mathbb{T}^n, \quad \Omega_{\operatorname{st}} = \sum_{i=1}^n \mathrm{d}\theta_i \wedge \mathrm{d}x^i.$$

Remark 2.7. Every symplectic torus $p: (\mathcal{T}, \Omega) \to M$ is locally equivalent to the standard one $(\mathbb{T}^n \times \mathbb{R}^n, \Omega_{\mathrm{st}}) \to \mathbb{R}^n$. Indeed, an integral affine chart (U, x^i) induces an isomorphism

$$\mathcal{T}|_U \simeq \mathbb{T}^n \times U,$$

which identifies Ω and $\Omega_{\rm st}$.

Example 2.8. When n=2 we have an exotic integral affine structure on \mathbb{T}^2 defined by

$$\Lambda_{\text{ex}} = \mathbb{Z}\{\mathrm{d}x^1, \mathrm{d}x^2 - x^1\mathrm{d}x^1\}.$$

The corresponding symplectic torus bundle can be described as follows. Consider the discrete subgroup $\Gamma \subset \operatorname{Aff}_{\mathbb{Z}}(\mathbb{R}^4)$ generated by the translations

$$\gamma_1(\theta_1, \theta_2, x^1, x^2) = (\theta_1, \theta_2, x^1 + 1, x^2), \quad \gamma_2(\theta_1, \theta_2, x^1, x^2) = (\theta_1, \theta_2, x^1, x^2 + 1),$$

$$\gamma_3(\theta_1, \theta_2, x^1, x^2) = (\theta_1 + 1, \theta_2, x^1, x^2),$$

and by the element

$$\gamma_4(\theta_1, \theta_2, x^1, x^2) = (\theta_1 - x^1, \theta_2 + 1, x^1, x^2).$$

This group acts proper and free, by symplectic transformations of the canonical symplectic form

$$\Omega_{\rm can} = \mathrm{d}\theta_1 \wedge \mathrm{d}x^1 + \mathrm{d}\theta_2 \wedge \mathrm{d}x^2.$$

The sought after symplectic torus bundle has total space $\mathcal{T} := \mathbb{R}^4/\Gamma$, with symplectic form Ω induced by Ω_{can} , and projection

$$p: \mathcal{T} \to \mathbb{T}^2, \quad [\theta_1, \theta_2, x^1, x^2] \mapsto [x^1, x^2].$$

Indeed, this map has Lagrangian fibers and admits the Lagrangian section

$$s(x^1, x^2) = [0, 0, x^1, x^2].$$

This is the zero section for the multiplication

$$m([\theta_1, \theta_2, x^1, x^2], [\bar{\theta}_1, \bar{\theta}_2, x^1, x^2]) = [\theta_1 + \bar{\theta}_1, \theta_2 + \bar{\theta}_2, x^1, x^2].$$

Note that (\mathcal{T}, Ω) is the Kodaira-Thurston symplectic manifold.

Let $p:(\mathcal{T},\Omega)\to M$ be a symplectic torus bundle inducing an integral affine structure $\Lambda\subset T^*M$. Then M carries a **canonical flat connection** ∇ , namely the unique torsion free connection satisfying

$$\nabla_{\partial_{x^i}}\partial_{x^j}=0,$$

for any integral affine chart (U, x^i) . We will denote by the same symbol ∇ the dual connection on T^*M : it is the unique linear connection for which every local section of Λ is flat. The corresponding **horizontal distribution** will be denoted by $H^{\nabla} \subset T(T^*M)$.

At the level of the torus bundle $\mathcal{T} \to M$ the existence of this flat connection is reflected in the existence of a Lagrangian foliation transverse to the fibers.

Proposition 2.9. Let $p:(\mathcal{T},\Omega)\to M$ be a symplectic torus bundle inducing an integral affine structure $\Lambda\subset T^*M$. Then

$$H := (\operatorname{d} \exp)(H^{\nabla}) \subset T(\mathcal{T}) \tag{2.1}$$

is a flat Ehresmann connection by Lagrangian subspaces, hence defines a Lagrangian foliation transverse to the fibers of $p: \mathcal{T} \to M$.

Proof. Under the local trivialization induced by an integral affine chart (see Remark (2.7)), the exponential map $\exp: T^*M \to \mathcal{T}$ is just the projection

$$\exp: \mathbb{R}^n \times U \to \mathbb{T}^n \times U$$
,

and we find

$$H = (\mathrm{d} \exp)(H^{\nabla}) = \bigcap_{i=1}^{n} \ker(\mathrm{d}\theta_i).$$

The statement now follows by observing that the forms $d\theta_i$ are multiplicative. \Box

Definition 2.10. The distribution $H \subset T(\mathcal{T})$ given by (2.1) is called the **canonical** horizontal distribution of the symplectic torus bundle.

Remark 2.11. The distribution H is an example of a multiplicative Ehresmann connection. In general, a distribution in a Lie groupoid \mathcal{G} is called multiplicative if it is a subgroupoid of the tangent groupoid $T(\mathcal{G})$. We refer to [21, 22] for more details on multiplicative Ehresmann connections.

2.2. Morphisms of symplectic torus bundles. We will make use of the following notion of morphism of symplectic torus bundles.

Definition 2.12. A morphism of symplectic torus bundles

$$(\phi, \Phi) : (\mathcal{T}_1, \Omega_1) \dashrightarrow (\mathcal{T}_2, \Omega_2)$$

consists of a map $\phi: M_1 \to M_2$ between the basis and a bundle map

$$\phi^* \mathcal{T}_2 \xrightarrow{\Phi} \mathcal{T}_1$$

$$\downarrow^{p_1} \qquad \qquad \downarrow^{p_1}$$

$$M_1 \xrightarrow{\text{Id}} M_1$$

satisfying:

- (i) Φ restricts on each fiber to a group morphism;
- (ii) $Graph(\Phi) \subset \overline{\mathcal{T}_1} \times \mathcal{T}_2$ is a Lagrangian submanifold.

The graph in the last item in the previous definition is the relation defined by:

Graph(
$$\Phi$$
) := {($\Phi(g, x), g$) : $(g, x) \in \mathcal{T}_2 \times_{M_1} M_1$ }.

The notation $\overline{\mathcal{T}}$ means, as usual, the symplectic manifold \mathcal{T} with the opposite symplectic structure.

Remark 2.13. The notion of morphism in the previous definition is actually an instance of the notion of a groupoid comorphism [8]. Since we do not consider groupoid morphisms or other notions of morphism for torus bundles, we will use the term "morphism".

The notion of morphism of symplectic torus bundles is intimately related to the concept of integral affine map which we now recall (see [14, 4, 23] for more details).

Definition 2.14. Let
$$(M_1, \Lambda_1)$$
 and (M_2, Λ_2) be integral affine manifolds. A map $\phi: (M_1, \Lambda_1) \to (M_2, \Lambda_2)$ (2.2)

is called an integral affine map if $\phi^*(\Lambda_2) \subset \Lambda_1$. It is called a **primitive integral** affine map if $\phi^*(\Lambda_2) = \Lambda_1$.

Remark 2.15. A map $\phi: (M_1, \Lambda_1) \to (M_2, \Lambda_2)$ is integral affine if and only if in integral affine charts (with connected domains) it is of the form

$$x \mapsto Ax + b$$
,

for some linear integral affine map $A: (\mathbb{R}^{m_1}, \mathbb{Z}^{m_1}) \to (\mathbb{R}^{m_2}, \mathbb{Z}^{m_2})$ and some $b \in \mathbb{R}$.

The next proposition shows that the category **IntAffMan** of integral affine manifolds is equivalent to the category **SympTorBun**.

Proposition 2.16. The assignment $(M, \Lambda) \mapsto (\mathcal{T}_{\Lambda}, \Omega_{\Lambda})$ extends to a functor

$$\mathbf{IntAffMan} \to \mathbf{SympTorBun}$$

by assigning to an integral affine map ϕ as in (2.2) the morphism

$$(\phi, \phi^*): (\mathcal{T}_{\Lambda_1}, \Omega_{\Lambda_1}) \dashrightarrow (\mathcal{T}_{\Lambda_2}, \Omega_{\Lambda_2}), \quad \phi^*([\alpha], x) = [(d_x \phi)^* \alpha].$$

This functor is in fact an equivalence of categories.

Proof. By the remark above the map $\underline{\phi}^*$ is well-defined. It is readily verified that $(\phi, \underline{\phi}^*)$ is a morphism, and that this construction defines a functor. To see that this is an equivalence of categories, let $(\phi, \Phi) : (\mathcal{T}_1, \Omega_1) \dashrightarrow (\mathcal{T}_2, \Omega_2)$ be any morphism between symplectic torus bundles. Then Φ has a unique lift to a vector bundle map

$$\begin{array}{ccc}
\phi^* T^* M_2 & \xrightarrow{\widetilde{\Phi}} & T^* M_1 \\
\text{Id} \times \exp \downarrow & & & \exp \downarrow \\
\phi^* \mathcal{T}_2 & \xrightarrow{\Phi} & \mathcal{T}_1
\end{array}$$

whose graph

$$\operatorname{Graph}(\widetilde{\Phi}) \subset \overline{T^*M_1} \times T^*M_2$$

is a Lagrangian submanifold. One checks (e.g., by working in local coordinates) that this last condition implies that

$$\widetilde{\Phi} = \phi^*$$
.

The commutativity of the diagram then forces

$$\phi^*(\Lambda_2) \subset \Lambda_1$$
,

where Λ_1 and Λ_2 are the integral affine structures induced by $(\mathcal{T}_1, \Omega_1)$ and $(\mathcal{T}_2, \Omega_2)$. By the remark above, we conclude that ϕ is an integral affine map.

2.3. Hamiltonian \mathcal{T} -spaces. One of our main objects of study are Hamiltonian spaces for symplectic torus bundles. An action of a torus bundle $p: \mathcal{T} \to M$ on map $\mu: S \to M$ is given by a map

$$\mathcal{A}: \mathcal{T} \times_M S \to S, \quad (g, p) \mapsto g \cdot p,$$

satisfying the usual properties:

- (i) $g \cdot (h \cdot p) = (gh) \cdot p$;
- (ii) $u(\mu(p)) \cdot p = p$.

In other words, this is just a smooth varying fiberwise action.

Symplectic torus bundles act on maps whose domain is a symplectic manifold:

Definition 2.17. Let $p: (\mathcal{T}, \Omega) \to M$ be a symplectic torus bundle. A Hamiltonian \mathcal{T} -space consists of:

- (i) a symplectic manifold (S, ω) ;
- (ii) a map $\mu: S \to M$;
- (iii) an action $\mathcal{A}: \mathcal{T} \times_M S \to S$ which is symplectic, i.e., that satisfies

$$\mathscr{A}^*\omega = \operatorname{pr}_{\mathcal{T}}^*\Omega + \operatorname{pr}_{\mathcal{S}}^*\omega.$$

Since a Hamiltonian \mathcal{T} -space consists fiberwise of ordinary abelian actions, we obtain an **infinitesimal action** of the bundle of abelian Lie algebras $T^*M \to M$ on $\mu: S \to M$. In other words, we have a linear map $\alpha: \Omega^1(M) \to \mathfrak{X}(S)$ satisfying

$$\mu_*(\alpha(\alpha)) = 0, \quad [\alpha(\alpha), \alpha(\beta)] = 0, \quad (\alpha, \beta \in \Omega^1(M)).$$

We call $\mu: S \to M$ the **moment map** of the action and it satisfies the moment map condition (see [13])

$$i_{\alpha(\alpha)}\omega = \mu^*\alpha \quad (\alpha \in \Omega^1(M)).$$
 (2.3)

Example 2.18 (Classical Hamiltonian spaces). A classical Hamiltonian \mathbb{T}^n -space with moment map $\mu: (S, \omega) \to \mathbb{R}^n$ is the same thing as Hamiltonian \mathcal{T} -space for the symplectic torus bundle $\mathcal{T} := (\mathbb{T}^n \times \mathbb{R}^n, \Omega_{\operatorname{can}}) \to \mathbb{R}^n$. The \mathcal{T} -action and is given in terms of the \mathbb{T}^n -action determine each other by

$$\mathscr{A}: (\mathbb{T}^n \times \mathbb{R}^n) \times_{\mathbb{R}^n} S \to S, \ (g, x, p) \mapsto gp, \quad \text{if} \quad x = \mu(p).$$

Conversely, any \mathcal{T} -action takes this form for a unique \mathbb{T}^n -action.

Example 2.19 (The trivial Hamiltonian \mathcal{T} -space). Let (\mathcal{T}, Ω) be any symplectic torus bundle. Then \mathcal{T} acts on itself by left translations

$$\mathscr{A}: \mathcal{T} \times_M \mathcal{T} \to \mathcal{T}, (g,h) \mapsto gh,$$

with moment map the projection $p: \mathcal{T} \to M$. The multiplicativity of Ω shows that this is a Hamiltonian \mathcal{T} -space.

Example 2.20 (The trivial \mathbb{S}^2 -bundle over \mathbb{T}^2). Consider the symplectic manifold

$$(S,\omega) := (\mathbb{T}^2, \omega_{\mathbb{T}^2}) \times (\mathbb{S}^2, \omega_{\mathbb{S}^2}),$$

where $\omega_{\mathbb{T}^2}$ and $\omega_{\mathbb{S}^2}$ denote the area forms with total area 1, so

$$\omega_{\mathbb{T}^2} := \mathrm{d}y \wedge \mathrm{d}x, \quad \omega_{\mathbb{S}^2} := \mathrm{d}\phi \wedge \mathrm{d}h,$$

where (ϕ, h) are cylindrical coordinates on \mathbb{S}^2 . This admits an action of the symplectic torus bundle (\mathcal{T}, Ω) corresponding to the standard integral affine cylinder

$$(M, \Lambda) := (\mathbb{S}^1 \times \mathbb{R}, \mathbb{Z} dx \oplus \mathbb{Z} dh).$$

Explicitly, the symplectic torus bundle

$$(\mathcal{T}, \Omega) = (\mathbb{T}^2 \times \mathbb{S}^1 \times \mathbb{R}, dy \wedge dx + d\theta \wedge dh),$$
$$p: \mathcal{T} \to \mathbb{S}^1 \times \mathbb{R}. \quad (y, \theta, x, h) \mapsto (x, h),$$

acts along the map

$$\mu: \mathbb{T}^2 \times \mathbb{S}^2 \to \mathbb{S}^1 \times \mathbb{R}, (y, x, \phi, h) \to (x, h),$$

as follows

$$(y, \theta, x, h) \cdot (\tilde{y}, x, \phi, h) = (y + \tilde{y}, x, \theta + \phi, h).$$

Example 2.21 (The non-trivial \mathbb{S}^2 -bundle over \mathbb{T}^2). The non-trivial orientable \mathbb{S}^2 -bundle over \mathbb{T}^2 can be obtained by taking the quotient of the trivial \mathbb{S}^2 -bundle $\mathbb{R}^2 \times \mathbb{S}^2 \to \mathbb{R}^2$ by the proper and free action of \mathbb{Z}^2 given by

$$(k_1, k_2) \cdot (y, x, \phi, h) = (y + k_1, x + k_2, \phi - k_2 y, h).$$

Let (S, ω) be the resulting manifold $\mathbb{T}^2 \times \mathbb{S}^2 := (\mathbb{R}^2 \times \mathbb{S}^2)/\mathbb{Z}^2$ equipped with the symplectic form induced by the \mathbb{Z}^2 -invariant symplectic form

$$(h+2)dy \wedge dx + (xdy + d\phi) \wedge dh$$
.

This symplectic manifold admits an action of the symplectic torus bundle (\mathcal{T}, Ω) associated to the integral affine manifold

$$(M, \Lambda) = (\mathbb{S}^1 \times] - 2, \infty[, \mathbb{Z}((h+2)dx + xdh) \oplus \mathbb{Z}dh).$$

Explicitly, this torus bundle is

$$\mathcal{T} = (\mathbb{T}^2 \times \mathbb{R} \times] - 2, \infty[) / \mathbb{Z},$$

$$p: \mathcal{T} \to \mathbb{S}^1 \times] - 2, \infty[, \quad (y, \theta, x, h) \mapsto (x, h),$$

where \mathbb{Z} acts as

$$k \cdot (y, \theta, x, h) = (y, \theta - ky, x + k, h),$$

and the multiplication on the fibers is just addition. The symplectic form Ω is induced by the \mathbb{Z} -invariant symplectic form

$$(h+2)dy \wedge dx + (xdy + d\theta) \wedge dh$$
.

The symplectic torus bundle (\mathcal{T}, Ω) acts on (S, ω) along the map

$$\mu: \mathbb{T}^2 \widetilde{\times} \mathbb{S}^2 \to \mathbb{S}^1 \times]-2, \infty[, (y, x, \phi, h) \mapsto (x, h),$$

as follows

$$(y, \theta, x, h) \cdot (\tilde{y}, x, \phi, h) = (y + \tilde{y}, x, \theta + \phi, h).$$

Let $\mu_1:(S_1,\omega_1)\to M$ and $\mu_2:(S_2,\omega_2)\to M$ be Hamiltonian \mathcal{T} -spaces. Then a morphism from μ_1 to μ_2 is a symplectic map

$$S_1 \xrightarrow{\Psi} S_2$$

$$\downarrow^{\mu_1} \qquad \qquad \downarrow^{\mu_2}$$

$$M \xrightarrow{\text{Id}} M$$

which is \mathcal{T} -equivariant:

$$\Psi(g \cdot p) = g \cdot \Psi(p).$$

We need a generalization of this notion to Hamiltonian spaces of distinct symplectic torus bundles.

Definition 2.22. Let $(\phi, \Phi): (\mathcal{T}_1, \Omega_1) \dashrightarrow (\mathcal{T}_2, \Omega_2)$ be a morphism of symplectic torus bundles, and let $\mu_i: (S_i, \omega_i) \to M_i$ be Hamiltonian \mathcal{T}_i -spaces. A morphism from μ_1 to μ_2 covering (ϕ, Φ) is a map

$$S_1 \xrightarrow{\Psi} S_2$$

$$\downarrow^{\mu_1} \qquad \qquad \downarrow^{\mu_2}$$

$$M_1 \xrightarrow{\phi} M_2$$

satisfying:

- (i) Ψ is a Poisson map;
- (ii) Ψ is (ϕ, Φ) -equivariant, i.e., $\Psi(\Phi(g, \mu_1(p)) \cdot p) = g \cdot \Psi(p)$.

The base map of a morphism of Hamiltonian spaces is an integral affine map by Proposition 2.16. For an **isomorphism** this map must be an integral affine isomorphism, while the the map Ψ between the total spaces must be a symplectomorphism. An isomorphism for which the base map ϕ is the identity, and so $\mathcal{T}_1 = \mathcal{T}_2$, will be called an **equivalence**.

Example 2.23. Let $\mu: (S, \omega) \to \mathbb{R}^n$ be a Hamiltonian \mathbb{T}^n -space and $K_\theta: \mathbb{T}^m \to \mathbb{T}^n$ a Lie group homomorphism. The induced Lie algebra homomorphism $\theta: \mathbb{R}^m \to \mathbb{R}^n$ is a linear integral affine map $(\mathbb{R}^m, \mathbb{Z}^m) \to (\mathbb{R}^n, \mathbb{Z}^n)$, and we have a morphism of symplectic torus bundles

$$(\phi, \Phi) : \mathbb{T}^n \times \mathbb{R}^n \longrightarrow \mathbb{R}^m \times \mathbb{T}^m, \phi = \theta^*, \ \Phi(g, x) = (x, K_{\theta}(g)).$$

On the other hand, the induced \mathbb{T}^m -action on S

$$h \cdot x := K_{\theta}(h) \cdot x,$$

is Hamiltonian, with momentum map $\tilde{\mu} := \theta^* \circ \mu : S \to \mathbb{R}^m$. Moreover,

$$S \xrightarrow{\text{Id}} S$$

$$\downarrow \tilde{\mu}$$

$$\mathbb{R}^n \xrightarrow{\phi} \mathbb{R}^m$$

is a morphism of Hamiltonian spaces covering (ϕ, Φ) .

2.4. \mathcal{T} -invariant tensors. Let $p:(\mathcal{T},\Omega)\to M$ be a symplectic torus bundle. Given a Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$, the torus bundle \mathcal{T} acts on the μ -fibers so each $g\in\mathcal{T}$ induces a map between the tangent spaces to the fibers:

$$g_*: T\mu^{-1}(x) \to T\mu^{-1}(x)$$
, with $x = p(g)$.

In order to extend the action of g to the tangent bundle TS we use the canonical horizontal distribution H (see Definition 2.10). We denote the corresponding horizontal lift of tangent vectors by:

$$\operatorname{hor}_g: T_xM \to T_g\mathcal{T}, \quad \operatorname{hor}_g(w) := (\operatorname{d}_g p)|_H^{-1}(w).$$

Definition 2.24. Given a symplectic torus bundle $p:(\mathcal{T},\Omega)\to M$ and a Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$ the tangent action of $g\in\mathcal{T}$ is the map

$$g_*: T_pS \to T_{gp}S, \quad g_*v := d\mathscr{A}(\mathrm{hor}_g(\mathrm{d}\mu(v)), v).$$

The multiplicativity of the distribution H ensures that this defines an action of the torus bundle \mathcal{T} on the map $\mu \circ \operatorname{pr}: TS \to M$.

Remark 2.25. The distribution H is an example of a Cartan connection on the torus bundle $p: \mathcal{T} \to M$. The construction of the action in Definition 2.24 is a special case of a more general construction valid for actions of Lie groupoids $\mathcal{G} \rightrightarrows M$ on a map $\mu: S \to M$. Whenever the Lie groupoid \mathcal{G} is equipped with a Cartan connection one obtains an action of \mathcal{G} on $\mu \circ \operatorname{pr}: TS \to M$ (see, e.g., [3])

Definition 2.26. We say that a tensor field on the total space of a Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$ is \mathcal{T} -invariant if it is invariant under the tangent action of every $g\in\mathcal{T}$.

Similarly, one can talk about \mathcal{T} -invariance of other objects. For example, a distribution $D \subset TS$ is \mathcal{T} -invariant if is preserved under the tangent action. A foliation of S is \mathcal{T} -invariant if the corresponding distribution if \mathcal{T} -invariant.

Example 2.27. For any symplectic torus bundle $p:(\mathcal{T},\Omega)\to M$ the symplectic form Ω and the horizontal distribution H are both \mathcal{T} -invariant. For any Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$ the symplectic form ω is also \mathcal{T} -invariant.

Given a Hamiltonian (\mathcal{T},Ω) -space $\mu:(S,\omega)\to M$, fixing a integral affine chart (U,x^i) , one obtains a \mathbb{T}^n -action on $S|_U$. This follows from the fact that a choice of integral affine chart induces a local trivialization of the symplectic torus bundle (cf. Remark 2.7). Although these locally defined \mathbb{T}^n -actions depend on the choice of integral affine chart, it turns out that \mathcal{T} -invariance is equivalent to \mathbb{T}^n -invariance, as stated in the next proposition. For the statement, we will the fact that a local section $s:U\to\mathcal{T}$ of $\mathcal{T}\to M$ acts on $S|_U$ as the fiber preserving diffeomorphism

$$p \mapsto s(\mu(p)) \cdot p$$
.

Proposition 2.28. Given a tensor field K on the total space of a Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$ the following are equivalent:

- (i) K is \mathcal{T} -invariant;
- (ii) K is invariant under the action of any horizontal local section of \mathcal{T} ;
- (iii) K is invariant under the infinitesimal action of any locally defined flat 1-form

$$\mathcal{L}_{\alpha(\alpha)}K = 0 \text{ if } \nabla \alpha = 0; \tag{2.4}$$

(iv) K is \mathbb{T}^n -invariant relative to the locally defined \mathbb{T}^n -action induced by any integral affine chart.

Proof. Obviously, a tensor is \mathcal{T} -invariant if and only if it is $\mathcal{T}|_{U_a}$ -invariant for some open cover $\{U_a\}$ of M. Hence, it is enough to check the statement on an integral affine chart (U, x^i) with connected domain.

The equivalence of (i) and (ii) follows from the fact that any element $g \in \mathcal{T}$ extends to a horizontal local section (see proof of Proposition 2.9).

For the equivalence between (ii) and (iii), observe that if $\alpha \in \Omega^1(U)$ is any flat 1-form then $\exp(t\alpha): U \to \mathcal{T}$ is a horizontal section, and acting by this local section is given by the flow of the vector field $\alpha(\alpha) \in \mathfrak{X}(S)$ (cf. (2.3))

$$\mathscr{A}(\exp(t\alpha), p) = \phi_{a(\alpha)}^t(p).$$

For the equivalence between (ii) and (iv), observe that the choice of integral affine chart gives an identification

$$\mathbb{T}^n \times U \simeq \mathcal{T}|_U$$
.

Under this identification, the horizontal sections of \mathcal{T} become the constant sections of $\mathbb{T}^n \times U \to U$. Therefore, the action by $g \in \mathbb{T}^n$ coincides with the action by the horizontal section $x \mapsto (g, x)$, and the equivalence follows.

3. Principal Hamiltonian \mathcal{T} -spaces a.K.A. Lagrangian fibrations

A very important class of Hamiltonian \mathcal{T} -spaces are Lagrangian fibrations. In this section we show that they correspond exactly to principal Hamiltonian \mathcal{T} -spaces and we recall their classification, from this point of view.

3.1. Lagrangian fibrations. By a Lagrangian fibration we mean the following.

Definition 3.1. A Lagrangian fibration is a symplectic manifold (S, ω) together with a surjective submersion $\mu: S \to M$ satisfying the following properties:

- (i) $\dim(S) = 2\dim(M)$;
- (ii) $\mu:(S,\omega)\to M$ is a Poisson map, where M is equipped with the zero Poisson structure;
- (iii) μ is a proper with connected fibers.

Notice that conditions (i) and (ii) can be replaced by the simpler statement that the fibers are Lagrangian submanifolds. We prefer this formulation since it is more natural from the perspective of Poisson geometry adopted here, specially having in mind generalizations to the non-commutative setting.

Given any Lagrangian fibration $\mu:(S,\omega)\to M$ one obtains a symplectic torus bundle $p:(\mathcal{T},\Omega)\to M$ which acts in a Hamiltonian fashion on μ as follows. First, the Lagrangian fibration induces an integral affine structure Λ on M given by

$$\Lambda := \{ \alpha \in T^*M : \phi^1_{\alpha(\alpha)} = \mathrm{Id} \}.$$

Here, for $\alpha \in T_x^*M$ we denoted by $\phi_{\alpha(\alpha)}^1$ the time-1 flow of the vector field $\alpha(\alpha)$ on the fiber $\mu^{-1}(x)$ defined by (2.3). Then the symplectic torus bundle $(\mathcal{T}_{\Lambda}, \Omega_{\Lambda})$ associated with Λ acts on the fibration by setting:

$$[\alpha] \cdot p := \phi^1_{a(\alpha)}(p) \quad (\alpha \in T^*_{\mu(p)}M).$$

One checks that this is indeed a Hamiltonian \mathcal{T}_{Λ} -action (see, e.g., [13, Chp. 12]). Moreover, this is a **principal action**, i.e., the map

$$\mathcal{T}_{\Lambda} \times_M S \to S \times_M S$$
, $(g, p) \mapsto (gp, p)$,

is a diffeomorphism.

Conversely, given a symplectic torus bundle $p:(\mathcal{T},\Omega)\to M$, every principal Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$ is a Lagrangian fibration. In other words:

$$\left\{ \begin{array}{l} \text{principal Hamiltonian } \mathcal{T}_{\Lambda}\text{-spaces} \\ \mu: (S, \omega) \to M \end{array} \right\} \ = \ \left\{ \begin{array}{l} \text{Lagrangian fibrations} \\ \mu: (S, \omega) \to M \text{ inducing } \Lambda \end{array} \right\}$$

Two Lagrangian fibrations $\mu_i:(S_i,\omega_i)\to M$ are called **equivalent** if there exists a symplectomorphism $\Psi:(S_1,\omega_1)\to(S_2,\omega_2)$ commuting with the projections:

$$S_1 \xrightarrow{\Psi} S_2$$

$$\downarrow^{\mu_1} \qquad \qquad \downarrow^{\mu_2}$$

$$M \xrightarrow{\text{Id}} M$$

It is easy to see that equivalent Lagrangian fibrations induce the same integral affine structure $\Lambda \subset T^*M$ and Ψ is an equivalence of Hamiltonian \mathcal{T}_{Λ} -spaces.

Example 3.2 (Symplectic torus bundles). A symplectic torus bundle $p:(\mathcal{T},\omega)\to M$ is an example of a Lagrangian fibration satisfying a very special property: it admits a global Lagrangian section, namely the identity section. Conversely, if a principal Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$ admits a global Lagrangian section $s:M\to S$ then we obtain an equivalence

$$(\mathcal{T}, \Omega) \xrightarrow{\sim} (S, \omega), \quad g \mapsto g \cdot s(p(g)).$$

Under this equivalence, the \mathcal{T} -action on S becomes the action of \mathcal{T} on itself by translations.

In general, a Lagrangian fibration does not admit a global Lagrangian section. However, locally such sections always exists, and this gives a local model for a Lagrangian fibrations, as discussed in the next example.

Remark 3.3 (Action-angle coordinates). Let $p:(\mathcal{T},\Omega)\to M$ be a symplectic torus bundle. Any principal Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$ is locally equivalent to $p:(\mathcal{T},\Omega)\to M$. Namely, choosing an open set $U\subset M$ where there exists a Lagrangian section $s:U\to S$ of μ , we obtain an equivalence as in the previous example

$$\Psi: \mathcal{T}|_{U} \xrightarrow{\sim} S|_{U}, \quad q \mapsto q \cdot s(p(q)).$$

It follows also from the previous discussion that any two Lagrangian fibrations inducing the same integral affine structure Λ are locally equivalent.

Moreover, if we fix integral affine coordinates (U, x^i) over which there exists a Lagrangian section $s: U \to S$ of μ , we obtain an equivalence (cf. Remark (2.7))

$$S|_U \simeq \mathbb{T}^n \times U, \quad \omega|_U \simeq \sum_{i=1}^n \mathrm{d}\theta_i \wedge \mathrm{d}x^i.$$

This local form only depends on the choice of an integral affine chart and a Lagrangian section. This is sometimes referred to as the Arnold-Liouville Theorem, and the coordinates (x^i, θ_i) are called action-angle coordinates.

3.2. Classification of principal Hamiltonian \mathcal{T} -spaces. The obstruction for a Lagrangian fibration to admit a global Lagrangian section is given by the *Lagrangian-Chern class*, as we now recall. This class also yields Duistermaat's global classification of Lagrangian fibrations [19]. In our language, it allows to classify principal Hamiltonian \mathcal{T} -spaces, up to equivalence.

Given a symplectic torus bundle $p:(\mathcal{T},\Omega)\to M$ denote by \mathcal{T}_{Lag} its sheaf of Lagrangian sections. The groupoid multiplication makes this into an abelian sheaf. Given a principal Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$, the usual construction of the Chern class using Čech cocycles can be performed using local Lagrangian sections. This yields a Čech cohomology class

$$c_1(S,\omega) \in \check{H}^1(M,\mathcal{T}_{Lag}),$$

called the Lagrangian-Chern class.

Theorem 3.4 (Duistermaat). Given a symplectic torus bundle $p:(\mathcal{T},\Omega)\to M$ the Lagrangian-Chern class gives a 1:1 correspondence:

$$c_1: \left\{ \begin{array}{c} principal \ Hamiltonian \ \mathcal{T}\text{-}spaces \\ \mu: (S, \omega) \to M \\ up \ to \ equivalence \end{array} \right\} \stackrel{\sim}{\longrightarrow} \check{H}^1(M, \underline{\mathcal{T}_{Lag}})$$

Since $\check{H}^1(M, \mathcal{T}_{Lag})$ is an abelian group, one also has an abelian group structure on the equivalence classes of principal Hamiltonian \mathcal{T} -spaces. This group structure can be described explicitly using the fusion product of principal Hamiltonian \mathcal{T} -spaces (see, e.g., [14]).

An integral affine manifold (M, Λ) is called **complete** if the canonical flat connection ∇ is complete. Lagrangian fibrations over a complete integral affine manifold have the following simple description.

Proposition 3.5. Let (M, Λ) be a complete, integral affine manifold so $M \simeq \mathbb{R}^n/\Gamma$. There is a 1:1 correspondence:

$$\left\{ \begin{array}{c} \textit{principal Hamiltonian \mathcal{T}_{Λ}-spaces} \\ \mu: (S, \omega) \to M \end{array} \right\} \stackrel{\tilde{}}{\longleftrightarrow} \left\{ \begin{array}{c} \textit{symplectic actions} \\ \Gamma \curvearrowright (\mathbb{T}^n \times \mathbb{R}^n, \omega_{\operatorname{can}}) \\ \textit{covering $\Gamma \curvearrowright \mathbb{R}^n$} \end{array} \right\}$$

Proof. Since (M, Λ) is complete, we have $M \simeq \mathbb{R}^n/\Gamma$, with $\Gamma = \pi_1(M) \subset \operatorname{Aff}_{\mathbb{Z}}(\mathbb{R}^n)$ acting properly and free on \mathbb{R}^n .

Assume $\Gamma \curvearrowright (\mathbb{T}^n \times \mathbb{R}^n, \omega_{\operatorname{can}})$ is a symplectic action covering $\Gamma \curvearrowright \mathbb{R}^n$. It is a proper and free action, and the induced symplectic form on the quotient

$$S := (\mathbb{T}^n \times \mathbb{R}^n)/\Gamma \to M = \mathbb{R}^n/\Gamma,$$

yields a Lagrangian fibration with base the integral affine manifold (M, Λ) . So it is a principal Hamiltonian \mathcal{T}_{Λ} -space.

Conversely, given a principal Hamiltonian \mathcal{T}_{Λ} -space $\mu:(S,\omega)\to M$ we consider its pullback under the covering projection $q:\mathbb{R}^n\to M$

$$\widetilde{S} \xrightarrow{\widetilde{q}} S .$$

$$\downarrow \mu$$

$$\mathbb{R}^n \xrightarrow{q} M$$

Here $\tilde{q}: \widetilde{S} \to S$ is also a Γ -covering where Γ acts on the first factor of $\widetilde{S} = \mathbb{R}^n \times_M S$. This action makes $\tilde{\mu}$ equivariant and preserves the pullback symplectic

$$\tilde{\omega} := \tilde{q}^* \omega.$$

On the other hand, $\tilde{\mu}: (\widetilde{S}, \tilde{\omega}) \to \mathbb{R}^n$ is a principal Hamiltonian \mathbb{T}^n -space. Any such space is isomorphic to the canonical Hamiltonian \mathbb{T}^n -space $(\mathbb{T}^n \times \mathbb{R}^n, \omega_{\operatorname{can}}) \to \mathbb{R}^n$, so the result follows.

Remark 3.6. The previous result can be related to Duistermaat classification Theorem 3.4 as follows. On the one hand, under the assumptions of Proposition 3.5, one has an identification:

$$\check{H}^1(M, \underline{\mathcal{T}_{Lag}}) \simeq \check{H}^1_{\Gamma}(\mathbb{R}^n, \mathbb{T}^n_{Lag})$$

where the right-hand side denotes Γ -equivariant cohomology for the Γ -sheaf of Lagrangian sections of $(\mathbb{T}^n \times \mathbb{R}^n, \omega_{\operatorname{can}}) \to \mathbb{R}^n$.

On the other hand, one has a Γ -equivariant version of Duistermaat result, which gives a 1:1 correspondence:

$$\left\{ \begin{array}{c} \Gamma\text{-}equivariant \\ principal \ Hamiltonian } \mathbb{T}^n\text{-}spaces \\ \tilde{\mu}: (\widetilde{S}, \tilde{\omega}) \to \mathbb{R}^n, \ up \ to \ isomorphism \end{array} \right\} \stackrel{\sim}{\longrightarrow} \check{H}^1_{\Gamma}(\mathbb{R}^n, \underline{\mathbb{T}^n_{Lag}})$$

Any such Hamiltonian space admits a global Lagrangian section and so is symplectomorphic to the canonical bundle $\operatorname{pr}:(\mathbb{T}^n\times\mathbb{R}^n,\omega_{\operatorname{can}})\to\mathbb{R}^n$, recovering the correspondence in the proposition.

Notice that the induced symplectic action of Γ on $\mathbb{T}^n \times \mathbb{R}^n$, in general, does not coincide with the canonical lift of the action $\Gamma \subset \mathbb{R}^n$. This happens precisely when $\tilde{\mu}: (\tilde{S}, \tilde{\omega}) \to \mathbb{R}^n$ admits a Γ -invariant Lagrangian section, i.e., when it is represented by the trivial class in $\check{H}^1_{\Gamma}(\mathbb{R}^n, \mathbb{T}^n_{Lag})$.

Proposition 3.5 is also useful to construct examples. We illustrate it with one such example.

Example 3.7. The standard integral affine structure on the torus $M = \mathbb{R}^2/\Gamma$ is obtained from the action of $\Gamma = \mathbb{Z}^2$ on \mathbb{R}^2 by translations:

$$(m,n)\cdot(x^1,x^2)=(x^1+m,x^2+n).$$

The canonical lift $\Gamma \curvearrowright \mathbb{R}^2 \times \mathbb{T}^2$ is given by

$$(m,n)\cdot(x^1,x^2,\theta_1,\theta_2)=(x^1+m,x^2+n,\theta_1,\theta_2).$$

The zero section is a Γ -equivariant Lagrangian section and this agrees with the fact that the corresponding quotient is the trivial bundle $(\mathbb{T}^2 \times \mathbb{T}^2, \omega_{\operatorname{can}}) \to \mathbb{T}^2$, which has representative the trivial class in $\check{H}^1(\mathbb{T}^2, \mathcal{T}_{\operatorname{Lag}})$

More generally, fix $a \in [0,1[$ and consider the symplectic action $\Gamma \curvearrowright \mathbb{R}^2 \times \mathbb{T}^2$ covering $\Gamma \curvearrowright \mathbb{R}^2$ given by

$$(m,n)\cdot(x^1,x^2,\theta_1,\theta_2) = (x^1+m,x^2+n,\theta_1+an,\theta_2).$$
 (3.1)

For this action, the bundle $\mathbb{R}^2 \times \mathbb{T}^2 \to \mathbb{R}^2$ still admits a Γ -equivariant section, namely

$$s(x^1, x^2) = (x^1, x^2, -ax^2, 0).$$

Hence, we obtain a family of Lagrangian fibrations, each isomorphic to the trivial fibration $\mathbb{T}^2 \times \mathbb{T}^2 \to \mathbb{T}^2$, but with a new symplectic form

$$\omega_a = \omega_{\rm can} + a \, \mathrm{d}x^1 \wedge \mathrm{d}x^2$$
.

Notice that the integral affine structure induced on the base \mathbb{T}^2 is still the standard one. If $s: \mathbb{T}^2 \to \mathbb{T}^2 \times \mathbb{T}^2$ is any section, $s^*\omega_{\operatorname{can}}$ is an exact form and applying Stokes formula we find that

$$\int_{\mathbb{T}^2} s^* \omega_a = a \int_{\mathbb{T}^2} dx^1 \wedge dx^2 = a.$$

Therefore, if $a \in]0,1[$ the fibration $(\mathbb{T}^2 \times \mathbb{T}^2,\omega_a) \to \mathbb{T}^2$ does not admit any Lagrangian section. Equivalently, there is no Γ -equivariant section of $\mathbb{R}^2 \times \mathbb{T}^2 \to \mathbb{R}^2$ which is Lagrangian (this can also be checked directly). This gives examples of Lagrangian fibrations with trivial Chern class and non-trivial Lagrangian-Chern class $c(S,\omega) \in \check{H}^1(\mathbb{T}^2, \mathcal{T}_{Laq}).$

3.3. Lagrangian connections. In the construction of the Chern class of a principal torus bundle one passes from integral to real coefficients using connections. One has a similar situation for principal Hamiltonian \mathcal{T} -spaces, for which the concept of a Lagrangian connection is needed.

Definition 3.8. A connection for a principal Hamiltonian \mathcal{T} -space $\mu: (S, \omega) \to \mathbb{R}$ M is a \mathcal{T} -invariant distribution $D \subset TS$ such that $TS = D \oplus \ker(d\mu)$. We call such a connection **Lagrangian** if $D_p \subset (T_p S, \omega_p)$ is Lagrangian for all $p \in S$.

Example 3.9. For $p:(\mathcal{T},\Omega)\to M$, viewed as a principal Hamiltonian \mathcal{T} -space with the action by translations, the canonical horizontal distribution (see Definition 2.10) is a Lagrangian connection.

Example 3.10. Let $\mu:(S,\omega)\to\mathbb{R}^n$ be a classical Hamiltonian \mathbb{T}^n -space, viewed as Hamiltonian \mathcal{T} -space for the symplectic torus bundle $\mathcal{T} = (\mathbb{T}^n \times \mathbb{R}^n, \Omega_{\operatorname{can}}) \to \mathbb{R}^n$. If the action is principal, then a connection in the sense of Definition 3.8 is just an ordinary principal bundle connection. It is Lagrangian if and only if its horizontal spaces are Lagrangian.

Connections can also be described by connection 1-forms, which are defined as follows. For a Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$ and a vector bundle $E\to M$ we denote by $\Omega^k(S, E)$ the space of k-forms with values in μ^*E .

Definition 3.11. A connection 1-form for a principal Hamiltonian T-space $\mu:(S,\omega)\to M$ is a form $\theta\in\Omega^1(S,T^*M)$ which satisfies:

- (i) T-invariance: θ_{gp}(g · v) = θ_p(v), for all v ∈ T_pS, g ∈ T_{μ(p)};
 (ii) θ_p(a_p(α)) = α, for all α ∈ T^{*}_{μ(p)}M and p ∈ S.

Note that in the previous definition, in (i) we have used the tangent action of \mathcal{T} on S and in (ii) its infinitesimal version $\alpha: \mu^*T^*M \to TS$.

Similar to ordinary principal connections, there is a bijective correspondence between connections and connection 1-forms for a principal Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$, in which the distribution corresponding to a connection 1-form θ is $D = \ker \theta$. The following lemma characterizes those connection 1-forms giving rise to Lagrangian connections.

Lemma 3.12. Let θ be a connection 1-form for a principal Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$. Consider the \mathcal{T} -invariant, non-degenerate, 2-form $\omega_\theta\in\Omega^2(S)$ defined by

$$\omega_{\theta}(v, w) := \langle \theta(v), d\mu(w) \rangle - \langle \theta(w), d\mu(v) \rangle.$$

The connection $\ker \theta$ is Lagrangian if and only if $\omega = \omega_{\theta}$.

Proof. The backward direction is immediate. For the forward direction, note that $\operatorname{Im}(\alpha) = \ker(d\mu)$ by principality of the action. So, it suffices to verify the equality $\omega = \omega_{\theta}$ on tangent vectors of the form $v + \alpha_p(\alpha)$, with $v \in \ker(\theta_p)$ and $\alpha \in T^*_{\mu(p)}M$. This is readily done using the moment map condition (2.3).

Proposition 3.13. Every principal Hamiltonian T-space admits a Lagrangian connection.

Proof. Remark 3.3 and Example 3.9 show that over a sufficiently small integral affine chart a Lagrangian connection always exists. Consider an open cover $\{U_i\}_{i\in I}$ of M together with connection 1-forms θ_i for $\mu:S|_{U_i}\to U_i$, such that $\ker(\theta_i)$ is Lagrangian. Choosing a partition of unity $\{\rho_i\}_{i\in I}$ subordinated to this cover, we can construct a global connection 1-form $\theta:=\sum_{i\in I}(\rho_i\circ\mu)\theta_i$. In view of the lemma above, $\ker(\theta)$ is Lagrangian, since

$$\omega_{\theta} = \sum_{i \in I} (\rho_i \circ \mu) \omega_{\theta_i} = \sum_{i \in I} (\rho_i \circ \mu) \omega = \omega.$$

Next we define the curvature 2-form of a connection on a principal Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$. Pulling back the canonical flat connection ∇ on T^*M along the projection $\mu:S\to M$ we obtain a flat connection ∇ on μ^*T^*M and this gives a differential $d^{\nabla}:\Omega^{\bullet}(S,T^*M)\to\Omega^{\bullet+1}(S,T^*M)$. We further denote by $\Omega^{\bullet}_{\partial}(M,T^*M)$ the kernel of the anti-symmetrization map

$$\partial: \Omega^{\bullet}(M, T^*M) \to \Omega^{\bullet+1}(M),$$
 (3.2)

which is a subcomplex of

$$(\Omega^{\bullet}(M, T^*M), \mathbf{d}^{\nabla}).$$

Proposition 3.14. Let D be a connection on $\mu:(S,\omega)\to M$ with connection 1-form $\theta\in\Omega^1(S,T^*M)$. There is a unique 2-form $K_\theta\in\Omega^2(M,T^*M)$ such that

$$\mu^* K_\theta = \mathrm{d}^\nabla \theta.$$

This satisfies the following properties:

- (i) K_{θ} is d^{∇} -closed;
- (ii) $K_{\theta} = 0$ if and only if D is involutive.

Moreover, if D is a Lagrangian connection then $K_{\theta} \in \Omega^2_{\partial}(M, T^*M)$, meaning that

$$\partial K_{\theta}(v_1,v_2,v_3):=\sum_{\sigma\in S_3}(-1)^{|\sigma|}\langle K_{\theta}(v_{\sigma(1)},v_{\sigma(2)}),v_{\sigma(3)}\rangle=0.$$

Proof. The existence of K_{θ} follows from the remark that $d^{\nabla}\theta$ is horizontal and \mathcal{T} -invariant, and its uniqueness is clear. Properties (i) and (ii) are immediate, whilst the last property follows by observing that

$$d\omega_{\theta} = \frac{1}{2}\mu^*(\partial K_{\theta}),$$

so that (by Lemma 3.12) ∂K_{θ} must vanish if θ is Lagrangian.

According to the previous proposition, a choice of Lagrangian connection on $\mu:(S,\omega)\to M$ gives rise to a cohomology class

$$[K_{\theta}] \in H^2(\Omega_{\partial}^{\bullet}(M, T^*M), \mathrm{d}^{\nabla}).$$

This class is independent of the choice of Lagrangian connection and, as for principal S¹-bundles, it is related to the Lagrangian Chern class by a map that 'passes from integer to real coefficients'. To make this precise, consider the composite

$$\check{H}^1(M, \underline{\mathcal{T}_{\text{Lag}}}) \xrightarrow{\simeq} \check{H}^2(M, \mathcal{O}_{\Lambda}) \longrightarrow \check{H}^2(M, \mathcal{O}_{\text{Aff}}) \xrightarrow{\simeq} H^2(\Omega_{\partial}^{\bullet}(M, T^*M), d^{\nabla}) , \quad (3.3)$$

where $\mathcal{O}_{\mathrm{Aff}}$ and \mathcal{O}_{Λ} denote respectively the sheaves of locally defined functions on M that are affine and integral affine with respect to Λ . The first map in this sequence is the connecting homomorphism induced by the short exact sequence

$$0 \longrightarrow \mathcal{O}_{\Lambda} \longrightarrow \mathcal{C}^{\infty} \stackrel{d}{\longrightarrow} \underline{\mathcal{T}_{Lag}} \longrightarrow 0,$$

while the last map is the isomorphism induced by the fine resolution

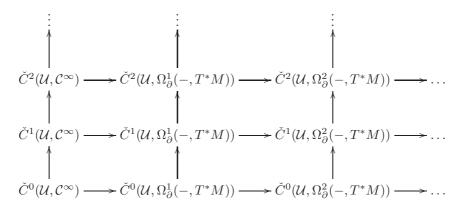
$$0 \longrightarrow \mathcal{O}_{\mathrm{Aff}} \longrightarrow \mathcal{C}^{\infty} \xrightarrow{\mathrm{d}^{\nabla} \circ \mathrm{d}} \Omega^{1}_{\partial}(-, T^{*}M) \xrightarrow{\mathrm{d}^{\nabla}} \Omega^{2}_{\partial}(-, T^{*}M) \xrightarrow{\mathrm{d}^{\nabla}} \dots$$
 (3.4)

Theorem 3.15. If θ is a Lagrangian connection for a principal Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$, then (3.3) maps the Lagrangian Chern class $c_1(S,\omega)$ to the class $[K_{\theta}]$.

Proof. Let $\mathcal{U} = \{U_i\}_{i \in I}$ be a good open cover of M such that μ admits a Lagrangian section σ_i over U_i for each $i \in I$. The class $c_1(S, \omega) \in \check{H}^1(M, \underline{\mathcal{T}_{Lag}})$ is represented by the 1-cocycle $\tau = [\tau_{ij}] \in \check{C}^1(\mathcal{U}, \mathcal{T}_{Lag})$, defined by the relation:

$$\tau_{ij}(x) \cdot \sigma_i(x) = \sigma_j(x), \quad x \in U_{ij}.$$

The connecting homomorphism in (3.3) sends $c_1(S, \omega)$ to the class represented by the 2-cocycle $df \in \check{C}^2(\mathcal{U}, \mathcal{O}_{\Lambda})$, where $f = [f_{ij}] \in \check{C}^1(\mathcal{U}, \mathcal{C}^{\infty})$ is any 1-cochain lifting τ (which exists since U_{ij} is contractible for all i and j). The last map in (3.3) is induced by the 'Čech-de Rham'-type double complex



In this complex the vertical differentials are those of the Čech complex and the horizontal differentials are induced by (3.4). Notice that both the rows and columns are exact at the $(p,q)^{\text{th}}$ entry whenever p,q>0. We need to show that $(\check{\mathbf{d}}f,0,0)$ and $(0,0,K_{\theta})$ represent the same class in the cohomology of the total complex. This follows because

$$(df, 0, 0) - (0, 0, K_{\theta}) = d_{Tot}(f, \sigma^*\theta),$$

where $\sigma^*\theta \in \check{C}^0(\mathcal{U}, \Omega^1_{\partial}(M, T^*M))$ is given by $(\sigma^*\theta)_i := \sigma_i^*\theta$. Note that $\sigma_i^*\theta$ belongs to the kernel of ∂ because σ_i and θ are Lagrangian and, by Lemma 3.12, one has

$$\partial(\sigma_i^*\theta) = \sigma_i^*\omega_\theta = \sigma_i^*\omega = 0.$$

3.4. Flat Lagrangian connections. Flat Lagrangian connections will play a key role in the study of invariant Kähler metrics. In this subsection we show how Lagrangian fibrations with such connections can be classified in terms of a sheaf cohomology group, much like principal \mathbb{T}^n -bundles with flat connection.

Definition 3.16. A flat Lagrangian fibration is a Lagrangian fibration equipped with a flat Lagrangian connection.

Note that, by Proposition 3.14, a flat Lagrangian connection is the same thing as an invariant Lagrangian foliation transverse to the fibers.

Remark 3.17. In the literature on T-duality and mirror symmetry flat Lagrangian fibrations in our sense are sometimes called semi-flat (see, e.g., [5]).

Given an integral affine manifold (M, Λ) we denote by $\underline{\mathcal{T}_{\text{Flat}}}$ the sheaf of ∇ -flat sections of \mathcal{T}_{Λ} . If (U, x^i) an integral affine chart then the flat sections of $\mathcal{T}_{\Lambda}|_U$ take the form

$$s = \sum_{i=1}^{n} c_i dx^i \pmod{\Lambda},$$

where the coefficients c_i are locally constant. This shows that every flat section is automatically a Lagrangian section. Hence, $\underline{\mathcal{T}_{Flat}}$ is a subsheaf of $\underline{\mathcal{T}_{Lag}}$ and we have a map in cohomology

$$\check{H}^1(M, \mathcal{T}_{\operatorname{Flat}}) \to \check{H}^1(M, \mathcal{T}_{\operatorname{Lag}}).$$

This map is part of an exact sequence, which will allow us to express the first obstruction.

Proposition 3.18. Given a symplectic torus bundle $(\mathcal{T}, \Omega) \to M$ the sequence

$$\check{H}^1(M, \underline{\mathcal{T}_{Flat}}) \longrightarrow \check{H}^1(M, \mathcal{T}_{Lag}) \longrightarrow H^2(\Omega_{\partial}^{\bullet}(M, T^*M), d^{\nabla}),$$
 (3.5)

where the second map is given by (3.3), is exact.

Proof of Proposition 3.18. Consider the map of short exact sequences:

$$0 \longrightarrow \mathcal{O}_{\Lambda} \longrightarrow \mathcal{C}^{\infty} \xrightarrow{d} \underbrace{\mathcal{T}_{Lag}} \longrightarrow 0$$

$$\downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow$$

$$0 \longrightarrow \mathcal{O}_{Aff} \longrightarrow \mathcal{C}^{\infty} \longrightarrow \underline{\mathcal{T}_{Lag}}/\underline{\mathcal{T}_{Flat}} \longrightarrow 0$$

By naturality of the connecting homomorphism, the induced square:

$$\check{H}^{1}(M, \underline{\mathcal{T}_{\operatorname{Lag}}}) \xrightarrow{\sim} \check{H}^{2}(M, \mathcal{O}_{\Lambda}) \\
\downarrow \\
\check{H}^{1}(M, \mathcal{T}_{\operatorname{Lag}}/\underline{\mathcal{T}_{\operatorname{Flat}}}) \xrightarrow{\sim} \check{H}^{2}(M, \mathcal{O}_{\operatorname{Aff}})$$

commutes. So, up to isomorphism, (3.5) is part of the long exact sequence of:

$$0 \to \underline{\mathcal{T}_{\mathrm{Flat}}} \to \mathcal{T}_{\mathrm{Lag}} \to \mathcal{T}_{\mathrm{Lag}}/\underline{\mathcal{T}_{\mathrm{Flat}}} \to 0.$$

Combining this result, Proposition 3.14 and Theorem 3.15 we obtain the following corollary.

Corollary 3.19. Fix an integral affine manifold (M, Λ) . Given a Lagrangian fibration $\mu: (S, \omega) \to M$ inducing Λ the following conditions are equivalent:

- (i) $\mu:(S,\omega)\to M$ admits a flat Lagrangian connection;
- (ii) the Lagrangian-Chern class $c_1(S,\omega) \in \check{H}^1(M,\mathcal{T}_{Lag})$ lies in the image of (3.5).

Flat Lagrangian fibrations are classified by their flat Chern class. This is the element in $\check{H}^1(M, \mathcal{T}_{\mathrm{Flat}})$ constructed as the usual Chern class but using only flat local sections. More precisely, two flat Lagrangian fibrations $\mu_i: (S_i, \omega_i, \theta_i) \to (M, \Lambda)$ are said to be **equivalent** if there exists an equivalence of Lagrangian fibrations preserving the connections:

$$S_{1} \xrightarrow{\Psi} S_{2}$$

$$\mu_{1} \downarrow \qquad \qquad \downarrow^{\mu_{2}} \qquad \Psi^{*}\theta_{2} = \theta_{1}.$$

$$M \xrightarrow{\text{Id}} M$$

Then one has the following classification result.

Theorem 3.20. Fix an integral affine manifold (M, Λ) . Assigning to a flat Lagrangian fibration its flat Chern class yields a canonical 1:1 correspondence

$$\begin{cases}
flat \ Lagrangian \ fibrations \\
\mu: (S, \omega, \theta) \to M \\
up \ to \ equivalence
\end{cases}
\stackrel{\tilde{}}{\longleftarrow} \check{H}^1(M, \underline{\mathcal{T}_{Flat}})$$

Moreover, the flat Chern class is mapped to the Lagrangian Chern class by (3.5).

Proof. Using flat sections, the proof of the theorem is entirely similar to the proof of Theorem 3.4 (see, e.g., [19] or [14]). \Box

Remark 3.21. Note that $\underline{\mathcal{T}_{Flat}}$ is the locally constant sheaf associated to the representation of $\pi_1(M)$ on $\overline{\mathcal{T}_{\Lambda}}$ given by the holonomy of the integral affine manifold (M,Λ) . In particular, if the holonomy representation if trivial then the cohomology of $\underline{\mathcal{T}_{Flat}}$ is that of M with values in the abelian group \mathbb{T}^m , where $m = \dim(M)$. For example, when M is simply-connected one obtains that the cohomology vanishes in degree one.

Finally, we observe that one can specialize the correspondence given in Proposition 3.5 to obtain the following useful description of flat Lagrangian fibrations over complete integral affine manifolds.

Corollary 3.22. Let (M, Λ) be a complete integral affine manifold (meaning that $M \simeq \mathbb{R}^n/\Gamma$) and let H be the canonical horizontal distribution of $\mathbb{T}^n \times \mathbb{R}^n \to \mathbb{R}^n$. There is a 1:1 correspondence

Example 3.23. A simple example illustrating the above correspondences can be obtained by considering the integral affine circle $(M, \Lambda) = (\mathbb{S}^1, b \mathbb{Z} dx)$, where b > 0 is a parameter. Then $H^1(M, \underline{\mathcal{T}_{Lag}}) = 0$, so any Lagrangian fibration inducing (M, Λ) takes the form

$$\operatorname{pr}_2: (\mathbb{S}^1 \times \mathbb{S}^1, b \, \mathrm{d} y \wedge \mathrm{d} x) \to \mathbb{S}^1.$$

By the remark above, we have $H^1(M, \underline{\mathcal{T}_{Flat}}) = \mathbb{S}^1$. A class $e^{2\pi i a} \in \mathbb{S}^1$ can be realized as the Lagrangian connection

$$D_a = \langle \partial_x - a \partial_y \rangle.$$

Example 3.24. Consider the second Lagrangian fibration

$$(\mathbb{T}^2 \times \mathbb{T}^2, \omega_a) \to \mathbb{T}^2$$

in Example 3.7. We saw there that for $a \in]0,1[$ this fibration has non-trivial Lagrangian-Chern class. On the other hand, the canonical horizontal distribution of $\mathbb{T}^2 \times \mathbb{R}^2 \to \mathbb{R}^2$ is invariant under the action (3.1), so it follows from Corollary 3.22 that this Lagrangian fibration is flat.

4. Toric Hamiltonian \mathcal{T} -spaces a.K.A. Toric Lagrangian fibrations

The main class of Hamiltonian \mathcal{T} -spaces that we study in this paper is a generalization of both principal Hamiltonian \mathcal{T} -spaces (i.e., Lagrangian fibrations) and classical symplectic toric manifolds. They are defined as follows.

Definition 4.1. A Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$ is called **toric** if it satisfies the following conditions.

- (i) The \mathcal{T} -action is free on a dense subset of S.
- (ii) $\dim(S) = 2\dim(M)$.
- (iii) The map μ has connected fibers and it is proper as map onto its image.

In the rest of this section we will see that the theory of principal Hamiltonian \mathcal{T} -spaces, studied in the previous section, extends to the toric setting. In particular, in section 4.1, we extend the correspondence between principal Hamiltonian \mathcal{T} -spaces and Lagrangian fibrations by showing that toric Hamiltonian \mathcal{T} -spaces are essentially the same thing as toric Lagrangian fibrations, i.e., singular Lagrangian fibrations with only elliptic singularities.

4.1. **Toric Lagrangian fibrations.** We consider the following special class of singular Lagrangian fibrations.

Definition 4.2. By a singular Lagrangian fibration we mean a symplectic manifold (S, ω) together with a smooth map $\mu: S \to M$ satisfying the following properties:

- (i) $\dim(S) = 2\dim(M)$;
- (ii) $\mu:(S,\omega)\to M$ is a Poisson map, where M is equipped with the zero Poisson structure:
- (iii) μ has connected fibers, is proper as a map onto its image and its regular points form a dense open set in S.

A toric Lagrangian fibration is a singular Lagrangian fibration whose only singularities are of elliptic type.

An *elliptic type* singularity is the simplest non-degenerate singularity that a singular Lagrangian fibration can possess – see, e.g., [18, 37]. Instead of giving its definition, we recall the following characterization.

Theorem 4.3 (Dufour and Molino [18]). Let $\mu: (S, \omega) \to M$ be a singular Lagrangian fibration. A singular point $p_0 \in S$ is elliptic if and only if there is a neighborhood U of $x_0 := \mu(p_0)$ and an embedding $\phi: U \to \mathbb{R}^n$, such that $\phi \circ \mu: (\mu^{-1}(U), \omega) \to \mathbb{R}^n$ is the moment map of an effective \mathbb{T}^n -action.

Note that the regular fibers of a singular Lagrangian fibration are indeed Lagrangian submanifolds. For a general singular Lagrangian fibration a fiber of $\mu:S\to M$ can contain both regular and singular points. However, the previous result implies that for a toric Lagrangian fibration $\mu:S\to M$ this cannot happen: the rank of $\mathrm{d}\mu$ is the same for all points in the same fiber. Hence, for a toric fibration the set of regular points is a dense open set $\mathring{S}\subset S$ saturated by μ -fibers. It follows that $\mathring{\Delta}:=\mu(\mathring{S})$ is also an open subset of M which is dense in the image $\Delta:=\mu(S)$. Therefore, the restriction $\mu:(\mathring{S},\omega)\to\mathring{\Delta}$ is a (regular) Lagrangian fibration so, as we saw in Section 3.1, there is an induced integral affine structure $\mathring{\Lambda}$ on $\mathring{\Delta}$ and $\mu:(\mathring{S},\omega)\to\mathring{\Delta}$ is a principal Hamiltonian \mathcal{T}_{Λ} -space.

The following result shows that the integral affine structure on $\mathring{\Delta}$ extends uniquely to an open $M' \subset M$ containing Δ , so $\mu : (S, \omega) \to M'$ becomes a toric Hamiltonian \mathcal{T} -space.

Theorem 4.4. Let $\mu: (S, \omega) \to M$ be a toric Lagrangian fibration. Then there is an open $M' \subset M$ containing $\mu(S)$ and an integral affine structure Λ on M' such that $\mu: (S, \omega) \to M'$ is a toric Hamiltonian \mathcal{T}_{Λ} -space. The germ of (M', Λ) is unique. Conversely, every toric Hamiltonian \mathcal{T} -space is a toric Lagrangian fibration.

Proof. It follows from Theorem 4.3 that $\Delta := \mu(S)$ is a codimension 0 submanifold with corners of M, with interior $\mathring{\Delta} = \mu(\mathring{S})$. Moreover, the integral affine structure $\mathring{\Lambda}$ on $\mathring{\Delta}$ extends to the boundary $\partial \Delta$, so Δ is an integral affine manifold with corners. In fact, around a boundary point $x_0 \in \partial \Delta$ an integral affine chart is provided by the restriction $\phi: V \cap \Delta \to \mathbb{R}^n$ of the embedding given by Theorem 4.3.

Recall that any manifold with corners embeds as a codimension 0 submanifold of a manifold without corners and the germ of such embeddings is unique. Similarly, for embeddings of integral affine manifolds with corners we have the following lemma, which proves the first part of the statement of the theorem.

Lemma 4.5. Let (Δ, Λ) be an integral affine manifold manifold with corners.

- (i) Given any a codimension 0 embedding of Δ in a manifold without corners M, the integral affine structure Λ extends to an open neighborhood of Δ in M.
- (ii) The germ of codimension 0 integral affine embeddings of (Δ, Λ) in integral affine manifolds without corners is unique.

Proof of the Lemma 4.5. Any integral affine manifold manifold with corners can be embedded as a codimension 0 integral affine submanifold of an integral affine manifold manifold without corners. The proof is entirely similar to the proof given in [35] that any real analytic manifold admits a complexification (see also [17]). Fix such an embedding $\phi: (\Delta, \Lambda) \to (N, \Lambda_N)$ and let $\psi: \Delta \to M$ be any codimension 0 embedding in a manifold without corners. Using Whitney's embedding theorem we can assume that $N \subset \mathbb{R}^p$ and, by a partition of unity argument, that there is a smooth map $F: W \to \mathbb{R}^p$ extending the identity on Δ , defined on some open neighborhood of Δ in M. Choosing a retraction $r: U \to N$ of some neighborhood of N in \mathbb{R}^p , the composition $r \circ F: F^{-1}(U) \to U$ restricts to the identity on Δ . Hence, possibly after shrinking W, we obtain a local diffeomorphism $r \circ F: W \to N$, that extends the identity on Δ . Pulling back Λ_N by this diffeomorphism, we obtain an extension of Λ from Δ to an integral affine structure on the neighborhood W. This proves item (i).

Item (ii) in the lemma follows from item (i), since two integral affine structures on a manifold M which agree on Δ they must agree on some open neighborhood of Δ , because Δ has codimension 0.

It remains to prove the last statement in the theorem. Given a toric Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$ and a point $p_0\in S$, fixing a integral affine chart (U,ϕ) around $x_0:=\mu(p_0)$ we have that $\phi\circ\mu:(\mu^{-1}(U),\omega)\to\mathbb{R}^n$ is the moment map of an effective \mathbb{T}^n -action. If this action is free, p_0 is a regular point. Otherwise, p_0 is a singular point which, by Theorem 4.3, is elliptic. Hence, $\mu:(S,\omega)\to M$ is a toric Lagrangian fibration.

It follows from the previous results that the standard local model for toric symplectic manifolds is also a local model for toric Hamiltonian \mathcal{T} -spaces. Let $\mu:(S,\omega)\to M$ be a toric (\mathcal{T},Ω) -space with $\Delta:=\mu(S)$ and let $x\in\Delta$. As we saw before, a choice of integral affine chart $(U,\phi=(x^1,\ldots,x^n))$ centered at x gives a trivialization of the symplectic torus bundle

$$\Phi: (\mathcal{T}, \Omega)|_{U} \simeq (\mathbb{T}^{n} \times U, \sum_{i=1}^{n} d\theta_{i} \wedge dx^{i}).$$

Via this local isomorphism the toric \mathcal{T} -action corresponds to a toric \mathbb{T}^n -action with moment map

$$\phi \circ \mu : (\mu^{-1}(U), \omega) \to \mathbb{R}^n.$$

Since μ has connected fibers and is proper onto its image, it follows from the standard normal form for toric manifolds (see, e.g., [26, Lemma B.3]) that, around

x, there is a local isomorphism between this Hamiltonian \mathbb{T}^n -space and the standard local model. The latter is the Hamiltonian \mathbb{T}^n -space consisting of:

• the symplectic manifold

$$(S_{k,n},\omega_{k,n}) := (\mathbb{C}^k \times \mathbb{T}^{n-k} \times \mathbb{R}^{n-k}, \sum_{i=1}^k \frac{1}{2\pi i} dz_j \wedge d\overline{z}_j + \sum_{i=1}^{n-k} d\theta_j \wedge dx^j);$$

• the moment map is given by

$$\mu_{k,n}: \mathbb{C}^k \times \mathbb{T}^{n-k} \times \mathbb{R}^{n-k} \to \mathbb{R}^n, \quad (z,\theta,x) \mapsto (|z_1|^2,\dots,|z_k|^2,x),$$

with image $\Delta = \mathbb{R}_k^n$; • the \mathbb{T}^n -action given by

$$(\tau_1, \tau_2) \cdot (z, \theta, x) := (e^{2\pi i \tau_1} z, \tau_2 + \theta, x), \quad (\tau_1, \tau_2) \in \mathbb{T}^k \times \mathbb{T}^{n-k} = \mathbb{T}^n.$$
 (4.1)

So, after possibly changing the integral affine chart ϕ , we obtain an isomorphism (ϕ, Φ, Ψ) from the Hamiltonian $\mathcal{T}|_{U}$ -space $\mu : (\mu^{-1}(U), \omega) \to U$ to the Hamiltonian \mathbb{T}^n -space $\mu : (\mu_{k,n}^{-1}(V), \omega_{k,n}) \to V$, where $V := \phi(U) \subset \mathbb{R}^n$. Henceforth, we will refer to such an isomorphism, or to (z, θ, x) , as **standard toric coordinates** for $\mu : (S, \omega) \to M$ around x.

For future reference, we state the following result concerning invariant functions on the local model.

Proposition 4.6. Consider $S := \mathbb{C}^k \times \mathbb{T}^{n-k} \times \mathbb{R}^{n-k}$, equipped with the \mathbb{T}^n -action (4.1) and let U be an open in $\Delta := \mathbb{R}^n_k$. For any \mathbb{T}^n -invariant smooth function f on $\mu^{-1}(U)$, the following hold:

- (a) The unique function \underline{f} on U such that $f = \mu^* \underline{f}$ is smooth, i.e., it is the restriction of a smooth function defined on some open in \mathbb{R}^n ;
- (b) If f vanishes on $\mu^{-1}(U) \cap \{z_j = 0\}$ for some $j \in \{1, ..., k\}$, then it is of the form $f = |z_j|^2 \cdot \hat{f}$ for a unique \mathbb{T}^n -invariant smooth function \hat{f} on $\mu^{-1}(U)$.

Proof. Part (a) is well-known: it readily follows from Schwartz' theorem. Part (b) is immediate from part (a) and the fact that if $h \in C^{\infty}(U)$ vanishes on $U \cap \{x^j = 0\}$, then $h = x^j \hat{h}$, for some $\hat{h} \in C^{\infty}(U)$.

- **Remark 4.7.** In the literature singular Lagrangian fibrations admitting local effective \mathbb{T}^n -actions have been study by several authors [6, 36, 37, 38]. The result above shows that this form of symmetry can be encoded globally by toric Hamiltonian \mathcal{T} -actions. Moreover, the results to follow will show that this approach gives an effective, coordinate free way of studying the geometry of such fibrations.
- 4.2. Classification of toric Hamiltonian \mathcal{T} -spaces. Delzant's classification of compact symplectic toric manifolds in terms of polytopes ([15]) was extended to toric Hamiltonian \mathcal{T} -spaces in [28]. In this more general setup, Delzant's classification and Duistermaat's classification of Lagrangian fibrations (cf. Theorem 3.4) are combined, as we will now explain.

In Delzant's classification, the polytope corresponding to a symplectic toric manifold is the image of the moment map and lies in the integral affine manifold $(\mathbb{R}^n, \mathbb{Z}^n)$. These Delzant polytopes satisfy certain integrality conditions. For toric Hamiltonian \mathcal{T} -spaces, the image of μ is a more general object called a *Delzant subspace* of the integral affine manifold (M, Λ) , the base of the symplectic torus bundle (\mathcal{T}, Ω) .

Definition 4.8. A **Delzant subspace** Δ of an m-dimensional integral affine manifold (M, Λ) is a subspace of M with the property that for each $x \in \Delta$ there is an integral affine chart (U, ϕ) for (M, Λ) centered at x such that $\phi(U \cap \Delta)$ is an open in $\mathbb{R}^m_k := [0, \infty[^k \times \mathbb{R}^{m-k} \text{ for some } k \in \{0, \dots, m\} \text{ (depending on } x).$

In other words, a Delzant subspace of (M, Λ) is a codimension zero integral affine submanifold with corners.

Example 4.9 (Compact symplectic toric manifolds). For any compact symplectic toric manifold $\mu_0: (S, \omega) \to \mathbb{R}^n$, the image of the moment map is a Delzant polytope in \mathbb{R}^n . Delzant polytopes are precisely the compact and connected Delzant subspaces of \mathbb{R}^n equipped with the standard integral affine structure.

Example 4.10 (Non-compact symplectic toric manifolds). Non-compact symplectic toric manifold $\mu_0: (S, \omega) \to \mathbb{R}^n$ also fit into our framework. It was observed in [26] that the orbit space S/\mathbb{T}^n is a manifold with corners and the induced map

$$\phi: S/\mathbb{T}^n \to \mathbb{R}^n$$

is a local embedding. The pullback along ϕ of the standard integral affine structure in \mathbb{R}^n makes $\Delta := S/\mathbb{T}^n$ an integral affine manifold with corners. By Lemma 4.5, Δ embeds as a Delzant subspace of an integral affine manifold (M, Λ) without corners. Note that the composition of the quotient map with this embedding

$$\mu: S \to \Delta \hookrightarrow M$$
,

yields a toric Hamiltonian \mathcal{T}_{Λ} -space $\mu:(S,\omega)\to M$.

Example 4.11. The Hamiltonian \mathcal{T} -spaces in examples 2.20 and 2.21 are toric and the image of their moment maps are Delzant spaces. In fact:

- For the standard integral affine cylinder $\mathbb{R} \times \mathbb{S}^1$, appearing in Example 2.20, $\Delta = [a, b] \times \mathbb{S}^1$ is a Delzant subspace, for any real numbers a < b.
- Similarly, for the exotic integral affine cylinder $]-2,\infty[\times\mathbb{S}^1]$ of Example 2.21, $\Delta=[a,b]\times\mathbb{S}^1$ is also a Delzant subspace, for any -2< a< b.

A version of the classification theorem for toric Hamiltonian \mathcal{T} -spaces can be stated as follows. For a complete proof and details we refer to [28].

Theorem 4.12 ([28]). Let $(\mathcal{T}, \Omega) \to (M, \Lambda)$ be a symplectic torus bundle. For any toric Hamiltonian \mathcal{T} -space $\mu : (S, \omega) \to M$, the image $\Delta := \mu(S)$ is a Delzant subspace of (M, Λ) . Moreover, such Hamiltonian \mathcal{T} -spaces are classified by their:

- (i) Delzant subspace $\Delta := \mu(S)$, and
- (ii) Lagrangian-Chern class $c_1(S,\omega) \in \check{H}^1(\Delta, \mathcal{T}_{Lag})$.

Here \mathcal{T}_{Lag} denotes the sheaf of Lagrangian sections of $\mathcal{T}|_{\Delta}$ and the Lagrangian-Chern class is defined similarly to the regular case (see [28]) and the proof of Theorem 4.31).

Remark 4.13. As for classical toric symplectic manifolds [15], the map

$$\mu: S/\mathcal{T} \to M \tag{4.2}$$

is a homeomorphism onto $\Delta := \mu(S)$. Moreover, it respects the natural stratifications on S/\mathcal{T} and Δ , namely:

- \bullet Δ is naturally stratified, being a manifold with corners;
- S/T is naturally stratified, being the orbit space of a proper Lie groupoid action [31].

We refer to [28] for details.

Remark 4.14. The classification result above, beside generalizing Duistermaat and Delzant classification results, is also closely related to classification results in various other settings, as in Remark 4.7. For example, the classification of non-compact symplectic toric manifolds due to Karshon and Lerman [26] follows from this theorem.

4.3. Classical symplectic toric manifolds. Motivated by Example 4.10 we introduce the following definition.

Definition 4.15. A toric Hamiltonian \mathcal{T} -space $\mu: (S^{2n}, \omega) \to M$ is called a classical symplectic toric manifold if there exists an effective Hamiltonian \mathbb{T}^n -action on (S, ω) with moment map $\mu_0: S \to \mathbb{R}^n$ and a local embedding $\phi: \Delta \to \mathbb{R}^n$ such that

$$\mu_0 = \phi \circ \mu.$$

The toric Hamiltonian \mathcal{T} -spaces that are classical symplectic toric manifolds can be easily characterized in terms of the integral affine geometry of their Delzant subspaces.

Theorem 4.16. A Hamiltonian \mathcal{T} -space $\mu:(S^{2n},\omega)\to M$ is a classical symplectic toric manifold if and only if the associated Delzant space $\Delta=\mu(S)$ has trivial affine holonomy.

Proof. The Delzant space $\Delta = \mu(S)$ has trivial affine holonomy if and only if the developing map $\operatorname{dev}_{x_0} : \widetilde{\Delta} \to \mathbb{R}^n$ factors through the covering map to an integral affine local embedding $\phi : \Delta \to \mathbb{R}^n$.

On the other hand, a map $\mu_0: S \to \mathbb{R}^n$ which factors through a local embedding $\phi: \Delta \to \mathbb{R}^n$ such that

$$\mu_0 = \phi \circ \mu$$

is the moment map of an effective Hamiltonian \mathbb{T}^n -action if and only if ϕ is integral affine. Hence, the result follows.

Recall that a compact toric symplectic manifold is always 1-connected. In this respect we also have the following result.

Corollary 4.17. A Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$ whose associated Delzant space $\Delta=\mu(S)$ is 1-connected is a classical symplectic toric manifold. In particular this holds whenever S is 1-connected.

Proof. The first part of the statement follows immediately from the theorem. For the second part, consider the inclusions

$$\begin{array}{ccc}
S & \xrightarrow{\mu} & \Delta \\
\downarrow & & \downarrow \\
\mathring{S} & \xrightarrow{\mu|_{\mathring{S}}} & \Delta
\end{array}$$

The map $\mu: \mathring{S} \to \Delta$ is a principal \mathbb{T}^n -bundle while $\mathring{\Delta}$ and Δ have the same homotopy type. Therefore, passing to fundamental groups we obtain a commutative diagram

$$\pi_1(S) \xrightarrow{\mu_*} \pi_1(\Delta)$$

$$\uparrow \qquad \qquad \uparrow \simeq$$

$$\pi_1(\mathring{S}) \longrightarrow \pi_1(\mathring{\Delta})$$

where the bottom horizontal arrow is surjective. It follows that $\mu_* : \pi_1(S) \to \pi_1(\Delta)$ is also surjective. Hence, if S is 1-connected, so is Δ .

Corollary 4.18. A Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$ with S compact is a classical symplectic toric manifold if and only if S is 1-connected.

Note that non-compact symplectic toric manifolds may fail to be 1-connected (e.g., $S = T^*\mathbb{T}^n$). Hence, the last corollary does not hold if one removes the compactness assumption.

4.4. The elliptic and b-tangent bundle.

4.4.1. Background on the b-tangent bundle. Let Δ be a manifold with corners. Recall that a b-vector field in Δ is a smooth vector field that is tangent to all open faces (or strata) of Δ [29]. The sheaf of b-vector fields, denoted ${}^b\mathfrak{X} := {}^b\mathfrak{X}_{\Delta}$ is a locally free sheaf of \mathcal{C}^{∞} -modules, with local bases

$$x^1 \partial_{x^1}, \dots, x^k \partial_{x^k}, \partial_{x^{k+1}}, \dots, \partial_{x^n},$$
 (4.3)

for any coordinates (U, x^i) that map onto an open in \mathbb{R}^n_k . Hence, the vector spaces

$${}^bT_x\Delta := \frac{{}^b\mathfrak{X}_x}{\mathfrak{m}_x \cdot {}^b\mathfrak{X}_x} \quad (x \in \Delta),$$

fit together into a rank n vector bundle ${}^bT\Delta$ – the b-tangent bundle or \log tangent bundle of Δ – with smooth local frames given by (4.3). Here ${}^b\mathfrak{X}_x$ denotes the stalk of ${}^b\mathfrak{X}$ at x and \mathfrak{m}_x is the ideal in \mathcal{C}_x^{∞} of germs of functions that vanish at x. The map

$$\rho: {}^bT\Delta \to T\Delta \tag{4.4}$$

induced by the evaluation maps $\mathfrak{X}_x \to T_x \Delta$, identifies the sheaf of smooth sections of ${}^bT\Delta$ with ${}^b\mathfrak{X}_\Delta$. The *b*-tangent bundle has the structure of a Lie algebroid over Δ , with bracket the usual Lie bracket of vector fields and anchor map (4.4).

The smooth sections of the b-cotangent bundle

$${}^bT^*\Delta := ({}^bT\Delta)^*$$

are determined by their restriction to the interior $\mathring{\Delta}$, which are just ordinary smooth 1-forms. In view of this, sections of the dual bundle are often simply denoted by their underlying 1-forms on $\mathring{\Delta}$. The local frame of ${}^bT^*\Delta$ dual to (4.3) consists of those smooth sections that restrict to the 1-forms

$$\frac{1}{x^1} dx^1, \dots, \frac{1}{x^k} dx^k, dx^{k+1}, \dots, dx^n,$$

on $\mathring{\Delta}$. In summary, smooth sections of the *b*-cotangent bundle can be represented by smooth 1-forms on $\mathring{\Delta}$ with poles of order at most 1 at the boundary.

Next, we turn to residues. The open faces of Δ are the leaves of the Lie algebroid ${}^bT\Delta$. Accordingly, for each open face F of Δ we have a short exact sequence

$$0 \longrightarrow \ker(\rho)|_F \longrightarrow {}^bT^*\Delta|_F \stackrel{\rho}{\longrightarrow} TF \longrightarrow 0.$$

When F is a facet, i.e., a face of codimension 1 in Δ , $\ker(\rho)|_F$ is a line bundle that admits a canonical non-vanishing section, which can be characterized as follows.

Proposition 4.19. Let F be an open facet of a manifold with corners Δ . There is a unique non-vanishing section

$$\mathcal{E}_F \in \Gamma^{\infty}(\ker(\rho)|_F)$$

with the property that any $X \in {}^b\mathfrak{X}(U)$ that is Euler-like with respect to F extends $\mathcal{E}_F|_{U\cap F}$.

Here by an Euler-like vector field $X \in \mathfrak{X}(\Delta)$ relative to the submanifold $F \subset \Delta$ we mean a vector field such that $X|_F = 0$ and the linearization of X along F induces the identity map on the normal bundle to F in Δ . This proposition is well-known (see, e.g., [9, 25]) so we omit the proof.

Remark 4.20. Let $(U, x^1, ..., x^n)$ be coordinates for Δ onto an open in \mathbb{R}^n_k . Writing a given b-vector field $X \in {}^b\mathfrak{X}(U)$ as

$$X = \sum_{i=1}^{k} f_i x^i \partial_{x^i} + \sum_{i=k+1}^{n} f_i \partial_{x^i}, \quad f_i \in C^{\infty}_{\Delta}(U),$$

then X is Euler-like with respect to F if and only if for each $x \in U \cap F$

$$f_i(x) = \begin{cases} 1 & \text{if } x^i = 0 \text{ and } i \le k, \\ 0 & \text{otherwise.} \end{cases}$$

In particular, if k = 1, then $x^1 \partial_{x^1} \in {}^b \mathfrak{X}(U)$ is an extension of $\mathcal{E}_F|_{U \cap F}$.

Using the previous proposition the residue of a vector-valued 1-form can be defined as follows.

Definition 4.21. Let Δ be a manifold with corners and F an open facet of Δ . The **residue along** F of a vector-valued 1-form $\alpha \in \Omega^1({}^bT\Delta, E)$ is the section

$$\operatorname{res}_F(\alpha) := \alpha(\mathcal{E}_F) \in \Gamma^{\infty}(E|_F).$$

4.4.2. Background on the elliptic tangent bundle. The elliptic tangent bundle ${}^{\mu}TS$ of a toric (\mathcal{T}, Ω) -space $\mu: (S, \omega) \to M$ is a Lie algebroid over S, similar to the b-tangent bundle introduced in the previous subsection. This Lie algebroid was first introduced in [9] in the case of a single elliptic divisor and then generalized for several divisors, including the case of a classical symplectic toric action, in [10, 11]. In our case, we can define the elliptic tangent bundle more directly in terms of its sheaf of sections as follows.

Recall that $\Delta := \mu(S)$ is a submanifold with corners of M, so that it comes with a natural sheaf of smooth functions $\mathcal{C}^{\infty}_{\Delta}$. Consider the sheaf $\mu_*(\mathfrak{X}_S)^{\mathcal{T}}$ on Δ that assigns to an open V the vector space of \mathcal{T} -invariant vector fields on the invariant open $\mu^{-1}(V)$ in S. This is naturally a sheaf of $\mathcal{C}^{\infty}_{\Delta}$ -modules, which is locally free of rank 2n, where $n = \dim(\Delta) = \frac{1}{2}\dim(S)$. Indeed, in the standard toric coordinates $(u_j + iv_j, \theta_l, x^l)$ around a point $x \in \Delta$ of depth k – see Proposition 4.6 – a basis for $\mu_*(\mathfrak{X}_S)^{\mathcal{T}}$ around x is given by the vector fields

$$\partial_{\phi_1}, \dots, \partial_{\phi_k}, r_1 \partial_{r_1}, \dots, r_k \partial_{r_k}, \dots, \partial_{\theta_1}, \dots, \partial_{\theta_{n-k}}, \partial_{x^1}, \dots, \partial_{x^{n-k}}.$$
 (4.5)

Here our convention for the angular and radial vector fields on \mathbb{C}^k is so that

$$\begin{split} \frac{1}{2\pi}\partial_{\phi_j} &= u_j\partial_{v_j} - v_j\partial_{u_j}, \\ r_j\partial_{r_j} &= u_j\partial_{u_j} + v_j\partial_{v_j}. \end{split}$$

The sheaf of $\mathcal{C}_{\Delta}^{\infty}$ -modules $\mu_*(\mathfrak{X}_S)^{\mathcal{T}}$ pulls back along μ to a sheaf ${}^{\mu}\mathfrak{X}$ of \mathcal{C}_S^{∞} -modules, which is locally free of the same rank. More concretely, ${}^{\mu}\mathfrak{X}$ can be viewed as the subsheaf of \mathfrak{X}_S consisting of those vector fields on S locally generated by \mathcal{T} -invariant vector fields. We will call ${}^{\mu}\mathfrak{X}$ the **sheaf of elliptic vector fields** on S relative to μ . The **elliptic tangent bundle** ${}^{\mu}TS$ is the corresponding vector bundle over S. Like the b-tangent bundle, ${}^{\mu}TS$ has a natural Lie algebroid structure. The anchor is the canonical map

$$\rho: {}^{\mu}TS \to TS$$
,

which identifies its sheaf of sections with ${}^{\mu}\mathfrak{X}$, and the Lie bracket is the usual Lie bracket of vector fields. By construction, the vector fields (4.5) form a smooth local frame of ${}^{\mu}TS$. The elliptic tangent bundle allows to resolve the singularities of the differential of μ and of the infinitesimal action α (the ranks of which drop at points outside of \mathring{S}), in the following sense.

Proposition 4.22. The differential of μ lifts uniquely to a fiberwise surjective Lie algebroid map μ_*

$$\begin{array}{c|c} {}^{\mu}TS - \overset{\mu_*}{-} > {}^{b}T\Delta \\ \\ \rho & & \downarrow \rho \\ TS \xrightarrow{\quad \text{d}\mu \quad} T\Delta \end{array}$$

Moreover, the infinitesimal action lifts uniquely to a vector bundle map a_*

$$\mu^*(T^*M) \xrightarrow{a_*} TS$$

that is fiberwise injective and has image $\ker(\mu_*)$.

Proof. The first statement follows from the remark that any invariant vector field on S is μ -related to a unique b-vector field on Δ , which is readily verified using the bases (4.5). The second statement follows from the fact that $\alpha(\alpha)$ is an invariant vector field tangent to $\ker(d\mu)$ for every 1-form α .

Finally, we recall the notion of radial residue. As for classical symplectic toric manifolds, for a toric (\mathcal{T}, Ω) -space $\mu : (S, \omega) \to M$ the stratification of S induced by the \mathcal{T} -action consists of the submanifolds of S of the form $S_F := \mu^{-1}(F)$, with F an open face of $\Delta := \mu(S)$. These strata are the leaves of the Lie algebroid ${}^{\mu}TS$. In particular, for any open face F of Δ , we have a short exact sequence

$$0 \longrightarrow \ker(\rho)|_{S_F} \longrightarrow {}^{\mu}TS|_{S_F} \xrightarrow{\rho} TS_F \longrightarrow 0.$$

If F is an open facet of Δ , then $\ker(\rho)|_{S_F}$ is a rank 2 vector bundle that admits a canonical non-vanishing section, which can characterized as follows.

Proposition 4.23. Let $\mu:(S,\omega)\to M$ be a toric (\mathcal{T},Ω) -space and let F be an open facet of $\Delta:=\mu(S)$. There is a unique non-vanishing section

$$\mathcal{E}_{S_F} \in \Gamma^{\infty}(\ker(\rho)|_{S_F})$$

such that any \mathcal{T} -invariant vector field on an invariant open U in S that is Euler-like with respect to S_F extends $\mathcal{E}_{S_F}|_{U\cap S_F}$. Moreover, \mathcal{E}_{S_F} is μ_* -related to $2\mathcal{E}_F$.

Remark 4.24. In standard toric coordinates, as in (4.5), a \mathcal{T} -invariant vector field X on U can be written as

$$X = \sum_{i=1}^{k} f_i^r r_i \partial_{r_i} + f_i^{\phi} \partial_{\phi_i} + \sum_{j=1}^{n-k} f_j^{\theta} \partial_{\theta_j} + f_j^x \partial_{x^j},$$

for some invariant functions $f_i^r, f_i^{\phi}, f_j^{\theta}, f_j^x \in \mathcal{C}^{\infty}(U)^{\mathcal{T}}$. Then X is Euler-like with respect to S_F if and only if for each $p = (z, t, x) \in U \cap S_F$ one has

$$f_i^{\phi}(p) = 0$$
, $f_j^{\theta}(p) = 0$, $f_j^{x}(p) = 0$ and $f_i^{r}(p) = \begin{cases} 1 & \text{if } z_i = 0, \\ 0 & \text{otherwise,} \end{cases}$

for all $i \in \{1, ..., k\}$ and $j \in \{1, ..., n - k\}$. In particular, if k = 1, then $r\partial_r$ is an extension of $\mathcal{E}_{S_F}|_{U \cap S_F}$.

Similar to the definition of residues for vector-valued b-forms, we can define residues of vector-valued elliptic 1-forms as follows.

Definition 4.25. Let $\mu:(S,\omega)\to M$ be a toric Hamiltonian \mathcal{T} -space, F an open facet of $\Delta := \mu(S)$ and E a vector bundle over Δ . The radial residue along F of a vector-valued 1-form $\alpha \in \Omega^1({}^{\mu}TS, E)$ is the section

$$\operatorname{res}_{F,\operatorname{Rad}}(\alpha) := \alpha(\mathcal{E}_{S_F}) \in \Gamma^{\infty}(E|_{S_F}).$$

4.5. Elliptic Lagrangian connections. We will now show that Theorem 3.15 extends to toric Hamiltonian \mathcal{T} -spaces. For that, we need an appropriate notion of connection 1-form on a toric \mathcal{T} -space $\mu:(S,\omega)\to M$. First, notice that there is a canonical fiberwise linear \mathcal{T} -action on ${}^{\mu}TS$ along the composition of the bundle projection with μ , because ${}^{\mu}TS$ is the pull-back along μ of a vector bundle on $\Delta := \mu(S)$. For any $p \in S$ the action by an element $g \in \mathcal{T}_{\mu(p)}$ is the canonical isomorphism ${}^{\mu}T_{p}S \to {}^{\mu}T_{g \cdot p}S$. The anchor map of the elliptic tangent bundle is \mathcal{T} -equivariant with respect to this action and the tangent action of \mathcal{T} .

Definition 4.26. An elliptic connection 1-form for a toric Hamiltonian Tspace $\mu:(S,\omega)\to M$ is a Lie algebroid form $\theta\in\Omega^1({}^{\mu}TS,T^*M)$ which satisfies:

- (i) *T-invariance*: θ_{gp}(g · v) = θ_p(v), for all v ∈ ^μT_pS, g ∈ *T*_{μ(p)};
 (ii) θ_p((α*)_p(α)) = α, for all α ∈ T*_{μ(p)}M and p ∈ S.

We call such a connection 1-form Lagrangian if $\ker(\theta)_p \subset (T_p S, \omega_p)$ is Lagrangian for every $p \in \mathring{S} := \mu^{-1}(\mathring{\Delta})$.

Remark 4.27. In the case of torus actions the notion of elliptic connection already appears in [12].

Example 4.28. An elliptic Lagrangian connection for the standard toric local model $\mu_{k,n}:(S_{k,n},\omega_{k,n})\to\mathbb{R}^n$ is given by

$$\theta(r_i \partial_{r_i}) = 0$$
, $\theta(\partial_{\phi_i}) = dx^i$, $\theta(\partial_{x^i}) = 0$, $\theta(\partial_{\theta_i}) = dx^{i+k}$.

Note that this has zero radial residue along all open facets of \mathbb{R}^n_k .

Proposition 4.29. Every toric Hamiltonian \mathcal{T} -space admits an elliptic Lagrangian connection 1-form with zero radial residue along all open facets.

Proof. In view of the above example such connection 1-forms exist locally. A global such 1-form can be constructed from these using a partition of unity for the manifold with corners $\Delta := \mu(S)$, as in the proof of Proposition 3.3.

Next, we turn to the curvature of such connection 1-forms. Let $\mu:(S,\omega)\to M$ be a toric Hamiltonian \mathcal{T} -space. There is a flat ${}^{\mu}TS$ -connection on the bundle μ^*T^*M obtained by first pulling-back the canonical flat connection ∇ on T^*M along μ to a TS-connection on μ^*T^*M and then composing with the anchor of $^{\mu}TS$. This gives a differential

$$d^{\nabla}: \Omega^{\bullet}({}^{\mu}TS, T^*M) \to \Omega^{\bullet+1}({}^{\mu}TS, T^*M).$$

It follows from Proposition 4.6, the standard local normal form and the properties of a connection 1-form θ that there is a unique 2-form

$$K_{\theta} \in \Omega^2({}^bT\Delta, T^*\Delta)$$

such that

$$\mu^* K_\theta = \mathrm{d}^\nabla \theta \in \Omega^2({}^\mu TS, T^*M).$$

We call K_{θ} the curvature of the elliptic connection θ .

Notice that ∇ also induces a flat ${}^bT\Delta$ -connection on $T^*\Delta$, with corresponding differential

$$d^{\nabla}: \Omega^{\bullet}({}^{b}T\Delta, T^{*}\Delta) \to \Omega^{\bullet+1}({}^{b}T\Delta, T^{*}\Delta).$$

The curvature K_{θ} is d^{∇} -closed and its cohomology class in $H^{2}({}^{b}T\Delta, T^{*}\Delta)$ does not depend on the choice of θ . If θ has zero radial residues, then by the proposition below the curvature is an honest smooth 2-form $K_{\theta} \in \Omega^{2}(\Delta, T^{*}\Delta)$. So, in view of Proposition 4.29, the connection-curvature construction actually defines a cohomology class $H^{2}(\Delta, T^{*}\Delta)$. In the case of torus actions this was also observed in [12].

Proposition 4.30. Let $\theta \in \Omega^1({}^{\mu}TS, T^*M)$ be an elliptic connection 1-form for a toric Hamiltonian \mathcal{T} -space $\mu : (S, \omega) \to M$ and suppose that θ has zero radial residues. Then $d^{\nabla}\theta \in \Omega^2(S, T^*M)$ and $K_{\theta} \in \Omega^2(\Delta, T^*\Delta)$. Moreover, if θ is Lagrangian, then $K_{\theta} \in \Omega^2_{\partial}(\Delta, T^*\Delta)$, meaning that

$$\partial K_{\theta}(v_1,v_2,v_3) := \sum_{\sigma \in S_3} (-1)^{|\sigma|} \langle K_{\theta}(v_{\sigma(1)},v_{\sigma(2)}),v_{\sigma(3)} \rangle = 0.$$

Proof. Note that $\iota_{\alpha(\alpha)}(\mathrm{d}^{\nabla}\theta)=0$ for all 1-forms α , since θ is a connection 1-form. Also $\iota_{\mathcal{E}_{S_F}}(\mathrm{d}^{\nabla}\theta)=0$ for each open facet F, since θ has zero radial residues. Hence, $\mathrm{d}^{\nabla}\theta$ is a smooth 2-form on S. Since $\mu_*(\mathcal{E}_{S_F})=2\,\mathcal{E}_F$, it follows that K_{θ} is a smooth 2-form as well. Finally, $\partial K_{\theta}=0$ if θ is Lagrangian, since this holds on $\mathring{\Delta}$ by Proposition 3.14, so it holds on all of Δ by density of $\mathring{\Delta}$.

This proposition shows that a choice of elliptic Lagrangian connection with zero radial residue gives rise to a cohomology class

$$[K_{\theta}] \in H^2(\Omega_{\partial}^{\bullet}(\Delta, T^*\Delta), \mathrm{d}^{\nabla}),$$

with the complex $(\Omega_{\partial}^{\bullet}(\Delta, T^*\Delta), d^{\nabla})$ defined like in Section 3.3. In order to extend Theorem 3.15, consider the composite

$$\check{H}^{1}(\Delta, \underline{\mathcal{T}_{Lag}}) \xrightarrow{\simeq} \check{H}^{2}(\Delta, \mathcal{O}_{\Lambda}) \longrightarrow \check{H}^{2}(\Delta, \mathcal{O}_{Aff}) \xrightarrow{\simeq} H^{2}(\Omega_{\partial}^{\bullet}(\Delta, T^{*}\Delta), d^{\nabla}) , \quad (4.6)$$

where \mathcal{O}_{Aff} and \mathcal{O}_{Λ} denote respectively the sheaves of locally defined functions on Δ that are affine and integral affine with respect to Λ . The first map in this sequence is the connecting homomorphism induced by the short exact sequence

$$0 \longrightarrow \mathcal{O}_{\Lambda} \longrightarrow \mathcal{C}^{\infty} \stackrel{d}{\longrightarrow} \underline{\mathcal{T}_{Lag}} \longrightarrow 0,$$

while the last map is the isomorphism induced by the fine resolution

$$0 \longrightarrow \mathcal{O}_{\mathrm{Aff}} \longrightarrow \mathcal{C}^{\infty} \xrightarrow{\mathrm{d}^{\nabla} \circ \mathrm{d}} \Omega^{1}_{\partial}(-, T^{*}\Delta) \xrightarrow{\mathrm{d}^{\nabla}} \Omega^{2}_{\partial}(-, T^{*}\Delta) \xrightarrow{\mathrm{d}^{\nabla}} \dots$$

Theorem 4.31. Let $\mu:(S,\omega)\to M$ be a toric Hamiltonian \mathcal{T} -space. If θ is an elliptic Lagrangian connection for μ with zero radial residue, then (4.6) maps the Lagrangian Chern class $c_1(S,\omega)$ to the class $[K_{\theta}]$.

For the proof it will be useful to recall from [28] how, given a Delzant subspace Δ of an integral affine manifold (M, Λ) , one constructs the **canonical toric** \mathcal{T} -space $\mu_{\Delta}: (S_{\Delta}, \omega_{\Delta}) \to M$ with momentum map image Δ and $c_1(S_{\Delta}, \omega_{\Delta}) = 0$. This construction consists of the following steps:

- (i) As a topological space, S_{Δ} is the quotient of $\mathcal{T}_{\Lambda}|_{\Delta}$ by the normal subgroupoid with isotropy group at $x \in \Delta$ given by the subtorus with Lie algebra $(T_x F)^0$, the annihilator in T_x^*M of the tangent space to the open face F through x.
- (ii) The bundle projection of \mathcal{T}_{Λ} descends to a continuous map $\mu_{\Delta}: S_{\Delta} \to M$ and the action of \mathcal{T}_{Λ} along its bundle projection descends to a continuous action of \mathcal{T}_{Λ} along μ_{Δ} .

(iii) There are a unique smooth and symplectic structures on S_{Δ} with the following property: for any integral affine chart $(U, \phi = (x^1, ..., x^n))$ onto a connected open $\phi(U)$ around the origin in \mathbb{R}^n_k such that $\phi(U \cap \Delta) = \phi(U) \cap \mathbb{R}^n_k$, the induced homeomorphism

$$\mu_{\Delta}^{-1}(U) \xrightarrow{\sim} \mu_{k,n}^{-1}(\phi(U))$$

$$\left[\sum_{j=1}^{n} \theta_{j} dx^{j}\right] \mapsto \left(e^{2\pi i \theta_{1}} \sqrt{x^{1}}, \dots, e^{2\pi i \theta_{k}} \sqrt{x^{k}}, \theta_{k+1}, \dots, \theta_{n}, x^{k+1}, \dots, x^{n}\right)$$

$$(4.7)$$

is a symplectomorphism with respect to $\omega_{k,n}$.

All together, this gives a toric \mathcal{T}_{Λ} -space

$$\mu_{\Delta}: (S_{\Delta}, \omega_{\Delta}) \to M$$

with moment map image Δ and trivial Lagrangian Chern class (by definition). Note that this comes with a canonical symplectic open embedding

$$\mathcal{T}_{\Lambda}|_{\mathring{\Lambda}} \hookrightarrow S_{\Delta}$$

onto the dense subset $\mathring{S}_{\Delta} = \mu_{\Lambda}^{-1}(\mathring{\Delta})$.

Proof of Theorem 4.31. Consider $\mathcal{U} = \{U_i\}_{i \in I}$ a good open cover of Δ together with equivalences of Hamiltonian \mathcal{T} -spaces

$$(\mu^{-1}(U_i), \omega) \xrightarrow{\Psi_i} (\mu_{\Delta}^{-1}(U_i), \omega_{\Delta})$$

$$M$$

For any two $i, j \in I$ there is a unique Lagrangian section $\tau_{ij} \in \mathcal{T}_{\text{Lag}}(U_{ij})$ such that

$$\tau_{ij}(\mu(p)) \cdot \Psi_j(p) = \Psi_i(p), \quad p \in \mu^{-1}(U_{ij}).$$

The class $c_1(S,\omega)$ is represented by the Čech 1-cocycle $\tau = [\tau_{ij}] \in \check{C}^1(\mathcal{U}, \mathcal{T}_{\text{Lag}})$. The zero-section of \mathcal{T}_{Λ} induces a continuous section $\sigma_{\Delta} : \Delta \to S_{\Delta}$ of μ_{Δ} , which is smooth and Lagrangian on $\mathring{\Delta}$ and we set

$$\sigma_i := \psi_i^{-1} \circ \sigma_\Delta : U_i \to S. \tag{4.8}$$

The fact that $c_1(S,\omega)$ is mapped to $[K_{\theta}]$ by (4.6) follows from an argument identical to that in the proof of Theorem 3.15, where the Lagrangian sections σ_i are now given by (4.8). There is however one technical issue to overcome; now the sections σ_i are not smooth on all of U_i , only on $\mathring{U}_i = U_i \cap \mathring{\Delta}$, so a priori we can we can only consider

$$\sigma_i^* \theta \in \Omega^1_{\partial}(\mathring{U}_i, T^*\Delta).$$

We need to show that the 1-forms $\sigma_i^*\theta$ extend smoothly to all of U_i for each $i \in I$. Since this is a local property, it can be checked in the standard toric coordinates for μ_{Δ} induced by integral affine coordinates (U, x^i) as in (4.7). In such toric coordinates $(\psi_i^{-1})^*\theta$ is of the form

$$(\psi_i^{-1})^*\theta = \sum_{j=1}^k \mathrm{d}\phi_j \otimes \alpha_j + \mu_{k,n}^*(\mathrm{d}x^j) \otimes \beta_j + \sum_{j=1}^{n-k} \mathrm{d}\theta_j \otimes \alpha_{j+k} + \mu_{k,n}^*(\mathrm{d}x^{j+k}) \otimes \beta_{j+k}$$

for $\alpha_j, \beta_j \in \Omega^1(U_i)$, because θ has zero radial residues. Moreover, σ_{Δ} is given by

$$\sigma_{\Delta}(x) = \left(\sqrt{x^1}, \dots, \sqrt{x^k}, 0, \dots, 0, x^{k+1}, \dots, x^n\right)$$

Therefore, $\sigma_i^* \theta = \sum_{j=1}^n \mathrm{d} x^j \otimes \beta_j$ on $U \cap \mathring{U}_i$, so it extends smoothly to U_i .

4.6. Flat elliptic Lagrangian connections. Flat Lagrangian elliptic connections with zero radial residue will play a key role in the study of invariant Kähler metrics. In this subsection we extend the results of Section 3.4 to such connections.

Definition 4.32. A flat toric Hamiltonian \mathcal{T} -space is a toric Hamiltonian \mathcal{T} -space equipped with a flat Lagrangian elliptic connection that has zero radial residues.

Given an integral affine manifold (M, Λ) and a Delzant subspace Δ , we denote by $\underline{\mathcal{T}_{\text{Flat}}}$ the sheaf on Δ of ∇ -flat sections of $\mathcal{T}_{\Lambda}|_{\Delta}$. This coincides with the restriction of the sheaf of flat sections of \mathcal{T} to Δ and, as before, it is a subsheaf of $\underline{\mathcal{T}_{\text{Lag}}}$. Also, the induced map in cohomology fits in an exact sequence

$$\check{H}^{1}(\Delta, \underline{\mathcal{T}_{\mathrm{Flat}}}) \longrightarrow \check{H}^{1}(\Delta, \underline{\mathcal{T}_{\mathrm{Lag}}}) \longrightarrow H^{2}(\Omega_{\partial}^{\bullet}(\Delta, T^{*}\Delta), \mathrm{d}^{\nabla}), \tag{4.9}$$

where the second map is given by (4.6). Therefore, Corollary 3.19 extends. The same goes for Theorem 3.20.

Theorem 4.33. Fix a Delzant subspace Δ of an integral affine manifold (M, Λ) . There is a canonical 1:1 correspondence

$$\left\{
\begin{array}{l}
flat \ toric \ Hamiltonian \ \mathcal{T}_{\Lambda}\text{-spaces} \\
\mu: (S, \omega, \theta) \to M \\
with \ \mu(S) = \Delta, \ up \ to \ equivalence
\end{array}
\right\} \stackrel{\sim}{\longleftarrow} \check{H}^{1}(\Delta, \underline{\mathcal{T}_{Flat}})$$

The cohomology class corresponding to a flat toric Hamiltonian \mathcal{T} -space is mapped to its Lagrangian Chern class by the first map in (4.9).

For the proof of this, we use the following observation.

Proposition 4.34. The canonical toric \mathcal{T} -space $\mu_{\Delta}: (S_{\Delta}, \omega_{\Delta}) \to M$ admits a unique elliptic connection θ_{Δ} that restricts to the canonical flat Lagrangian connection on \mathcal{T}_{Λ} via the canonical open embedding

$$\mathcal{T}_{\Lambda}|_{\mathring{\Lambda}} \hookrightarrow S_{\Delta}.$$
 (4.10)

The connection θ_{Δ} is flat, Lagrangian and has zero radial residues.

Proof. Uniqueness holds since the image of (4.10) is dense in S_{Δ} . This also implies that for existence, it is enough to show that locally the canonical flat connection on $\mathcal{T}_{\Lambda}|_{\mathring{\Delta}}$ extends to an elliptic connection 1-form for μ_{Δ} with zero radial residues. So we can work in the toric coordinates induced by an integral affine chart (U, x^i) , as in (4.7), over which we also have an induced trivialization of the symplectic torus bundle $\mathcal{T}_{\Lambda}|_{\mathring{\Delta}}$. The embedding (4.10) becomes the map $\mathbb{T}^n \times \mathring{\mathbb{R}}^n_k \to S_{k,n}$ given by

$$(\theta_1, ..., \theta_n, x^1, ..., x^n) \mapsto (e^{2\pi i \theta_1} \sqrt{x^1}, ..., e^{2\pi i \theta_k} \sqrt{x^k}, \theta_{k+1}, ..., \theta_n, x^{k+1}, ..., x^n).$$

On the other hand, the canonical flat connection on $\mathcal{T}_{\Lambda}|_{\mathring{\Delta}}$ becomes $\sum_{i=1}^{n} \mathrm{d}\theta_{i} \otimes \mathrm{d}x^{i}$ so corresponds under (4.10) with the restriction to \mathring{S}_{Δ} of the connection given in Example 4.28. Therefore, the canonical flat connection on $\mathcal{T}_{\Lambda}|_{\mathring{\Delta}}$ indeed extends to an elliptic connection 1-form for μ_{Δ} with zero radial residues. Since the canonical connection on \mathcal{T}_{Λ} is flat and Lagrangian and \mathring{S}_{Δ} is dense in S_{Δ} , it follows that θ_{Δ} is also flat and Lagrangian.

Proof of Theorem 4.33. The proof is virtually the same as that in the case of Lagrangian fibrations, where we now take the equivalence class of the flat toric Hamiltonian \mathcal{T}_{Λ} -space of the above proposition as the equivalence class corresponding to the zero element of the group $\check{H}^1(\Delta, \mathcal{T}_{\text{Flat}})$.

Example 4.35. Consider the Delzant subspace $\Delta = \mathbb{S}^1 \times [-1,1]$ of the standard cylinder $(\mathbb{S}^1 \times \mathbb{R}, \Lambda_{st})$. Notice that

$$\check{H}^1(\Delta, \mathcal{T}_{Lag}) = \check{H}^2(\Delta, \mathcal{O}_{\Lambda}) = 0,$$

so every toric \mathcal{T}_{Λ} -space is isomorphic to the space $\mu: (\mathbb{T}^2 \times \mathbb{S}^2, \omega) \to \mathbb{S}^1 \times \mathbb{R}$ of Example 2.20.

Since Λ has trivial holonomy representation it follows – see Remark 3.21 – that the equivalence classes of flat \mathcal{T}_{Λ} -toric fibrations are in 1-1 correspondence with

$$\check{H}^1(\Delta, \mathcal{T}_{Flat}) = \check{H}^1(\Delta, \mathbb{T}^2) = \mathbb{T}^2.$$

For $a, b \in \mathbb{R}$, the classes $(e^{2\pi i a}, e^{2\pi i b}) \in \mathbb{T}^2$ can be realized by the elliptic connections on $\mu : \mathbb{T}^2 \times \mathbb{S}^2 \to \Delta$ given by the connection 1-form

$$\theta_{a,b} = (-a\mathrm{d}x + \mathrm{d}y) \otimes \mathrm{d}x + (-b\mathrm{d}h + \mathrm{d}\phi) \otimes \mathrm{d}h.$$

This corresponds to the Lagrangian foliation on $\mu^{-1}(]-1,1[)$ given by

$$D_{a,b} := \langle \partial_x + a \partial_y, \partial_h + b \partial_\phi \rangle.$$

Example 4.36. Consider the Delzant subspace $\Delta = \mathbb{S}^1 \times [-1, 1]$ of the non-standard cylinder $(\mathbb{S}^1 \times] - 2, \infty[, \mathbb{Z}((h+2)\mathrm{d}x + x\mathrm{d}h) \oplus \mathbb{Z}\mathrm{d}h)$, as in Example 2.21. We still have $\check{H}^1(\Delta, \mathcal{T}_{Lag}) = 0$ so it follows that every toric \mathcal{T}_{Λ} -space is isomorphic to the space $\mu : (\mathbb{T}^2 \times \mathbb{S}^2, \omega) \to \mathbb{S}^1 \times] - 2, \infty[$ appearing in Example 2.21.

A computation using the Mayer-Vietoris sequence, shows that

$$\check{H}^1(\Delta, \mathcal{T}_{Flat}) = \check{H}^1(\Delta, \mathbb{T}^2) = \mathbb{T}^2,$$

so we conclude that equivalence classes of flat \mathcal{T}_{Λ} -toric fibrations are parameterized by $(e^{2\pi i a}, e^{2\pi i b}) \in \mathbb{T}^2$, with $a, b \in \mathbb{R}$. These can be realized by the elliptic connections on $\mu: (\mathbb{T}^2 \times \mathbb{S}^2, \omega) \to \mathbb{S}^1 \times]-2, \infty[$ given by the connection 1-form

$$\theta_{a,b} = (h+2)(-adx + dy) \otimes dx + (-bdh + d\phi + xdy) \otimes dh.$$

This corresponds to the Lagrangian foliation on $\mu^{-1}(]-1,1[)$ given by

$$D_{a,b} := \langle \partial_x + a(\partial_y - x\partial_\phi), \partial_h + b\partial_\phi \rangle.$$

5. Delzant construction

The proof of the classification theorem of toric Hamiltonian \mathcal{T} -spaces (Theorem 4.12) requires the construction of a toric Hamiltonian \mathcal{T} -space $\mu: (S, \omega) \to M$ with moment map image $\mu(S)$ a given Delzant subspace $\Delta \subset (M, \Lambda)$.

In the case of a Delzant polytope $\Delta \subset (\mathbb{R}^n, \mathbb{Z}^n)$ Delzant gave a construction of a compact symplectic toric manifold with moment map image Δ by symplectic reduction of a linear Hamiltonian torus action on $(\mathbb{C}^d, \omega_{\rm st})$, where d is the number of facets. For a general Delzant subspace, as we recalled in Section 4.5, the construction of canonical toric \mathcal{T} -space uses a different method. In this section we will give a generalization of Delzant's construction for a large class of Delzant subspaces. Although this construction does not apply to all Delzant subspaces, it does cover many natural examples and has the advantage of realizing the desired toric space via symplectic reduction of a rather simple symplectic manifold.

5.1. The primitive outward pointing normals. The aim of this section is to show for a Delzant subspace Δ in a 1-connected integral affine manifold each facet of Δ admits a naturally defining integral affine function.

In order to state a precise result, we recall that for a manifold with corners Δ , given $x \in \partial \Delta$ the cone $C_x(\Delta)$ consists of all inward-pointing tangent vectors at x. We further denote by $S^1(\Delta)$ the collection of codimension 1 strata of Δ (i.e., the open facets of Δ).

Proposition 5.1. Let (M, Λ) be a 1-connected integral affine manifold and let Δ be a Delzant subspace. For each open facet Σ of Δ , there is a unique integral affine function $\ell = \ell_{\Sigma} \in \mathcal{O}_{\Lambda}(M)$ satisfying the following properties:

- (i) $\ell|_{\Sigma} = 0$ and $\ker(d\ell)|_{\Sigma} = T\Sigma$;
- (ii) ℓ is outward-pointing, i.e., $d_x \ell(v) \leq 0$ for all $v \in C_x(\Delta)$ and all $x \in \Sigma$;
- (iii) for any $f \in \mathcal{O}_{\Lambda}(M)$ with property (i), there is a $k \in \mathbb{Z}$ such that $f = k \ell$.

Moreover, any $x \in \Delta$ admits an open neighbourhood U in M such that

$$\Delta \cap U = \bigcap_{\{\Sigma \in \mathcal{S}^1(\Delta) : x \in \overline{\Sigma}\}} \{\ell_{\Sigma} \le 0\} \cap U.$$
 (5.1)

The number of open facets of Δ with x in their closure equals the depth of x in Δ .

Given a Delzant subspace Δ of a 1-connected integral affine manifold (M,Λ) we let

$$\mathcal{H}(\Delta) := \{ \ell_{\Sigma} \mid \Sigma \in \mathcal{S}^{1}(\Delta) \}$$
 (5.2)

be the collection of integral affine functions ℓ_{Σ} associated to the open facets of Δ given by the previous proposition. We call the elements of $\mathcal{H}(\Delta)$ primitive boundary defining (integral affine) functions.

Example 5.2. It can happen that the same integral affine function is associated to different codimension 1 strata. An example of this is

$$M:=\mathbb{R}^2-\bigsqcup_{k\in\mathbb{Z}}\{k\}\times[0,\infty[,\quad \Delta=M\cap(\mathbb{R}\times]-\infty,0]),$$

where M is equipped with the integral affine structure inherited from $(\mathbb{R}^2, \mathbb{Z}^2)$. Then Δ in fact has infinitely many codimension 1 strata, but $\mathcal{H}(\Delta)$ consist of a single function.

For the proof of Proposition 5.1, we first recall the following fact.

Lemma 5.3. Let (V^*, Λ) be an integral affine vector space. Suppose that $H \subset V$ is an hyperplane, which is primitive in the sense that $\operatorname{span}_{\mathbb{R}}(H \cap \Lambda^{\vee}) = H$. Then there is an $\alpha \in \Lambda$ such that:

- (i) $H = \ker(\alpha)$;
- (ii) if $\beta \in \Lambda$ and $H = \ker(\beta)$, then $\beta = k \alpha$ for some $k \in \mathbb{Z}$.

Moreover, α is unique up to a sign.

We call $\alpha \in \Lambda$, as in this lemma, a **primitive normal covector** to the hyperplane H.

Lemma 5.4. Let (M, Λ) be an integral affine manifold, let Δ be a Delzant subspace and let Σ be a codimension 1 stratum of Δ . For each $x \in \Sigma$, there is a unique outward-pointing primitive normal covector $\alpha_x \in \Lambda_x$ to the hyperplane $T_x\Sigma \subset (T_xM, \Lambda_x^{\vee})$. The family of all such outward-pointing primitive normals is holonomy-invariant.

In this lemma, by 'holonomy invariant' we mean that for any path γ in Σ , the holonomy representation $\text{hol}([\gamma]): T_{\gamma(0)}M \to T_{\gamma(1)}M$ pulls $\alpha_{\gamma(1)}$ back to $\alpha_{\gamma(0)}$.

Proof. The existence and uniqueness of the covectors α_x follows from the previous lemma and the fact that open facets of Delzant subspaces are primitive codimension 1 submanifolds of (M, Λ) . By the uniqueness of primitive normal covectors, to prove holonomy-invariance it suffices to show that for any path γ in Σ , the holonomy representation $\text{hol}([\gamma]): T_{\gamma(0)}M \to T_{\gamma(1)}M$ maps the tangent cone $C_{\gamma(0)}(\Delta)$ onto the tangent cone $C_{\gamma(1)}(\Delta)$. It is enough to check this for a path contained in the domain of an integral affine chart.

Let $(U, \phi = (x^1, \dots, x^m))$ be an integral affine chart adapted to Δ in the sense that $\phi(U \cap \Delta)$ is an open in $[0, \infty[\times \mathbb{R}^{m-1}]$ around the origin. Then for any point $x \in \phi^{-1}(\{0\} \times \mathbb{R}^{m-1})$ we have

$$C_x(\Delta) = \operatorname{Cone}(\partial_{x^1}, \pm \partial_{x^2}, \dots, \pm \partial_{x^m}).$$

If γ is a path lying in an open facet $\Sigma \cap U \subset \phi^{-1}(\{0\} \times \mathbb{R}^{m-1})$, then $\operatorname{hol}([\gamma])$ maps $C_{\gamma(0)}(\Delta)$ onto $C_{\gamma(1)}(\Delta)$, since the frames induced by integral affine coordinate charts are flat and the coordinate vector fields ∂_{x^i} are invariant under the action of $\operatorname{hol}([\gamma])$.

Proof of Proposition 5.1. Let Σ be a codimension 1 stratum of Δ . Since M is 1-connected, for any $x_0 \in \Sigma$ there is a unique parallel 1-form $\alpha \in \Omega^1(M)$ that evaluates at x_0 to the the outward-pointing primitive normal covector. By the holonomy-invariance in Lemma 5.4, for any $x \in \Sigma$ the value α_x is the outward-pointing primitive normal covector at x. As M is 1-connected, there is a unique function $\ell = \ell_{\Sigma} \in C^{\infty}(M)$ such that $d\ell = \alpha$ and $\ell|_{\Sigma} = 0$. Since α is parallel and $\alpha_{x_0} \in \Lambda_{x_0}$, α takes values in Λ . Hence, ℓ is an integral affine function. It satisfies the required properties (i)–(iii) and is the unique such integral affine function, due to the properties of the covectors in Lemma 5.4 and the fact that the differential of an integral affine function is a parallel 1-form.

Next, fix $x \in \Delta$ of depth k. Pick an integral affine chart $(U, \phi = (x^1, \dots, x^n))$ centered at x such that $W := \phi(U \cap \Delta)$ is a convex open set in $[0, \infty[^k \times \mathbb{R}^{n-k}]$. The set of points in $U \cap \Delta$ of depth 1 corresponds to the disjoint union of the convex subsets

$$W_i := \{(x^1, \dots, x^m) \in W \mid x^i = 0 \text{ and } x^j > 0 \text{ for } 1 \le j \le k, \ j \ne i\},$$

for i = 1, ..., k. Since each W_i is connected, $\phi^{-1}(W_i)$ is contained in a single open facet Σ_i of Δ , with defining function satisfying $\ell_{\Sigma_i}|_U = -x^i$. The latter shows that $\Sigma_i \neq \Sigma_j$ if $i \neq j$. Therefore, the number of open facets with x in their closure is indeed equal to k. It is now also clear that (5.1) holds for this choice of U.

5.2. **Delzant subspaces of finite type.** Let (M, Λ) be a connected integral affine manifold and let Δ be a connected Delzant subspace. Consider the canonical map

$$(i_{\Delta})_*: \widetilde{\Delta} \to \widetilde{M},$$

from the universal cover of Δ into that of M, relative to some choice of base-point. The image $\widehat{\Delta} := (i_{\Delta})_*(\widetilde{\Delta})$ is a Delzant subspace of \widetilde{M} . For the Delzant subspaces to which our construction applies, the collection $\mathcal{H}(\widehat{\Delta})$ of primitive boundary defining functions is finite and determines the Delzant subspace in the following sense.

Definition 5.5. A connected Delzant subspace Δ is of finite type if $\mathcal{H}(\widehat{\Delta})$ is finite and

$$\widehat{\Delta} = \bigcap_{f \in \mathcal{H}(\widehat{\Delta})} \{ f \le 0 \}. \tag{5.3}$$

Below we give two examples illustrating how each of these conditions may fail.

Example 5.6. Let

$$M := \mathbb{R}^2 - \{(0, y) \mid y > 0\}$$

with the standard integral affine structure $\Lambda = \mathbb{Z} dx \oplus \mathbb{Z} dy$. Consider the Delzant subspace

$$\Delta = \{(x, y) \in M \mid y \le |x|\}.$$

This is closed in M and has two open facets, with primitive boundary defining functions $\ell_{\pm}(x,y) = \pm (x-y)$. However, Δ does not satisfy (5.3).

Example 5.7. Consider the non-standard integral affine cylinder

$$(M,\Lambda) := (\mathbb{S}^1 \times \mathbb{R}, \mathbb{Z} dx \oplus \mathbb{Z} (dh - x dx))$$

and the Delzant subspace

$$\Delta = \left\{ (x, h) \in \mathbb{S}^1 \times \mathbb{R} \mid h \le \frac{1}{2} x^2 - \frac{1}{8}, \ -\frac{1}{2} \le x \le \frac{1}{2} \right\}.$$

The lift $\widehat{\Delta} \subset \mathbb{R}^2 = \widetilde{M}$ is the region bounded from above by the curves

$$\left\{h = \frac{1}{2}(x+n)^2 - \frac{1}{8}\right\} \subset \mathbb{R}^2, \quad n \in \mathbb{Z}.$$

In this example, even though Δ has only one open facet, the collection $\mathcal{H}(\widehat{\Delta})$ is infinite, as it consists of the functions

$$\ell_n(x,h) = h - \frac{1}{2}(x+n)^2 + \frac{1}{8}, \quad n \in \mathbb{Z}.$$

In both of these examples the Delzant subspace is not compact. We do not know of an example of a compact Delzant subspace that is not of finite type.

In the coming subsection, the following property of Delzant subspaces of finite type will be important.

Proposition 5.8. Let (M, Λ) be a 1-connected integral affine manifold, Δ a Delzant subspace of finite type and $x \in \Delta$. Consider the primitive boundary defining functions $\ell \in \mathcal{H}(\Delta)$ for which $\ell(x) = 0$.

- (i) The number of such functions equals the depth of x.
- (ii) Their differentials at x can be extended to a basis of Λ_x and span $(T_x F)^0$.

Proof of Proposition 5.8. Let $x \in \Delta$. By Proposition 5.1 the number of $\ell \in \mathcal{H}(\Delta)$ for which $\ell(x) = 0$ is at least $k := \operatorname{depth}_{\Delta}(x)$. To show that these are in fact equal, given $\ell_0 \in \mathcal{H}(\Delta)$ such that $\ell_0(x) = 0$, we need to prove that ℓ_0 is one of the functions ℓ_i associated to one of the k open facets Σ_i with x in their closure. Choose an integral affine chart $(U, \phi = (x^1, \dots, x^n))$ centered at x, as in the second part of the proof of Proposition 5.1. Since ℓ_0 is affine and vanishes at x, its restriction to U is of the form:

$$\ell_0|_U = -\sum_{i=1}^n t_i x^i, \quad t_i \in \mathbb{R}.$$

In view of (5.3), ℓ_0 is non-positive on Δ and so $t_i \geq 0$ for all i = 1, ..., k and $t_i = 0$ for all i = k + 1, ..., n. As in the proof of Proposition 5.1, $\ell_i|_U = -x^i$ for each i = 1, ..., k. So,

$$\ell_0 = \sum_{i=1}^k t_i \ell_i, \quad t_i \ge 0,$$

since this equality holds on U and the functions on both sides are affine. It follows from property (iii) in Proposition 5.1 that, if $\ell_0 \neq \ell_i$ for all i = 1, ..., k, then there are at least two distinct $i_1, i_2 \in \{1, ..., k\}$ for which $t_{i_1}, t_{i_2} \neq 0$. In that case, since Δ satisfies (5.3), Σ_0 must be contained in the codimension 2 submanifold $\{\ell_{i_1} = \ell_{i_2} = 0\}$, which is a contradiction. So, our first claim follows. Moreover, the fact that $\ell_i|_U = -x^i$ for all i = 1, ..., k shows that the differentials of these functions at x extend to a basis of Λ_x and span $(T_x F)^0$.

5.3. The 1-connected case. In this section we give a Delzant type construction for a finite type Delzant subspace of a 1-connected integral affine manifold. Treating the 1-connected case first is convenient for the proof of the general case, and moreover it is interesting on its own, as it already covers a class of non-compact toric symplectic manifolds (cf. Section 4.3).

Let (M,Λ) be a 1-connected integral affine manifold and let Δ be a Delzant subspace of finite type so

$$\Delta = \bigcap_{i=1}^{d} \{\ell_i \le 0\},\,$$

where ℓ_1, \ldots, ℓ_d are the primitive boundary defining functions. We consider the map:

$$\phi := (\ell_1, ..., \ell_d) : (M, \Lambda) \to (\mathbb{R}^d, \mathbb{Z}^d).$$

Since this map is integral affine, it induces a morphism of symplectic torus bundles

$$(\phi, \underline{\phi}^*): (\mathcal{T}_{\Lambda}, \Omega_{\Lambda}) \longrightarrow (\mathbb{T}^d \times \mathbb{R}^d, \sum_{i=1}^d \mathrm{d}\theta_i \wedge \mathrm{d}x^i)$$

as in Proposition 2.16. This, in turn, induces a Hamiltonian \mathbb{T}^d -action on $(\mathcal{T}_{\Lambda}, \Omega_{\Lambda})$ with moment map the composition of ϕ with the bundle projection π and action given by

$$(\theta_1, ..., \theta_d) \cdot [\alpha] = \left[\alpha + \sum_{i=1}^d \theta_i \, \mathrm{d}\ell_i\right].$$

Theorem 5.9. Consider the diagonal Hamiltonian \mathbb{T}^d -action with moment map

$$\mu_{\phi} := \phi + (|z_1|^2, ..., |z_d|^2) : (\mathcal{T}_{\Lambda}, \Omega_{\Lambda}) \times (\mathbb{C}^d, \omega_{st}) \to \mathbb{R}^d$$

The \mathbb{T}^d -action is free on $\mu_{\phi}^{-1}(0)$ and the symplectic quotient

$$((\mathcal{T}_{\Lambda} \times \mathbb{C}^d) /\!\!/ \mathbb{T}^d, \omega_{\mathrm{red}})$$

is a toric Hamiltonian \mathcal{T}_{Λ} -space for the action induced by translations on the first factor. Moreover, this space is equivalent to the canonical toric Hamiltonian \mathcal{T}_{Λ} -space $\mu_{\Delta}: (S_{\Delta}, \omega_{\Delta}) \to M$.

Proof. We start by checking the diagonal \mathbb{T}^d -action on $\mu_{\phi}^{-1}(0)$ is free, so the symplectic quotient is well-defined. Let $([\alpha_x], z) \in \mu_{\phi}^{-1}(0)$ and $\theta = (\theta_1, ..., \theta_d) \in \mathbb{T}^d$ be such that θ fixes $([\alpha_x], z)$. Since θ fixes z, it follows that $\theta_i = 0 \mod \mathbb{Z}$ whenever $z_i \neq 0$. On the other hand, because $\ell_i(x) = -|z_i|^2$, the remaining $i \in \{1, ..., d\}$, say $i_1, ..., i_k$, are those for which $\ell_i(x) = 0$. So, by Proposition 5.8, $(\mathrm{d}\ell_{i_1})_x, \ldots, (\mathrm{d}\ell_{i_k})_x$ extends to a basis of Λ_x . Hence, the fact that θ fixes $[\alpha_x]$ implies that $\theta_{i_1} = \ldots = \theta_{i_k} = 0 \mod \mathbb{Z}$ as well.

Next, observe that the action of \mathcal{T}_{Λ} on itself by translation descends to a Hamiltonian \mathcal{T}_{Λ} -action along

$$\mu: \left((\mathcal{T}_{\Lambda} \times \mathbb{C}^d) /\!\!/ \mathbb{T}^d, \omega_{\mathrm{red}} \right) \to M, \quad [\alpha, z] \mapsto \pi(\alpha),$$

which has moment map image

$$\bigcap_{i=1}^{d} \{\ell_i \le 0\} = \Delta.$$

Finally, we claim that we have an equivalence of Hamiltonian \mathcal{T}_{Λ} -spaces

$$(S_{\Delta}, \omega_{\Delta}) \xrightarrow{\Psi} ((\mathcal{T}_{\Lambda} \times \mathbb{C}^{d}) /\!\!/ \mathbb{T}^{d}, \omega_{\text{red}})$$

given by

$$[\alpha_x] \longmapsto [\alpha_x, (\sqrt{-\ell_1(x)}, \dots, \sqrt{-\ell_d(x)})].$$

This map is a \mathcal{T}_{Λ} -equivariant bijection with inverse induced by

$$(\alpha_x, z) \longmapsto [t^{-1} \cdot \alpha_x],$$

where $t = (t_1, \ldots, t_d)$ is given by

$$t_i = t_i(z, x) := \begin{cases} \frac{z_i}{|z_i|}, & \text{if } \ell_i(x) \neq 0, \\ 0, & \text{if } \ell_i(x) = 0. \end{cases}$$

To see that Ψ is a smooth map, we note that around a point x_0 of depth k its expression in the chart (4.7) is

$$(z_1,\ldots,z_k,\theta_{k+1},\ldots,\theta_n,x^{k+1},\ldots,x^n)\mapsto \left[\sum_{i=k+1}^n\theta_i\mathrm{d}x^i,(w_1,\ldots,w_d)\right],$$

where

$$w_i := \begin{cases} z_i, & \text{if } \ell_i(x_0) = 0, \\ \sqrt{-\ell_i(x)}, & \text{if } \ell_i(x_0) \neq 0. \end{cases}$$

Finally, we observe that this map is a symplectomorphism. Indeed, over $\mathring{\Delta}$, where k=0, it is given by the symplectic map

$$(\theta_1, \dots, \theta_n, x^1, \dots, x^n) \mapsto \left[\sum_{i=1}^n \theta_i dx^i, (\sqrt{-\ell_1(x)}, \dots, \sqrt{-\ell_d(x)}) \right].$$

By density, we conclude that Φ is a symplectic map. Since it is a bijection between manifolds of the same dimension, it is a symplectomorphism.

Example 5.10 (The standard Delzant construction). One can recover the usual Delzant construction of a compact symplectic manifold from the construction in Theorem 5.9 via reduction by stages as follows.

Fix a Delzant polytope $\Delta \subset \mathbb{R}^n$ with d facets. In this case, Theorem 5.9 gives a symplectic toric manifold

$$\mu: ((\mathbb{T}^n \times \mathbb{R}^n \times \mathbb{C}^d) /\!\!/ \mathbb{T}^d, \omega_{\text{red}}) \to \mathbb{R}^n.$$
 (5.4)

If ℓ_1, \ldots, ℓ_d are the primitive boundary defining functions, one has a linear map

$$\mathbb{R}^d \to \mathbb{R}^n, \quad e_a \mapsto \mathrm{d}\ell_a,$$

where $\{e_a\}$ is the standard basis of \mathbb{R}^d . The kernel of this map is a Lie subalgebra $\mathfrak{n} \subset \mathbb{R}^n$, which integrates to a subtorus $N \subset \mathbb{T}^d$. Choosing a subtorus $\mathbb{T}^n \subset \mathbb{T}^d$ complementary to N, one can first perform symplectic reduction by this subtorus. The resulting reduced space is canonically isomorphic to the d-dimensional complex vector space with its canonical symplectic form via the map

$$(\mathbb{T}^n \times \mathbb{R}^n \times \mathbb{C}^d) / \!\!/ \mathbb{T}^d, \omega_{\mathrm{red}}) \to (\mathbb{C}^d, \omega_{\mathrm{st}}), \quad (x, \theta, z) \mapsto (-\theta) \cdot z.$$

Therefore, the symplectic toric manifold (5.4) is canonically isomorphic to

$$\mu: (\mathbb{C}^d /\!\!/ N, \omega_{\text{red}}) \to \mathbb{R}^n.$$
 (5.5)

This is the compact toric symplectic manifold constructed by Delzant [15].

5.4. The general construction. Let (M, Λ) be a connected integral affine manifold and let Δ be a Delzant subspace of finite type. Consider the canonical map

$$(i_{\Delta})_*: \widetilde{\Delta} \to \widetilde{M},$$

from the universal cover of Δ into that of M, relative to a fixed base-point in Δ . The image $\widehat{\Delta} := (i_{\Delta})_*(\widetilde{\Delta})$ is a Delzant subspace of \widetilde{M} . Let Γ be the image of the group homomorphism $(i_{\Delta})_* : \pi_1(\Delta) \to \pi_1(M)$. Note that the canonical Γ -action on \widetilde{M} is by integral affine isomorphisms and preserves $\widehat{\Delta}$. Therefore, it induces an action on the set of primitive boundary defining functions $\mathcal{H}(\widehat{\Delta})$. Fixing an ordering $\mathcal{H}(\Delta) = \{\ell_1, ..., \ell_d\}$, this induces a homomorphism $\Gamma \to \operatorname{Sym}(1, ..., d)$ and, therefore, actions on \mathbb{C}^d and \mathbb{T}^d by coordinate permutations. The group Γ also acts on $\mathcal{T}_{\widetilde{\Lambda}}$ via the cotangent lift of the action on \widetilde{M} . All together, we obtain a Hamiltonian action of the semi-direct product $\Gamma \ltimes \mathbb{T}^d$, with moment map

$$\mu_{\phi} := \phi + (|z_1|^2, ..., |z_d|^2) : (\mathcal{T}_{\widetilde{\Lambda}}, \Omega_{\widetilde{\Lambda}}) \times (\mathbb{C}^d, \omega_{\mathrm{st}}) \to \mathbb{R}^d,$$

where $(\mathcal{T}_{\widetilde{\Lambda}}, \Omega_{\widetilde{\Lambda}})$ is the symplectic torus bundle over $(\widetilde{M}, \widetilde{\Lambda})$.

Theorem 5.11. The $\Gamma \ltimes \mathbb{T}^d$ -action is free on $\mu_{\phi}^{-1}(0)$ and the symplectic quotient

$$((\mathcal{T}_{\widetilde{\Lambda}} \times \mathbb{C}^d) / \!\!/ (\Gamma \ltimes \mathbb{T}^d), \, \omega_{\mathrm{red}})$$

is a toric Hamiltonian \mathcal{T}_{Λ} -space, which is equivalent to the canonical toric Hamiltonian \mathcal{T}_{Λ} -space $\mu_{\Delta}: (S_{\Delta}, \omega_{\Delta}) \to M$.

Proof. The fact that the $\Gamma \ltimes \mathbb{T}^d$ -action on $\mu_{\phi}^{-1}(0)$ is free and proper, follows using that the \mathbb{T}^d -action on this set is free and the Γ -action on \widetilde{M} is free and proper.

Next, note that the symplectic torus bundle $(\mathcal{T}_{\widetilde{\Lambda}}, \Omega_{\widetilde{\Lambda}})$ is canonical isomorphic to the pull-back of $(\mathcal{T}_{\Lambda}, \Omega_{\Lambda})$ along the covering map $\widetilde{M} \to M$. The action of $(\mathcal{T}_{\widetilde{\Lambda}}, \Omega_{\widetilde{\Lambda}})$ on the first factor in $\mathcal{T}_{\widetilde{\Lambda}} \times \mathbb{C}^d$ descends to a Hamiltonian \mathcal{T}_{Λ} -action on the symplectic quotient. This makes it a toric \mathcal{T}_{Λ} -space.

For the last statement, we use the following lemma.

Lemma 5.12. Let (M,Λ) be a connected integral affine manifold, let Δ be a connected Delzant subspace and consider $\widehat{\Delta}$ and Γ as above. The Γ -action on $\widehat{\Delta}$ lifts to a symplectic action on $(S_{\widehat{\Delta}}, \omega_{\widehat{\Delta}})$ and there is an equivalence of Hamiltonian \mathcal{T}_{Λ} -spaces

$$(S_{\widehat{\Delta}}, \omega_{\widehat{\Delta}})/\Gamma \xrightarrow{\mu_{\widehat{\Delta}}} (S_{\Delta}, \omega_{\Delta})$$

where $\underline{\mu_{\widetilde{\Delta}}}$ is the composition of the map $S_{\widehat{\Delta}}/\Gamma \to \widetilde{M}/\Gamma$ induced by $\mu_{\widetilde{\Delta}}$ with the quotient map $\widetilde{M}/\Gamma \to M$.

Proof. This readily follows from the naturality of the construction of the canonical toric space associated to a Delzant subspace (see [28]).

Since \mathbb{T}^d is a normal subgroup of $\Gamma \ltimes \mathbb{T}^d$, there is an induced Γ -action on the symplectic quotient $((\mathcal{T}_{\widetilde{\Lambda}} \times \mathbb{C}^d) /\!\!/ \mathbb{T}^d, \omega_{\mathrm{red}})$. The equivalence between $\mathcal{T}_{\widetilde{\Lambda}}$ -spaces

$$(S_{\widehat{\Delta}}, \omega_{\widehat{\Delta}}) \to (\mathcal{T}_{\widetilde{\Lambda}} \times \mathbb{C}^d) /\!\!/ \mathbb{T}^d, \, \omega_{\mathrm{red}})$$

given by Theorem 5.9 is Γ -equivariant. Passing to the quotients, the equivalence in the statement follows from the previous lemma.

Remark 5.13 (Realizing non-trivial Lagrangian-Chern classes). Theorem 5.11 gives a Delzant type construction for toric \mathcal{T} -spaces with trivial Lagrangian-Chern class. This construction can be extended to the case of non-trivial Lagrangian-Chern class. After possible shrinking M, one can assume that any class in $\check{H}^1(\Delta, \mathcal{T}_{Lag})$ can be realized as the restriction of the Lagrangian-Chern class of a principal \mathcal{T}_{Λ} -space $\mu_P: (P, \omega_P) \to M$. Then a toric \mathcal{T} -space with a non-trivial class, can be realized as a symplectic quotient of the form

$$((q^*P \times \mathbb{C}^d) /\!\!/ (\Gamma \ltimes \mathbb{T}^d), \, \omega_{\text{red}})$$

where $q: \widetilde{M} \to M$ is the covering map.

6. Invariant Kähler metrics I: Lagrangian fibrations

In this section we study \mathcal{T} -invariant Kähler structures on *principal* Hamiltonian \mathcal{T} -spaces, i.e., Lagrangian fibrations. In the next section we will consider toric Hamiltonian \mathcal{T} -spaces.

Definition 6.1. Given a Hamiltonian \mathcal{T} -space $\mu:(S,\omega)\to M$, a \mathcal{T} -invariant Kähler structure is a \mathcal{T} -invariant Kähler metric G on S with Kähler form ω .

By Proposition 2.28, the \mathcal{T} -invariance of the Kähler structure can be expressed as

$$\mathcal{L}_{\alpha(\alpha)}G = 0 \quad \text{if} \quad \nabla \alpha = 0.$$
 (6.1)

Since ω is \mathcal{T} -invariant, this is equivalent to the \mathcal{T} -invariance of the complex structure $J: TS \to TS$, i.e.,

$$\mathcal{L}_{\alpha(\alpha)}J = 0 \quad \text{if} \quad \nabla \alpha = 0.$$
 (6.2)

Given a Lagrangian fibration $\mu:(S,\omega)\to M$ we will call a compatible Kähler metric g on S invariant if it is \mathcal{T}_{Λ} -invariant, where $\Lambda\subset T^*M$ is the induced integral affine structure on the base. Invariant Kähler metrics on a Lagrangian fibration are intimately related to Hessian metrics on the base of the fibration. We recall that a **Hessian metric** on an (integral) affine manifold M is a Riemannian metric g satisfying

$$d^{\nabla}g^{\flat} = 0. \tag{6.3}$$

where $g^{\flat}:TM\to T^*M$ denotes the T^*M -valued form on M given by contraction with g. This condition is equivalent to the existence of a potential for the metric in each (integral) affine chart (U,x^i) with contractible domain, i.e., a function $\phi\in C^\infty(U)$ such that

$$g|_{U} = \sum_{i,j} \frac{\partial^{2} \phi}{\partial x^{i} \partial x^{j}} dx^{i} \otimes dx^{j}.$$

We refer to [33] for details on Hessian metrics.

The main theorem of this section is the following.

Theorem 6.2. Let $\mu:(S,\omega)\to M$ be a a Lagrangian fibration. A choice of invariant Kähler metric G on S makes $\mu:S\to M$ into a Riemannian submersion, with the following properties:

- (i) $(\ker d\mu)^{\perp}$ is a flat Lagrangian connection;
- (ii) The metric g induced on the base M is a Hessian metric.

Conversely, given a flat Lagrangian connection D and a Hessian metric g on M, there is unique invariant Kähler metric G on S inducing g such that $D = (\ker d\mu)^{\perp}$.

Remark 6.3. This theorem shows that the existence problem for invariant Kähler metric on a Lagrangrian fibration reduces to two independent obstruction problems. As discussed in Section 3.4, the obstruction to the existence of a flat Lagrangian connection for a Lagrangian fibration can be expressed in terms of its Lagrangian Chern class. The obstruction to the existence of a Hessian metric on an (integral) affine manifold are more subtle and have been studied by several authors (see, e.g., [33] and the references therein).

Example 6.4. Consider the symplectic torus bundle in Example 2.8. Its base $(\mathbb{T}^2, \mathbb{Z} dx^1 \oplus \mathbb{Z} (dx^2 - x^1 dx^1))$ is an integral affine manifold which does not admit a Hessian metric. Indeed, this being a symplectic torus bundle, it admits a flat Lagrangian connection. However, its total space (\mathcal{T}, Ω) does not admit any Kähler structure, as it is the Kodaira-Thurston symplectic manifold.

Notice that the symplectic manifold (\mathcal{T}, Ω) admits another Lagrangian fibration

$$\mu: \mathcal{T} \to \mathbb{T}^2, \quad [\theta_1, \theta_2, x^1, x^2] \mapsto [\theta_2, x^1].$$

The induced integral affine structure on the base \mathbb{T}^2 is now the standard one. This fibration does not admit a Lagrangian section. In fact, due to Theorem 6.2, it does not even admit a flat Lagrangian connection, since its base $(\mathbb{T}^2, \Lambda_{st})$ admits a Hessian metric, but its total space is not Kähler.

Two equivalent Kähler Lagrangian fibrations induce the same metric on their base. Moreover, given two Kähler Lagrangian fibrations that induce the same Hessian metric on M, an equivalence of the underlying Lagrangian fibrations intertwines the Kähler structures if and only if it intertwines the orthogonal complements to the fibers. Therefore, we conclude the following from Theorems 3.20 and 6.2.

Corollary 6.5. Given an integral affine manifold (M, Λ) , there is a canonical 1:1 correspondence

$$\left\{ \begin{array}{c} \textit{K\"{a}hler Lagrangian fibrations} \\ \mu: (S, \omega, G) \to M \\ \textit{up to equivalence} \end{array} \right\} \stackrel{\sim}{\longleftarrow} \left\{ \begin{array}{c} \textit{Hessian metrics} \\ \textit{g on } M \end{array} \right\} \times \check{H}^1(M, \underline{\mathcal{T}_{Flat}})$$

Choosing an integral affine chart (U, x^i) with contractible domain, there exist action-angle coordinates $(\mu^{-1}(U), x^i, \theta_j)$ (see Remark 3.3) in which the connection takes the form

$$\theta = \sum_{i=1}^{n} \mathrm{d}\theta_i \otimes \mathrm{d}x^i.$$

In such coordinates the invariant Kähler metric G can be written as

$$G = \sum_{i,j=1}^{n} g_{ij} \, \mathrm{d}x^{i} \otimes \mathrm{d}x^{j} + \sum_{i,j=1}^{n} g^{ij} \, \mathrm{d}\theta_{i} \otimes \mathrm{d}\theta_{j}, \tag{6.4}$$

where

$$g_{ij} = \frac{\partial^2 \phi}{\partial x^i \partial x^j},$$

for some function $\phi \in C^{\infty}(U)$, and (g^{ij}) denotes the inverse matrix of (g_{ij}) . The corresponding complex structure takes the form

$$J = \sum_{i,j=1}^{n} g_{ij} \, \mathrm{d}x^{i} \otimes \partial_{\theta_{j}} - \sum_{i,j=1}^{n} g^{ij} \, \mathrm{d}\theta_{i} \otimes \partial_{x^{j}}.$$

6.1. **Proof of Theorem 6.2.** Let Λ be the induced integral affine structure on the base of $\mu: (S, \omega) \to M$. Denote by G a \mathcal{T}_{Λ} -invariant Kähler metric on S. The distribution orthogonal to the fibers

$$D := (\ker d\mu)^{\perp}$$

is \mathcal{T}_{Λ} -invariant and the restriction of G to D is also \mathcal{T}_{Λ} -invariant. It follows that there is a unique Riemannian metric g on M such that $d_x \mu : D_x \to T_p M$ is an isometry for all $x \in \mu^{-1}(p)$, i.e., $\mu : (S, G) \to (M, g)$ is a Riemannian submersion.

Now observe that we can express D has:

$$D = J(\ker d\mu),$$

where $J: TS \to TS$ denotes the complex structure. Since $\ker d\mu$ is Lagrangian, we conclude that D is Lagrangian. It follows also that the vector fields $J_{\alpha}(\alpha)$, with α flat 1-forms, generate D. Now, J is \mathcal{T}_{Λ} -invariant, so by (6.2) we find that:

$$[a(\alpha), J(a(\beta))] = (\mathcal{L}_{a(\alpha)}J) + J([a(\alpha), a(\beta)]) = 0,$$

for any flat 1-forms α and β . Then the vanishing of the Nijenhuis torsion of J gives:

$$[J(a(\alpha)),J(a(\beta))] = J([J(a(\alpha)),a(\beta)] + [a(\alpha),J(a(\beta))]) + [a(\alpha),a(\beta)] = 0.$$

This shows that D is flat, so (i) holds.

To prove that g is an Hessian metric we will check that (6.3) holds:

$$d^{\nabla} g^{\flat}(X,Y) = \nabla_X g^{\flat}(Y) - \nabla_Y g^{\flat}(X) - g^{\flat}([X,Y]) = 0, \quad (X,Y \in \mathfrak{X}(M)).$$

To prove this it is enough to consider vector fields of the form $X = g^{\sharp}(\alpha)$ and $Y = g^{\sharp}(\beta)$, with α and β flat, since these locally generate all vector fields. Therefore, we are left to check that:

$$[g^{\sharp}(\alpha), g^{\sharp}(\beta)] = 0$$
 if $\nabla \alpha = \nabla \beta = 0$.

Now observe that the definition of the metric h yields:

$$\mu_*(J(\alpha(\alpha))) = g^{\sharp}(\alpha).$$

Hence, if α and β are flat, this last relation and the computation above shows that:

$$[g^{\sharp}(\alpha), g^{\sharp}(\beta)] = \mu_*([J(\alpha(\alpha)), J(\alpha(\beta))] = 0.$$

This shows that (ii) holds.

To prove the converse, note that given a flat Lagrangian connection D we can define a unique Riemannian metric G on S by requiring the following properties to hold:

- (a) $\ker d\mu$ and D are orthogonal;
- (b) On D the metric is the unique one that gives isometries

$$d_p \mu : (D_p, G|_{D_p}) \to (T_{\mu(p)}M, g_{\mu(p)});$$

(c) On ker $d\mu$ the metric is the unique one that gives isometries

$$(T_{\mu(p)}^*M, g_{\mu(p)}^{-1}) \to (\ker d_p \mu, G|_{\ker d_p \mu}), \quad \alpha \mapsto a(\alpha)|_p.$$

The resulting Riemannian metric is clearly invariant and we are left to prove that it is a Kähler metric with Kähler form ω .

Given $p \in S$ and $\alpha \in T_{\mu(p)}M$ there is a unique horizontal vector $g^{\sharp}(\alpha) \in D_p$ such that

$$d_p \mu(\widetilde{g^{\sharp}(\alpha)}) = g^{\sharp}(\alpha).$$

Since both sides of the previous equation are linear in α , it follows that there is a unique vector bundle map $J : \ker d\mu \to D$ such that

$$J(\alpha(\alpha)) := \widetilde{q^{\sharp}(\alpha)}. \tag{6.5}$$

Since $TS = \ker d\mu \oplus D$, we obtain a vector bundle map $J: TS \to TS$ by requiring $J^2 = -I$. Notice that J is an invariant almost complex structure

$$\mathcal{L}_{a(\alpha)}J = 0$$
, if $\nabla \alpha = 0$,

and claim that

$$G(X,Y) = \omega(X,JY), \quad (X,Y \in TS).$$

To see this, we check that the bilinear form $\omega(\cdot, J\cdot)$ satisfy properties (a)-(c) above:

- (a) Since $J(\ker d\mu) = D$ and $J(D) = \ker d\mu$, and both distributions are Lagrangian, it follows that they are orthogonal relative to the bilinear form $\omega(\cdot, J\cdot)$.
- (b) By (6.5), it follows that

$$\begin{split} \omega(\widetilde{g^{\sharp}(\alpha)}, J\widetilde{g^{\sharp}(\beta)}) &= -\omega(\widetilde{g^{\sharp}(\alpha)}, \alpha(\beta)) \\ &= (\mu^{*}\beta)(\widetilde{g^{\sharp}(\alpha)}) \\ &= \beta(g^{\sharp}(\alpha)) = h(g^{\sharp}(\alpha), g^{\sharp}(\beta)). \end{split}$$

Hence, the restriction of $d\mu$ to D maps the bilinear form $\omega(\cdot, J\cdot)$ to g.

(c) Again by (6.5), it follows that

$$\begin{split} \omega(a(\alpha),J(a(\beta))) &= \omega(a(\alpha),\widetilde{g^{\sharp}(\beta)})) \\ &= (\mu^*\alpha)(\widetilde{g^{\sharp}(\beta)}) \\ &= \alpha(g^{\sharp}(\beta)) = g^{-1}(\alpha,\beta). \end{split}$$

Hence, the last item is also satisfied.

It remains to show that J is integrable, i.e., that its Nijenhuis torsion vanishes. For this, note that:

$$[a(\alpha), J(a(\beta))] = (\mathcal{L}_{a(\alpha)}J)(a(\beta)) + J([a(\alpha), a(\beta)]) = 0, \quad \text{if} \quad \nabla \alpha = \nabla \beta = 0,$$

$$(6.6)$$

since J is invariant and $\alpha(\alpha)$ and $\alpha(\beta)$ commute. On the other hand, since g is Hessian, we have for flat α and β :

$$g^{\flat}([g^{\sharp}(\alpha), g^{\sharp}(\beta)]) = g^{\flat}([g^{\sharp}(\alpha), g^{\sharp}(\beta)]) - \nabla_{g^{\sharp}(\alpha)}\beta + \nabla_{g^{\sharp}(\beta)}\alpha$$
$$= -\mathrm{d}^{\nabla} g^{\flat}(g^{\sharp}(\alpha), g^{\sharp}(\beta)) = 0.$$

It follows that $[g^{\sharp}(\alpha), g^{\sharp}(\beta)] = 0$, and using (6.5), we conclude that:

$$[J(\alpha(\alpha)), J(\alpha(\beta))] = 0, \quad \text{if} \quad \nabla \alpha = \nabla \beta = 0.$$
 (6.7)

From (6.6) and (6.7), we find that the Nijenhuis torsion of J satisfies:

$$N_J(\alpha(\alpha), \alpha(\beta)) = N_J(\alpha(\alpha), J(\alpha(\beta))) = N_J(J(\alpha(\alpha)), J(\alpha(\beta))) = 0,$$

for any flat sections α and β . Since the vector fields $a(\alpha)$ and $J(a(\alpha))$ locally generate all vector fields, we conclude that $N_J \equiv 0$. This concludes the proof. \square

6.2. Abreu's equation. The scalar curvature of an invariant Kähler structure on a Lagrangian fibration is an invariant smooth function on the total space, and hence corresponds to a smooth function on the base of the fibration. In his work on classical symplectic toric manifolds [1], Abreu gave an explicit expression for this function in terms of integral affine coordinates and observed that the Kähler metric is extremal in the sense of Calabi (see, e.g., [7]) if and only if this function is affine. This generalizes to toric \mathcal{T} -spaces. In this section we consider the case of Lagrangian fibrations.

Recall that for an affine manifold (M, ∇) with a Hessian metric:

• the first Koszul form α is the 1-form on M defined by:

$$\alpha(X)\nu = \nabla_X \nu, \quad X \in \mathfrak{X}(M),$$

with ν the volume density of the Hessian metric,

• the second Koszul form $\beta := \nabla \alpha$ is the symmetric (0, 2)-tensor given by:

$$(\nabla \alpha)(X, Y) = (\nabla_X \alpha)(Y).$$

As will be clear from the proof below, the second Koszul form is an incarnation of the Ricci tensor in Hessian geometry. Further, recall that any integral affine manifold (M, Λ) carries a canonical volume density ν_{Λ} , which in any integral affine chart (U, x^i) is given by

$$\nu_{\Lambda}|_{U} = |\mathrm{d}x^{1} \wedge \cdots \wedge \mathrm{d}x^{n}|.$$

Theorem 6.6. Let $\mu: (S, \omega, G) \to M$ be a Kähler Lagrangian fibration, inducing an integral affine structure Λ on M and a Hessian metric g on (M, Λ) . Let α and β be the first and second Koszul forms of (M, Λ, g) , ν_{Λ} the volume density of Λ and ∇^g the Levi-Civita connection of g. The scalar curvature of G is given by

$$S_G = \operatorname{Tr}_q(2\nabla^g \alpha - \beta) \circ \mu = \operatorname{div}_{\nu_{\Lambda}}(g^{\sharp}(\alpha)) \circ \mu. \tag{6.8}$$

Moreover, G is an extremal metric if and only if S_G is affine, viewed as function on the integral affine manifold (M, Λ) .

Remark 6.7.

(i) Given a compact complex manifold (S, J) and a Kähler class, the Calabi functional is defined on the space of J-compatible Kähler metrics G in the given Kähler class and is given by

$$G \mapsto \int_M S_G^2 \, \mathrm{d}v_G,$$
 (6.9)

where v_G is the Riemannian volume form. A Kähler metric G is called **extremal** if it is a critical point of this functional [7]. Using the corresponding Euler-Lagrange equations one finds (see, e.g., [34]) that a Kähler metric G is extremal if and only if

$$(\operatorname{grad} S_G)^{(1,0)}$$
 is a holomorphic vector field. (E)

We adopt condition (E) as the definition of extremal Kähler metric, whether S is a compact manifold or not.

(ii) In our approach, where we fix a symplectic manifold (S,ω), one has the following equivalent approach. The functional (6.9) is now defined on the space of ω-compatible Kähler metrics G whose complex structure belong to a fixed symplectomorphism class. The critical points are still the Kähler metrics satisfying (E), which in symplectic terms can be reformulated as

$$X_{S_G}$$
 is a Killing vector field. (E')

(iii) In an integral affine chart (U, x^1, \dots, x^n) for (M, Λ) , the first Koszul form is given by

$$\alpha|_{U} = \frac{1}{2} \sum_{i=1}^{n} \frac{\partial \log(\det(g))}{\partial x^{j}}$$

and (6.8) yields

$$S_G|_U = -\frac{1}{2} \sum_{j,k=1}^n \frac{\partial^2 g^{jk}}{\partial x^j \partial x^k},$$

where $g^{-1} = \sum_{j,k=1}^{n} g^{jk} \partial_{x^{j}} \partial_{x^{k}}$. The condition that the function S_{G} is affine then becomes a 4th order PDE for the potential of the metric g, known as Abreu's equation.

Proof. The proof is essentially as in [1]. In view of Corollary 6.5 and Remark 3.21, M can be covered by opens U over which the given Kähler Lagrangian fibration is equivalent to the Lagrangian fibration $(\mathcal{T}_{\Lambda}, \Omega_{\Lambda}) \to M$ equipped with the Kähler structure induced as in Theorem 6.2 by g and the canonical horizontal distribution. So, we can assume that $(S, \omega) = (\mathcal{T}_{\Lambda}, \Omega_{\Lambda})$ and μ is the bundle projection.

Given an integral affine manifold (M,Λ) with a Hessian metric g, there is another integral affine structure on M defined by the lattice dual to

$$\Lambda^{\sharp} := g^{\sharp}(\Lambda) \subset TM.$$

The metric g is Hessian with respect to Λ^{\sharp} as well. This defines the dual Hessian structure, in the terminology of [33]. The second Koszul form of (M, Λ^{\sharp}, g) is (see [33, Lemma 3.1])

$$\beta_{\sharp} = \beta - 2\nabla^g \alpha. \tag{6.10}$$

Like $\mathcal{T}_{\Lambda} = T^*M/\Lambda$, the torus bundle $\pi: TM/\Lambda^{\sharp} \to M$ comes with a canonical horizontal distribution and vector bundle isomorphism $\alpha: \pi^*TM \xrightarrow{\sim} \ker(\mathrm{d}\pi)$. Moreover, TM/Λ^{\sharp} comes with a natural complex structure J given by

$$J(\alpha(X)) = \widetilde{X}, \quad J(\widetilde{X}) = -\alpha(X),$$

and the metric g induces a metric G_{\sharp} on TM/Λ^{\sharp} given by

$$G_{\sharp}(a(X_1) + \widetilde{Y_1}, a(X_2) + \widetilde{Y_2}) = g(X_1, X_2) + g(Y_1, Y_2),$$

where \widetilde{X} denotes the horizontal lift of $X \in TM$. These define a Kähler structure, which corresponds to the above Kähler structure on \mathcal{T}_{Λ} via the torus bundle isomorphism:

$$TM/\Lambda^{\sharp} \xrightarrow{\sim} \mathcal{T}_{\Lambda}$$
 (6.11)

induced by g (see, e.g., [5]). It follows from [33, Proposition 3.5] that the Ricci tensor R_{\sharp} of G_{\sharp} is given by:

$$R_{\sharp}(\alpha(X_1) + \widetilde{Y_1}, \alpha(X_2) + \widetilde{Y_2}) = -\left(\beta_{\sharp}(X_1, X_2) + \beta_{\sharp}(Y_1, Y_2)\right),$$

with β_{\sharp} the second Koszul form of (M, Λ^{\sharp}, g) . From this it readily follows that the scalar curvature S_G (which equals that of G_{\sharp} , since (6.11) is an isometry) is equal to $-\text{Tr}_g(\beta_{\sharp}) \circ \mu$, which proves the first equality in (6.8) in view of (6.10). The second equality follows from Remark 6.7.

A straightforward computation using action-angle coordinates and expression (6.4) for G shows that for a function f, depending only on the action coordinates, the Hamiltonian vector field X_f is a Killing vector field for G if and only if f is affine. This yields the equivalence of the extremal condition (E') with the condition for S_G .

6.3. **Examples.** We will now illustrate how one can use Theorems 6.2 and 6.6 to construct extremal Kähler metrics on Lagrangian fibrations.

Example 6.8. Any metric on $(\mathbb{S}^1, b\mathbb{Z}dx)$, with b > 0, is Hessian (for dimensional reasons) and of the form $f dx^2$, for $f \in C^{\infty}(\mathbb{S}^1)$ strictly positive. It follows from (6.8) that the scalar curvature of any invariant Kähler metric G on the complex torus that induces this Hessian metric is given by

$$S_G = \frac{f''}{2f^2} - \frac{(f')^2}{f^3}. (6.12)$$

Since \mathbb{S}^1 is compact, if S_G is affine, then it is in fact constant. Since f is strictly positive and periodic, it follows that this constant must then be zero. The only solutions to the ODE

$$ff'' - 2(f')^2 = 0,$$

are the constant functions on \mathbb{S}^1 . Therefore, we conclude that the only extremal metrics are those for which f is constant.

As we saw in Example 3.23, any Lagrangian fibration inducing (M,Λ) takes the form

$$\operatorname{pr}_2: (\mathbb{S}^1 \times \mathbb{S}^1, b \, \mathrm{d} y \wedge \mathrm{d} x) \to \mathbb{S}^1.$$

If we fix the Hessian metric $g = b^2 dx^2$ and choose any of the Lagrangian connections D_a in that example, the resulting extremal Kähler metric on $S = \mathbb{T}^2$ is the flat metric

$$G = (a^2 + b^2) dx^2 + 2a dx dy + dy^2.$$

The 2-torus equipped with corresponding complex structure is biholomorphic to the complex torus $\mathbb{C}/\langle 1, \tau \rangle$, where $\tau = a + ib$.

Example 6.9. Consider the Lagrangian fibration $\operatorname{pr}_1: (\mathbb{T}^2 \times \mathbb{T}^2, \omega_a) \to \mathbb{T}^2$ of Examples 3.7 and 3.24, where $a \in \mathbb{R}$ and $\omega_a = \omega_{\operatorname{can}} + \operatorname{ad} x^1 \wedge \operatorname{d} x^2$. This admits the flat Lagrangian connection

$$D = \langle \partial_{x_1}, \partial_{x_2} + a \partial_{\theta_1} \rangle.$$

If we consider the flat Hessian metric $g = dx^1 dx^1 + dx^2 dx^2$ on \mathbb{T}^2 , we obtain from Theorem 6.2 the ω_a -compatible extremal Kähler metric

$$G = dx^1 dx^1 + (1 + a^2) dx^2 dx^2 - 2a dx^1 d\theta_2 + d\theta_1 d\theta_1 + d\theta_2 d\theta_2.$$

Notice that, when one varies $a \in [0,1[$, these give non-isomorphic Kähler metrics.

Example 6.10. Consider the standard integral affine cylinder

$$(M,\Lambda) = (\mathbb{S}^1 \times \mathbb{R}, \mathbb{Z} dx \oplus \mathbb{Z} dh)$$

of Example 2.20. Given a metric

$$q = Adh^2 + 2Bdhdx + Cdx^2$$

on this cylinder, We find that

$$d^{\nabla} g^{\flat}(\partial_h, \partial_x) = (\partial_h B - \partial_x A) dh + (\partial_h C - \partial_x B) dx.$$

Therefore, we have a family of Hessian metrics

$$g = \frac{1}{\tau(h)} dh^2 + \frac{1}{\epsilon(x)} dx^2,$$

where both $\tau(h)$ and $\epsilon(x)$ are strictly positive.

Note that $H^1(M, \mathcal{T}_{Lag}) = H^2(M, \mathcal{O}_{\Lambda}) = 0$, so that any toric \mathcal{T}_{Λ} -space is isomorphic to the symplectic torus bundle over (M, Λ) (see Example 2.20). Applying (6.8), it follows that the scalar curvature of the lifted Kähler metric G on this symplectic torus bundle is given by

$$S_G = -\frac{1}{2}(\tau''(h) + \epsilon''(x)),$$

for any choice of flat Lagrangian connection. The condition for G to be extremal, i.e., for S_G to be affine, amounts to the condition that $\epsilon(x)$ is constant and $\tau(h)$ is a cubic polynomial in h. Since $\tau(h)$ is strictly positive, this leads to the following two possibilities for G to be extremal:

- (i) $\tau(h) = bh^2 + ch + d$ with b > 0 and $c^2 4bd < 0$, in which case G has constant negative scalar curvature $-\frac{b}{2}$;
- (ii) $\tau(h)$ is constant, in which case G has zero scalar curvature.

Example 6.11. Consider the non-standard integral affine cylinder of Example 2.21. Given a general metric on $\mathbb{S}^1 \times]-2, \infty[$, written in the form

$$q = A dh^2 + 2B dh dx + C dx^2.$$

We find that

$$d^{\nabla} g^{\flat}(\partial_h, \partial_x) = \left(\partial_h B - \partial_x A + \frac{B}{h+2}\right) dh + \left(\partial_h C - \partial_x B - \frac{C}{h+2}\right) dx.$$

Therefore, we have a family of Hessian metrics

$$g = \frac{1}{\tau(h)} dh^2 + (h+2)\epsilon dx^2,$$

where $\epsilon > 0$ and $\tau(h)$ is a strictly positive smooth function on $]-2,\infty[$.

Like in the previous example, $H^1(M, \underline{\mathcal{T}_{Lag}}) = H^2(M, \mathcal{O}_{\Lambda}) = 0$, so any toric \mathcal{T}_{Λ} space is isomorphic to the symplectic torus bundle over (M, Λ) (see Example 2.21).
Applying (6.8), it follows that the scalar curvature of the lifted Kähler metric G on this symplectic torus bundle is given by

$$S_G = -\frac{1}{2}\tau''(h) - \frac{1}{h+2}\tau'(h),$$

for any choice of flat Lagrangian connection. Such a metric is extremal if

$$\frac{1}{2}\tau''(h) + \frac{1}{h+2}\tau'(h) = c_1(h+2) + c_0$$

for some constants c_1 and c_0 . One finds that

$$\tau(h) = \frac{c_1}{6}(h+2)^3 + \frac{c_0}{3}(h+2)^2 + \frac{c_2}{h+2} + c_3$$

where c_2 and c_3 are constants of integration. Therefore, choosing the constants such that $\tau(h) > 0$, we obtain extremal Kähler metrics on the symplectic torus bundle. These include examples both with constant and non-constant scalar curvature.

7. INVARIANT KÄHLER METRICS II: TORIC LAGRANGIAN FIBRATIONS

In this section we will generalize the characterization of compatible invariant Kähler metrics on Lagrangian fibrations given in Theorem 6.2 to toric (\mathcal{T}, Ω) -spaces.

Below, in Section 7.1, we will introduce the notion of **hybrid** b-metric for manifolds with corners. These are metrics admitting a specific type of singularity at the boundary and with a well-defined notion of residue at the open facets. Using this notion, we can state the main result of this section as follows.

Theorem 7.1. Let (M, Λ) be an integral affine manifold and let $\mu : (S, \omega) \to M$ be a toric $(\mathcal{T}_{\Lambda}, \Omega_{\Lambda})$ -space, with Delzant subspace $\Delta := \mu(S)$. Denote by $\mathring{\Delta}$ the interior of Δ and set $\mathring{S} := \mu^{-1}(\mathring{\Delta})$. For any invariant Kähler metric G on S compatible with ω , the following hold:

- (i) $(\ker d\mu)^{\perp}|_{\mathring{S}}$ extends to an elliptic connection with zero radial residue over the open facets;
- (ii) The Hessian metric g on $\mathring{\Delta}$, induced via Theorem 6.2, extends to a hybrid b-metric on Δ with the residue at the open facets given by the primitive outward-pointing normals multiplied by $\frac{1}{4\pi}$.

Conversely, given a flat Lagrangian elliptic connection θ with zero radial residues and a hybrid b-metric g on Δ with residues as in (ii), there is a unique invariant compatible Kähler metric G on S inducing g and such that $\ker \theta|_{\mathring{S}} = (\ker d\mu)^{\perp}|_{\mathring{S}}$.

Remark 7.2. The scalar curvature S_G of an invariant Kähler metric G descends to a smooth function on Δ , because it is \mathcal{T} -invariant. It follows from the case of smooth Lagrangian fibrations (by restricting to $\mathring{\Delta}$) that G is an extremal Kähler metric if and only if $S_G: \Delta \to \mathbb{R}$ is an affine function.

By the same reasoning as for Corollary 6.5, we conclude the following from Theorems 4.33 and 7.1.

Corollary 7.3. Given an integral affine manifold (M, Λ) and a Delzant subspace Δ , there is a canonical 1:1 correspondence

$$\left\{ \begin{array}{l} \textit{K\"{a}hler toric \mathcal{T}-spaces} \\ \mu: (S, \omega, G) \to M \text{ with } \mu(S) = \Delta \\ \textit{up to equivalence} \end{array} \right\} \xleftarrow{\sim} \left\{ \begin{array}{l} \textit{Hessian hybrid} \\ \textit{b-metrics } \textit{g on } \Delta \end{array} \right\} \times \check{H}^1(\Delta, \underline{\mathcal{T}_{Flat}})$$

7.1. **Hybrid** b-metrics. Let Δ be a manifold with corners. Given a smooth section $q \in \Gamma^{\infty}({}^bT^*\Delta \otimes T^*\Delta),$ (7.1)

we let $g^{\flat}: {}^bT\Delta \to T^*\Delta$ denote the induced vector bundle map. We also denote by $\widehat{q} \in \Gamma^{\infty}({}^bT^*\Delta \otimes {}^bT^*\Delta)$

the section induced by g via the anchor map of ${}^bT\Delta$, so that $\widehat{g}^{\flat} = \rho^* \circ g^{\flat}$.

Definition 7.4. A smooth section g of ${}^bT^*\Delta \otimes T^*\Delta$ will be called:

- (i) non-degenerate if g_x^{\flat} is an isomorphism for each $x \in \Delta$;
- (ii) symmetric if \hat{g}_x is symmetric for all $x \in \Delta$ (equivalently, for all $x \in \mathring{\Delta}$);
- (iii) **positive semi-definite** if \widehat{g}_x is positive semi-definite for all $x \in \Delta$ (equivalently, for all $x \in \mathring{\Delta}$).

We will call g a hybrid b-metric on Δ if it satisfies all these three properties.

A hybrid b-metric on Δ can be thought of as a smooth Riemannian metric on $\mathring{\Delta}$ with specified singularities at the boundary. In local coordinates, these singularities are of the same type as those of the singular metrics in [1]. Assume Δ is an open in \mathbb{R}^n_k . A smooth section g of ${}^bT^*\Delta\otimes T^*\Delta$ is symmetric if and only if it is of the form

$$g = \sum_{i=1}^{k} \frac{1}{x^i} g_{ii} dx^i \otimes dx^i + \sum_{(i,j) \in I_k} g_{ij} dx^i \otimes dx^j,$$
 (7.2)

for some $g_{ij} \in C^{\infty}(\Delta)$ such that $g_{ij} = g_{ji}$ for all $i, j \in \{1, ..., n\}$, where we denote

$$I_k := \{(i, j) \in \{1, \dots, n\}^2 \mid i \neq j \text{ or } i = j > k\}.$$

If g is symmetric, then

• positive semi-definiteness of g means that for each $x \in \mathring{\Delta}$ the matrix $\mathring{g}(x)$ given by

$$\mathring{g}(x)_{ij} := \begin{cases} \frac{1}{x^i} g_{ii}(x) & \text{if } i = j \le k, \\ g_{ij}(x) & \text{if } (i, j) \in I_k, \end{cases}$$
(7.3)

is positive semi-definite.

• non-degeneracy of g at a point in Δ means that

$$(x^1 \cdot \dots \cdot x^k) \cdot \det(\mathring{g}) \in C^{\infty}(\Delta) \tag{7.4}$$

is non-zero at that point.

Therefore, if g is symmetric and positive semi-definite, then it is non-degenerate if and only if (7.4) is strictly positive on all of Δ . The latter condition is as in [1].

Assume now that Δ is an affine manifold with corners, i.e., Δ has an atlas for which the transition functions are restrictions of affine transformations. An **Hessian hybrid** b-metric g on Δ is a hybrid b-metric satisfying

$$\mathrm{d}^{\nabla} g^{\flat} = 0,$$

where ∇ is the associated flat ${}^bT\Delta$ -connection on $T^*\Delta$. Such a b-metric g admits local potentials around points in the boundary of Δ which are of a very particular form.

Proposition 7.5. Let Δ is an affine manifold with corners and g a Hessian hybrid b-metric on Δ . Around a point $x \in \partial \Delta$ of depth k there exists a chart (U, x^i) centered at x for which

$$g = \sum_{i,j=1}^{n} \frac{\partial^{2} \phi}{\partial x^{i} \partial x^{j}} dx^{i} \otimes dx^{j}$$

where ϕ is a smooth function on $\mathring{\Delta} \cap U$ of the form

$$\phi = \sum_{i=1}^{k} c_i x^i \log(x^i) + f, \quad c_i := g_{ii}(0) \in \mathbb{R}, \quad f \in C^{\infty}(U).$$
 (7.5)

Proof. Fix an affine chart for Δ centered at x onto an open $[0, \delta[^k \times] - \delta, \delta[^{n-k}]$. The fact that g is Hessian means that the coefficients (7.3) of the Riemannian metric on $\mathring{\Delta}$ underlying g satisfy the usual set of differential equations

$$\frac{\partial \mathring{g}^{ij}}{\partial x^l} = \frac{\partial \mathring{g}^{il}}{\partial x^j}, \quad 1 \le i, j, l \le n.$$
 (7.6)

In terms of the functions $g_{ij} \in C^{\infty}(U)$ as in (7.2) this means that

$$\frac{\partial g_{ii}}{\partial x^j} = x^i \frac{\partial g_{ij}}{\partial x^i} \quad \text{if } i \le k, \ i \ne j, \tag{7.7}$$

$$\frac{\partial g_{ij}}{\partial x^l} = \frac{\partial g_{il}}{\partial x^j} \quad \text{if } (i,j), (i,l) \in I_k. \tag{7.8}$$

Since (7.7) vanishes if $x^i = 0$, for $i \in \{1, ..., k\}$ the function

$$x \mapsto g_{ii}(x^1, \dots, x^{i-1}, 0, x^{i+1}, \dots, x^n)$$

is constant on U with value c_i . Since $g_{ii}(x) - c_i$ vanishes if $x^i = 0$, $g_{ii} - c_i$ is of the form $x^i h_i$ for a smooth function $h_i \in C^{\infty}(U)$. The equations (7.7) and (7.8) then express the fact that the 1-forms α_i on U given by

$$\alpha_i = \begin{cases} h_i dx^i + \sum_{j \neq i} g_{ij} dx^j & \text{if } 1 \leq i \leq k, \\ \sum_{j=1}^n g_{ij} dx^j, & \text{if } k < i \leq n, \end{cases}$$

are closed. By the Poincaré lemma for manifolds with corners, each α_i must in fact be exact. So, there are $\phi_i \in C^{\infty}(U)$ such that $\mathrm{d}\phi_i = \alpha_i$. Applying the Poincaré lemma once more, this time to the closed 1-form $\sum_{i=1}^n \phi_i \mathrm{d}x^i$ on U, we find an $f \in C^{\infty}(U)$ such that:

$$\frac{\partial^2 f}{\partial x^i \partial x^j} = \begin{cases} h_i & \text{if } i = j < k, \\ \\ g_{ij} & \text{if } (i, j) \in I_k, \end{cases}$$

with I_k as in (7.3). For this choice of f, the function ϕ defined by (7.5) is indeed a potential for g on $\mathring{\Delta} \cap U$.

Next, we introduce the notion of residue appearing in Theorem 7.1.

Definition 7.6. The **residue** of a hybrid b-metric g at an open facet of Δ is the residue of the vector valued 1-form $g^{\flat} \in \Omega^1({}^bT\Delta, T^*\Delta)$ at the facet (see Definition 4.21).

Example 7.7. Consider a Delzant polytope

$$\Delta := \bigcap_{i=1}^d \{\ell_i \le 0\} \subset \mathbb{R}^n.$$

Then $\mathring{\Delta}$ is contractible, so any Hessian hybrid b-metric on Δ admits a global potential $\phi \in C^{\infty}(\mathring{\Delta})$. By applying successively Proposition 7.5, one concludes that for a Delzant polytope a Hessian hybrid b-metric as in Theorem 7.1 (ii) has potential of the form

$$\phi(x) = -\frac{1}{4\pi} \sum_{i=1}^{d} \ell_i(x) \log \ell_i(x) + f(x),$$

where f is smooth on Δ (not just on $\check{\Delta}$). In view of this and (7.4), we recover the type of singular Hessian metrics on Delzant polytopes appearing in the works of Guillemin [24] and Abreu [1].

Remark 7.8. In [1] Abreu also observed that the difference between any two of his singular hessian metrics on a Delzant polytope extends smoothly over the boundary. This holds more generally for any two hybrid b-metrics on a manifold with corners Δ that have the same residues.

For the proof of Theorem 7.1, it will be useful to also consider the notion dual to that of the singular metrics above. These will be smooth sections

$$\delta \in \Gamma^{\infty}(T\Delta \otimes {}^bT\Delta).$$

Given such a section δ , we denote by $\delta^{\sharp}: T^*\Delta \to {}^bT\Delta$ the induced vector bundle map. We also denote by

$$\widehat{\delta} \in \Gamma^{\infty}(T\Delta \otimes T\Delta)$$

the section induced by δ via the anchor map of ${}^bT\Delta$, so that $\widehat{\delta}^{\sharp}=\rho\circ\delta^{\sharp}$.

Definition 7.9. A smooth section δ of $T\Delta \otimes {}^bT\Delta$ will be called:

- (i) non-degenerate if δ_x^{\sharp} is an isomorphism for each $x \in \Delta$;
- (ii) symmetric if $\hat{\delta}_x$ is symmetric for all $x \in \Delta$ (equivalently, for all $x \in \mathring{\Delta}$);
- (iii) **positive semi-definite** if $\hat{\delta}_x$ is positive semi-definite for all $x \in \Delta$ (equivalently, for all $x \in \Delta$).

We will call δ a hybrid b^* -metric on Δ if it satisfies all these three properties.

A hybrid b^* -metric has an underlying metric on $T^*\mathring{\Delta}$ that extends smoothly to the tensor $\widehat{\delta}$ on all of Δ . Note, however, that $\widehat{\delta}$ is degenerate at the boundary. To see how, suppose that Δ is an open around the origin in \mathbb{R}^n_k . Then a smooth section δ of $T\Delta\otimes {}^bT\Delta$ is symmetric if and only if it is of the form

$$\delta = \sum_{i,j=1,j\neq i}^{k} x^{i} x^{j} \delta^{ij} \partial_{x^{i}} \otimes \partial_{x^{j}} + \sum_{i=1}^{k} x^{i} \delta^{ii} \partial_{x^{i}} \otimes \partial_{x^{i}} + \sum_{i,j=k+1}^{n} \delta^{ij} \partial_{x^{i}} \otimes \partial_{x^{j}}$$

$$+ \sum_{i=1}^{k} \sum_{j=k+1}^{n} x^{i} \delta^{ij} \left(\partial_{x^{i}} \otimes \partial_{x^{j}} + \partial_{x^{j}} \otimes \partial_{x^{i}} \right),$$

$$(7.9)$$

for $\delta^{ij} \in C^{\infty}(\Delta)$ such that $\delta^{ij} = \delta^{ji}$ for all $1 \leq i, j \leq n$. For positive semi-definiteness and non-degeracy, there are criteria analogous to those for hybrid b-metrics.

On a given manifold with corners, hybrid b-metrics are in bijective correspondence with hybrid b^* -metrics, in which a hybrid b-metric g and its corresponding hybrid b^* -metric δ are related by the fact that g^{\flat} and δ^{\sharp} are inverse to each other.

7.2. **Proof of Theorem 7.1.** In this section we prove the two directions of the statement of Theorem 7.1. We start by proving the following local result concerning invariant metrics in the local model discussed in Section 4.1.

Lemma 7.10. Let $(S_{k,n}, \omega_{k,n})$ be a standard local model with the \mathbb{T}^n -action (4.1), and let U be an open in $\Delta := \mathbb{R}^n_k$. Then:

(i) A smooth \mathbb{T}^n -invariant symmetric tensor:

$$G: \mu_{k,n}^{-1}(U \cap \mathring{\Delta}) \to T^*S_{k,n} \otimes T^*S_{k,n}$$

extends smoothly to all of $\mu_{k,n}^{-1}(U)$ if and only if it takes the following form

$$G = \sum_{j=1}^{k} \left(g_{r_{j},r_{j}} (\mathrm{d}r_{j})^{2} + r_{j}^{3} g_{r_{j},\phi_{j}} \mathrm{d}r_{j} \mathrm{d}\phi_{j} + r_{j}^{2} g_{\phi_{j},\phi_{j}} (\mathrm{d}\phi_{j})^{2} \right)$$

$$+ \sum_{j,l=1,j\neq l}^{k} \left(r_{j} r_{l} g_{r_{j},r_{l}} \mathrm{d}r_{j} \mathrm{d}r_{l} + r_{j} r_{l}^{2} g_{r_{j},\phi_{l}} \mathrm{d}r_{j} \mathrm{d}\phi_{l} + r_{j}^{2} r_{l}^{2} g_{\phi_{j},\phi_{l}} \mathrm{d}\phi_{j} \mathrm{d}\phi_{j} \right)$$

$$+ \sum_{j,l=1}^{k,n-k} \left(r_{j} g_{r_{j},x^{l}} \mathrm{d}r_{j} \mathrm{d}x^{l} + r_{j} g_{r_{j},\theta_{l}} \mathrm{d}r_{j} \mathrm{d}\theta_{l} + r_{j}^{2} g_{\phi_{j},x^{l}} \mathrm{d}\phi_{j} \mathrm{d}x^{l} + r_{j}^{2} g_{\phi_{j},\theta_{l}} \mathrm{d}\phi_{j} \mathrm{d}\theta_{l} \right)$$

$$+ \sum_{j,l=1}^{n-k} \left(g_{\theta_{j},\theta_{l}} \mathrm{d}\theta_{j} \mathrm{d}\theta_{l} + g_{x^{j},\theta_{l}} \mathrm{d}x^{j} \mathrm{d}\theta_{l} + g_{x^{j},x^{l}} \mathrm{d}x^{j} \mathrm{d}x^{l} \right)$$

where the coefficients functions are \mathbb{T}^n -invariant smooth functions on $\mu_{k,n}^{-1}(U)$ and $g_{\phi_j,\phi_j} = (2\pi)^2 g_{r_j,r_j}$ over $U \cap \{x^j = 0\}$. (ii) Dually, a smooth \mathbb{T}^n -invariant symmetric tensor

$$G^*: \mu_{k,n}^{-1}(U \cap \mathring{\Delta}) \to TS_{k,n} \otimes TS_{k,n}$$

extends smoothly to all of $\mu_{k,n}^{-1}(U)$ if and only if its coefficients with respect to the coframe on \mathring{S}

$$\mathrm{d}\phi_1,\ldots,\mathrm{d}\phi_k,\frac{1}{r_1}\mathrm{d}r_1,\ldots,\frac{1}{r_k}\mathrm{d}r_k,\mathrm{d}\theta_1,\ldots,\mathrm{d}\theta_{n-k},\mathrm{d}x^1,\ldots,\mathrm{d}x^{n-k}$$

are \mathbb{T}^n -invariant smooth functions on $\mu_{k,n}^{-1}(U)$, with the exception of the following coefficients, which take the form

$$G^*\left(\frac{1}{r_j}dr_j, \frac{1}{r_j}dr_j\right) = \frac{1}{r_j^2}g_{r_j, r_j}^*, \quad G^*\left(d\phi_j, d\phi_j\right) = \frac{1}{r_j^2}g_{\phi_j, \phi_j}^*,$$

with g_{r_j,r_j}^* and g_{ϕ_j,ϕ_j}^* \mathbb{T}^n -invariant smooth functions on $\mu_{k,n}^{-1}(U)$ such that $g_{\phi_i,\phi_i}^* = (2\pi)^2 g_{r_i,r_i}^* \text{ over } U \cap \{x^j = 0\}.$

Proof. The backward implication in (i) readily follows by expressing the coefficients of G with respect to the frame:

$$\partial_{u_1}, \partial_{v_1}, \dots, \partial_{u_k}, \partial_{v_k}, \partial_{\theta_1}, \dots, \partial_{\theta_{n-k}}, \partial_{x^1}, \dots, \partial_{x^{n-k}}$$

on U in terms of the coefficients with respect to the frame (4.5) on \mathring{U} . For the forward implication, suppose that G extends smoothly to all of $\mu_{k,n}^{-1}(U)$. By continuity this extension is T-invariant as well, hence so are its coefficient functions with respect to the frame (4.5). Applying Proposition 4.6 to these, it follows that the coefficients in the last 3 lines of the formula for G are of the desired form. Moreover, it follows that there are \mathbb{T}^n -invariant smooth functions $g_{\phi_i,\phi_i},g_{r_i,r_i},\widetilde{g}_{\phi_i,r_i}$ on $\mu_{k,n}^{-1}(U)$ such that:

$$G\left(\partial_{\phi_{j}}, \partial_{\phi_{j}}\right) = r_{j}^{2} g_{\phi_{j}, \phi_{j}},$$

$$G\left(r_{j} \partial_{r_{j}}, r_{j} \partial_{r_{j}}\right) = r_{j}^{2} g_{r_{j}, r_{j}},$$

$$G\left(\partial_{\phi_{i}}, r_{j} \partial_{r_{i}}\right) = r_{i}^{2} \widetilde{g}_{\phi_{i}, r_{i}}.$$

Denote the smooth extension of G to $\mu_{k,n}^{-1}(U)$ by \widehat{G} . Comparing the limits of the function $\widehat{G}(\partial_{u_i}, \partial_{v_i})$ along the two paths:

$$\mathbb{R} \ni \varepsilon \mapsto (z_1, \dots, z_{j-1}, \varepsilon, z_{j+1}, \dots, z_k, t, x)$$
$$\mathbb{R} \ni \varepsilon \mapsto (z_1, \dots, z_{j-1}, i\varepsilon, z_{j+1}, \dots, z_k, t, x)$$

as ε tends to zero (for any given $j \in \{1, \ldots, k\}$ and $(z, t, x) \in U \cap \{z_j = 0\}$) leads to the conclusion that $\widetilde{g}_{\phi_j, r_j}$ vanishes over $U \cap \{x^j = 0\}$, so $\widetilde{g}_{\phi_j, r_j} = r_j^2 g_{\phi_j, r_j}$. Computing the same limits for the function $\widehat{G}(\partial_{u_j}, \partial_{u_j})$ shows that g_{ϕ_j, ϕ_j} and $(2\pi)^2 \cdot g_{r_j, r_j}$ coincide over $U \cap \{x^j = 0\}$, which completes the proof of (i). Part (ii) follows from the same type of arguments.

7.2.1. From invariant (Kähler) metrics to hybrid b-metrics. Let $\mu:(S,\omega)\to M$ be a toric $(\mathcal{T}_{\Lambda},\Omega_{\Lambda})$ -space with Delzant subspace $\Delta:=\mu(S)$. Further, let G be a ω -compatible invariant Kähler metric on S. As in the proof of Theorem 6.2, the \mathcal{T} -invariance of G implies that there is a unique symmetric, positive semi-definite section $\hat{\delta} \in \Gamma^{\infty}(T\Delta \otimes T\Delta)$ making the following diagrams commute

$$TS \xrightarrow{G^{\flat}} T^{*}S \qquad T^{*}S \xrightarrow{(G^{\flat})^{-1}} TS$$

$$\downarrow a^{\uparrow} \qquad \downarrow d\mu \qquad (7.10)$$

$$\mu^{*}(T^{*}\Delta) \xrightarrow{\widehat{\delta}^{\sharp}} \mu^{*}(T\Delta) \qquad \mu^{*}(T^{*}\Delta) \xrightarrow{\widehat{\delta}^{\sharp}} \mu^{*}(T\Delta)$$

The tensor $\hat{\delta}$ extends the metric on $T^*\mathring{\Delta}$ dual to the unique Riemannian metric on g on $\mathring{\Delta}$ making $\mu: (\mathring{S}, G) \to (\mathring{\Delta}, g)$ a Riemannian submersion. For each locally defined 1-form α on Δ the vector field $(G^{\flat})^{-1}(\mu^*\alpha)$ is \mathcal{T} -invariant, since both $\mu^*\alpha$ and G are. Therefore, $(G^{\flat})^{-1} \circ (d\mu)^*$ lifts to a unique vector bundle map:

$$\begin{array}{ccc}
 & & & \mu TS \\
 & & & \downarrow \rho \\
 & \downarrow \rho$$

From this and the commutativity of the right-hand square in (7.10), it follows that $\hat{\delta}^{\sharp}$ takes 1-forms on Δ to b-vector fields. Therefore, δ lifts to a symmetric and positive semi-definite section $\delta \in \Gamma^{\infty}(T\Delta \otimes {}^bT\Delta)$ making the following digrams commute

$$\begin{array}{cccc}
 & & \mu T S \\
 & & \downarrow \rho & & \downarrow \mu_* \\
 & & & \downarrow \mu_* & & \downarrow \mu_* \\
 & & & & \downarrow \mu^* & & \downarrow \mu^* \\
 & & & & \downarrow \mu^* & & \downarrow \mu^* & & \downarrow \mu^* \\
 & & & & & \downarrow \mu^* & \downarrow \mu^* & & \downarrow \mu^* & \downarrow \mu$$

with μ_* as in Proposition 4.22. In what follows, we will show that δ is non-degenerate, so that it is a hybrid b^* -metric on Δ . Its dual will then be the hybrid b-metric on Δ extending the Riemannian metric g, as in (i). Moreover, by commutativity of the right-hand triangle in (7.12), the composite

$$\mu^*({}^bT\Delta) \xrightarrow{(\delta^{\sharp})^{-1}} \mu^*(T^*\Delta) \xrightarrow{h} {}^{\mu}TS$$
 (7.13)

will be a section of μ_* , which gives the extension of $(\ker d\mu)^{\perp}|_{\mathring{S}}$ to the elliptic connection θ in (i).

It remains to prove that:

- (i) δ is non-degenerate at each $x \in \partial \Delta$;
- (ii) the residue of δ at each open facet is the primitive outward-pointing normal multiplied by $\frac{1}{4\pi}$;
- (iii) θ has zero radial residue.

Let us fix $x \in \partial \Delta$ and standard toric coordinates (z_i, θ_j, x^j) centered at x (see Section 4.1). In these coordinates, the smooth section δ of $T\Delta \otimes {}^bT\Delta$ takes the form (7.9), so we can write the map $\delta_x^{\sharp} : T_x^*\Delta \to {}^bT_x\Delta$ as a matrix of the form

$$\frac{\begin{pmatrix} D_k & D_{n-k,k} \\ 0 & D_{n-k} \end{pmatrix}}{},$$
(7.14)

with respect to standard bases of $T_x^*\Delta$ and ${}^bT_x\Delta$ for $\Delta=\mathbb{R}^n_k$, where D_k is the diagonal k by k matrix with i^{th} diagonal entry $\delta^{ii}(x)$, D_{n-k} is the n-k by n-k matrix with (i,j)-entry $\delta^{k+i,k+j}(x)$, and similarly for $D_{n-k,k}$. Since

$$\partial_{\phi_1}, \dots, \partial_{\phi_k}, \partial_{\theta_1}, \dots, \partial_{\theta_{n-k}},$$

are the vector fields associated to standard coframe on \mathbb{R}^n by the infinitesimal action α , it follows from part (i) of Lemma 7.10 and the left diagram in (7.10) that

$$\delta^{ij} = \begin{cases} g_{\phi_{i},\phi_{j}} & \text{if } i, j \leq k, \\ g_{\phi_{i},\theta_{j-k}} & \text{if } i \leq k, \ j \geq k+1, \\ g_{\phi_{j},\theta_{i-k}} & \text{if } i \geq k+1, \ j \leq k, \\ g_{\theta_{i-k},\theta_{j-k}} & \text{if } i \geq k+1, \ j \geq k+1. \end{cases}$$

$$(7.15)$$

From this and the fact that G is positive definite, it follows that the functions δ^{ii} are strictly positive on Δ and the matrix (7.14) is invertible. This proves item (i).

For items (ii) and (iii) we can further assume that the depth of x is 1, i.e., k = 1. We are left to show that $\delta^{11}(x) = 4\pi$. Since

$$2rdr, dx^1, \dots, dx^{n-1},$$

are the 1-forms obtained by pulling back the standard coframe on \mathbb{R}^n along μ , it follows from part (ii) of Lemma 7.10 and the right diagram in (7.10) that

$$\delta^{ij} = \begin{cases}
4 g_{r,r}^*, \\
2 g_{r,x^{j-1}}^* & \text{if } j \ge 2, \\
2 g_{r,x^{i-1}}^* & \text{if } i \ge 2, \\
g_{x^{i-1},x^{j-1}}^* & \text{if } i \ge 2, j \ge 2.
\end{cases}$$
(7.16)

By considering the coefficient functions of g with respect to the frame

$$\frac{1}{r}\partial_{\phi}, \partial_{r}, \partial_{\theta_{1}}, \dots, \partial_{\theta_{n-1}}, \partial_{x^{1}}, \dots, \partial_{x^{n-1}}$$

over \mathring{S} and those of g^* with respect to the dual coframe

$$rd\phi, dr, d\theta_1, \dots, d\theta_{n-1}, dx^1, \dots, dx^{n-1}$$

over \mathring{S} , we obtain mutually inverse matrices of functions that converge as z tends to zero. Comparing the two limits as z tends to zero leads to the conclusion that

$$q_{r,r}^*(x) q_{r,r}(x) = 1.$$

Combined with the fact that $g_{\phi,\phi}(x) = (2\pi)^2 g_{r,r}(x)$ by Lemma 7.10, and with (7.15) and (7.16), it follows that $\delta^{11}(x) = 4\pi$.

To prove item (iii), we ought to show that, for any b-vector field ν that is Euler-like with respect to a open facet F, the lift of 2ν along (7.13) is Euler-like with

respect to S_F . In view of Remark 4.20, we can assume that $\nu = x^1 \partial_{x^1}$. The lift of the b-vector field $2x^1 \partial_{x^1}$ is of the form

$$\widetilde{2x^1\partial_{x^1}} = r\partial_r + f^\phi\partial_\phi + \sum_{i=1}^{n-1} f_j^\theta\partial_{\theta_j},$$

where f^{ϕ} and f_{j}^{θ} are \mathbb{T}^{n} -invariant smooth functions on $\mu_{1,n}^{-1}(U)$. By Remark 4.24, it is enough to show that $f^{\phi}(x) = f_{1}^{\theta}(x) = \cdots = f_{n-1}^{\theta}(x) = 0$ whenever $x^{1} = 0$. Note that over \mathring{S} one has

$$0 = g\left(\widetilde{2x^{1}\partial_{x^{1}}}, \partial_{\theta_{l}}\right) = r^{2} g_{r,\theta_{l}} + g_{\phi,\theta_{l}} f^{\phi} + \sum_{j=1}^{n-1} g_{\theta_{j},\theta_{l}} f_{j}^{\theta},$$

$$0 = \frac{1}{r^2} g\left(\widetilde{2x^1 \partial_{x^1}}, \partial_{\phi}\right) = r^2 g_{\phi,r} + g_{\phi,\phi} f^{\phi} + \sum_{j=1}^{n-1} g_{\phi,\theta_j} f_j^{\theta},$$

where we first we used that $\ker(\mathrm{d}\mu)$ and \mathcal{L} are orthogonal over S, and then we applied Lemma 7.10. In view of (7.15), letting z tend to zero it follows that $(f^{\phi}(x), f_1^{\theta}(x), \dots, f_{n-1}^{\theta}(x))$ belongs to the kernel of the invertible matrix (7.14) whenever $x^1 = 0$. So, $f^{\phi}(x) = f_1^{\theta}(x) = \dots = f_{n-1}^{\theta}(x) = 0$ if $x^1 = 0$.

This concludes the proof of one direction of Theorem 7.1.

7.2.2. From hybrid b-metrics to invariant (Kähler) metrics. Let $\mu:(S,\omega)\to M$ be a toric $(\mathcal{T}_{\Lambda},\Omega_{\Lambda})$ -space with Delzant subspace $\Delta:=\mu(S)$. Further, let θ be an elliptic connection and let g be a hybrid b-metric on Δ as in the statement of the theorem. We use δ to denote the corresponding hybrid b^* -metric and we let G be the unique invariant ω -compatible Kähler metric on \mathring{S} such that $\mu:(\mathring{S},G)\to(\mathring{\Delta},g)$ is a Riemannian submersion and $\ker\theta|_{\mathring{S}}=(\ker\mathrm{d}\mu)^{\perp}|_{\mathring{S}}$. By the proof of Theorem 6.2, this data satisfies (7.10) on \mathring{S} . We ought to show that G extends to a Riemannian metric on all of S. This extension is then automatically invariant and compatible with ω , due to density of \mathring{S} .

First, we will show that G extends smoothly to S as a tensor. Since this is a local property, we can verify this in standard toric coordinates (z, θ, x) by showing that the coefficients of G are of the form in part (i) of Lemma 7.10. Because the left square in (7.10) commutes, the coefficients of G involving only

$$\partial_{\phi_1}, \dots, \partial_{\phi_k}, \partial_{\theta_1}, \dots, \partial_{\theta_{n-k}}$$

are of this form, with the required \mathbb{T}^n -invariant smooth functions on $\mu_{k,n}^{-1}(U)$ given by the pull-backs of the corresponding coefficients δ^{ij} of δ , as in (7.9). For the coefficients of G involving $r_i \partial_{r_i}$, notice that the horizontal lift of $2x^i \partial_{x^i}$ must be of the form

$$\widetilde{2x^i\partial_{x^i}} = r_i\partial_{r_i} + r_i^2 \left(\sum_{j=1}^k f_{i,j}^\phi \partial_{\phi_j} + \sum_{j=1}^{n-k} f_{i,j}^\theta \partial_{\theta_j}\right),\tag{7.17}$$

where f_j^{ϕ} and f_j^{θ} are \mathbb{T}^n -invariant smooth functions on $\mu_{k,n}^{-1}(U)$. Indeed, this follows from the condition in (ii) in Theorem 7.1, Remarks 4.20 and 4.24, and Proposition 4.6. Since the horizontal lift is orthogonal to $\ker d\mu$, it follows that the coefficients $G(r_i\partial_{r_i},\partial_{\phi_l})$ and $G(r_i\partial_{r_i},\partial_{\theta_l})$ are of the required form, and that

$$G\left(\widetilde{2x^i\partial_{x^i}}, \widetilde{2x^l\partial_{x^l}}\right) = G\left(\widetilde{2x^i\partial_{x^i}}, r_l\partial_{r_l}\right). \tag{7.18}$$

for $i, l \leq k$. Since μ is a Riemannian submersion, it holds that:

$$G\left(\widetilde{2x^i\partial_{x^i}}, \widetilde{2x^l\partial_{x^l}}\right) = \begin{cases} r_i^2r_l^2\mu^*(g_{il}) & \text{if } i \neq l, \\ r_i^2\mu^*(g_{ii}) & \text{if } i = l, \end{cases}$$

with $g_{il} \in \mathcal{C}^{\infty}(U)$ as in (7.2). So, it follows from (7.18) that the coefficients $G(r_i \partial_{r_i}, r_l \partial_{r_l})$ are also of the required form, and that

$$g_{\phi_i,\phi_i} = \mu_{k,n}^*(\delta^{ii})$$
 and $g_{r_i,r_i} = \mu_{k,n}^*(g_{ii})$ over $x^i = 0$.

Since g^{\flat} and δ^{\sharp} are inverse to each other, it holds that $g_{ii}(x)\delta^{ii}(x)=1$ when $x^{i}=0$. By the assumption on the residue of g, one has that $g_{ii}(x)=\frac{1}{4\pi}$ when $x^{i}=0$. Hence, it follows that

$$g_{\phi_i,\phi_i} = (2\pi)^2 g_{r_i,r_i}$$
 over $x^i = 0$.

By similar arguments, the other coefficients are of the required form as well. So, the tensor G indeed extends smoothly to all of S. This extension is symmetric and positive semi-definite, since it is so on the dense subset \mathring{S} . So, to conclude that it is a Riemannian metric on S, it suffices to show that the dual metric G^* on \mathring{S} extends smoothly, as a tensor, to all of S. This follows from an argument along the same lines as that for G, by instead using part (ii) of Lemma 7.10 and the coframe over $\mathring{S} \cap \mu^{-1}(U)$ dual to the frame:

$$\widetilde{2x^1}\widetilde{\partial_{x^1}},\ldots,\widetilde{2x^k}\widetilde{\partial_{x^k}},\widetilde{\partial_{x^{k+1}}},\ldots,\widetilde{\partial_{x^n}},\partial_{\phi_1},\ldots,\partial_{\phi_k},\partial_{\theta_1},\ldots,\partial_{\theta_{n-k}}.$$

This concludes the proof of Theorem 7.1.

7.3. Examples.

Example 7.11. Consider the integral affine cylinder $(M, \Lambda) = (\mathbb{S}^1 \times \mathbb{R}, \mathbb{Z} dx \oplus \mathbb{Z} dh)$ and the Delzant subspace $\Delta = \mathbb{S}^1 \times [-1, 1]$ as in Example 4.35. Further, consider the corresponding canonical toric \mathcal{T}_{Λ} -space $\mu : (\mathbb{T}^2 \times \mathbb{S}^2, \omega) \to \mathbb{S}^1 \times \mathbb{R}$ described in Example 2.20. As in Example 6.10, there are Hessian hybrid b-metrics of the form

$$g = \left(\frac{1}{4\pi(1-h^2)} + f(h)\right) dh^2 + c(x) dx^2,$$

where now the singular term is so that the residue at both facets is $\frac{1}{4\pi}$. By a computation as in Example 6.10, we find that the extremal condition holds if and only if f = 0 and c(x) is constant. Using the flat Lagrangian elliptic connection $D_{a,b}$ of Example 4.35, Theorem 7.1 gives the family of ω -compatible extremal Kähler metrics

$$G = \left(\frac{1}{\tau(h)} + b^2 \tau(h)\right) dh^2 + \tau(h) d\phi (d\phi - 2bdh) + g_{\mathbb{T}^2}, \tag{7.19}$$

where $\tau(h) = 4\pi(1-h^2)$ and $g_{\mathbb{T}^2}$ is the flat metric on the torus given by

$$g_{\mathbb{T}^2} = \frac{1}{c} ((a^2 + c^2) dx^2 - 2a dx dy + dy^2).$$

Note that when a=b=0 and c=1 we recover the product of the round metric on \mathbb{S}^2 with the standard flat metric on \mathbb{T}^2 .

Example 7.12. Let $(M, \Lambda) = (\mathbb{S}^1 \times] - 2, \infty[, \mathbb{Z}((h+2)dx + xdh) \oplus \mathbb{Z}dh)$ be the non-standard integral affine cylinder and consider the Delzant subspace $\Delta = \mathbb{S}^1 \times [-1, 1]$ (see Example 4.36). Further, we consider the corresponding canonical toric \mathcal{T}_{Λ} -space $\mu: (\mathbb{T}^2 \times \mathbb{S}^2, \omega) \to \mathbb{S}^1 \times] - 2, \infty[$, which is described in Example 2.21. Similar to Example 6.11, there are Hessian hybrid b-metrics of the form

$$g = \left(\frac{1}{4\pi(1-h^2)} + f(h)\right) dh^2 + (h+2)c dx^2,$$

with c>0 a constant and $f\in C^{\infty}(]-2,\infty[)$. Let us define a function $\tau(h)$ by

$$\frac{1}{\tau(h)} := \frac{1}{4\pi(1-h^2)} + f(h).$$

One finds the boundary conditions

$$\tau(\pm 1) = 0, \quad \tau'(\pm 1) = \mp 8\pi.$$

Applying formula (6.8), one finds that

$$S_G = -\frac{1}{2}\tau''(h) - \frac{\tau'(h)}{h+2}.$$

Proceeding as in Example 6.11, taking into account the boundary conditions, one finds that S_G is an affine function if and only if

$$\tau(h) = -\frac{4\pi}{11} \left(2(h+2)^3 - 5(h+2)^2 - 15 + \frac{18}{h+2} \right).$$

This gives the affine function

$$S_G = \frac{4\pi}{11}(12h + 9).$$

The corresponding hybrid Hessian b-metric takes the form

$$g = \left(\frac{1}{4\pi(1-h^2)} + \frac{1}{2\pi(2h^2 + 11h + 20)}\right) dh^2 + (h+2)c dx^2.$$

We can now use the family of elliptic Lagrangian connections $D_{a,b}$ on the \mathcal{T}_{Λ} -space $\mu: (\mathbb{T}^2 \times \mathbb{S}^2, \omega) \to \mathbb{S}^1 \times]-2, \infty[$ discussed in Example 4.36 to lift g to the family of ω -compatible extremal Kähler metrics

$$G = \left(\frac{1}{\tau(h)} + b^2 \tau(h)\right) dh^2 + \tau(h)\theta(\theta - 2bdh) + (h+2)g_{\mathbb{T}^2}, \tag{7.20}$$

where $\theta := (xdy + d\phi)$ and $g_{\mathbb{T}^2}$ is the flat metric on the torus given by

$$g_{\mathbb{T}^2} = \frac{1}{c} ((a^2 + c^2) dx^2 - 2a dx dy + dy^2).$$

Notice the similarity between formulas (7.19) and (7.20). When b=0, the metric (7.20) appears as a special case of the metrics considered by Apostolov et al. [2] (see the formula in Theorem 3, loc. cit.). The precise relation between the approach followed here and the results in [2] will be discussed in a sequel to this paper.

7.4. Invariant Kähler metrics via Kähler reduction. The Delzant-type construction from Section 5 (see Theorem 5.11) can be used to construct invariant Kähler metrics via Kähler reduction, much like in [24].

Let (M,Λ) be a connected integral affine manifold and $\Delta\subset M$ a Delzant subspace of finite type. Assume that M admits a Hessian metric g and let \widetilde{g} be its lift to the universal covering space $(\widetilde{M},\widetilde{\Lambda})$. Let $G_{\widetilde{\Lambda}}$ be the $\Omega_{\widetilde{\Lambda}}$ -compatible invariant Kähler metric on $\mathcal{T}_{\widetilde{\Lambda}}$ obtained by lifting \widetilde{g} via the canonical Lagrangian connection.

Proposition 7.13. Let (M, Λ, g) be a connected integral affine Hessian manifold and let Δ be a Delzant subspace of finite type. Consider the product metric $G_{\widetilde{\Lambda}} \times g_{\rm st}$ on $\mathcal{T}_{\widetilde{\Lambda}} \times \mathbb{C}^d$. The Hessian hybrid b-metric g_{Δ} on Δ induced by the reduced Kähler metric on the symplectic quotient

$$((\mathcal{T}_{\widetilde{\Lambda}} \times \mathbb{C}^d) / \!\!/ (\Gamma \ltimes \mathbb{T}^d), \, \omega_{\mathrm{red}})$$

takes the form

$$g_{\Delta} = g + \operatorname{Hess}_{\Lambda}(\phi),$$

where ϕ is the smooth function on $\mathring{\Delta}$ corresponding to the function on \widetilde{M} given by

$$\widetilde{\phi} = -\frac{1}{4\pi} \sum_{i=1}^{d} \ell_i \log |\ell_i|. \tag{7.21}$$

The proof follows the usual Kähler reduction recipe: one restricts the metric to the zero level, obtaining a $(\Gamma \ltimes \mathbb{T}^d)$ -invariant metric, that then descends to the symplectic quotient, yielding the expression in the theorem. Notice that, although each term in (7.21) is a function on \widetilde{M} which may fail to descend to $\mathring{\Delta}$, the sum does descend to a smooth function, since the Γ -action permutes the primitive boundary defining functions.

Remark 7.14. For a Delzant polytope, Guillemin showed in [24] that, if one applies Kähler reduction to the standard Delzant construction, one obtains an invariant Kähler metric on the symplectic toric manifold which induces a Hessian metric on $\mathring{\Delta}$ with potential given by (7.21). Our Delzant type construction is different from the standard one (see Remark 5.10) and results in the presence of the original Hessian metric on M as an additional term. This is unavoidable since for a general Delzant subspace of finite type there may not exist a global potential. Moreover, the Hessian of (7.21) may not even define a metric in $\mathring{\Delta}$. This is the case, for instance, in Examples 7.11 and 7.12. Also, the Hessian hybrid b-metrics constructed in those examples show that Δ may carry Hessian hybrid b-metrics with residues as in Theorem 7.1 which are not obtained by Kähler reduction as in Proposition 7.13.

Corollary 7.15. Any finite-type Delzant subspace of a Hessian integral affine manifold admits a Hessian hybrid b-metric with residues as in Theorem 7.1.

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