

universal form

$$\frac{Y_{a,s}^+ Y_{a,s}^-}{Y_{a+1,s} Y_{a-1,s}} = \frac{(1 + Y_{a,s+1})(1 + Y_{a,s-1})}{(1 + Y_{a+1,s})(1 + Y_{a-1,s})}. \quad (1)$$

Throughout the paper we denote $f^\pm = f(u \pm i/2)$ and $f^{[a]} = f(u + ia/2)$. At the boundaries of the fat-hook we have $Y_{0,s} = \infty$, $Y_{2,|s|>2} = \infty$ and $Y_{a>2,\pm 2} = 0$. The product $Y_{23}Y_{32}$ should be finite so that $Y_{2,\pm 2}$ are finite.

The anomalous dimension of a particular operator (or the energy of a string state in the AdS context) is defined through the corresponding solution of the Y-system and is given by the formula ($E = \Delta - J$)

$$E = \sum_j \epsilon_1(u_{4,j}) + \sum_{a=1}^{\infty} \int_{-\infty}^{\infty} \frac{du}{2\pi i} \frac{\partial \epsilon_a^*}{\partial u} \log(1 + Y_{a,0}^*(u)). \quad (2)$$

In terms of $x(u)$ defined by $u/g = x + 1/x$, the energy dispersion relation reads $\epsilon_a(u) = a + \frac{2ig}{x^{[+a]}} - \frac{2ig}{x^{[-a]}}$, evaluated in the physical kinematics i.e. for $|x^{[\pm a]}| > 1$, while $\epsilon_a^*(u)$ is given by the same expression evaluated in the mirror kinematics where $|x^{[s]}| > 1$ for $a \geq s \geq -a + 1$ and $|x^{[-a]}| < 1$ [13]. Similarly the asterisk in $Y_{a,0}^*$ indicates that this function should also be evaluated in mirror kinematics. Finally, the Bethe roots are defined by the finite L Bethe equations

$$Y_{1,0}(u_{4,j}) = -1, \quad (3)$$

where this expression is evaluated at physical kinematics.

The Y-system is equivalent to an integrable discrete dynamics on a T-shaped ‘‘fat hook’’ drawn in Fig.1 given by Hirota equation [17]

$$T_{a,s}^+ T_{a,s}^- = T_{a+1,s} T_{a-1,s} + T_{a,s+1} T_{a,s-1}, \quad (4)$$

$$\text{where } Y_{a,s} = \frac{T_{a,s+1} T_{a,s-1}}{T_{a+1,s} T_{a-1,s}}. \quad (5)$$

The non-zero $T_{a,s}$ are represented by all visible circles in Fig.1. Hirota equation is invariant w.r.t. the gauge transformations $T_{a,s} \rightarrow g_1^{[a+s]} g_2^{[a-s]} g_3^{[s-a]} g_4^{[-a-s]} T_{a,s}$. Choosing an appropriate gauge we can impose $T_{0,s} = 1$.

Both the Y and the T systems are infinite sets of functional equations which must still be supplied by certain boundary conditions and analyticity properties. Alternatively, we can identify the proper large L solutions to these equations and find T and Y functions at finite L by continuously deforming from this limit [19]. Hopefully this deformation is unique, as in [19]. Such a numerics can be done by means of an integral DdV-like equation or by some sort of truncation of the Y-system equations.

LARGE L SOLUTIONS AND ABA

We expect the Y-functions to be smooth and regular at large u : $Y_{a,s \neq 0}(u \rightarrow \infty) \rightarrow \text{const}$, whereas for the

black, momentum carrying nodes in Fig.1, we impose the asymptotics

$$Y_{a \geq 1,0}^* \sim \left(\frac{x^{[-a]}}{x^{[+a]}} \right)^L \quad (6)$$

for large L or u . As we will now show these asymptotics are consistent with the Y-system (1). Indeed, when L is large $Y_{a,0}$ goes to zero and we can drop the denominator in the r.h.s. of (1) at $s = 0$. Using $1 + Y_{a,s} = \frac{T_{a,s}^+ T_{a,s}^-}{T_{a+1,s} T_{a-1,s}}$ following from (4)-(5), we have

$$\frac{Y_{a,0}^+ Y_{a,0}^-}{Y_{a-1,0} Y_{a+1,0}} \simeq \left(\frac{T_{a,1}^+ T_{a,1}^-}{T_{a-1,1} T_{a+1,1}} \right) \left(\frac{T_{a,-1}^+ T_{a,-1}^-}{T_{a-1,-1} T_{a+1,-1}} \right), \quad (7)$$

where in the equation for $a = 1$ one should replace $Y_{0,0}$ by 1 as can be seen from (1). From our study of the $O(4)$ σ -model [19] we expect that $T_{a,s \leq 0}$ and $T_{a,s \geq 0}$ cannot be simultaneously finite as $L \rightarrow \infty$. However, in this limit the full T-system splits into two independent $SU(2|2)_{R,L}$ subsystems and, noticing that each factor in the r.h.s. is gauge invariant, we can always choose finite solutions $T_{a,s \leq 0}^R$ and $T_{a,s \geq 0}^L$ and interpret them as one solution of the full T-system in two different gauges (see [19] for more details). These are the transfer matrices associated to the rectangular representations of $SU(2|2)_{R,L}$, described in detail in the next section and in the appendix.

The general solution of this discrete 2D Poisson equation in z and a is then

$$Y_{a,0}(u) \simeq \left(\frac{x^{[-a]}}{x^{[+a]}} \right)^L \frac{\phi^{[-a]}}{\phi^{[+a]}} T_{a,-1}^L T_{a,1}^R \quad (8)$$

where the first two factors in the r.h.s. represent a zero mode of the discrete Laplace equation $\frac{A_a^+ A_a^-}{A_{a-1}^+ A_{a+1}^-} = 1$. Thus we obtained all $Y_{a,0}$, describing for $a > 1$ the AdS/CFT bound states [25], in terms of $T_{a,s}^{L,R}$ up to a single, yet to be fixed, function ϕ . We pulled out the first factor in (8) from the zero mode to explicitly match the asymptotics (6). The second factor will become the product of fused AdS/CFT dressing factors [6, 9, 11] as we shall see below.

ASYMPTOTIC TRANSFER MATRICES

In the large L limit $Y_{a,0}$ are small and the whole Y-system splits into two $SU(2|2)_{L,R}$ fat hooks on Fig.1. The Hirota equation (4) also splits into two independent subsystems. For each of these subsystems there already exists a solution compatible with the group theoretical interpretation of Y and T-systems: $T_{a,-1}^L (T_{1,-s}^L)$ and $T_{a,1}^R (T_{1,s}^R)$ are the transfer matrix eigenvalues of anti-symmetric (symmetric) irreps of the $SU(2|2)_L$ and $SU(2|2)_R$ subgroups of the full $PSU(2,2|4)$ symmetry. It is known [20, 21] that these transfer-matrices can be

easily generated by the usual fusion procedure. Explicit expressions for $T_{a,s}$ are given in the Appendix. E.g.,

$$T_{1,1} = \frac{R^{(+)} R^{(-)}}{R^{(-)}} \left[\frac{Q_2^- Q_3^+}{Q_2 Q_3} - \frac{R^{(-)} Q_3^+}{R^{(+)} Q_3^-} + \frac{Q_2^+ Q_1^-}{Q_2 Q_1^+} - \frac{B^{(+)} Q_1^-}{B^{(+)} Q_1^+} \right] \quad (9)$$

where $Q_l(u) = \prod_{j=1}^{J_l} (u - u_{l,j}) = -R_l(u) B_l(u)$ and

$$R_l^{(\pm)}(u) \equiv \prod_{j=1}^{K_l} \frac{x(u) - x_{l,j}^{\mp}}{(x_{l,j}^{\mp})^{1/2}}, \quad B_l^{(\pm)}(u) \equiv \prod_{j=1}^{K_l} \frac{1}{(x_{l,j}^{\mp})^{1/2}}.$$

The index $l = 1, 2, 3$ corresponds to the roots $x_{1,j}, x_{2,j}, x_{3,j}$ ($x_{7,j}, x_{6,j}, x_{5,j}$) for $T_{1,1}^L$ ($T_{1,1}^R$) in the notations of [7]. $R^{(\pm)}$ and $B^{(\pm)}$ with no subscript l correspond to the roots $x_{4,j}$ of the middle node and R_l, B_l without superscript (+) or (-) are defined with x_j^{\pm} replaced by x_j . The choice (9) is dictated by the condition that the asymptotic BAE's ought to be reproduced from the analyticity of $T_{1,1}$ at the zeroes $u_{1,j}, u_{2,j}, u_{3,j}$ of the denominators. For Q -functions of the left and right wings the ABA's read:

$$1 = \frac{Q_2^+ B^{(-)}}{Q_2^- B^{(+)}} \Big|_{u_{1,k}}, \quad -1 = \frac{Q_2^- Q_1^+ Q_3^+}{Q_2^{++} Q_1^- Q_3^-} \Big|_{u_{2,k}}, \quad 1 = \frac{Q_2^+ R^{(-)}}{Q_2^- R^{(+)}} \Big|_{u_{3,k}} \quad (10)$$

Once the unknown function ϕ is fixed to be

$$\frac{\phi^-}{\phi^+} = S^2 \frac{B^{(+)} R^{(-)}}{B^{(-)} R^{(+)}} \frac{B_{1L}^+ B_{3L}^- B_{1R}^+ B_{3R}^-}{B_{1L}^- B_{3L}^+ B_{1R}^- B_{3R}^+} \quad (11)$$

the Bethe equation (3) yields the middle node equation for the full AdS/CFT ABA of [7] at $u = u_{4,k}$

$$-1 = \left(\frac{x^-}{x^+} \right)^L \left(\frac{Q_4^{++} B_{1L}^- R_{3L}^- B_{1R}^- R_{3R}^-}{Q_4^{--} B_{1L}^+ R_{3L}^+ B_{1R}^+ R_{3R}^+} \right)^\eta \left(\frac{B^{(+)}}{B^{(-)}} \right)^{1-\eta} S^2, \quad (12)$$

where $\eta = -1$ in the present case and the dressing factor is $S(u) = \prod_j \sigma(x(u), x_{4,j})$. The subscripts L, R refer to the wings. We will see in the next section that with the factor (11) $Y_{a,0}$ exhibits crossing invariance and that this choice of the factor allows to reproduce all known results for the first wrapping correction of various operators.

SCALAR FACTOR FROM CROSSING

We will now see that the Y -system constrains the dressing factor by the crossing invariance condition of [9]. The S-matrix $\hat{S}(1, 2)$ of Beisert [8] admits Janik's crossing relation which relates the S-matrix with one argument replaced by $x^\pm \rightarrow 1/x^\pm$ (particle \rightarrow anti-particle) to the initial one. Since the transfer matrices can be constructed as a trace of the product of S-matrices we expect $Y_{a,0}$ to respect this symmetry. Indeed, we notice that under the transformation $x^\pm \rightarrow 1/x^\pm$ (denoted by \star) and complex conjugation, $T_{1,1}$ transforms as $\overline{T_{1,1}^*} = \frac{Q_1^+ Q_3^-}{Q_1^- Q_3^+} \Psi T_{1,1}$,

where $\Psi \equiv \frac{R^{(-)} B^{(+)}}{R^{(+)} B^{(-)}}$. By demanding the combination $ST_{1,1} \frac{B_1^+ B_3^-}{B_1^- B_3^+}$ to be invariant under that transformation we get $\overline{S^*} = \frac{S}{\Psi}$. This renders, using $\frac{R^{(-)}}{B^{(+)}} = \frac{R^{(+)}}{B^{(-)}}$, the relation $SS^* = \frac{R^{(-)} B^{(-)}}{R^{(+)} B^{(+)}}$ which is in fact nothing but the crossing relation for the scalar factor [9]

$$\sigma_{12} \sigma_{\bar{1}2} = \frac{x_2^- x_1^- - x_2^- 1/x_1^- - x_2^+ 1/x_1^+ - x_2^+}{x_2^+ x_1^+ - x_2^- 1/x_1^- - x_2^+ 1/x_1^+ - x_2^-}. \quad (13)$$

Note that crossing does not simply mean $x^\pm \rightarrow 1/x^\pm$, but it is also accompanied by an analytical continuation, so one should be careful with the way the continuation is done because the dressing factor is a multi-valued function of (x_1^\pm, x_2^\pm) . Thus we see that the invariance of $Y_{1,0}$ imposes the crossing transformation rule of the dressing factor. The same invariance property holds for all $Y_{a,0}$.

We conclude that Janik's crossing relation fits nicely with our Y -system. The dressing factor is encoded in the Y -system, as for relativistic models (see [19]).

WEAK COUPLING WRAPPING CORRECTIONS

Here we will reproduce from our Y -system the results of [13, 15] in a rather efficient way and explain how to generalize them to any operator of $\mathcal{N} = 4$ SYM. Notice that the large L solution is now completely fixed by (8),(11) with the transfer matrices for each $SU(2|2)$ wing generated from \mathcal{W} as explained in the Appendix.

To compute the leading wrapping corrections associated to *any* single trace operator it suffices to plug the Bethe roots obtained from the ABA into $Y_{a,0}$ [23]. Next we expand this expression for $g \rightarrow 0$ and substitute it into the sum (2). This ought to be contrasted with the computations in [13],[14] which relied on the explicit form of the S-matrix elements and which are therefore very hard to generalize to generic states.

For example, for the case of two roots $u_{4,1} = -u_{4,2}$ and $L = 2$, satisfying the $SL(2)$ ABA ($u_{4,1} = \frac{1}{2\sqrt{3}} + \mathcal{O}(g^2)$), we find

$$Y_{a,0}^* = g^8 \left(3 \cdot 2^7 \frac{3a^3 + 12au^2 - 4a}{(a^2 + 4u^2)^2} \right)^2 \frac{1}{y_a(u) y_{-a}(u)} \quad (14)$$

where $y_a(u) = 9a^4 - 36a^3 + 72u^2 a^2 + 60a^2 - 144u^2 a - 48a + 144u^4 + 48u^2 + 16$. Plugging this expression into (2) we obtain $(324 + 864\zeta_3 - 1440\zeta_5)g^8$, coinciding with the wrapping correction to the anomalous dimension of Konishi operator $\text{tr}(ZD^2Z - DZDZ)$ of [13, 15].

The Konishi state could also be represented as the operator $\text{tr}[Z, X]^2$ in $SU(2)$ sector. To get the ABA equations for the $SU(2)$ grading we make the following replacement $T_{a,s}^{su(2)} = \overline{T_{s,a}^{sl(2)}}$. The scalar factor (11) becomes $\frac{\phi^-}{\phi^+} = S^2 \frac{Q_4^{++} B_{1L}^- B_{3L}^- B_{1R}^+ B_{3R}^+}{Q_4^{--} B_{1L}^+ B_{3L}^+ B_{1R}^- B_{3R}^-}$ as we can see by

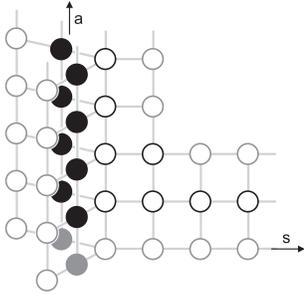


Figure 2: “Fat hook” for AdS_4/CFT_3 . The $OSp(2,2|6)$ symmetry of the ABJM theory, with two momentum carrying nodes, and the $SU(2|2)$ subgroup is manifest in the diagram.

matching with the ABA equations (12) for $\eta = 1$. Repeating the same computation for two magnons, now with $L = 4$, we find precisely the same result for wrapping correction. This is yet another important consistency check of our Y-system.

Another important set of operators are the so called twist two operators for which $L = 2$ (in the $SL(2)$ grading) and the Bethe roots are in a symmetric configuration, $u_{4,2j-1} = -u_{4,2j}$ with $j = 1, \dots, M/2$. Plugging such configuration into the transfer matrices in the appendix and constructing the corresponding $Y_{a,0}$ from (8) we find a perfect match with the results of [14].

AdS_4/CFT_3 CORRESPONDENCE

The recently conjectured [24] AdS_4/CFT_3 correspondence with the ABA formulated in [26], following [27, 28], can be treated similarly to the AdS_5/CFT_4 case. The corresponding Y-system is represented in Fig.2. There are now two sequences of momentum carrying bound-states and the corresponding Y-functions are denoted by $Y_{a,0}^4$ and $Y_{a,0}^{\bar{4}}$. At large L we find $Y_{a,0}^4 \simeq \left(\frac{x^{[-a]}}{x^{[+a]}}\right)^L \frac{\phi_4^{[-a]}}{\phi_4^{[+a]}} T_{a,1}^{su(2)}$, $Y_{a,0}^{\bar{4}} \simeq \left(\frac{x^{[-a]}}{x^{[+a]}}\right)^L \frac{\phi_{\bar{4}}^{[-a]}}{\phi_{\bar{4}}^{[+a]}} T_{a,1}^{su(2)}$ where $\frac{\phi_{\bar{4}}^-}{\phi_4^+} = -S_4 S_{\bar{4}} \frac{Q_4^{++} B_4^- B_3^+}{Q_4^- B_1^+ B_3^-}$ and $\phi_{\bar{4}}$ is given by the same expression with $Q_4 \rightarrow Q_{\bar{4}}$. $T_{a,1}$ can be found from the generating functional \mathcal{W} in the appendix replacing $R^{(+)} \rightarrow R_4^{(+)} R_{\bar{4}}^{(+)}$ etc. Finally $\epsilon_a(u) = \frac{a}{2} + \frac{ih}{x^{[+a]}} - \frac{ih}{x^{[-a]}}$, and in all formulae we should replace g by the interpolating function $h(\lambda) = \lambda + O(\lambda^2)$. The energy is then computed from an expression analogous to (2) which to leading order at small λ yields

$$E = \sum_j \epsilon_1(u_{4,j}) + \sum_j \epsilon_1(u_{\bar{4},j}) - \sum_{a=1}^{\infty} \int_{-\infty}^{\infty} \frac{du}{2\pi} \left(Y_{a,0}^{4*} + Y_{a,0}^{\bar{4}*} \right)$$

Thus, as before we can very easily compute the leading wrapping corrections to any operator of the theory. E.g., for the simplest unprotected length four operator ($L = 2$)

(irrep **20**, see [27] for details) we find $E = 8h^2(\lambda) - 32\lambda^4 + E_{\text{wrapping}}\lambda^4 + O(\lambda^6)$ where $E_{\text{wrapping}} = 32 - 16\zeta(2)$.

APPENDIX: TRANSFER MATRICES

The $SU(2|2)$ transfer matrices for symmetric ($T_{1,s}$) and antisymmetric ($T_{a,1}$) representations can be found from the expansion of the generating functional [20, 21]

$$\begin{aligned} \mathcal{W} &= \left[1 - \frac{Q_1^- B^{(+)} R^{(-)}}{Q_1^+ B^{(-)} R^{(-)}} D \right] \left[1 - \frac{Q_1^- Q_2^{++} R^{(-)}}{Q_1^+ Q_2 R^{(-)}} D \right]^{-1} \times \\ &\times \left[1 - \frac{Q_2^- Q_3^+ R^{(-)}}{Q_2 Q_3^- R^{(-)}} D \right]^{-1} \left[1 - \frac{Q_3^+}{Q_3} D \right], \quad D = e^{-i\partial_u} \\ \text{as } \mathcal{W} &= \sum_{s=0}^{\infty} T_{1,s}^{[1-s]} D^s, \quad \mathcal{W}^{-1} = \sum_{a=0}^{\infty} (-1)^a T_{a,1}^{[1-a]} D^a. \end{aligned} \quad (15)$$

It can be checked that the transfer matrices $T_{a,1}$ are functions of $x^{[\pm a]}$ alone ($T_{1,s}$ depend on all $x^{[b]}$, $b = -a, -a+2, \dots, a$). The transfer matrices for other representations can be obtained from these by use of the Bazhanov-Reshitikhin formula [22].

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