Negative-energy Perturbations in General and in Arbitrary One-dimensional Vlasov-Maxwell Equilibria

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Abstract

The expression for the free energy of arbitrary perturbations of general Vlasov-Maxwell equilibria derived by Morrison and Pfirsch is transformed and put in a concise form, which is subsequently evaluated for arbitrary, double-symmetric equilibria in the case of internal perturbations, i.e. perturbations which vanish outside the plasma, and on its boundary. With the single exception of the configurations in which the equilibrium distribution functions are everywhere isotropic and monotonically decreasing functions of the particle energy, these equilibria always allow negative-energy perturbations, \textit{without requiring a large spatial variation of the perturbation across the equilibrium magnetic field.}
1 INTRODUCTION

Considering arbitrary perturbations of general Vlasov-Maxwell equilibria, Morrison and Pfirsch [1, 2] derived expressions for the second variation of the free energy and concluded that negative-energy modes (which are potentially dangerous because they may become nonlinearly unstable and cause anomalous transport [3, 4, 5]) exist in any Vlasov-Maxwell equilibrium whenever the unperturbed distribution function \( f^{(0)}_\nu \) of any particle species \( \nu \) deviates from monotonicity and/or isotropy in the vicinity of a single point, i.e., whenever the condition

\[
(v \cdot k) \left( k \cdot \frac{\partial f^{(0)}_\nu}{\partial \nu} \right) > 0
\]

holds (in the frame of reference of minimum equilibrium energy) for any particle species \( \nu \) for some position vector \( x \) and velocity \( v \) and for some local wave vector \( k \). The proof of this result obtained by Morrison and Pfirsch was based on infinitely strongly localized perturbations, which correspond to \( |k| \rightarrow \infty \). This raises the question of the degree of localization actually required for negative-energy modes to exist in a certain equilibrium. Studying a homogeneous Vlasov-Maxwell plasma with constant magnetic field, Correa-Restrepo and Pfirsch [6] showed that negative-energy modes exist for any deviation of the equilibrium distribution function of any of the species from monotonicity and/or isotropy, without having to impose any restricting conditions on the perpendicular wave number \( k_\perp \), i.e., without requiring large \( k_\perp \). These results were later extended to the more interesting case of an inhomogeneous, force-free equilibrium with a sheared magnetic field [7]. In the present paper, the investigations are carried out for a whole class of equilibria (which includes the previous configurations as particular cases), in that the general expression for the perturbation energy is evaluated for arbitrary double-symmetric, i.e., one-dimensional, equilibria. In generalized coordinates \( q_1, q_2, q_3 \), such equilibria depend only on \( q_1 \), the equilibrium magnetic field \( B^{(0)} \) is perpendicular to \( \nabla q_1 \), \( B^{(0)} \cdot \nabla q_1 = 0 \), and the equilibrium distribution function of each particle species \( \nu \) has the general form \( f^{(0)}_\nu = f^{(0)}_\nu(\mathcal{H}_\nu, p_{\nu 2}, p_{\nu 3}) \), where \( \mathcal{H}_\nu \) is the (conserved) particle energy and \( p_{\nu 2}, p_{\nu 3} \) are the (conserved) canonical momenta corresponding to the two ignorable coordinates \( q_2, q_3 \), respectively. This class of configurations investigated here includes, for instance, all cylindrical axisymmetric (dependent only on the radius \( r \)) and all plane symmetric (dependent only on one Cartesian coordinate, \( x \)) equilibria.

For double-symmetric equilibria, one obtains a sufficient (but not necessary!) condition for the existence of negative-energy perturbations which is somewhat
similar to inequality (1), namely

\[ \left( k_{23} \cdot v \right) \left( k_{23} \cdot \frac{\partial f_{\nu}^{(0)}}{\partial v} \right) > 0 , \tag{2} \]

where the angles are mean values along the unperturbed particle orbits and the wave vector \( k_{23} \) is given by \( k_{23} = k_2 \nabla q_2 + k_3 \nabla q_3 \). Unlike in the case of inequality (1), \( k_{23} = |k_{23}| \) does not have to be large, the only condition imposed on \( k_{23} \) being \( k_{23} \neq 0 \).

Negative-energy waves are also possible even if Eq. (2) is not satisfied, namely if the equilibrium distribution function of any of the particle species is nonmonotonic \( \frac{\partial f_{\nu}^{(0)}}{\partial \mathcal{H}_\nu} > 0 \) and/or locally anisotropic in phase space \( \frac{\partial f_{\nu}^{(0)}}{\partial p_{\nu 2}} \) and \( \frac{\partial f_{\nu}^{(0)}}{\partial p_{\nu 3}} \) are not both identically zero. This does not exclude isotropic pressure tensors. Large spatial variation of the perturbations across the equilibrium magnetic field is not required in these cases either. If there is only anisotropy, however, \( k_{23} \) is not completely arbitrary because, at given \( \frac{k_2}{k_3} \), the quotient \( \frac{n_{\nu}}{k_{23}} \), where \( n_{\nu} \) is an arbitrary integer (positive or negative), can assume values only in a certain range. The result then is that it is only configurations for which the equilibrium distribution functions of all species are everywhere isotropic and monotonically decreasing functions of the particle energy that do not allow the kind of negative-energy perturbations studied here.

In Sec. II, the expression for the free energy \( \delta^2 H \) available upon arbitrary perturbations of general Vlasov-Maxwell equilibria derived by Morrison and Pfirsch [1] is transformed and put in a clear and concise form, which is then evaluated in Sec. III for arbitrary, double-symmetric equilibria. For these equilibria, a convenient representation of the generating function of the perturbations further simplifies the expression for \( \delta^2 H \). Considering internal perturbations, i.e. those which vanish outside the plasma, and on its boundary, the minimizing perturbations are obtained in Sec. IV, where the expression for the minimized energy is also obtained. In deriving this expression, the difference between particles with periodic motion (PPM) and particles with non-periodic motion (PNPM) plays a major role. Section V is devoted to an extensive discussion of the energy expression. This discussion leads to the main results, which are then summarized in Sec. VI.

A considerable part of the calculations is done in the appendices. The relations which are necessary to transform the general expression for the perturbation energy are derived in Appendix A. A convenient representation of derivatives in \( x - v \) space is introduced in Appendix B. The motion of the charged particles is treated in Appendix C, and the two different groups of particles, namely the
particles with periodic motion PPM and the particles with non-periodic motion PNPM, are introduced. In Appendix D, the constant of the motion $C_{\nu}$, which plays a crucial role in the expression for the minimized perturbation energy, is determined. Appendix E introduces coordinates in $x - v$ space which are particularly suited to treating the expression for the perturbation energy. Finally, in Appendix F, an expression is derived for the perturbed electric charge density, and it is shown that this can be made to vanish by an appropriate nontrivial choice of the perturbations.

2 THE PERTURBATION ENERGY
FOR GENERAL EQUILIBRIA

The expressions for the free energy $\delta^2 H$ available upon arbitrary perturbations of general Vlasov-Maxwell equilibria derived by Morrison and Pfirsch [1, 2] can be written as [6]

$$\delta^2 H = \sum_{\nu} \int d^3x \frac{d^3v}{2m_{\nu}} \left\{ \left( \frac{\partial f_{\nu}^{(0)}}{\partial v} \right) \cdot \left[ -\left( v \cdot \frac{\partial G_{\nu}}{\partial x} \right) \frac{\partial G_{\nu}}{\partial v} + \left( a_{\nu}^{(0)} \cdot \frac{\partial G_{\nu}}{\partial v} \right) \right. 
+ \frac{e_{\nu}}{m_{\nu}c} \frac{G_{\nu}}{v} \times \frac{\partial}{\partial v} \left( B_{\nu}^{(0)} \cdot \frac{\partial G_{\nu}}{\partial x} \right)

- \frac{e_{\nu}}{m_{\nu}c} \frac{G_{\nu}}{v} \partial \times \frac{\partial G_{\nu}}{\partial v} \times G_{\nu}^{(0)} \right] 
+ \frac{\partial f_{\nu}^{(0)}}{\partial x} \cdot \left[ -\left( \frac{\partial G_{\nu}}{\partial v} \cdot \frac{\partial G_{\nu}}{\partial v} \right) v + \left( d_{\nu} G_{\nu} \right) \frac{\partial G_{\nu}}{\partial \nu} \right]

\left. + f_{\nu}^{(0)} \left( \frac{e_{\nu}}{c} \delta A \right)^2 - 2 \frac{e_{\nu}}{c} \frac{\partial f_{\nu}^{(0)}}{\partial v} \cdot \left[ \frac{d_{\nu} G_{\nu} \delta A - G_{\nu} \frac{\partial}{\partial x} (v \cdot \delta A)}{\delta E^2 + \delta B^2} \right] \right\} + \frac{1}{8\pi} \int d^3x \left( \delta E^2 + \delta B^2 \right). \quad(3)$$

Here, the species $\nu$ with equilibrium distribution function $f_{\nu}^{(0)}(x, v)$ consists of particles of electric charge $e_{\nu}$ and mass $m_{\nu}$ (c is the velocity of light). $E^{(0)}$ and $B^{(0)}$ are the equilibrium electric and magnetic fields, respectively. $G_{\nu}(x, v)$
is a generating function for the perturbation of the particle position and velocity, \( \delta A \) is the perturbation of the vector potential and \( \delta E^2/8\pi \) and \( \delta B^2/8\pi \) are the perturbations in the electric and magnetic field energy densities. The operator \( d_{\nu} \) is the equilibrium Vlasov operator, i.e.

\[
d_{\nu} = v \cdot \frac{\partial}{\partial x} + a_{\nu}^{(0)} \cdot \frac{\partial}{\partial \nu},
\]

where

\[
a_{\nu}^{(0)} = \frac{e_{\nu}}{m_{\nu}} \left[ E^{(0)} + \frac{v \times B^{(0)}}{c} \right].
\]

Taking into account the relations derived in Appendix A, Eqs. (A.1-A.4), Eq. (3) can easily be transformed to yield

\[
\delta^2 H = \sum_{\nu} \int \frac{d^3 x \, d^3 \nu}{2m_{\nu}} \left\{ (d_{\nu} G_{\nu}) \left[ F_{\nu}^{(0)} \cdot \frac{\partial G_{\nu}}{\partial \nu} - \frac{\partial f_{\nu}^{(0)}}{\partial \nu} \cdot \frac{\partial G_{\nu}}{\partial x} \right]
\right.
\]
\[
+ f_{\nu}^{(0)} \left( \frac{e_{\nu}}{c} \delta A \right)^2 - 2 \frac{e_{\nu}}{c} \frac{\partial f_{\nu}^{(0)}}{\partial \nu} \cdot \left[ d_{\nu} (G_{\nu} \delta A) - G_{\nu} \frac{\partial}{\partial x} (v \cdot \delta A) \right] \right\}
\]
\[
+ \frac{1}{8\pi} \int d^3 x \left( \delta E^2 + \delta B^2 \right),
\]

where

\[
F_{\nu}^{(0)} = \frac{\partial f_{\nu}^{(0)}}{\partial x} + \frac{e_{\nu}}{m_{\nu} c} B^{(0)} \times \frac{\partial f_{\nu}^{(0)}}{\partial \nu},
\]

so that the equilibrium Vlasov's equation is

\[
d_{\nu} f_{\nu}^{(0)} = F_{\nu}^{(0)} \cdot v + \frac{e_{\nu}}{m_{\nu}} E^{(0)} \cdot \frac{\partial f_{\nu}^{(0)}}{\partial \nu} = 0.
\]

Equation (6) becomes particularly simple if one evaluates \( \delta^2 H \) in terms of electrostatic initial perturbations, which have \( \delta A = 0, \delta B = \nabla \times \delta A = 0 \). This yields

\[
\delta^2 H = \sum_{\nu} \int \frac{d^3 x \, d^3 \nu}{2m_{\nu}} \left\{ (d_{\nu} G_{\nu}) \left[ F_{\nu}^{(0)} \cdot \frac{\partial G_{\nu}}{\partial \nu} - \frac{\partial f_{\nu}^{(0)}}{\partial \nu} \cdot \frac{\partial G_{\nu}}{\partial x} \right] \right\}
\]
\[
+ \frac{1}{8\pi} \int d^3 x \, \delta E^2.
\]
For time-independent equilibrium fields \( \mathbf{E}^{(0)} = -\nabla \Phi^{(0)} \) and \( \mathbf{B}^{(0)} = \nabla \times \mathbf{A}^{(0)} \), the particle energy \( \mathcal{H}_\nu \),

\[
\mathcal{H}_\nu = \frac{m_\nu}{2} \mathbf{v}^2 + e_\nu \Phi^{(0)} ,
\]

is a constant of the motion. The equilibrium distribution functions \( f^{(0)}_\nu \) can be written as

\[
f^{(0)}_\nu(x, \mathbf{v}) = f^{(0)}_\nu(\mathcal{H}_\nu(x, \mathbf{v}), \mathcal{K}_{\nu\kappa}(x, \mathbf{v})) ,
\]

where \( \kappa \) runs over as many indices as there are other constants of the motion \( \mathcal{K}_{\nu\kappa} \) in the problem under consideration.

If one introduces generalized coordinates \( q_i(x), i = 1, \ldots, 3 \), with the corresponding covariant velocity components \( v_i(x, \mathbf{v}) \) and takes into account the relations derived in Appendix B, in particular Eq. (B.10), the perturbation energy \( \delta^2 H \), Eq. (9) can be expressed as

\[
\delta^2 H = \sum_{\nu, \kappa} \int \frac{d^3 x d^3 v}{2m_\nu} \left\{ -m_\nu (d_\nu G_\nu)^2 \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} |_{\mathcal{K}_{\nu\kappa}} 
\right. \\
\left. - (d_\nu G_\nu) \frac{\partial f^{(0)}_\nu}{\partial \mathcal{K}_{\nu\kappa}} |_{\mathcal{H}_\nu} \frac{\partial \mathcal{K}_{\nu\kappa}}{\partial v_i} |_{x} \cdot \frac{\partial G_\nu}{\partial x} |_{v_i} \\
+ (d_\nu G_\nu) \frac{\partial f^{(0)}_\nu}{\partial \mathcal{K}_{\nu\kappa}} |_{\mathcal{H}_\nu} \frac{\partial G_\nu}{\partial v_i} |_{x} \left[ \frac{\partial \mathcal{K}_{\nu\kappa}}{\partial x} |_{v_i} + \frac{e_\nu}{m_\nu c} \mathbf{B}^{(0)} \times \frac{\partial \mathcal{K}_{\nu\kappa}}{\partial v_i} |_{x} \right] \right\} \\
+ \frac{1}{2\pi} \int d^3 x \delta \mathbf{B}^2 .
\]

Note that, in Eq. (12), the derivatives with respect to \( x \) are now performed at constant \( v_i(x, \mathbf{v}) = v \cdot \frac{\partial x}{\partial q_i} \), and not at constant \( v \).

It is evident from Eq. (12) that there cannot be negative-energy perturbations if all \( f^{(0)}_\nu = f^{(0)}_\nu(\mathcal{H}_\nu) \) and if \( \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} < 0 \), a result already proved in Ref. [8].

3 THE PERTURBATION ENERGY FOR ARBITRARY, ONE-DIMENSIONAL EQUILIBRIA
Double-symmetric equilibria are now considered, i.e. configurations in which the equilibrium scalar quantities depend only on one of the three spatial coordinates $q_1$, $q_2$, $q_3$.

Let $q_1$ be the generalized coordinate on which the equilibrium depends. Since $q_2$ and $q_3$ are ignorable, the corresponding canonical momenta are constants of the motion.

The equilibrium magnetic field $B^{(0)}$ has the following general form:

$$
B^{(0)} = \nabla \times A^{(0)} = \nabla \times \left[ A^{(0)}_i(q_1) \nabla q_i \right]
$$

$$
= - \frac{dA^{(0)}_3}{dq_1} \nabla q_3 \times \nabla q_1 + \frac{dA^{(0)}_2}{dq_1} \nabla q_1 \times \nabla q_2
$$

$$
= \frac{1}{J(q_1)} \left[ - \frac{dA^{(0)}_3}{dq_1} \frac{\partial x}{\partial q_2} + \frac{dA^{(0)}_2}{dq_1} \frac{\partial x}{\partial q_3} \right],
$$

where

$$
J(q_1) = \frac{\partial x}{\partial q_1} \cdot \frac{\partial x}{\partial q_2} \times \frac{\partial x}{\partial q_3}.
$$

($A^{(0)}_1 \equiv 0$ without loss of generality).

The Lagrangian $L_\nu$ of a particle of species $\nu$ is

$$
L_\nu = \frac{m_\nu}{2} v^2 + \frac{e_\nu}{c} A^{(0)}(x) \cdot v - e_\nu \Phi^{(0)}(x),
$$

from which the momentum canonically conjugated to $x$ follows:

$$
p_\nu = \frac{\partial L_\nu}{\partial v} = m_\nu v + \frac{e_\nu}{c} A^{(0)},
$$

with covariant components

$$
p_{\nu i} = m_\nu v_i(x, v) + \frac{e_\nu}{c} A^{(0)}_i(q_1)
$$

$$
= m_\nu v \cdot \frac{\partial x}{\partial q_i} + \frac{e_\nu}{c} A^{(0)}_i(q_1),
$$

which are the momenta canonically conjugated to the $q_i$’s.

Besides the particle energy $\mathcal{H}_\nu$, also the canonical momenta $p_{\nu 2}$ and $p_{\nu 3}$ are constants of the motion. In the four-dimensional space $(v_i, q_1)$, $i = 1, \ldots, 3$, the general equilibrium solution of Vlasov’s equation is

$$
f^{(0)}_\nu = f^{(0)}_\nu(\mathcal{H}_\nu, p_{\nu 2}, p_{\nu 3}).
$$
Then, in Eq. (12), \( \mathcal{K}_{\nu \kappa} = p_{\nu \kappa}, \kappa = 2, 3 \). From Eq. (17) one has

\[
\left. \frac{\partial p_{\nu \kappa}}{\partial x} \right|_{v_i} = \frac{e_{\nu}}{c} \left. \frac{dA_{\nu \kappa}^{(0)}}{dq_1} \right|_{v_i} \nabla q_1 = \frac{e_{\nu}}{c} \nabla A_{\nu \kappa}^{(0)}
\]

(19)

and

\[
\left. \frac{\partial p_{\nu \kappa}}{\partial v} \right|_x = m_{\nu} \frac{\partial x}{\partial q_{\kappa}} ,
\]

(20)

and, therefore,

\[
\frac{\partial \mathcal{K}_{\nu \kappa}}{\partial x} \Bigg|_{v_i} + \frac{e_{\nu}}{m_{\nu} c} B^{(0)} \times \frac{\partial \mathcal{K}_{\nu \kappa}}{\partial v} \bigg|_x \Rightarrow \left. \frac{\partial p_{\nu \kappa}}{\partial x} \right|_{v_i} + \frac{e_{\nu}}{m_{\nu} c} B^{(0)} \times \frac{\partial p_{\nu \kappa}}{\partial v} \bigg|_x
\]

\[
= \left. \frac{\partial p_{\nu \kappa}}{\partial x} \right|_{v_i} + \frac{e_{\nu}}{m_{\nu} c} \left[ \nabla A_{\nu \kappa}^{(0)} \times \nabla q_i \right] \times \frac{\partial p_{\nu \kappa}}{\partial v} \bigg|_x
\]

\[
= \frac{e_{\nu}}{c} \left[ \nabla A_{\nu \kappa}^{(0)} - \delta_{i \kappa} \nabla A_{\nu i}^{(0)} + \frac{\partial A_{\nu i}^{(0)}}{\partial q_{\kappa}} \nabla q_i \right] = 0 ,
\]

(21)

because \( A_{\nu i}^{(0)} \) does not depend on \( q_{\kappa} \) for \( \kappa = 2, 3 \).

Hence, for equilibria which depend only on one spatial coordinate \( q_1 \), Eq. (12) reduces to

\[
\delta^2 H = \sum_{\kappa = 2, 3} \int \frac{d^3 x d^3 v}{2} \left\{ - \left( d_{\nu} G_{\nu} \right)^2 \frac{\partial f_{\nu}^{(0)}}{\partial H_{\nu}} \right. \\
- \left( d_{\nu} G_{\nu} \right) \left[ \frac{\partial x}{\partial q_{\kappa}} \cdot \frac{\partial G_{\nu}}{\partial x} \bigg|_{v_i} \right] \frac{\partial f_{\nu}^{(0)}}{\partial p_{\nu \kappa}} \bigg\} \\
+ \frac{1}{8\pi} \int d^3 x \delta E^2 .
\]

(22)

Note that, in this representation, derivatives of \( G_{\nu} \) in \( v \) space appear only in \( d_{\nu} G_{\nu} \), the derivative of \( G_{\nu} \) along the unperturbed particle orbits.

Since the equilibrium is independent of \( q_2 \) and \( q_3 \), an appropriate ansatz for the generating function \( G_{\nu} \) is

\[
G_{\nu}(x, v) = G_{\nu}(x, v_1(x, v)) = \\
\frac{1}{2} \left[ g_{\nu}(q_1, v_1) e^{i [k_2 q_2 + k_3 q_3]} + g_{\nu}^*(q_1, v_1) e^{-i [k_2 q_2 + k_3 q_3]} \right] .
\]

(23)
$G_\nu$ is obviously a real function since $g_\nu^*$ is the complex conjugate of $g_\nu$.

The constants $k_2$ and $k_3$ are the covariant components of a wave vector $k_{23}$, given by

$$k_{23} = k_2 \nabla q_2 + k_3 \nabla q_3 . \quad (24)$$

Derivation of the expressions in the exponents of Eq. (23) along the unperturbed orbits yields

$$d_\nu (k_2 q_2 + k_3 q_3) = k_2 \dot{q}_2 + k_3 \dot{q}_3$$

$$= k_2 v^2 + k_3 v^3$$

$$= k_{23} \cdot \mathbf{v} \quad (25)$$

($v^i, i = 1, \ldots 3$ are the contravariant components of the velocity).

Inserting Eq. (23) in Eq. (22), integrating with respect to $q_2$ between $q_{20}$ and $q_{20} + \frac{2\pi}{k_2}$ and with respect to $q_3$ between $q_{30}$ and $q_{30} + \frac{2\pi}{k_3}$, taking into account that

$$d^3 x = J(q_1) dq_1 dq_2 dq_3 \quad (26)$$

and defining $s(q_1)$ by the relation

$$s(q_1) = J(q_1) \int_{q_{20}}^{q_{20} + \frac{2\pi}{k_2}} \int_{q_{30}}^{q_{30} + \frac{2\pi}{k_3}} dq_2 dq_3 \quad (27)$$

yields

$$\delta^2 H = \sum_{\nu=2,3} \int \frac{s(q_1)}{4} dq_1 d^3 v \left\{ -\frac{\partial f^{(0)}_\nu}{\partial H_\nu} \left[ [d_\nu g_\nu + (v \cdot k_{23}) g_\nu]^2 \right] \\
- i \frac{\partial f^{(0)}_\nu}{\partial p_\nu} k_0 \left[ g_\nu d_\nu g_\nu^* - g_\nu^* d_\nu g_\nu - 2i (v \cdot k_{23}) g_\nu g_\nu^* \right] \right\} + \frac{1}{2\pi} \int d^3 x \delta E^2 . \quad (28)$$

The complex functions $g_\nu$ are conveniently represented as

$$g_\nu(q_1, v_i) = \Psi_\nu(q_1, v_i) e^{i \Gamma_\nu(q_1, v_i)} , \quad (29)$$

where $\Psi_\nu$ and $\Gamma_\nu$ are real functions and are such that the $g_\nu$'s are single-valued functions of $q_1$ and $v_i$. 

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Inserting Eq. (29) in Eq. (28) yields

\[ \delta^2 H = \sum_{\kappa=2,3} \int \frac{s(q_1)}{4} dq_1 d^3 v \left\{ -\frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \left[ (d_\nu \Psi_\nu)^2 \right] 
+ \Psi_\nu^2 [d_\nu \Gamma_\nu + (v \cdot k_{23})]^2 \right\} \frac{\partial f^{(0)}_\nu}{\partial p_{\kappa \nu}} k_\kappa \Psi_\nu^2 [d_\nu \Gamma_\nu + (v \cdot k_{23})] \right\}. \] (30)

Here, the electrostatic energy term \( \frac{1}{8\pi} \int d^3 x \delta E^2 \) has been dropped since the perturbed charge density can be made zero by an appropriate choice of the signs of \( \Psi_\nu \), which do not influence Eq. (30). This is explicitly shown in Appendix F.

Note that \( \delta^2 H \) is a functional of \( \Psi_\nu \), which appears as \( \Psi_\nu \) and \( d_\nu \Psi_\nu \), and of \( \Gamma_\nu \), which appears only through its derivative \( d_\nu \Gamma_\nu \) along the unperturbed orbits.

### 4 EXTREMIZATION OF THE SECOND-ORDER PERTURBATION ENERGY

Complete minimization of the expression for the perturbation energy, Eq. (30), with respect to \( \Gamma_\nu \) is now possible. In order to do this, we first consider the variation of \( \delta^2 H \) brought about by a variation \( \delta \Gamma_\nu \) of \( \Gamma_\nu \). This quantity can easily be calculated and is

\[ \delta_{\Gamma_\nu} (\delta^2 H) = \delta^2 H (\Gamma_\nu + \delta \Gamma_\nu) - \delta^2 H (\Gamma_\nu) \]

\[ = \sum_{\kappa=2,3} \int \frac{1}{4} s(q_1) dq_1 d^3 v \left[ \left\{ -2 \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} [d_\nu \Gamma_\nu + v \cdot k_{23}] \right\} \right] \left\{ \frac{\partial f^{(0)}_\nu}{\partial p_{\kappa \nu}} k_\kappa \Psi_\nu^2 \right\} \]

\[ = \sum_{\kappa=2,3} \int \frac{1}{4} s(q_1) dq_1 d^3 v \left\{ d_\nu \left[ \delta \Gamma_\nu \left\{ -2 \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} [d_\nu \Gamma_\nu + v \cdot k_{23}] - \frac{\partial f^{(0)}_\nu}{\partial p_{\kappa \nu}} k_\kappa \Psi_\nu^2 \right\} \right] \right\}
+ \left[ \delta \Gamma_\nu \right] d_\nu \left\{ 2 \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \Psi_\nu^2 [d_\nu \Gamma_\nu + v \cdot k_{23}] + \frac{\partial f^{(0)}_\nu}{\partial p_{\kappa \nu}} k_\kappa \Psi_\nu^2 \right\} \}. \] (31)
Taking $\delta \Gamma_\nu$ to vanish outside the plasma, and on its boundary, as is appropriate for the internal perturbations considered here, Eq. (31) reduces to

$$
\delta \Gamma_\nu(\delta^2 H) = \sum_{\kappa=2,3} \int \frac{1}{4} s(q_1) dq_1 d^3 v \left[ \delta \Gamma_\nu \right] 
$$

$$
\times d_\nu \left[ 2 \frac{\partial f_\nu^{(0)}}{\partial H_\nu} \Psi_\nu^2 \left[ d_\nu \Gamma_\nu + v \cdot k_{23} \right] + \frac{\partial f_\nu^{(0)}}{\partial p_{\nu\kappa}} k_{\kappa} \Psi_\nu^2 \right] , \tag{32}
$$

and, since $\delta \Gamma_\nu$ is arbitrary in the internal region, the condition for the vanishing of $\delta \Gamma_\nu(\delta^2 H)$ is

$$
d_\nu \left[ 2 \frac{\partial f_\nu^{(0)}}{\partial H_\nu} \Psi_\nu^2 \left[ d_\nu \Gamma_\nu + v \cdot k_{23} \right] + \frac{\partial f_\nu^{(0)}}{\partial p_{\nu\kappa}} k_{\kappa} \Psi_\nu^2 \right] = 0 . \tag{33}
$$

Since $d_\nu$ is the rate of change seen by the moving particles along the unperturbed orbits, the general solution of Eq. (33), in the four-dimensional space $q_1, v_i$, $i = 1, \ldots, 3$, is given by

$$
2 \frac{\partial f_\nu^{(0)}}{\partial H_\nu} \Psi_\nu^2 \left[ d_\nu \Gamma_\nu + v \cdot k_{23} \right] + \left[ k_2 \frac{\partial f_\nu^{(0)}}{\partial p_{\nu2}} + k_3 \frac{\partial f_\nu^{(0)}}{\partial p_{\nu3}} \right] \Psi_\nu^2 = C_\nu(H_\nu, p_{\nu2}, p_{\nu3}) , \tag{34}
$$

where $C_\nu$ is a single-valued function of the constants of the motion. $C_\nu(H_\nu, p_{\nu2}, p_{\nu3})$ is explicitly determined in Appendix D by using the fact that $\Gamma_\nu$ must be such that the generating function $g_\nu$ for the perturbations, Eq. (29), must be single-valued. Inserting Eq. (34) in Eq. (30) yields the minimized perturbation energy in the form

$$
\delta^2 H = \sum_\nu \int \frac{1}{4} s(q_1) dq_1 d^3 v \left[ \frac{\partial f_\nu^{(0)}}{\partial H_\nu} \right] \left\{ -[d_\nu \Psi_\nu]^2 
$$

$$
+ \frac{1}{4} \Psi_\nu^2 \left[ k_2 \frac{\partial f_\nu^{(0)}}{\partial p_{\nu2}} + k_3 \frac{\partial f_\nu^{(0)}}{\partial p_{\nu3}} \right]^2 \frac{\left[ \frac{\partial f_\nu^{(0)}}{\partial H_\nu} \right]^2}{\left[ \frac{\partial f_\nu^{(0)}}{\partial H_\nu} \right]^2} 
$$

$$
- \frac{1}{4} \frac{C_\nu^2}{\left[ \frac{\partial f_\nu^{(0)}}{\partial H_\nu} \right]^2} \Psi_\nu^2 \right\} . \tag{35}
$$
According to Appendices C and D, the particles of each species $\nu$ can be divided into two classes, namely the particles with periodic motion PPM, for which $q_1(t)$ is a periodic function of time, and the particles with non-periodic motion PNPM. This is utilized to split the perturbation energy into two parts:

$$\delta^2 H = (\delta^2 H)_{PPM} + (\delta^2 H)_{PNPM},$$  \hspace{1cm} (36)$$

where $(\delta^2 H)_{PPM}$ is the contribution of the particles with periodic motion, and $(\delta^2 H)_{PNPM}$ that of the particles with non-periodic motion. According to Appendices C and D, these contributions are, explicitly,

$$\begin{align*}
(\delta^2 H)_{PNPM} & = \sum_{\nu} \int \frac{1}{4} s(q_1) dq_1 d^3v \left\{ \frac{\partial f^{(0)}_{\nu}}{\partial H_{\nu}} \right\} \left\{ -[d_\nu \Psi_\nu]^2 \\
+ \frac{1}{4} \Psi_\nu^2 \left[ k_2 \frac{\partial f^{(0)}_{\nu}}{\partial p_{\nu 2}} + k_3 \frac{\partial f^{(0)}_{\nu}}{\partial p_{\nu 3}} \right]^2 \\
- \frac{1}{4} \frac{C^2_\nu}{\left[ \frac{\partial f^{(0)}_{\nu}}{\partial H_{\nu}} \right]^2} \Psi_\nu^2 \right\}, \hspace{1cm} (37)$$

where $C_\nu(H_{\nu}, p_{\nu 2}, p_{\nu 3})$ is a completely arbitrary function, and

$$\begin{align*}
(\delta^2 H)_{PPM} & = \sum_{\nu} \int \frac{1}{4} s(q_1) dq_1 d^3v \left\{ \frac{\partial f^{(0)}_{\nu}}{\partial H_{\nu}} \right\} \left\{ -[d_\nu \Psi_\nu]^2 \\
+ \frac{1}{4} \Psi_\nu^2 \left[ k_2 \frac{\partial f^{(0)}_{\nu}}{\partial p_{\nu 2}} + k_3 \frac{\partial f^{(0)}_{\nu}}{\partial p_{\nu 3}} \right]^2 \\
- \frac{1}{\Psi_\nu^2} \left\{ \frac{2\pi}{\tau} \right\}^2 \right\}
\end{align*}$$
\[ n_\nu + \frac{\tau}{4\pi} \frac{1}{\partial f^{(0)}_{\nu} / \partial \mathcal{H}_{\nu}} \left[ 2 \frac{\partial f^{(0)}_{\nu}}{\partial \mathcal{H}_{\nu}} (k_{23} \cdot \mathbf{v}) + k_2 \frac{\partial f^{(0)}_{\nu}}{\partial p_{\nu2}} + k_3 \frac{\partial f^{(0)}_{\nu}}{\partial p_{\nu3}} \right] \right] \right)^2 \right\}^2 \]  \\

where \( n_\nu \) is any integer number, i.e. \( n_\nu = 0, \pm 1, \ldots \)

By employing the coordinate system \( t, \mathcal{H}_{\nu}, p_{\nu2}, p_{\nu3} \) introduced in Appendix E the contribution of the particles with periodic motion to the perturbation energy can be expressed as

\[ (\delta^2 H)_{\text{PPM}} = \sum_\nu \int \frac{s_0}{4m^3_\nu} d\mathcal{H}_{\nu} dp_{\nu2} dp_{\nu3} dt \left\{ -\left[ \frac{\partial \Psi_\nu}{\partial t} \right]^2 \right. \]

\[ + \frac{1}{4} \Psi^2_\nu \left[ k_2 \frac{\partial f^{(0)}_{\nu}}{\partial p_{\nu2}} + k_3 \frac{\partial f^{(0)}_{\nu}}{\partial p_{\nu3}} \right]^2 \]

\[ - \frac{1}{\Psi^2_\nu} \left\langle \frac{2\pi}{\tau} \right\rangle^2 \]

\[ \times \left\{ n_\nu + \frac{\tau}{4\pi} \frac{1}{\partial f^{(0)}_{\nu} / \partial \mathcal{H}_{\nu}} \left[ 2 \frac{\partial f^{(0)}_{\nu}}{\partial \mathcal{H}_{\nu}} (k_{23} \cdot \mathbf{v}) + k_2 \frac{\partial f^{(0)}_{\nu}}{\partial p_{\nu2}} + k_3 \frac{\partial f^{(0)}_{\nu}}{\partial p_{\nu3}} \right] \right\}^2 \right\} , \]

where

\[ s_0 = \frac{s}{J(q_1)} = \frac{4\pi^2}{k_2 k_3} . \]

Performing the integration over \( t \) in Eq. (39) yields

\[ (\delta^2 H)_{\text{PPM}} = \sum_\nu \int \frac{s_0}{4m^3_\nu} d\mathcal{H}_{\nu} dp_{\nu2} dp_{\nu3} \tau \left[ \frac{\partial f^{(0)}_{\nu}}{\partial \mathcal{H}_{\nu}} \right] \left\{ -\left\langle \frac{\partial \Psi_\nu}{\partial t} \right\rangle^2 \right\} \]
\[ + \frac{1}{4} \langle \Psi^2 \rangle \left[ \frac{k_2 \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 2}} + k_3 \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 3}}}{\mathcal{H}_\nu} \right]^2 \]

\[ - \frac{1}{\langle \Psi^2 \rangle} \left[ \frac{2\pi}{\tau} \right]^2 \]

\[ \times \left[ n_\nu + \frac{\tau}{4\pi} \frac{1}{\mathcal{H}_\nu} \left[ 2\frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} (k_{23} \cdot v) + k_2 \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 2}} + k_3 \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 3}} \right] \right]^2, \tag{41} \]

where the term \( \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} (k_{23} \cdot v) \) could also be expressed in a different way according to the relations

\[ \frac{1}{m_\nu} \left. \frac{\partial f^{(0)}_\nu}{\partial v} \right|_x = v \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} + \frac{\partial x}{\partial q_2} \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 2}} + \frac{\partial x}{\partial q_3} \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 3}}, \tag{42} \]

\[ \frac{1}{m_\nu} k_{23} \cdot \left. \frac{\partial f^{(0)}_\nu}{\partial v} \right|_x = k_{23} \cdot v \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} + k_2 \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 2}} + k_3 \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 3}}. \tag{43} \]

Note that the only derivative of \( \Psi_\nu \) which appears in the expressions for \( \delta^2 H \), Eqs. (37)-(41), is \( d_\nu \Psi_\nu = \frac{d\Psi_\nu}{dt} \bigg|_{\text{along orbits}} \), the rate of change of \( \Psi_\nu \) along the unperturbed orbits. In particular, there are no explicit spatial derivatives.

5 DISCUSSION OF THE EXPRESSION FOR THE SECOND-ORDER PERTURBATION ENERGY

5.1 The perturbation energy \( (\delta^2 H)_{PPM} \) for particles with periodic motion

To study the sign of \( (\delta^2 H)_{PPM} \), Eq. (41), one has to distinguish the following two cases:
5.1.1 \( k_2 = k_3 = 0 \rightarrow k_{23} = 0 \), perpendicular wave propagation

In this case, the wave propagation is perpendicular to \( \mathbf{B}^{(0)} \) since \( k_{23} \cdot \mathbf{B}^{(0)} = 0 \) for all \( q_1 \).

If follows immediately from Eq. (41) that \( \delta^2 H < 0 \) if \( \frac{\partial f_{\nu}^{(0)}}{\partial \mathcal{H}_{\nu}} > 0 \) for some \( \mathcal{H}_{\nu}, p_{\nu 2}, p_{\nu 3} \) around \( \mathcal{H}_{\nu 0}, p_{\nu 20}, p_{\nu 30} \) corresponding to PPM, and for any particle species \( \nu \). This means that the presence of a local minimum with respect to \( \mathcal{H}_{\nu} \)
\( \text{inf}_{\nu} f_{\nu}^{(0)}(\mathcal{H}_{\nu}, p_{\nu 2}, p_{\nu 3}) \) guarantees \( \delta^2 H < 0 \), without any restrictions on the spatial variation of the perturbations perpendicular to \( \mathbf{B}^{(0)} \): it suffices to localize \( \Psi_{\nu} \) (\( d_{\nu} \Psi_{\nu} \) is then also localized) to the region around \( \mathcal{H}_{\nu 0}, p_{\nu 20}, p_{\nu 30} \) where \( \frac{\partial f_{\nu}^{(0)}}{\partial \mathcal{H}_{\nu}} > 0 \). Outside this region \( \Psi_{\nu} \) vanishes. All other \( \Psi_{\mu} \) are set equal to zero. The \( \Psi_{\nu} \) corresponding to the PNPM are likewise all set equal to zero, so that \( \langle \delta^2 H \rangle_{\text{PNPM}} = 0 \). The sign of \( \delta^2 H = (\delta^2 H)_{\text{PPM}} \) is then determined only by the sign of the integrant in the region of localization, which is then negative.

The kind of localization introduced here means that, for every \( q_1 \) in configuration space, only the particles whose constants of the motion have values near \( \mathcal{H}_{\nu 0}, p_{\nu 20}, p_{\nu 30} \) are perturbed; this localization is thus quite different from a localization in configuration space.

5.1.2 \( k_2, k_3 \) are not both zero, \( k_{23} \cdot \mathbf{B}^{(0)} \neq 0 \)

In this case, the wave vector \( k_{23} \) has a component in the direction of \( \mathbf{B}^{(0)} \) (with the possible exception of some isolated points \( q_1 \)) since

\[
k_{23} \cdot \mathbf{B}^{(0)} = k_2 B^{(0)2}(q_1) + k_3 B^{(0)3}(q_1)
= \frac{1}{f(q_1)} \left[ -k_2 \frac{dA_3^{(0)}}{dq_1} + k_3 \frac{dA_2^{(0)}}{dq_1} \right].
\]

(44)

If \( \frac{\partial f_{\nu}^{(0)}}{\partial \mathcal{H}_{\nu}} > 0 \) for some \( \mathcal{H}_{\nu}, p_{\nu 2}, p_{\nu 3} \) around \( \mathcal{H}_{\nu 0}, p_{\nu 20}, p_{\nu 30} \) corresponding to PPM, and for any particle species \( \nu \), one again localizes the perturbations \( \Psi_{\nu} \) around these values, as in the preceding cases. All \( \Psi_{\nu} \) corresponding to PNPM are set equal to zero; therefore \( \langle \delta^2 H \rangle_{\text{PNPM}} = 0 \).

If \( \frac{\partial f_{\nu}^{(0)}}{\partial p_{\nu 2}} = \frac{\partial f_{\nu}^{(0)}}{\partial p_{\nu 3}} = 0 \) (local isotropy), all terms in Eq. (41) are negative.

If \( \frac{\partial f_{\nu}^{(0)}}{\partial p_{\nu 2}} \) and/or \( \frac{\partial f_{\nu}^{(0)}}{\partial p_{\nu 3}} \neq 0 \), one can use the arbitrary \( n_{\nu} \) to make the integrand in Eq. (41) negative. This is most easily shown if one chooses \( \Psi_{\nu} \) independently of \( t \), i.e. \( \Psi_{\nu} = \Psi_{\nu}(\mathcal{H}_{\nu}, p_{\nu 2}, p_{\nu 3}) \). In this case, the integrand in Eq. (41) is given
by

\[- \frac{\partial f^{(0)}_\nu}{\partial H_\nu} \left[ n_\nu + \frac{\tau}{2\pi} (k_{23} \cdot v) \right] \left[ n_\nu + \frac{\tau}{2\pi} \frac{1}{m_\nu} \frac{1}{\partial f^{(0)}_\nu}{\partial H_\nu} \left\langle k_{23} \cdot \left. \frac{\partial f^{(0)}_\nu}{\partial v} \right|_x \right\rangle \right]. \quad (45)\]

If \( \langle v \cdot k_{23} \left\langle k_{23} \cdot \left. \frac{\partial f^{(0)}_\nu}{\partial v} \right|_x \right\rangle \rangle > 0 \), it suffices to take \( n_\nu = 0 \) to make the expression (45) (and thus \( \delta^2 H \)) negative. For any \( \langle v \cdot k_{23} \left\langle k_{23} \cdot \left. \frac{\partial f^{(0)}_\nu}{\partial v} \right|_x \right\rangle \rangle \), it is negative if the factors in the square brackets are either both positive or both negative. Both factors are positive if

\[ n_\nu > -\frac{\tau}{2\pi} \langle k_{23} \cdot v \rangle \text{ and } n_\nu > -\frac{\tau}{2\pi} \frac{1}{m_\nu} \frac{1}{\partial f^{(0)}_\nu}{\partial H_\nu} \left\langle k_{23} \cdot \left. \frac{\partial f^{(0)}_\nu}{\partial v} \right|_x \right\rangle, \quad (46)\]

which can easily be satisfied by the appropriate choice of \( n_\nu \), i.e. by choosing \( n_\nu \) large enough to satisfy both inequalities.

The expression (45) is also negative if both factors are negative, i.e. if

\[ n_\nu < -\frac{\tau}{2\pi} \langle k_{23} \cdot v \rangle \text{ and } n_\nu < -\frac{\tau}{2\pi} \frac{1}{m_\nu} \frac{1}{\partial f^{(0)}_\nu}{\partial H_\nu} \left\langle k_{23} \cdot \left. \frac{\partial f^{(0)}_\nu}{\partial v} \right|_x \right\rangle, \quad (47)\]

which can be satisfied by choosing the arbitrary \( n_\nu \) appropriately small.

Note that when \( \frac{\partial f^{(0)}_\nu}{\partial H_\nu}(H_{\nu_0, p_{\nu_2}, p_{\nu_3}}) > 0 \), \( \delta^2 H < 0 \) is possible without imposing any conditions on \( k_{23} \). It is not necessary either to assume large derivatives of the perturbations across the magnetic field.

If \( \frac{\partial f^{(0)}_\nu}{\partial H_\nu} < 0 \) for some \( H_{\nu, p_{\nu_2}, p_{\nu_3}} \) around \( H_{\nu_0, p_{\nu_2}, p_{\nu_3}} \) corresponding to PPM, and for any particle species \( \nu \), one again localizes \( \Psi_\nu \) around \( H_{\nu_0, p_{\nu_2}, p_{\nu_3}} \). All other \( \Psi_\mu \), and all \( \Psi_\nu \) for the PNPM are set equal to zero. The positive contribution of \( d_\nu \Psi_\nu^2 = \left[ \frac{\partial \Psi_\nu}{\partial t} \right]^2 \) to the integral in Eq. (41) can be eliminated by choosing \( \Psi_\nu = \Psi_{\nu}(H_{\nu, p_{\nu_2}, p_{\nu_3}}) \). In this case, Eq. (41) reduces to

\[ \delta^2 H = (\delta^2 H)_{\text{PPM}} \]
\[
\begin{align*}
\sum \int \frac{s_0}{4m^3_\nu} d\mathcal{H}_\nu d\nu_2 d\nu_3 \frac{4\pi^2}{\tau} \Psi^2_\nu \\
\times \left[ -\frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \right] \left[ n_\nu + \frac{\tau}{2\pi} \langle k_{23} \cdot \mathbf{v} \rangle \right] \left[ n_\nu + \frac{\tau}{2\pi} \frac{1}{m_\nu} \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \frac{1}{2\pi} \langle k_{23} \cdot \frac{\partial f^{(0)}_\nu}{\partial \mathbf{v}} \rangle \right] \right) .
\end{align*}
\]

(48)

Since \( \Psi_\nu \) is localized around \( \mathcal{H}_{\nu_0}, \nu_{\nu_20}, \nu_{\nu_30} \), the condition for \( \delta^2 H < 0 \) is

\[
\left[ -\frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \right] \left[ n_\nu + \frac{\tau}{2\pi} \langle k_{23} \cdot \mathbf{v} \rangle \right] \left[ n_\nu + \frac{\tau}{2\pi} \frac{1}{m_\nu} \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \frac{1}{2\pi} \langle k_{23} \cdot \frac{\partial f^{(0)}_\nu}{\partial \mathbf{v}} \rangle \right] < 0 ,
\]

(49)

or, equivalently, when Eq. (42) is taken into account,

\[
\left[ -\frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \right] \left[ n_\nu + \frac{\tau}{2\pi} \langle k_{23} \cdot \mathbf{v} \rangle \right] \times \left[ n_\nu + \frac{\tau}{2\pi} \langle k_{23} \cdot \mathbf{v} \rangle + \frac{\tau}{2\pi} \frac{1}{m_\nu} \left[ k_2 \frac{\partial f^{(0)}_\nu}{\partial \nu_2} + k_3 \frac{\partial f^{(0)}_\nu}{\partial \nu_3} \right] \right] < 0 .
\]

(50)

If \( \langle k_{23} \cdot \mathbf{v} \rangle \left\langle k_{23} \cdot \frac{\partial f^{(0)}_\nu}{\partial \mathbf{v}} \right\rangle \rangle > 0 \), it is clear that choosing \( n_\nu = 0 \) satisfies inequality (49) without any conditions being imposed on \( k_{23} \), except \( k_{23} \neq 0 \). For a homogeneous plasma with constant \( B^{(0)} \), and choosing \( k_{23} = k_{||}\mathbf{e}_B \), one obtains the result of Morrison and Pfirsch, Eq. (144.b) of Ref. [2], which was obtained in the context of drift-kinetic theory. For a \( y \)-dependent, force-free plasma slab, and choosing \( k_{23} = k_{||}\mathbf{e}_B (y = y_0) \), one obtains the result of Ref. [7], which is also valid for a guiding centre plasma [9].

If \( \langle k_{23} \cdot \mathbf{v} \rangle \left\langle k_{23} \cdot \frac{\partial f^{(0)}_\nu}{\partial \mathbf{v}} \right\rangle \rangle < 0 \), inequality (50) can also be satisfied. With the arguments of the mean values given explicitly for the sake of clarity, this inequality can be written as

\[
\left[ -\frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \right] k_3^2 \left[ \frac{n_\nu}{k_3} + b_\nu(\mathcal{H}_\nu, \nu_{\nu_20}, \nu_{\nu_30}; \frac{k_2}{k_3}) \right] \\
\times \left[ \frac{n_\nu}{k_3} + b_\nu(\mathcal{H}_\nu, \nu_{\nu_20}, \nu_{\nu_30}; \frac{k_2}{k_3}) + h_\nu(\mathcal{H}_\nu, \nu_{\nu_20}, \nu_{\nu_30}; \frac{k_2}{k_3}) \right] < 0 ,
\]

(51)
where
\[
b_\nu(\mathcal{H}_\nu, p_{\nu 2}, p_{\nu 3}; \frac{k_2}{k_3} = \frac{\tau}{2\pi} \left\langle \frac{k_{23}}{k_3} \cdot \nu \right\rangle,
\]
\[
h_\nu(\mathcal{H}_\nu, p_{\nu 2}, p_{\nu 3}; \frac{k_2}{k_3} = \frac{\tau}{2\pi} \frac{1}{\mathcal{H}_\nu} \left[ \frac{k_2}{k_3} \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 2}} + \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 3}} \right].
\]

Instead of prescribing the two arbitrary components \(k_2, k_3\), one can consider \(k_3\) and the quotient \(\frac{k_2}{k_3}\) as independent of each other.

Inequality (51) is satisfied if one factor is positive and the other is negative. This is the case (since \(-\frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} > 0\) here) if either
\[
0 < \frac{n_\nu}{k_3} + b_\nu < -h_\nu \quad \text{(for } h_\nu < 0) \tag{54}
\]
or
\[
-h_\nu < \frac{n_\nu}{k_3} + b_\nu < 0 \quad \text{(for } h_\nu > 0) \tag{55}
\]
which can always be satisfied by choosing the arbitrary \(\frac{n_\nu}{k_3}\) correspondingly.

Inequalities (54) and (55) extend to the general one-dimensional case the results obtained for a homogeneous plasma in Ref. [6], and for a force-free plasma slab with shear in Ref. [7]. The quantity
\[
1 + \frac{h_\nu}{b_\nu}
\]
can be interpreted as the local anisotropy of the distribution function in phase space, and coincides with the previous definition of the anisotropy in the homogeneous and force-free cases.

It has just been shown that, when \(\frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} > 0\), it is always possible to have \(\delta^2 H < 0\) without any restriction on \(k_{23}\) or the spatial variation of the perturbation across \(B^{(0)}\). When \(\frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} < 0\) and \(\left\langle k_{23} \cdot \nu \right\rangle \left( k_{23} \cdot \frac{\partial f^{(0)}_\nu}{\partial \nu} \right) > 0\), it is also possible to have \(\delta^2 H < 0\) without any restriction on \(k_{23}\), except \(k_{23} \neq 0\), and without any restrictions on the spatial variation of the perturbation across \(B^{(0)}\). In the case where \(\frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} < 0\) and \(\left\langle k_{23} \cdot \nu \right\rangle \left( k_{23} \cdot \frac{\partial f^{(0)}_\nu}{\partial \nu} \right) \left| x \right| < 0\), \(\delta^2 H < 0\) is also possible.
In this case, however, $\frac{n_\nu}{k_3}$ is restricted by inequalities (54) or (55), which reflect the explicit dependence of the equilibrium distribution function on the canonical momenta, i.e. the (local) anisotropy of $f^{(0)}_\nu$.

If $\frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} < 0$ and $\frac{\partial f^{(0)}_\nu}{\partial p_{\nu 2}} = 0$, $\frac{\partial f^{(0)}_\nu}{\partial p_{\nu 3}} = 0$, then $h_\nu = 0$ for $\mathcal{H}_\nu = \mathcal{H}_{\nu 0}$, $p_{\nu 2} = p_{\nu 2 0}$, $p_{\nu 3} = p_{\nu 3 0}$, the equilibrium distribution function is locally monotonically decreasing and isotropic, and inequality (51) cannot be satisfied for these $\mathcal{H}_{\nu 0}$, $p_{\nu 2 0}$, $p_{\nu 3 0}$.

If $\frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} < 0$ and $h_\nu = 0$ for all $\mathcal{H}_\nu, p_{\nu 2}, p_{\nu 3}$, then $f^{(0)}_\nu = f^{(0)}_\nu(\mathcal{H}_\nu)$, the equilibrium is everywhere isotropic and homogeneous, and there is no electric current since $\nabla \times \mathbf{B}^{(0)} = 0$ in this case. The equilibrium distribution functions are monotonically decreasing functions of the particle energy, and no negative-energy modes are possible, in accordance with the general results obtained in Section II and Ref. [8].

5.2 The perturbation energy $(\delta^2 H)_{PNPM}$ for particles with non-periodic motion

It should be noted that the particles with non-periodic motion usually do not have the same importance as those with periodic motion. For instance, in a homogeneous equilibrium, there are only particles with periodic motion (Appendix C and Ref. [7]); also, in the case of a force-free plane slab configuration, the overwhelming majority of particles perform a periodic motion, as shown in Ref. [7]. The particles with non-periodic motion, however, must be taken into account when the equilibrium distribution functions allow arbitrarily large velocities and energies, e.g. when one considers Maxwell-like distributions, which could then lead to the particles being untrapped and having a non-periodic motion, as described in Appendix C.

To study the sign of $(\delta^2 H)_{PNPM}$, Eq. (37), one again has to distinguish the following two cases:

5.2.1 $k_2 = k_3 = 0$, perpendicular wave propagation

If follows immediately from Eq. (37) that $\delta^2 H < 0$ if $\frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} > 0$ for some $\mathcal{H}_\nu, p_{\nu 2}, p_{\nu 3}$ corresponding to PNPM, and for any particle species $\nu$. This means that the presence of a local minimum with respect to $\mathcal{H}_\nu$ in $f^{(0)}_\nu(\mathcal{H}_\nu, p_{\nu 2}, p_{\nu 3})$ guarantees $\delta^2 H < 0$, without any restrictions on the spatial variation of the perturba-
tions perpendicular to $B^{(0)}$: it suffices to localize $\Psi_\nu$ ($d_\nu \Psi_\nu$ is then also localized) to the region in $H_\nu, p_{\nu 2}, p_{\nu 3}$ where $\frac{\partial f_\nu^{(0)}}{\partial H_\nu} > 0$. Outside this region $\Psi_\nu$ vanishes. All other $\Psi_\mu$ are set equal to zero. The $\Psi_\nu$ corresponding to the PPM are likewise all set equal to zero, so that $(\delta^2H)_{PPM} = 0$. The sign of $\delta^2H = (\delta^2H)_{NPPM}$ is then determined only by the sign of the integrand in the region of localization, which is then negative.

5.2.2 $k_2 \neq 0$ and/or $k_3 \neq 0$, $k_{23} \cdot B^{(0)} \neq 0$

If $\frac{\partial f_\nu^{(0)}}{\partial H_\nu} > 0$ for some $H_\nu, p_{\nu 2}, p_{\nu 3}$, the positive contribution of the term dependent on $k_2, k_3$ in Eq. (37) can be completely eliminated with the help of the arbitrary $C_\nu$. Then, the same line of reasoning as in the preceding case shows that $\delta^2H$ is negative.

If $\frac{\partial f_\nu^{(0)}}{\partial H_\nu} < 0$ for some $H_\nu, p_{\nu 2}, p_{\nu 3}$, the positive contribution of $[d_\nu \Psi_\nu]^2$ can be eliminated by choosing $\Psi_\nu$ as a function of the constants of the motion only, i.e., $\Psi_\nu = \Psi_\nu(H_\nu, p_{\nu 2}, p_{\nu 3})$, $d_\nu \Psi_\nu = 0$, and the contribution of $C_\nu^2$ is eliminated by choosing $C_\nu = 0$. No condition is imposed on $k_2, k_3$ or, alternatively, on $k_{23}$ except $k_{23} \neq 0$. If the equilibrium is locally monotonically decreasing and isotropic, i.e. if $\frac{\partial f_\nu^{(0)}}{\partial H_\nu} < 0$ and $\frac{\partial f_\nu^{(0)}}{\partial p_{\nu 2}} = 0$, $\frac{\partial f_\nu^{(0)}}{\partial p_{\nu 3}} = 0$ for $H_\nu = H_{\nu 0}, p_{\nu 2} = p_{\nu 20}$, and $p_{\nu 3} = p_{\nu 30}$, then $\delta^2H$ cannot be made negative at these values of $H_\nu, p_{\nu 2}$ and $p_{\nu 3}$, as was also the case for the PPM.

It has just been shown that if there is nonmonotonicity ($\frac{\partial f_\nu^{(0)}}{\partial H_\nu} > 0$) for some $H_\nu, p_{\nu 2}, p_{\nu 3}$ corresponding to particles with non-periodic motion, $\delta^2H$ can be made negative without imposing any condition on $k_{23}$. If $f_\nu^{(0)}$ is locally monotonic ($\frac{\partial f_\nu^{(0)}}{\partial H_\nu} < 0$), but anisotropic ($\frac{\partial f_\nu^{(0)}}{\partial p_{\nu 2}} \neq 0$ and/or $\frac{\partial f_\nu^{(0)}}{\partial p_{\nu 3}} \neq 0$). This local anisotropy in phase space does not exclude isotropic pressure tensors), $\delta^2H$ can also be made negative without imposing any condition on $k_{23}$, except $k_{23} \neq 0$. No restrictive assumptions have to be made concerning the behaviour of the perturbations across the magnetic field.

6 Conclusions

The general expression for the free energy $\delta^2H$ available upon arbitrary perturbations of general Vlasov-Maxwell equilibria derived by Morrison and Pfirsch [1] was transformed to a relatively simple and compact expression (Eqs. (6) and
(12)) which is very convenient for applications. From this expression, a previous result of Weitzner and Pfirsch [8] is immediately obtained, namely that equilibria for which the equilibrium distribution functions depend only on the particle energy and are monotonically decreasing do not allow negative-energy perturbations.

The general expression for the perturbation energy is then evaluated for arbitrary, double-symmetric, i.e. one-dimensional, equilibria. In generalized coordinates \( q_1, q_2, q_3 \), such equilibria depend only on \( q_1 \), the equilibrium magnetic field \( B^{(0)} \) is perpendicular to \( \nabla q_1 \), \( B^{(0)} \cdot \nabla q_1 = 0 \), and the equilibrium distribution functions of each particle species \( \nu \) are of the general form \( f^{(0)}_\nu = f^{(0)}_\nu(\mathcal{H}_\nu, p_{\nu 2}, p_{\nu 3}) \), where \( \mathcal{H}_\nu \) is the (conserved) particle energy and \( p_{\nu 2}, p_{\nu 3} \) are the (conserved) canonical momenta corresponding to the two ignorable coordinates \( q_2, q_3 \), respectively. For these equilibria, the following results are obtained.

Perturbations of negative energy \( (\delta^2 H < 0) \) exist for any local deviation from monotonicity (i.e. if \( \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} > 0 \) for some \( \mathcal{H}_\nu, p_{\nu 2}, p_{\nu 3} \)) of the distribution function of any of the particle species \( \nu \), and for any wave vector \( k = k_2 \nabla q_2 + k_3 \nabla q_3 \), without restrictions on the behaviour of the perturbations across the equilibrium magnetic field, i.e. large gradients of the perturbations across \( B^{(0)} \) are not needed.

If \( \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} < 0 \), only waves with \( k_2 \neq 0 \) (which therefore have a component in the direction of \( B^{(0)} \)) can possess negative energy.

For any \( \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \), if \( \langle k_2 \cdot v \rangle \left( k_2 \cdot \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \right) > 0 \) (the angles mean averages along the unperturbed particle orbits), negative-energy perturbations also exist, with no restriction on \( k_2 \), except \( k_2 \neq 0 \), and without requiring large gradients of the perturbations across \( B^{(0)} \).

If both \( \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} < 0 \) and \( \langle k_2 \cdot v \rangle \left( k_2 \cdot \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \right) < 0 \), but if \( \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 2}} \) and \( \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 3}} \) are not both identically zero for all \( \nu \), negative-energy perturbations also exist (\( \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 2}} = \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 3}} = 0 \) for all \( \nu \) only for equilibria which are everywhere isotropic, \( f^{(0)}_\nu = f^{(0)}_\nu(\mathcal{H}_\nu) \), which therefore have no electric current; for all cases of practical interest, \( \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 2}} \) and \( \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 3}} \) do not vanish identically). In this case, however, \( k_2 \) is not completely arbitrary, since \( \frac{n_{\nu}}{k_3} \) is restricted by inequalities (54) and (55). As in the preceding situations, no large gradients across \( B^{(0)} \) are needed in this case either.

The results derived here include those previously obtained in the case of a homogeneous plasma [6], and in the case of a force-free plasma with shear [7];
they are, however, much more general since they apply to all one-dimensional equilibria.
APPENDIX A

Relations for the transformation of the perturbation energy

The second-order perturbation energy, Eq. (3), can be put in a very convenient form by means of the relations derived in this appendix.

By taking the identities \( \frac{\partial}{\partial \mathbf{v}} \times \mathbf{v} = 0 \) and \( \frac{\partial}{\partial \mathbf{v}} \times \frac{\partial f^{(0)}_{\nu}}{\partial \mathbf{v}} = 0 \) into account the term \( \frac{\partial f^{(0)}_{\nu}}{\partial \mathbf{v}} \cdot \frac{e_{\nu}}{m_{\nu} c} G_{\nu} \mathbf{v} \times \frac{\partial}{\partial \mathbf{v}} \left( \mathbf{B}^{(0)} \cdot \frac{\partial G_{\nu}}{\partial \mathbf{x}} \right) \) can be expressed as the sum of a divergence in \( \mathbf{v} \) space, which vanishes after integration, and another term, according to the equation

\[
\frac{\partial f^{(0)}_{\nu}}{\partial \mathbf{v}} \cdot \frac{e_{\nu}}{m_{\nu} c} G_{\nu} \mathbf{v} \times \frac{\partial}{\partial \mathbf{v}} \left( \mathbf{B}^{(0)} \cdot \frac{\partial G_{\nu}}{\partial \mathbf{x}} \right) = \frac{-e_{\nu}}{m_{\nu} c} G_{\nu} \frac{\partial f^{(0)}_{\nu}}{\partial \mathbf{v}} \cdot \frac{\partial}{\partial \mathbf{v}} \left( \mathbf{B}^{(0)} \cdot \frac{\partial G_{\nu}}{\partial \mathbf{x}} \right) \times \mathbf{v}
\]

\[
= \frac{\partial}{\partial \mathbf{v}} \left[ \frac{e_{\nu}}{m_{\nu} c} G_{\nu} \left( \mathbf{B}^{(0)} \cdot \frac{\partial G_{\nu}}{\partial \mathbf{x}} \right) \right] \cdot \frac{\partial f^{(0)}_{\nu}}{\partial \mathbf{v}} \times \mathbf{v}
\]

\[
+ \frac{\partial f^{(0)}_{\nu}}{\partial \mathbf{v}} \cdot \frac{e_{\nu}}{m_{\nu} c} G_{\nu} \left( \mathbf{B}^{(0)} \cdot \frac{\partial G_{\nu}}{\partial \mathbf{x}} \right) \frac{\partial G_{\nu}}{\partial \mathbf{v}} \times \mathbf{v}.
\]

(A.1)

The term \( -\frac{\partial f^{(0)}_{\nu}}{\partial \mathbf{v}} \cdot \frac{e_{\nu}}{m_{\nu} c} G_{\nu} \frac{\partial}{\partial \mathbf{v}} \left( \frac{\partial G_{\nu}}{\partial \mathbf{x}} \times \mathbf{E}^{(0)} \right) \) can be similarly transformed to yield

\[
-\frac{\partial f^{(0)}_{\nu}}{\partial \mathbf{v}} \cdot \frac{e_{\nu}}{m_{\nu} c} G_{\nu} \frac{\partial}{\partial \mathbf{v}} \left( \frac{\partial G_{\nu}}{\partial \mathbf{x}} \times \mathbf{E}^{(0)} \right) = \frac{\partial}{\partial \mathbf{v}} \left[ \frac{e_{\nu}}{m_{\nu} c} G_{\nu} \frac{\partial f^{(0)}_{\nu}}{\partial \mathbf{v}} \times \left( \frac{\partial G_{\nu}}{\partial \mathbf{x}} \times \mathbf{E}^{(0)} \right) \right]
\]

\[
- \frac{e_{\nu}}{m_{\nu}} \left( \frac{\partial G_{\nu}}{\partial \mathbf{x}} \times \mathbf{E}^{(0)} \right) \cdot \frac{\partial}{\partial \mathbf{v}} \left( G_{\nu} \frac{\partial f^{(0)}_{\nu}}{\partial \mathbf{v}} \right)
\]

\[
= \frac{\partial}{\partial \mathbf{v}} \left[ \frac{e_{\nu}}{m_{\nu} c} G_{\nu} \frac{\partial f^{(0)}_{\nu}}{\partial \mathbf{v}} \times \left( \frac{\partial G_{\nu}}{\partial \mathbf{x}} \times \mathbf{E}^{(0)} \right) \right]
\]

\[
- \frac{e_{\nu}}{m_{\nu}} \left( \frac{\partial G_{\nu}}{\partial \mathbf{x}} \times \mathbf{E}^{(0)} \right) \cdot \frac{\partial f^{(0)}_{\nu}}{\partial \mathbf{v}}.
\]

(A.2)
The stationary Vlasov’s equation is $d_\nu f^{(0)}_\nu = 0$, where $d_\nu$ is the operator defined in Eqs. (4) and (5). With the help of the vector $\mathbf{F}^{(0)}_\nu$, defined by Eq. (7), namely

$$
\mathbf{F}^{(0)}_\nu = \frac{\partial f^{(0)}_\nu}{\partial \mathbf{x}} + \frac{e_\nu}{m_\nu c} \mathbf{B}^{(0)} \times \frac{\partial f^{(0)}_\nu}{\partial \mathbf{v}},
$$

the equilibrium Vlasov’s equation then takes the form given by Eq.(8):

$$
d_\nu f^{(0)}_\nu = \mathbf{F}^{(0)}_\nu \cdot \mathbf{v} + \frac{e_\nu}{m_\nu} \mathbf{E}^{(0)} \cdot \frac{\partial f^{(0)}_\nu}{\partial \mathbf{v}} = 0,
$$

and one has

$$
\frac{\partial f^{(0)}_\nu}{\partial x} \cdot \left\{ \left[ \frac{\partial G_{\nu}}{\partial x} \cdot \frac{\partial G_{\nu}}{\partial v} \right] v + \left( d_\nu G_{\nu} \right) \frac{\partial G_{\nu}}{\partial v} \right\} = \left[ \mathbf{F}^{(0)}_\nu - \frac{e_\nu}{m_\nu c} \mathbf{B}^{(0)} \times \frac{\partial f^{(0)}_\nu}{\partial \mathbf{v}} \right] \cdot \left[ \left( \frac{\partial G_{\nu}}{\partial x} \cdot \frac{\partial G_{\nu}}{\partial v} \right) v + \left( d_\nu G_{\nu} \right) \frac{\partial G_{\nu}}{\partial v} \right]
$$

$$
= \frac{e_\nu}{m_\nu} \left[ \frac{\partial G_{\nu}}{\partial x} \cdot \frac{\partial G_{\nu}}{\partial v} \right] \mathbf{E}^{(0)} \cdot \frac{\partial f^{(0)}_\nu}{\partial v} + \left( d_\nu G_{\nu} \right) \mathbf{F}^{(0)}_\nu \cdot \frac{\partial G_{\nu}}{\partial v}
$$

$$
+ \frac{e_\nu}{m_\nu c} \left[ \left( v \times \mathbf{B}^{(0)} \right) \cdot \frac{\partial f^{(0)}_\nu}{\partial v} \right] \left[ \frac{\partial G_{\nu}}{\partial x} \cdot \frac{\partial G_{\nu}}{\partial v} \right] + \left( d_\nu G_{\nu} \right)
$$

$$
+ \frac{e_\nu}{m_\nu} \left[ \mathbf{B}^{(0)} \times \frac{\partial G_{\nu}}{\partial v} \right] \cdot \frac{\partial f^{(0)}_\nu}{\partial v} \left( d_\nu G_{\nu} \right)
$$

$$
= \left[ a^{(0)}_\nu \cdot \frac{\partial f^{(0)}_\nu}{\partial v} \right] \left[ \frac{\partial G_{\nu}}{\partial x} \cdot \frac{\partial G_{\nu}}{\partial v} \right] + \left( d_\nu G_{\nu} \right) \mathbf{F}^{(0)}_\nu \cdot \frac{\partial G_{\nu}}{\partial v}
$$

$$
+ \frac{e_\nu}{m_\nu c} \left[ \mathbf{B}^{(0)} \times \frac{\partial G_{\nu}}{\partial v} \right] \cdot \frac{\partial f^{(0)}_\nu}{\partial v} \left( d_\nu G_{\nu} \right). \quad \text{(A.3)}
$$
The last term in Eq. (A.1) can also be further transformed if one takes into account the relation

\[
\frac{e_\nu}{m_\nu c} \left[ \mathbf{B}^{(0)} \cdot \frac{\partial G_\nu}{\partial x} \right] \frac{\partial G_\nu}{\partial \nu} \times \mathbf{v}
\]

\[
= \frac{e_\nu}{m_\nu c} \frac{\partial G_\nu}{\partial \nu} \times \left[ \frac{\partial G_\nu}{\partial \nu} \times (\mathbf{v} \times \mathbf{B}^{(0)}) + \left( \mathbf{v} \cdot \frac{\partial G_\nu}{\partial x} \right) \mathbf{B}^{(0)} \right]
\]

\[
= \frac{\partial G_\nu}{\partial \nu} \times \left[ \frac{\partial G_\nu}{\partial \nu} \times a^{(0)}_\nu - \frac{e_\nu}{m_\nu} \frac{\partial G_\nu}{\partial x} \times \mathbf{E}^{(0)} \right]
\]

\[
+ \frac{e_\nu}{m_\nu c} (d_\nu G_\nu) \mathbf{B}^{(0)} - \frac{e_\nu}{m_\nu c} \left( a^{(0)}_\nu \cdot \frac{\partial G_\nu}{\partial \nu} \right) \mathbf{B}^{(0)} \right] . \quad (A.4)
\]
APPENDIX B

Convenient representation of derivatives in \( x - v \) space

For time-independent equilibrium fields \( \mathbf{E}^{(0)} = - \nabla \Phi^{(0)} \) and \( \mathbf{B}^{(0)} = \nabla \times \mathbf{A}^{(0)} \), the particle energy \( \mathcal{H}_\nu = \frac{m_\nu}{2} (v)^2 + \epsilon_\nu \Phi^{(0)} \) is a constant of the motion. The equilibrium distribution functions \( f^{(0)}_\nu \) can be written as

\[
f^{(0)}_\nu(x,v) = f^{(0)}_\nu(\mathcal{H}_\nu(x,v), \mathcal{K}_{\nu\kappa}(x,v)),
\]

where \( \kappa \) runs over as many indices as there are other constants of the motion \( \mathcal{K}_{\nu\kappa} \) in the problem under consideration. The derivatives of \( f^{(0)}_\nu \) are then

\[
\begin{align*}
\frac{\partial f^{(0)}_\nu}{\partial x} & = -\epsilon_\nu \mathbf{E}^{(0)} \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} + \frac{\partial \mathcal{K}_{\nu\kappa}}{\partial x} \frac{\partial f^{(0)}_\nu}{\partial \mathcal{K}_{\nu\kappa}} \mathcal{H}_\nu, \\
\frac{\partial f^{(0)}_\nu}{\partial v} & = m_\nu v \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} + \frac{\partial \mathcal{K}_{\nu\kappa}}{\partial v} \frac{\partial f^{(0)}_\nu}{\partial \mathcal{K}_{\nu\kappa}} \mathcal{H}_\nu,
\end{align*}
\]

(B.1)

(B.2)

where the summation convention has been adopted (the quantities kept constant when partial derivatives are calculated are given explicitly only when this is particularly convenient). The vector \( \mathbf{F}^{(0)}_\nu \), Eq.(7), is then

\[
\mathbf{F}^{(0)}_\nu = -m_\nu \mathbf{a}^{(0)}_\nu \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} + \frac{\partial f^{(0)}_\nu}{\partial \mathcal{K}_{\nu\kappa}} \left[ \frac{\partial \mathcal{K}_{\nu\kappa}}{\partial x} + \frac{\epsilon_\nu}{m_\nu c} \mathbf{B}^{(0)} \times \frac{\partial \mathcal{K}_{\nu\kappa}}{\partial v} \right],
\]

(B.3)

and the quantity \( \mathbf{F}^{(0)}_\nu \cdot \frac{\partial G_\nu}{\partial v} - \frac{\partial f^{(0)}_\nu}{\partial v} \cdot \frac{\partial G_\nu}{\partial x} \), which appears in Eq. (6), takes the form

\[
\begin{align*}
\mathbf{F}^{(0)}_\nu \cdot \frac{\partial G_\nu}{\partial v} - \frac{\partial f^{(0)}_\nu}{\partial v} \cdot \frac{\partial G_\nu}{\partial x} = & \\
& -m_\nu \left[ \mathbf{a}^{(0)}_\nu \cdot \frac{\partial G_\nu}{\partial v} \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} + \frac{\partial f^{(0)}_\nu}{\partial \mathcal{K}_{\nu\kappa}} \frac{\partial G_\nu}{\partial \mathcal{K}_{\nu\kappa}} \left[ \frac{\partial \mathcal{K}_{\nu\kappa}}{\partial x} + \frac{\epsilon_\nu}{m_\nu c} \mathbf{B}^{(0)} \times \frac{\partial \mathcal{K}_{\nu\kappa}}{\partial v} \right] \right] \\
& -m_\nu \left[ v \cdot \frac{\partial G_\nu}{\partial x} \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} - \frac{\partial f^{(0)}_\nu}{\partial \mathcal{K}_{\nu\kappa}} \frac{\partial G_\nu}{\partial \mathcal{K}_{\nu\kappa}} \frac{\partial \mathcal{K}_{\nu\kappa}}{\partial x} \right] \\
& = -m_\nu (d_\nu G_\nu) \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} + \frac{\partial f^{(0)}_\nu}{\partial \mathcal{K}_{\nu\kappa}} \frac{\partial G_\nu}{\partial \mathcal{K}_{\nu\kappa}} \left[ \frac{\partial \mathcal{K}_{\nu\kappa}}{\partial x} + \frac{\epsilon_\nu}{m_\nu c} \mathbf{B}^{(0)} \times \frac{\partial \mathcal{K}_{\nu\kappa}}{\partial v} \right] \\
& \frac{\partial f^{(0)}_\nu}{\partial \mathcal{K}_{\nu\kappa}} \frac{\partial \mathcal{K}_{\nu\kappa}}{\partial x} \cdot \frac{\partial G_\nu}{\partial x}.
\end{align*}
\]

(B.4)
Let $q_i(x)$, $i = 1, \ldots 3$ now be generalized coordinates with covariant basis $\frac{\partial x}{\partial q_i}$ and contravariant basis $\frac{\partial q_i}{\partial x} = \nabla q_i$. The corresponding covariant and contravariant velocity components are, respectively,

$$v_i(x, v) = v \cdot \frac{\partial x}{\partial q_i} \quad \text{(B.5)}$$

and

$$v^i(x, v) = v \cdot \nabla q_i = \dot{q}_i \quad \text{(B.6)}$$

Since $v = v_i \nabla q_i$, one has

$$\frac{\partial v}{\partial v_i} = \nabla q_i \quad \text{(B.7)}$$

With $\mathcal{K}_{\nu \kappa}(x, v)$ taken as $\mathcal{K}_{\nu \kappa}(x, v_i(x, v))$, the derivatives are

$$\frac{\partial \mathcal{K}_{\nu \kappa}}{\partial x} \bigg|_v = \frac{\partial \mathcal{K}_{\nu \kappa}}{\partial x} \bigg|_{v_i} + \frac{\partial \mathcal{K}_{\nu \kappa}}{\partial v_i} \bigg|_x \frac{\partial v_i}{\partial x} \bigg|_v$$

$$= \frac{\partial \mathcal{K}_{\nu \kappa}}{\partial x} \bigg|_{v_i} + \left[ \frac{\partial v}{\partial v_i} \cdot \frac{\partial \mathcal{K}_{\nu \kappa}}{\partial v} \bigg|_x \right] \frac{\partial v_i}{\partial x} \bigg|_v$$

$$= \frac{\partial \mathcal{K}_{\nu \kappa}}{\partial x} \bigg|_{v_i} + \left[ \nabla q_i \cdot \frac{\partial \mathcal{K}_{\nu \kappa}}{\partial v} \bigg|_x \right] \frac{\partial v_i}{\partial x} \bigg|_v \quad \text{(B.8)}$$

and correspondingly for $G_{\nu}$

$$\frac{\partial G_{\nu}}{\partial x} \bigg|_v = \frac{\partial G_{\nu}}{\partial x} \bigg|_{v_i} + \left[ \nabla q_i \cdot \frac{\partial G_{\nu}}{\partial v} \bigg|_x \right] \frac{\partial v_i}{\partial x} \bigg|_v \quad \text{(B.9)}$$

Equations (B.4), (B.8) and (B.9) then yield

$$\mathbf{F}^{(0)}_{\nu} \cdot \left. \frac{\partial G_{\nu}}{\partial v} \bigg|_x - \frac{\partial f^{(0)}_{\nu}}{\partial v} \bigg|_x \cdot \frac{\partial G_{\nu}}{\partial x} \bigg|_v \right. =$$

$$-m_{\nu} (d_{\nu} G_{\nu}) \frac{\partial f^{(0)}_{\nu}}{\partial H_{\nu}} - \frac{\partial f^{(0)}_{\nu}}{\partial \mathcal{K}_{\nu \kappa}} \frac{\partial \mathcal{K}_{\nu \kappa}}{\partial v} \cdot \frac{\partial G_{\nu}}{\partial x} \bigg|_{v_i}$$

$$+ \frac{\partial f^{(0)}_{\nu}}{\partial \mathcal{K}_{\nu \kappa}} \frac{\partial G_{\nu}}{\partial v} \left[ \frac{\partial \mathcal{K}_{\nu \kappa}}{\partial x} \bigg|_{v_i} + \left[ \nabla q_i \cdot \frac{\partial \mathcal{K}_{\nu \kappa}}{\partial v} \bigg|_x \right] \frac{\partial v_i}{\partial x} \bigg|_v + \frac{e_{\nu}}{m_{\nu} c} B^{(0)}_{\nu} \times \frac{\partial \mathcal{K}_{\nu \kappa}}{\partial v} \right]$$

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\[- \left[ \frac{\partial v_i}{\partial x} \cdot \frac{\partial K_{\nu k}}{\partial v} \right] \nabla q_i \]

\[= -m_\nu (d_\nu G_\nu) \frac{\partial f_\nu^{(0)}}{\partial H_\nu} \frac{\partial K^{(0)}_{\nu k}}{\partial K_{\nu k}} \frac{\partial G_\nu}{\partial v} \bigg|_{v_i} + \frac{\partial f_\nu^{(0)}}{\partial K_{\nu k}} \frac{\partial G_\nu}{\partial v} \left[ \frac{\partial K_{\nu k}}{\partial x} \bigg|_{v_i} + \frac{e_\nu}{m_\nu c} B^{(0)} \times \frac{\partial K_{\nu k}}{\partial v} \right], \quad (B.10)\]

where the relation

\[\left[ \nabla q_i \cdot \frac{\partial K_{\nu k}}{\partial v} \right] \frac{\partial v_i}{\partial x} = \left[ \frac{\partial v_i}{\partial x} \cdot \frac{\partial K_{\nu k}}{\partial v} \right] \nabla q_i = \]

\[\frac{\partial K_{\nu k}}{\partial v} \times \left[ \frac{\partial v_i}{\partial x} \times \nabla q_i \right] \]

\[= \frac{\partial K_{\nu k}}{\partial v} \times \left[ \frac{\partial}{\partial x} \times (v_i \nabla q_i) \right] \]

\[= \frac{\partial K_{\nu k}}{\partial v} \times \left[ \frac{\partial}{\partial x} \times v \right] = 0 \quad (B.11)\]

has been taken into account.

The derivatives of \(G_\nu\) and \(K_{\nu k}\) with respect to \(x\) on the r.h.s. of Eq. (B.10) are now performed at constant \(v_i(x,v) = v \cdot \frac{\partial x}{\partial q_i}\), and not at constant \(v\).
APPENDIX C

Particle orbits: periodic motion and non-periodic motion in one-dimensional equilibria

The extremization of the second-order perturbation energy for configurations in which the equilibrium quantities depend on only one spatial coordinate, $q_1$, involves the determination of the constant of the motion $C_\nu(\mathcal{H}_\nu, p_{\nu 2}, p_{\nu 3})$, Eq.(34). To determine this constant, it is necessary to know whether the particles with given conserved energy $\mathcal{H}_\nu$ and conserved momenta $p_{\nu 2}$, $p_{\nu 3}$ perform a periodic motion in $(q_1, v_1, v_2, v_3)$ space. If $q_1(t)$ is a periodic variable, then so are $v_2(t)$ and $v_3(t)$, because, at constant $p_{\nu 2}$ and $p_{\nu 3}$, respectively, they depend only on $q_1$ (Eq. (C.2)). $v_1(t)$ is then also periodic since it depends only on $v_1 = \dot{q}_1$, $v_2$, $v_3$ and $q_1$ (Eq. (C.5)). This problem is investigated in this and in the following appendix.

Owing to the fact that the canonical momenta $p_{\nu 2}$, $p_{\nu 3}$ are constants of the motion, the particles moving in the magnetic field

$$
\mathbf{B}^{(0)} = \nabla \times (A_i^{(0)}(q_1) \nabla q_i) = \frac{1}{J(q_1)} \left[ -\frac{dA_3^{(0)}}{dq_1} \frac{\partial x}{\partial q_2} + \frac{dA_2^{(0)}}{dq_1} \frac{\partial x}{\partial q_3} \right]
$$

can be considered as effectively being in a one-dimensional potential $V_\nu(q_1)$, as will presently be shown.

(One can choose $A_i^{(0)} = 0$ without loss of generality.)

The Hamiltonian $H_\nu$ of a particle of species $\nu$ is given by

$$
H_\nu = \frac{m_\nu}{2} v^i v_i + e_\nu \Phi^{(0)}(q_1) , \ i = 1, \ldots 3 , \quad (C.1)
$$

where the velocities $v^i$, $v_i$ are related to the canonical momenta $p_{\nu i}$ by the equations

$$
v_i = v_i(p_{\nu i}, q_1) = \frac{1}{m_\nu} \left[ p_{\nu i} - \frac{e_\nu}{c} A_i^{(0)}(q_1) \right] , \quad (C.2)
$$

$$
v^i = g^{ik} v_k , \ i, k = 1, \ldots 3 , \quad (C.3)
$$

$$
g^{ik} = g^{ik}(q_1) = \nabla q_i \cdot \nabla q_k . \quad (C.4)
$$

From Eq. (C.3) one obtains

$$
v_1 = \frac{v^1}{g^{11}} - \frac{g^{1\lambda}}{g^{11}} v_\lambda , \ \lambda = 2, 3 , \quad (C.5)
$$

and $H_\nu$ can be written as

$$
H_\nu = \frac{m_\nu}{2} \left[ v^1 v_1 + v^\mu v_\mu \right] + e_\nu \Phi^{(0)} , \ \mu = 2, 3 \ , \quad (C.6)
$$

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\[ H_\nu = \frac{m_\nu}{2} \left[ v_1^2 + g^{1\mu}v_1 v_\mu + g^{\mu\lambda}v_\mu v_\lambda \right] + \epsilon_\nu \Phi^{(0)}, \quad \mu, \lambda = 2, 3. \]  

(C.7)

Inserting \( v_1 \) from Eq. (C.5) and taking into account that \( v^1 = \dot{q}_1 \), one can express this as

\[ H_\nu = \frac{m_\nu}{2} \frac{q_1^2}{g^{11}} + V_\nu(p_{\nu 2}, p_{\nu 3}, q_1), \]  

(C.8)

with

\[ V_\nu(p_{\nu 2}, p_{\nu 3}, q_1) = \frac{m_\nu}{2} \left[ -\frac{g^{1\mu}g^{1\lambda}}{g^{11}} v_\mu v_\lambda + g^{\mu\lambda}v_\mu v_\lambda \right] + \epsilon_\nu \Phi^{(0)} \quad \mu, \lambda = 2, 3. \]  

(C.9)

(The dependence on \( p_{\nu 2}, p_{\nu 3} \) is, of course, obtained from Eq. (C.2).)

From Eq. (C.8) one has, for a particle with conserved energy \( \mathcal{H}_\nu \) and conserved momenta \( p_{\nu 2}, p_{\nu 3} \)

\[ \dot{q}_1^2(\mathcal{H}_\nu, p_{\nu 2}, p_{\nu 3}, q_1) = \frac{2g^{11}(q_1)}{m_\nu} \left[ \mathcal{H}_\nu - V_\nu(p_{\nu 2}, p_{\nu 3}, q_1) \right]. \]  

(C.10)

If the potential \( V_\nu(p_{\nu 2}, p_{\nu 3}, q_1) \), as a function of \( q_1 \), has troughs, for instance a trough between two maxima \( V_{\nu \text{max}}(q_{1A}) \) and \( V_{\nu \text{max}}(q_{1B}) \), a particle of energy \( \mathcal{H}_\nu \) is trapped if \( \mathcal{H}_\nu < \min(V_{\nu \text{max}}) \), where \( \min(V_{\nu \text{max}}) \) is the smaller of the two maxima \( V_{\nu \text{max}}(q_{1A}), V_{\nu \text{max}}(q_{1B}) \). Otherwise, the particle is untrapped. For trapped particles, the motion is periodic; the particle oscillates between the turning points \( q_{1\alpha} \) and \( q_{1\beta} \), which can be determined from Eq. (C.10) by setting \( \dot{q}_1 = 0 \) and solving for \( q_1 \). A detailed discussion of the particle orbits can be found in Ref. [7] for the special case of a force-free plane slab configuration. In that case, it was found that the overwhelming majority of particles were trapped and performed a periodic motion.

As an example, consider a homogeneous equilibrium with no electric field, \( \Phi^{(0)} = 0 \), constant magnetic field \( B^{(0)} = B_0 \hat{e}_z \) and vector potential \( A^{(0)} = B_0(x - x_0) \hat{e}_y \), i.e. \( A^{(0)}_x = 0, A^{(0)}_y = B_0(x - x_0) \), \( A^{(0)}_z = 0 \). Therefore

\[ q_1 = x, \quad q_2 = y, \quad q_3 = z, \]  

(C.11)

and

\[ p_{\nu x} = m_\nu v_x, \quad p_{\nu y} = m_\nu v_y + \frac{e_\nu B^{(0)}(x - x_0)}{c}, \quad p_{\nu z} = m_\nu v_z. \]  

(C.12)

The potential, Eq.(C.9), is

\[ V_\nu = \frac{m_\nu}{e} \left[ v_y^2(p_{\nu y}, x) + v_z^2(p_{\nu z}) \right] \]

\[ = \frac{m_\nu}{2} \left[ \frac{p_{\nu y}^2}{m_\nu} - \frac{\omega_\nu(x - x_0)^2}{m_\nu^2} + \frac{p_{\nu z}^2}{m_\nu^2} \right], \]  

(C.13)
where $\omega_\nu = \frac{e_\nu B^{(0)}}{c m_\nu}$ is the gyration frequency. Since the potential is parabolic, all particles are trapped and have a periodic motion. The turning points follow from Eq. (C.10) with $v_x = 0$:

$$(x - x_0)_{\alpha, \beta} = \frac{1}{\omega_\nu} \left[ \frac{p_{\nu y}}{m_\nu} \pm \sqrt{\frac{2}{m_\nu} \mathcal{H}_\nu - \frac{p_{\nu x}^2}{m_\nu}} \right]$$

$$= \frac{1}{\omega_\nu} [v_y \pm v_y]$$

$$= R_g \pm R_g , \quad (C.14)$$

where $R_g$ is the gyroradius.

The general form of the equilibrium distribution functions, which do not depend on either $y$ or $z$ is, in this case, $f^{(0)}_\nu = f^{(0)}_\nu(\mathcal{H}_\nu, p_{\nu y}, p_{\nu z})$. However, if it is further required that $\frac{\partial f^{(0)}_\nu}{\partial x} \bigg|_\nu = 0$, then $f^{(0)}_\nu = f^{(0)}_\nu(\mathcal{H}_\nu, p_{\nu z})$. This case, which is a special case of the theory developed here, was treated in Ref. [6].
APPENDIX D

The constant of the motion \( C_\nu(\mathcal{H}_\nu, p_{\nu 2}, p_{\nu 3}) \)

The minimization of the perturbation energy \( \delta^2 H \), Eq. (30), with respect to \( \Gamma_\nu(q_1, v_1, v_2, v_3) \) leads to an equation of the form

\[
\left( \frac{d\Gamma_\nu}{dt} \right)_{\text{along orbit}} + \alpha_1(q_1, v_1, v_2, v_3) = \alpha_2(q_1, v_1, v_2, v_3) C_\nu(\mathcal{H}_\nu, p_{\nu 2}, p_{\nu 3}) .
\]

This follows from Eq. (34) since \( d_\nu \Gamma_\nu \) is the rate of change experienced by the moving particle along the unperturbed orbit, i.e., \( d_\nu \Gamma_\nu = \left( \frac{d\Gamma_\nu}{dt} \right)_{\text{along orbit}} \).

The question of interest in determining the constant of the motion \( C_\nu(\mathcal{H}_\nu, p_{\nu 2}, p_{\nu 3}) \) is whether the motion of the particle in \( (q_1, v_1, v_2, v_3) \) space is periodic or not. If it is periodic, \( q_1(t), v_1(t), v_2(t) \) and \( v_3(t) \) are periodic functions along the unperturbed particle orbits, with period \( \tau \),

\[
\tau = \oint_{q_1} dt .
\]

These particles constitute the group of particles with periodic motion, PPM. All other particles are the particles with non-periodic motion, PNPM.

For particles with periodic motion, mean values along the unperturbed orbits are now defined by the expression

\[
\langle \ldots \rangle = \left[ \int_{t_0}^{t_0 + \tau} \ldots dt \right] / \tau .
\]

Integrating Eq. (D.1) between \( t \) and \( t + \tau \) along orbits yields

\[
\Gamma_\nu(q_1(t + \tau), v_1(t + \tau), v_2(t + \tau), v_3(t + \tau)) - \Gamma_\nu(q_1(t), v_1(t), v_2(t), v_3(t)) + \tau \langle \alpha_1 \rangle = \tau \langle \alpha_2 \rangle C_\nu .
\]

Since, for the particles with periodic motion, \( q_1(t + \tau) = q_1(t) \), etc..., \( \Gamma_\nu(t + \tau) - \Gamma_\nu(t) \) in this equation is then determined from the fact that the generating function \( g_\nu(q_1, v_1, v_2, v_3) \) for the perturbations, Eq. (29), must be a single-valued function of its variables. Since

\[
g_\nu(q_1(t), \ldots) = \Psi_\nu(q_1(t), \ldots)e^{i\Gamma_\nu(q_1(t), \ldots)} ,
\]

\[31\]
this means that the functions $\Psi_\nu$ and $\Gamma_\nu$ are subject to the periodicity conditions

$$\Psi_\nu(q_1(t + \tau), \ldots) = \Psi_\nu(q_1(t), \ldots)$$  \hspace{1cm} (D.6)

and

$$\Gamma_\nu(q_1(t + \tau), \ldots) = \Gamma_\nu(q_1(t), \ldots) + 2\pi n_\nu,$$  \hspace{1cm} (D.7)

$n_\nu$ being any integer number, i.e., $n_\nu = 0, \pm 1, \ldots$ This then determines $C_\nu$ for the PPM from Eq. (D.4) as

$$C_\nu = \frac{1}{\langle \alpha_2 \rangle} \left[ \langle \alpha_1 \rangle + \frac{2\pi}{\tau} n_\nu \right],$$  \hspace{1cm} (D.8)

where, explicitly, from Eq. (34),

$$\alpha_1 = \frac{1}{2} \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \left[ 2 \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} k_{23} \cdot \mathbf{v} + k_2 \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 2}} + k_3 \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 3}} \right]$$

$$= \frac{1}{2} \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \left[ 2 k_{23} \cdot \frac{1}{m_\nu} \frac{\partial f^{(0)}_\nu}{\partial \mathbf{v}} \bigg|_{\mathbf{x}} - k_2 \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 2}} - k_3 \frac{\partial f^{(0)}_\nu}{\partial p_{\nu 3}} \right]$$

$$= \frac{1}{2} \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \left[ \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} k_{23} \cdot \mathbf{v} + k_{23} \cdot \frac{1}{m_\nu} \frac{\partial f^{(0)}_\nu}{\partial \mathbf{v}} \bigg|_{\mathbf{x}} \right],$$  \hspace{1cm} (D.9)

$$\alpha_2 = \frac{1}{2} \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \Psi^2_\nu.$$

(D.10)

On the other hand, for particles with non-periodic motion, Eq. (D.1) imposes no restriction on $C_\nu$. $C_\nu(\mathcal{H}_\nu, p_{\nu 2}, p_{\nu 3})$ can be chosen arbitrarily for the PNPM!
APPENDIX E

The coordinate system $t, \mathcal{H}_\nu, p_{\nu 2}, p_{\nu 3}$ in $q_1 - v_i$ space

It is useful to introduce coordinates which make discussion of the expression for the perturbation energy particularly simple.

Let the new coordinates be defined by the following transformation:

\[
\begin{bmatrix}
q_1 \\
v_1 \\
v_2 \\
v_3
\end{bmatrix} \quad \mapsto \quad \begin{bmatrix}
t = \int_{t_{q_1}}^{t_{q_1}} \frac{d\dot{q}_1}{\dot{q}_1} \\
\frac{\mathcal{H}_\nu}{p_{\nu 2}} \\
p_{\nu 2} \\
p_{\nu 3}
\end{bmatrix}.
\]  \hfill (E.1)

Therefore, one has

\[
\frac{\partial t}{\partial q_1} = \frac{1}{\dot{q}_1}, \quad \frac{\partial t}{\partial v_1} = 0, \quad \frac{\partial t}{\partial v_2} = 0, \quad \frac{\partial t}{\partial v_3} = 0.
\]  \hfill (E.2)

From the expressions for the particle energy, viz.

\[
\mathcal{H}_\nu = \frac{m_\nu}{2} g^{ij} (q_1) v_i v_j + e_\nu \Phi^{(0)} (q_1),
\]  \hfill (E.3)

and for the canonical momenta, viz.

\[
p_{\nu \kappa} = m_\nu v_\kappa + \frac{e_\nu}{c} A^{(0)}_\kappa (q_1),
\]  \hfill (E.4)

one obtains

\[
\frac{\partial \mathcal{H}_\nu}{\partial q_1} = \frac{m_\nu}{2} \frac{\partial g^{ij}}{\partial q_1} v_i v_j + e_\nu \frac{\partial \Phi^{(0)}}{\partial q_1},
\]  \hfill (E.5)

\[
\frac{\partial \mathcal{H}_\nu}{\partial v_1} = \frac{m_\nu}{2} \left[ g^{1j} v_j + g^{1i} v_i \right] = \frac{m_\nu}{2} \left[ v^1 + v^1 \right] = m_\nu v^1 = m_\nu \dot{q}_1,
\]  \hfill (E.6)

\[
\frac{\partial \mathcal{H}_\nu}{\partial v_2} = m_\nu \dot{q}_2, \quad \frac{\partial \mathcal{H}_\nu}{\partial v_3} = m_\nu \dot{q}_3,
\]  \hfill (E.7)
\[
\frac{\partial p_{\nu 2}}{\partial q_1} = \frac{e_{\nu}}{c} \frac{\partial A^{(0)}_2}{\partial q_1}, \quad \frac{\partial p_{\nu 2}}{\partial v_1} = 0, \quad \frac{\partial p_{\nu 2}}{\partial v_2} = m_{\nu}, \quad \frac{\partial p_{\nu 2}}{\partial v_3} = 0, \tag{E.8}
\]
\[
\frac{\partial p_{\nu 3}}{\partial q_1} = \frac{e_{\nu}}{c} \frac{\partial A^{(0)}_3}{\partial q_1}, \quad \frac{\partial p_{\nu 3}}{\partial v_1} = 0, \quad \frac{\partial p_{\nu 3}}{\partial v_2} = 0, \quad \frac{\partial p_{\nu 3}}{\partial v_3} = m_{\nu}. \tag{E.9}
\]

These relations enable one to calculate the Jacobian of the transformation
\[
\Delta = \frac{\partial (t, \mathcal{H}_\nu, p_{\nu 2}, p_{\nu 3})}{\partial (q_1, v_1, v_2, v_3)} \cdot \begin{vmatrix}
\frac{\partial t}{\partial q_1} & \frac{\partial t}{\partial v_1} & \frac{\partial t}{\partial v_2} & \frac{\partial t}{\partial v_3} \\
\frac{\partial \mathcal{H}_\nu}{\partial q_1} & \frac{\partial \mathcal{H}_\nu}{\partial v_1} & \frac{\partial \mathcal{H}_\nu}{\partial v_2} & \frac{\partial \mathcal{H}_\nu}{\partial v_3} \\
\frac{\partial p_{\nu 2}}{\partial q_1} & \frac{\partial p_{\nu 2}}{\partial v_1} & \frac{\partial p_{\nu 2}}{\partial v_2} & \frac{\partial p_{\nu 2}}{\partial v_3} \\
\frac{\partial p_{\nu 3}}{\partial q_1} & \frac{\partial p_{\nu 3}}{\partial v_1} & \frac{\partial p_{\nu 3}}{\partial v_2} & \frac{\partial p_{\nu 3}}{\partial v_3}
\end{vmatrix} \tag{E.10}
\]

One obtains
\[
\Delta = m_{\nu}^3, \tag{E.11}
\]
and the new coordinate system is therefore well-defined.

Taking into account Eq. (B.7), one obtains from the relations
\[
dt d\mathcal{H}_\nu dp_{\nu 2} dp_{\nu 3} = \Delta dq_1 dv_1 dv_2 dv_3 \tag{E.12}
\]
and
\[
d^3v = \frac{\partial \mathbf{v}}{\partial v_1} \cdot \frac{\partial \mathbf{v}}{\partial v_2} \times \frac{\partial \mathbf{v}}{\partial v_3} dv_1 dv_2 dv_3 = \nabla q_1 \cdot \nabla q_2 \times \nabla q_3 dv_1 dv_2 dv_3
\]
\[
= \frac{1}{J(q_1)} dv_1 dv_2 dv_3 \tag{E.13}
\]

the volume element in \( q_1 - v \) space,
\[
dq_1 d^3v = \frac{1}{J(q_1)m_{\nu}^3} dt d\mathcal{H}_\nu dp_{\nu 2} dp_{\nu 3}. \tag{E.14}
\]
APPENDIX F

Neglect of the electrostatic energy term

The contribution of the electrostatic energy term

\[ \frac{1}{8\pi} \int d^3x \delta E^2 \]  

has been neglected. To justify this, let us consider the perturbed electric charge density \( \delta \rho \). Generally, the charge density is

\[ \rho = \sum \nu e_\nu \int f_\nu d^3v \quad , \]  

and the perturbed charge density is

\[ \delta \rho = \sum \nu e_\nu \int \delta f_\nu d^3v \quad . \]  

The perturbation in the distribution function is given by

\[ \delta f_\nu = \left. \frac{\partial f_\nu^{(0)}}{\partial x} \right|_p \delta x_\nu + \left. \frac{\partial f_\nu^{(0)}}{\partial p_\nu} \right|_x \delta p_\nu \quad , \]  

with \( p_\nu \) the canonical momentum of species \( \nu \), given by Eq. (16). It therefore follows that

\[ \left. \frac{\partial f_\nu^{(0)}}{\partial \nu} \right|_x = m_\nu \left. \frac{\partial f_\nu^{(0)}}{\partial p_\nu} \right|_x \quad , \]  

\[ \left. \frac{\partial f_\nu^{(0)}}{\partial x} \right|_\nu = \left. \frac{\partial f_\nu^{(0)}}{\partial x} \right|_p + \left. \frac{\partial f_\nu^{(0)}}{\partial p_\nu} \right|_x \frac{\partial p_{\nu i}}{\partial x} \quad , \]  

\[ = \left. \frac{\partial f_\nu^{(0)}}{\partial x} \right|_p + \frac{e_\nu}{c} \left. \frac{\partial A^{(0)}_{\nu i}}{\partial x} \right|_x \frac{\partial f_\nu^{(0)}}{\partial p_{\nu i}} \quad , \]  

\[ \left. \frac{\partial f_\nu^{(0)}}{\partial x} \right|_p = \left. \frac{\partial f_\nu^{(0)}}{\partial x} \right|_v - \frac{e_\nu}{c} \left. \frac{\partial A^{(0)}_{\nu i}}{\partial x} \right|_x \frac{\partial f_\nu^{(0)}}{\partial p_{\nu i}} \quad , \]  

\[ = \left. \frac{\partial f_\nu^{(0)}}{\partial x} \right|_v - \frac{e_\nu}{m_\nu c} \left. \frac{\partial A^{(0)}_{\nu i}}{\partial x} \right|_x \frac{\partial f_\nu^{(0)}}{\partial v_{\nu i}} \quad . \]  

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The perturbations $\delta x_\nu$ and $\delta p_\nu$ are given by
\[
\delta x_\nu = \left. \frac{\partial G_\nu}{\partial p_\nu} \right|_x,
\]
\[
= \frac{1}{m_\nu} \left. \frac{\partial G_\nu}{\partial v} \right|_x,
\tag{F.8}
\]
\[
\delta p_\nu = -\left. \frac{\partial G_\nu}{\partial x} \right|_p,
\]
\[
= -\left. \frac{\partial G_\nu}{\partial x} \right|_v + \frac{e_\nu}{m_\nu c} \left. \frac{\partial A_i^{(0)}}{\partial x} \right|_{v_i} \left. \frac{\partial G_\nu}{\partial v} \right|_{v_i}.
\tag{F.9}
\]

Employing the relations above, one obtains $\delta f_{\nu}^{(0)}$ as a function of $x$ and $v$:
\[
\delta f_{\nu} = \frac{1}{m_\nu} \left[ \frac{\partial f_{\nu}^{(0)}}{\partial x} \cdot \frac{\partial G_\nu}{\partial v} + \frac{e_\nu}{m_\nu c} \left( B^{(0)} \times \frac{\partial f_{\nu}^{(0)}}{\partial v} \right) \cdot \frac{\partial G_\nu}{\partial v} - \frac{\partial f_{\nu}^{(0)}}{\partial v} \cdot \frac{\partial G_\nu}{\partial x} \right],
\tag{F.10}
\]
which, with Eq.(7) taken into account, yields
\[
\delta f_{\nu}^{(0)} = \frac{1}{m_\nu} \left[ F^{(0)}_{\nu} \cdot \frac{\partial G_\nu}{\partial v} - \frac{\partial f_{\nu}^{(0)}}{\partial v} \cdot \frac{\partial G_\nu}{\partial x} \right].
\tag{F.11}
\]

With Eqs. (B.10), (18), (20) and (21) taken into account, $\delta f_{\nu}$ can be expressed as
\[
\delta f_{\nu} = -(d_\nu G_\nu) \left. \frac{\partial f_{\nu}^{(0)}}{\partial H_{\nu}^{(0)}} \right|_{p_{\nu}, v_{\nu}} - \left[ \left. \frac{\partial x}{\partial q_\kappa} \cdot \left. \frac{\partial G_\nu}{\partial x} \right|_{v_{\nu}} \right] \left. \frac{\partial f_{\nu}^{(0)}}{\partial p_{\nu, \kappa}} \right|_{v_{\nu}}.
\tag{F.12}
\]

Since
\[
\left. \frac{\partial G_\nu}{\partial x} \right|_{v_{\nu}} = \nabla_{q_\lambda} \left. \frac{\partial G_\nu}{\partial q_\lambda} \right|_{v_{\nu}},
\tag{F.13}
\]
one obtains
\[
\left. \frac{\partial x}{\partial q_\kappa} \cdot \left. \frac{\partial G_\nu}{\partial x} \right|_{v_{\nu}} = \left. \frac{\partial G_\nu}{\partial q_\kappa} \right|_{v_{\nu}}.
\tag{F.14}
\]

With $G_\nu$ given by Eqs. (23) and (29), the following relations can be derived:
\[
d_\nu G_\nu = \frac{1}{2} (d_\nu \Psi_\nu) \left[ e^{i [\Gamma_\nu + k_2 q_2 + k_3 q_3]} + e^{-i [\Gamma_\nu + k_2 q_2 + k_3 q_3]} \right]
\]
\[
+ \frac{i}{2} \Psi_\nu [d_\nu \Gamma_\nu + k_{23} \cdot v]
\times \left[ e^{i [\Gamma_\nu + k_2 q_2 + k_3 q_3]} - e^{-i [\Gamma_\nu + k_2 q_2 + k_3 q_3]} \right].
\tag{F.15}
\]
and
\[
\frac{\partial G_\nu}{\partial q_\kappa}_{\nu} = \frac{i}{2} k_\kappa \Psi_\nu \left[ e^{i \left[ \Gamma_\nu + k_2 q_2 + k_3 q_3 \right]} - e^{-i \left[ \Gamma_\nu + k_2 q_2 + k_3 q_3 \right]} \right], \quad \kappa = 2, 3 , \tag{F.16}
\]

which, together with Eqs. (F.3) and (F.12), yield
\[
\delta \rho = -\sum_\nu \frac{e_\nu}{2} \int d^3v \left\{ \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \left[ d_\nu \Psi_\nu \left[ e^{i \left[ \Gamma_\nu + k_2 q_2 + k_3 q_3 \right]} + e^{-i \left[ \Gamma_\nu + k_2 q_2 + k_3 q_3 \right]} \right] 
+ i \Psi_\nu \left[ \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \left[ d_\nu \Gamma_\nu + k_2 \cdot \mathbf{v} + k_2 \frac{\partial f^{(0)}_\nu}{\partial p_{\nu,2}} + k_3 \frac{\partial f^{(0)}_\nu}{\partial p_{\nu,3}} \right] \right] \right\} . \tag{F.17}
\]

Taking \( d_\nu \Psi_\nu = 0 \), i.e. \( \Psi_\nu = \Psi_\nu(\mathcal{H}_\nu, p_{\nu,2}, p_{\nu,3}) \), does not have any influence whatsoever on the results obtained in Sec. V. In this case, the perturbed charge density is
\[
\delta \rho = -\sum_\nu \frac{i}{2} e_\nu \int d^3v \Psi_\nu \left[ \frac{\partial f^{(0)}_\nu}{\partial \mathcal{H}_\nu} \left[ d_\nu \Gamma_\nu + k_2 \cdot \mathbf{v} + k_2 \frac{\partial f^{(0)}_\nu}{\partial p_{\nu,2}} + k_3 \frac{\partial f^{(0)}_\nu}{\partial p_{\nu,3}} \right] \right] 
\times \left[ e^{i \left[ \Gamma_\nu + k_2 q_2 + k_3 q_3 \right]} - e^{-i \left[ \Gamma_\nu + k_2 q_2 + k_3 q_3 \right]} \right] . \tag{F.18}
\]

The perturbed charge density \( \delta \rho \) can be made zero since the expressions for \( \delta^2 H \) only contain \( \Psi^2 \), \( (d_\nu \Psi_\nu)^2 \). \( \Psi_\nu \) is chosen localized in \( \mathcal{H}_\nu \) and \( p_{\nu,\kappa} \). The distribution of signs in \( \Psi_\nu \) is free. For instance, one can take \( \Psi_\nu \) piecewise continuous in \( \mathcal{H}_\nu \) and \( p_{\nu,\kappa} \), with changing signs so that positive and negative contributions to \( \delta \rho \) balance each other.
References


