Modeling the gravitational wave signature of neutron star black hole coalescences: PhenomNSBH

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Accurate gravitational-wave (GW) signal models exist for black-hole binary (BBH) and neutron-star binary (BNS) systems, which are consistent with all of the published GW observations to date. Detections of a third class of compact-binary systems, neutron-star-black-hole (NSBH) binaries, have not yet been confirmed, but are eagerly awaited in the near future. For NSBH systems, GW models do not exist across the viable parameter space of signals. In this work we present the frequency-domain phenomenological model, PhenomNSBH, for GWs produced by NSBH systems with mass ratios from equal-mass up to 15, spin on the black hole (BH) up to a dimensionless spin of |\(\chi| = 0.5\), and tidal deformabilities ranging from 0 (the BH limit) to 5000. We extend previous work on a phenomenological amplitude model for NSBH systems to produce an amplitude model that is parameterized by a single tidal deformability parameter. This amplitude model is combined with an analytic phase model describing tidal corrections. The resulting approximant is accurate enough to be used to measure the properties of NSBH systems for signal-to-noise ratios (SNRs) up to 50, and is compared to publicly-available NSBH numerical-relativity simulations and hybrid waveforms constructed from numerical-relativity simulations and tidal inspiral approximants. For most signals observed by second-generation ground-based detectors within this SNR limit, it will be difficult to use the GW signal alone to distinguish single NSBH systems from either BNSs or BBHs, and therefore to unambiguously identify an NSBH system.

I. INTRODUCTION

Stellar-mass compact-binary coalescences have been the source of all current gravitational-wave (GW) observations made by the Advanced LIGO [1] and Advanced Virgo detectors [2]. The data collected during the first and second observing runs is publicly available [3, 4], and analyses of it have been published in several GW catalogues [5–8]. The compact-binary mergers expected to be observed by current ground-based detectors come in three varieties: black-hole binaries (BHs), neutron-star binaries (NSs), and binaries that consist of one black hole and one neutron star (BSHs). The majority of GW signals detected so far comes from BH mergers, with two detections, GW170817 [9] and GW190425 [10], inferred to be from BNS mergers. Although the GW signals from these two events are also consistent with NSBH mergers, e.g., [11, 12], this class of merger has yet to be unambiguously observed.

To extract physical information from GW signals, template waveforms constructed from theoretical models are compared with the data using a Bayesian framework. Much of the previous waveform modeling efforts have focused successfully on BHs — for examples of recent BBH waveform models, see SEOBNRv4HM [13], PhenomPv3HM [14, 15], and surrogates NRSur7dq4 [16] and NRHybSur3dq8 [17]. These BBH waveform models do not capture the changes to the waveform morphology introduced when one or both of the binary companions is a neutron star (NS). One effect is a shift to the waveform phase that arises from tidal deformation of the NS during the inspiral of the two bodies [18]. This shift has been the focus of recent research into BNS waveform modeling efforts, and has produced several available models: TE0BResumS [19], SEOBNRv4T [20–22], and the NRTidal models [23–25]. These phase corrections have been sufficient in observations to date, because disruption of the NSs produces changes in the GW amplitude at high frequency [26–28], where the detectors have been largely insensitive to the merger and post-merger BNS signal [29, 30].

In signals from NSBH systems, the phase shift during the inspiral stage due to NS tidal deformation is present, but it is unlikely that it will be observable with current detectors [31]. Further, and in contrast to BNS signals, merger and post-merger dynamics in NSBH systems are potentially accessible to current ground-based detectors due to these systems’ potential for higher total masses, which can shift the GW signal at merger to a more sensitive part of the frequency band. As the mass-ratio of the system increases, the merger morphology of the waveform can range from total disruption of the NS, in which case the amplitude of the waveform is exponentially suppressed at high frequency [32], to non-disruptive signals for which the waveform is comparable to a BBH waveform, where the high-frequency amplitude is governed by the ringdown of the companion black hole (BH) [33]. Observations of the merger signal in an NSBH could allow us to place tighter constraints on the NS equation of state (EOS) [34–36] and identify its source as an NSBH binary. Of the waveform models existing currently, LEA [37] and the upgraded LEA+ models are the only existing NSBH waveform models that include an NSBH-specific merger morphology and are calibrated against NSBH NR waveforms. While effective in their shared calibration range, their parameter space coverage is limited, in particular only to mass ratios between 2 and 5.

The aim of this work is to produce a new NSBH model called PhenomNSBH that combines an approximate reparameterization of the NSBH amplitude model described by [38] with the state-of-the-art tidal phase model described in [25]. As with previous work, the new model supports a spinning
BH with spin vector parallel to the orbital angular momen-
tum of the system and a non-spinning NS. Furthermore, we
simplify the previous amplitude modeling efforts by replacing
dependence on the NS EOS with a single tidal deformability
parameter. This change is essential to allow our new model
to be used for parameter estimation. With these changes to the
amplitude model and the integration of an improved phase
description, our new model is valid over a larger parameter space
and it is capable of generating accurate waveforms from equal
mass up to mass-ratio 15. At high mass ratios, the NS merges
with the BH before disrupting, and the GW signal approaches
that of an equivalent BBH. As we show in Sec. III, beyond
mass-ratio 8 a BBH model will be sufficient for observations
with a signal-to-noise ratio less than 300.

In Sec. II we describe and outline the waveform model
PhenomNSBH presented in this paper, which is implemented
as IMRPhenomNSBH in the open-source software package
LALSuite [39]. To assess the PhenomNSBH model, we com-
pare it against numerical-relativity (NR) data for various
NSBH systems in Sec. III, presenting alongside the same com-
parisons for other relevant waveform models, and we identify
the regions of parameter space where an NSBH model will be
necessary to prevent measurement biases. Finally we conclude
with Sec. IV, where we summarize our results and discuss di-
rections for future work. In the remaining sections of this
paper geometric units are used such that $G = c = 1$.

II. MODELLING NEUTRON STAR-BLACK HOLE
WAVEFORMS

In this section we present a model for the GW signal emitted
by an NSBH binary system that consists of a non-spinning NS
and a BH with spin angular momentum $S_{\text{BH}}$ parallel to the
orbital angular momentum $L$ of the system. Such a system may
be parameterized by four intrinsic parameters: $M$, the total
mass of the system, $M = M_{\text{BH}} + M_{\text{NS}}$, where $M_{\text{BH}}$ and $M_{\text{NS}}$
are the component masses of the BH and NS, respectively; $q,$
the mass ratio of the system where $q = M_{\text{BH}}/M_{\text{NS}} \geq 1$; $\chi,$
the dimensionless spin of the BH given by $\chi = S_{\text{BH}} \cdot L / M_{\text{BH}}^2;$
and $\Lambda$, the dimensionless NS tidal deformability parameter [18, 40]
defined in terms of the quadrupole Love number, $k_2$, and
compactness $C = M_{\text{NS}}/R_{\text{NS}}$ of the NS,

$$\Lambda = \frac{2}{3} \frac{k_2}{C^2}. \quad (1)$$

We encapsulate these four parameters in the vector $\theta = (M, q, \chi, \Lambda)$. Note that, unlike BBH models, the total mass
$M$ cannot be separated as a scaling factor due to the scale-
dependent effects that arise in the waveform from the presence
of the NS.

We seek a model of the complex spin in the frequency
domain, $h(f; \theta, \vartheta, \varphi)$, where the extrinsic parameters $(\vartheta, \varphi)$
represent the orientation of the system with respect to a distant
observer. The strain may be written as an expansion in spin-
weighted spherical harmonics $-Y_{\ell m}(\vartheta, \varphi)$. For the first step
in this preliminary model, we follow previous phenomeno-
logical models [38, 41–43] and focus only on the dominant
$(\ell, |m|) = (2, 2)$ multipole moments, i.e.,

$$\tilde{h}(f; \theta, \vartheta, \varphi) = \sum_{\ell, m} \hat{h}_{\ell m}(f; \theta) Y_{\ell m}(\vartheta, \varphi)$$

$$\approx \sum_{m = -2}^{2} \hat{h}_{2 m}(f; \theta) Y_{2 m}(\vartheta, \varphi). \quad (2)$$

The $\hat{h}_{2 2}$ multipole moment is further decomposed in terms of
an amplitude $A$ and phase $\phi$,

$$\hat{h}_{2 2}(f; \theta) = A(f; \theta) e^{-i \phi(f; \theta)}$$

and we relate $\hat{h}_{2 2}(f) = \tilde{h}_{2 2}(-f)$, where $*$ denotes complex
conjugation. Higher multipoles are also necessary for unbiased
parameter measurements for systems with $q \geq 3$ [44, 45]. A
quadrupole-only model is however sufficient to capture the
broad phenomenology of the signal from an NSBH system
including the effects of tidal disruption, and for all of the
conclusions that we draw in this work. We will discuss further
extensions in Sec. IV.

In the text that follows, we outline in detail how the ampli-
itude and phase are modeled for an NSBH system.

A. Amplitude model

To create an amplitude model for PhenomNSBH we start from
the NSBH amplitude description of Pannarale et al. in [38].
This model describes an amplitude based on the aligned-spin
BBH waveform amplitude of PhenomC [41], which depends on
three intrinsic parameters $(M, q, \chi)$ and an explicit choice of
a NS equation of state (EOS). Four choices of EOS were used
in its calibration, listed in order of increasing softness, i.e.,
decreasing tidal deformability: 2H, H, HB, and B [46]. Given
an EOS and NS gravitational mass $M_{\text{NS}}$ (assuming $M_{\text{NS}} \leq
M_{\text{BH}}$), the amplitude model of Pannarale et al. integrates the
Tolman-Oppenheimer-Volkoff equations [47–49] to find the
NS radius $R_{\text{NS}}$ associated with its gravitational mass. From
the mass and radius, the NS compactness is computed via
$C = M_{\text{NS}}/R_{\text{NS}}$ and the baryonic mass $M_{\text{b,NS}}$ from Eq. (8)
of [50].

While determination of the NS EOS may be possible after
several detections [51], it is more practical for our waveform
model to not be directly dependent on the EOS. To this end,
we replace the dependency of the amplitude model on the EOS
with a dependency on the dimensionless tidal deformability
$\Lambda$, outlined in Appendix B. With these augmentations made
to the original amplitude model, we have a working amplitude
for an aligned-spin NSBH system with dependence on the four
intrinsic parameters $(M, q, \chi, \Lambda)$. Based on the workflows
provided in Ref. [38, 52], the amplitude model is evaluated
using the following steps:

1. Calculate the NS compactness $C$
   Evaluate Eq. (32) to calculate compactness $C(\Lambda)$ of the
   NS.

2. Calculate the tidal disruption frequency $f_{\text{tide}}$
   Evaluate Eq. (8) to calculate the tidal disruption frequency
   $f_{\text{tide}}(q, \chi, C)$.

3. Calculate the baryonic mass ratio $M_{\text{b,torus}}/M_{\text{b,NS}}$
   Evaluate Eq. (11) to calculate the baryonic mass ratio of
   $M_{\text{b,torus}}/M_{\text{b,NS}}$.
the NS. This model depends only on the torus remnant baryonic mass \( M_{b,\text{t}} \) and the baryonic mass \( M_{b,\text{NS}} \) of the isolated NS at rest through expressions of the form \( M_{b,\text{t}} / M_{b,\text{NS}} \). As such it is not necessary to calculate an explicit value for \( M_{b,\text{NS}} \), which was required by [38].

4. Calculate remnant BH properties \((\chi_f, M_f)\)

Evaluate Eq. (13) to calculate the final spin \( \chi_f(\eta, \chi, \Lambda) \) and final mass \( M_f(\eta, \chi, \Lambda) \) of the remnant black hole, where \( \eta \equiv q/(1 + q)^2 \) is the symmetric mass ratio.

5. Calculate the remnant BH quantities \((f_{RD}, Q)\)

Evaluate Eqs. (16) and (17) to calculate the ringdown frequency \( f_{RD}(M_f, \chi_f) \) and quality factor \( Q(\chi_f) \).

6. Calculate merger-type dependent quantities

Calculate the merger-type dependent quantities \((\epsilon_{t}, \epsilon_{\text{ins}}, \sigma_{t}, f_0, f_1, f_2)\) using the conditions on \( f_{RD}, M_{b,\text{t}} \), and expressions provided in Table I.

7. Calculate non-merger-type dependent quantities

Evaluate Eq. (31) to calculate the phenomenological parameters \( \gamma_1, \delta_1, \text{and} \delta_2 \). Evaluate Eqs. (26) and (29) to calculate the phenomenological correction parameters \( \gamma'_1 \) and \( \delta'_2 \). While \( \delta_1 \) and \( \delta'_2 \) are not explicitly dependent on any merger-type dependent quantities, they are not required if the onset of tidal disruption happens before the ringdown frequency is reached.

8. Evaluate the amplitude

Evaluate the amplitude \( A(f; \theta) \),

\[
A(f) = A_{PN}(f) \omega_{f_0, 0.015, \sigma_{t}}^- (f) \\
+ \gamma'_1 f^5 \omega_{f_1, 0.015, \sigma_{t}}^- (f) \\
+ A_{RD}(f) \omega_{f_2, 0.015, \sigma_{t}}^- (f),
\]

where \( \omega_{f, \sigma}^- \) is defined by Eq. (30) and \( A_{PN} \) and \( A_{RD} \) are defined by Eqs. (25) and (27), respectively. We have suppressed all explicit parameterization in the component functions of the amplitude \( A \) for legibility.

A more detailed description of the amplitude model workflow is given in Appendix A. For full details of the amplitude model, along with the different merger types, we direct the reader to Sec. IV of Ref. [38].

## B. Phase model

In addition to a proper amplitude description, we need to model the GW phase \( \phi \) for the NSBH coalescence in such a way that it provides an accurate description within a large region of the parameter space and incorporates tidal effects imprinted in the signal. As a BBH baseline, we use the frequency-domain phase approximant from Phenom [42, 43]. This model allows for a description of BBH systems up to mass ratios of \( q \leq 18 \) and aligned-spin components up to \(|\chi| \leq 0.8\). We augment this BBH baseline with tidal effects modeled within the NRTidal approach [23, 24], using the newest version as described in Ref. [25]. The NRTidal phase model includes matter effects in the form of a closed-form, analytical expression, combining post-Newtonian knowledge with EOB and NR information. While this model was designed to be an accurate phase model for BNS systems, recent work [29] has shown that it is also a valid description in the NSBH limit.

## III. ANALYSIS OF MODEL

To quantify the effectiveness of our model at reproducing NSBH waveforms, we compare against a selection of NR NSBH waveforms produced by the SXS collaboration [29, 33, 53] with simulation parameters listed in Table II. To carry out these comparisons, it is useful to introduce the
Current Advanced LIGO and Virgo are sensitive to signals ranging between 20–200 Hz and covers between 10 and 16 orbits before merger. The amplitude model used for the BBH model and NR by studying the de-phasing, here we focus on computing the faithfulness, which is directly related to the loss in signal-to-noise ratio in matched-filter based searches, and takes into account both phase and amplitude differences.

Of the seven NR simulations considered in this paper, five are binary systems without any spin on either body (see Table II for a list of the non-spinning waveforms and their parameters). The two cases including spin, q1a2 and q2a2, are simulations where the NS is spinning with a dimensionless spin magnitude of 0.2 in a direction anti-parallel to the orbital angular momentum. The amplitude model used for the PhenomNSBH is not calibrated for spinning NSs, and so these two NR waveforms allow for an exploration of the viability of the model when the NS is spinning. We do not make direct comparisons to NR where the BH is spinning as no such simulations are currently publicly available. The amplitude model used in this work was calibrated against NSBH NR waveforms with a spinning BH. Furthermore, based on the faithfulness comparisons with LEA+, which is also calibrated to and validated against NSBH NR waveforms with a spinning BH, we expect the model to also perform well where the BH is spinning.

For q1a2, when we compare against the BBH model PhenomD the match is 0.809 (0.701) for the AZDHP (flat) noise curve. Including tidal effects in the model does improve the match where we find a match of ~0.89 (~0.84) for the AZDHP (flat) noise curve. For q2a2, the match is not as bad as q1a2 but the results are, in general, worse than the non-spinning cases. Interestingly, we find that PhenomD and LEA+ perform comparably for this case with matches of ~0.95 (~0.90) and ~0.96 (~0.94) for the AZDHP (flat) noise curve, respectively.

Reference [29] showed that the NR phase error is smaller than the systematic modelling error in the original NRtidal phase approximant model. Similarly, we also find a noticeable phase difference between the phase description employed in

<table>
<thead>
<tr>
<th>Name</th>
<th>SXS Name</th>
<th>q</th>
<th>MBH</th>
<th>MNS</th>
<th>Λ</th>
<th>Merger Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>q1a0</td>
<td>SXS:BBH:00004</td>
<td>1.4</td>
<td>1.4</td>
<td>1.4</td>
<td>0</td>
<td>791 Disruptive</td>
</tr>
<tr>
<td>q1a0</td>
<td>SXS:BBH:00006</td>
<td>1.5</td>
<td>2.1</td>
<td>1.4</td>
<td>0</td>
<td>791 Disruptive</td>
</tr>
<tr>
<td>q2a0</td>
<td>SXS:BBH:00002</td>
<td>2.8</td>
<td>1.4</td>
<td>1.4</td>
<td>0</td>
<td>791 Disruptive</td>
</tr>
<tr>
<td>q3a0</td>
<td>SXS:BBH:00003</td>
<td>4.05</td>
<td>1.35</td>
<td>1.35</td>
<td>0</td>
<td>607 Mildly Disruptive</td>
</tr>
<tr>
<td>q6a0</td>
<td>SXS:BBH:00001</td>
<td>6.8</td>
<td>1.4</td>
<td>1.4</td>
<td>0</td>
<td>525 Non-Dissruptive</td>
</tr>
<tr>
<td>q1a2</td>
<td>SXS:BBH:00005</td>
<td>1</td>
<td>1.4</td>
<td>1.4</td>
<td>-0.2</td>
<td>791 Disruptive</td>
</tr>
<tr>
<td>q2a2</td>
<td>SXS:BBH:00007</td>
<td>2.8</td>
<td>1.4</td>
<td>1.4</td>
<td>-0.2</td>
<td>791 Disruptive</td>
</tr>
</tbody>
</table>

**TABLE II.** SXS waveforms [29, 33, 53] and their parameters used for comparisons and in making the hybrids. Along with the name given in the SXS public catalog, we also list an abbreviated name given to each waveform in this paper.

The results from comparing directly with the NR waveforms are given in Table III, and the faithfulness is computed over the frequency range covered by each NR waveform. We provide results from using the AZDHP (design) noise curve, as well as a flat noise curve (in parentheses). We also compute the faithfulness of several other waveform models to gauge the systematic uncertainty that is incurred by using them. Specifically, we also compare against the NSBH model LEA+ [37], an inspiral NSBH model SEOBNRv4T [20, 21], a BBH model PhenomD [42, 43] and two inspiral BNS models PhenomDRT [24, 25, 42, 43] and SEOBNRv4NRT [24, 25, 58].

In Ref. [29] the authors analyse the same NR waveforms and the same models. We find similar results and plot these in Fig. 1. Although that work focuses on the agreement between the model and NR by studying the de-phasing, here we focus on computing the faithfulness, which is directly related to the loss in signal-to-noise ratio in matched-filter based searches, and takes into account both phase and amplitude differences.

A. **Comparison to numerical relativity**

NR simulations typically cover the last orbits before coalescence. For the NSBH NR waveforms we consider in validating the model, the typical starting GW frequency is between 300–400 Hz and covers between 10 and 16 orbits before merger. Currently Advanced LIGO and Virgo are sensitive to signals starting around 20 Hz, which for a true signal will include on the order of 10^7 orbits prior to merger, and therefore the NR waveforms used here are missing a large portion of the inspiral signal [57]. We will address this issue by constructing hybrid waveforms for comparison against the model; the results of a comparison against hybrid waveforms can be found in Sec. III B. We first compare against the NR data directly in order to assess the accuracy of the model during the late-inspiral and merger.

The notion of the overlap between two waveforms \( h_1 \) and \( h_2 \),

\[
\langle h_1 | h_2 \rangle = 4\pi \int_{f_1}^{f_2} \frac{\tilde{h}_1(f) \tilde{h}_2^*(f)}{S_n(f)} df,
\]

which is the functional inner-product weighted by the detector noise power-spectral density, \( S_n(f) \), taken for this work to be the Advanced LIGO zero-detuned, high-power (AZDHP) noise curve [54], which is the current goal for the detector’s design sensitivity. By maximizing the normalized overlap over phase (\( \phi_c \)) and time (\( t_c \)) shifts to \( h_1 \), one determines the faithfulness with which \( h_1 \) represents \( h_2 \),

\[
F = \max_{\phi_c, t_c} \frac{\langle h_1(\phi_c, t_c) | h_2 \rangle}{\| h_1 \|^2 \| h_2 \|^2},
\]

where \( \| h \|^2 = \langle h | h \rangle \).

As an initial test of the model, we compare PhenomNSBH against the LEA+ model [37]. The original LEA model was constructed as a phenomenological NSBH model from baseline PhenomC [41] and SEOBNR [55] BBH waveform models. Additions to the BBH models were made to include tidal PN terms during the inspiral, and a taper was applied to the merger contributions of the waveform that was calibrated against NSBH NR waveforms. The LEA+ model was introduced as an improvement to the LEA model by substituting a reduced-order model of SEOBNRv2 [56] for the underlying BBH waveform. The LEA+ model is calibrated for NS masses ranging between 1.2–1.4M\(_{\odot}\), mass-ratios \( q \in [2, 5] \), and BH spins \(-0.5 \leq \chi \leq 0.75\). To perform the comparison, we generate waveforms across the overlapping parameter spaces covered by the calibration ranges of LEA+ and PhenomNSBH and compute the faithfulness between waveforms generated using identical parameters. The results show good agreement between the models, with \( F > 0.99 \). The comparison only deviates noticeably when \( \chi < -0.4 \), where the faithfulness drops to 0.98.

The approximate names in the LALSuite code for LEA+, PhenomD, PhenomDRT, SEOBNRv4T and SEOBNRv4NRT are Lackey_Tidal_2013SEOBNRv2_ROM, IMRPhenomD, IMRPhenomD_NRTidalv2, SEOBNRv4T and SEOBNRv4_ROM_NRTidalv2, respectively.
TABLE III. The computed faithfulness between the seven SXS NSBH numerical relativity waveforms and the waveform approximants PhenomNSBH, PhenomD, PhenomDNRT, SEOBNRv4T, SEOBNRv4NRT, and LEA+. We compute two sets of matches. The first uses the Advanced LIGO zero-detuning, high-power noise curve and second, in parentheses, uses a flat noise curve. The frequency range used to compute the matches cover the entire bandwidth of the NR data.

<table>
<thead>
<tr>
<th>Sim Name</th>
<th>PhenomNSBH</th>
<th>PhenomD</th>
<th>PhenomDNRT</th>
<th>SEOBNRv4NRT</th>
<th>SEOBNRv4T</th>
<th>LEA+</th>
</tr>
</thead>
<tbody>
<tr>
<td>q1a0</td>
<td>0.988 (0.978)</td>
<td>0.911 (0.834)</td>
<td>0.986 (0.972)</td>
<td>0.988 (0.976)</td>
<td>0.997 (0.994)</td>
<td>-</td>
</tr>
<tr>
<td>q1.5a0</td>
<td>0.997 (0.994)</td>
<td>0.955 (0.906)</td>
<td>0.998 (0.995)</td>
<td>0.998 (0.995)</td>
<td>0.999 (0.997)</td>
<td>-</td>
</tr>
<tr>
<td>q2a0</td>
<td>0.999 (0.997)</td>
<td>0.973 (0.931)</td>
<td>0.994 (0.983)</td>
<td>0.994 (0.983)</td>
<td>0.997 (0.994)</td>
<td>0.999 (0.997)</td>
</tr>
<tr>
<td>q3a0</td>
<td>0.994 (0.990)</td>
<td>0.984 (0.971)</td>
<td>0.929 (0.841)</td>
<td>0.930 (0.842)</td>
<td>0.983 (0.963)</td>
<td>0.994 (0.994)</td>
</tr>
<tr>
<td>q6a0</td>
<td>0.999 (0.998)</td>
<td>0.999 (0.999)</td>
<td>0.893 (0.842)</td>
<td>0.893 (0.842)</td>
<td>0.983 (0.966)</td>
<td>-</td>
</tr>
<tr>
<td>q1a2</td>
<td>0.894 (0.844)</td>
<td>0.809 (0.701)</td>
<td>0.885 (0.822)</td>
<td>0.888 (0.826)</td>
<td>0.900 (0.850)</td>
<td>-</td>
</tr>
<tr>
<td>q2a2</td>
<td>0.986 (0.974)</td>
<td>0.947 (0.900)</td>
<td>0.992 (0.985)</td>
<td>0.994 (0.988)</td>
<td>0.985 (0.969)</td>
<td>0.999 (0.997)</td>
</tr>
</tbody>
</table>

PhenomNSBH and the NR data. These results suggest that further improvements such as a new phase calibration to NSBH NR simulations or the inclusion of spin-dependent f-mode resonance shifts near merger [20] may be important to include. In the next Section, however, we show that the measured dephasing is not an issue for Advanced LIGO at design sensitivity.

B. Comparison to hybrid numerical-relativity waveforms

We now repeat the comparisons performed above, but we use hybridized NR waveforms to test the accuracy of the models for realistic signals including the thousands of inspiral cycles prior to merger. To do this, we produce hybrid waveforms, attaching the SXS NSBH waveforms listed in Table II to the tidal inspiral approximant TEO8Resum$S$ [19], following the hybridization procedure outlined in [24, 59]. These hybrids have a starting frequency below 20 Hz and allow us to test the models in a realistic observational scenario where a current-generation ground-based detector would also be sensitive to the full inspiral from 20 Hz; for the faithfulness integrals we use a low frequency cutoff of 20 Hz. We have verified the accuracy of our hybrid construction method and find that the mismatch of a given hybrid with respect to itself subject to varying the hybridization parameters is $\mathcal{O}(10^{-4})$.

We list the results of the faithfulness calculations in Ta-
form and to be relatively low (not exceeding the total mass of the NSBH system for this model is expected binary from the standard BBH phase and may lead to disruption; in particular, we compare against both the SNR at which the NSBH waveform deviates from other detectors are not highly sensitive. One must then ask how important these effects are to the overall model of the waveform for current and future detectors, and how distinguishable the NSBH-specific effects are from BBH or BNS systems.

To estimate the importance of tidal effects and disruption for the detectability of an NSBH signal, we compute the SNR at which the NSBH waveform deviates from other waveform approximants covering the parameter space for these merger types; in particular, we compare against both PhenomNSBH with \( \Lambda = 0 \) to simulate a purely BBH waveform and PhenomDNRt, which contains the same phase model as PhenomNSBH but has a taper applied to the high-frequency merger content of the waveform.

Given an NSBH signal with four internal degrees-of-freedom (\( M, q, \chi, \Lambda \)), the SNR \( \rho \) associated with a 90% confidence region in parameter space for detection is related to the faithfulness \( \mathcal{F} \) between the NSBH signal (here produced by PhenomNSBH) and another waveform approximant via [60]

\[
\mathcal{F} = 1 - \frac{3.89}{\rho^2}, \quad (7)
\]

We initially compute a series of NSBH waveforms using fixed intrinsic parameters (\( M_{NS}, \chi, \Lambda \) = (1.35M\( \odot \), 0, 400)) and allow the mass ratio to vary between 1 and 8. This ensures that we evaluate all merger types captured by the amplitude model in the comparison.

The SNR resulting from these comparisons is plotted in Fig. 2. Focusing first on the distinguishability SNR between PhenomNSBH and PhenomDNRt, we see that the two models will be easier to distinguish with a modestly loud signal in an Advanced LIGO-type detector as the mass ratio of the system increases. In the NSBH system, the mass scale is fixed by the NS mass and therefore as \( q \) increases, so too does the total mass \( M \). This increase in \( M \) will push the merger regime of the system into a lower (and more sensitive) frequency band in the detector, making the high-frequency taper applied to the \( \text{NRT tidal} \) model more apparent in the faithfulness calculation. At lower \( q \) in the disruptive regime of the NSBH system, the taper applied to the \( \text{NRT tidal} \) model mimics the disruption at high frequency in the NSBH waveform. Furthermore, these differences between the two models occur at such high frequency that the lack of sensitivity in the detector makes them hard to distinguish.

When looking at the comparison between PhenomNSBH with and without tidal effects (i.e., comparing against a BBH waveform), we observe the inverse behavior with changing \( q \). Even though the disruptive mergers of comparable-mass NSBH binaries lie outside the most sensitive frequency ranges of ground-based detectors, the differences in the waveforms due to tidal effects in the inspiral still allow us to distinguish between BBH and NSBH systems above SNR of 28. This observation is consistent with GW170817 [9] that had an SNR of 32.4 and allowed us to bound the mass-weighted tidal deformability \( \Lambda \) away from zero. As the mass ratio increases, tidal effects scale away as \( q^{-4} \) in the phase and the NSBH signal becomes hard to differentiate from a BBH signal in the non-disruptive regime; the only differences between the two models are the properties of the remnant quantities after merger.

We expand this comparison to include the broader parameter space covered by PhenomNSBH. Specifically, we assume an AZDHP noise curve and calculate the distinguishability SNR between PhenomNSBH and its BBH limit, and between PhenomNSBH and PhenomDNRt for \( \sim 5 \times 10^3 \) NSBH systems with randomly chosen properties. \( M_{NS} \) is uniformly sampled between 1.0M\( \odot \) and 2.3M\( \odot \), \( M_{BH} \) between 1.0M\( \odot \) and 27M\( \odot \) (and we require \( M_{NS} \leq M_{BH} \)), while the NS and BH (aligned) spins are uniformly sampled in the intervals \([-0.05, 0.05]\) and \([-0.5, 0.5]\), respectively. Finally, the NS dimensionless tidal deformability parameter \( \Lambda \) is uniformly sampled in \([0, 3000] \). Our results are collected in Fig. 3. The

<table>
<thead>
<tr>
<th>Sim Name</th>
<th>PhenomNSBH</th>
<th>PhenomD</th>
<th>PhenomDNRT</th>
<th>SEOBNRv4NRT</th>
<th>SEOBNRv4T</th>
<th>LEA+</th>
</tr>
</thead>
<tbody>
<tr>
<td>q1a0</td>
<td>0.9996 (0.9996)</td>
<td>0.9906 (0.9936)</td>
<td>0.9985 (0.9989)</td>
<td>0.9992 (0.9994)</td>
<td>0.9986 (0.9982)</td>
<td>-</td>
</tr>
<tr>
<td>q1.5a0</td>
<td>0.9994 (0.9997)</td>
<td>0.9930 (0.9952)</td>
<td>0.9991 (0.9993)</td>
<td>0.9979 (0.9984)</td>
<td>0.9973 (0.9981)</td>
<td>-</td>
</tr>
<tr>
<td>q2a0</td>
<td>0.9987 (0.9990)</td>
<td>0.9954 (0.9966)</td>
<td>0.9989 (0.9993)</td>
<td>0.9969 (0.9978)</td>
<td>0.9970 (0.9976)</td>
<td>0.9997 (0.9998)</td>
</tr>
<tr>
<td>q3a0</td>
<td>0.9995 (0.9997)</td>
<td>0.9956 (0.9975)</td>
<td>0.9990 (0.9993)</td>
<td>0.9975 (0.9984)</td>
<td>0.9993 (0.9995)</td>
<td>0.9990 (0.9990)</td>
</tr>
<tr>
<td>q4a0</td>
<td>0.9974 (0.9981)</td>
<td>0.9964 (0.9972)</td>
<td>0.9946 (0.9974)</td>
<td>0.9957 (0.9972)</td>
<td>0.9977 (0.9988)</td>
<td>-</td>
</tr>
<tr>
<td>q1a2</td>
<td>0.9969 (0.9978)</td>
<td>0.9405 (0.9508)</td>
<td>0.9949 (0.9967)</td>
<td>0.9962 (0.9972)</td>
<td>0.9965 (0.9975)</td>
<td>-</td>
</tr>
<tr>
<td>q2a2</td>
<td>0.9991 (0.9992)</td>
<td>0.9806 (0.9837)</td>
<td>0.9985 (0.9992)</td>
<td>0.9988 (0.9990)</td>
<td>0.9982 (0.9989)</td>
<td>0.4515 (0.6070)</td>
</tr>
</tbody>
</table>
FIG. 2. The approximate SNR at which the waveforms PhenomNSBH and the BBH-limit of PhenomNSBH become distinguishable from PhenomNSBH is plotted as a function of mass-ratio for a nonspinning NSBH system with tidal deformability \( \Lambda = 400 \) and NS mass \( 1.35M_\odot \). The shaded regions of the plot indicate different merger types calculated from PhenomNSBH. The solid dots show the SNR computed from mismatches between PhenomNSBH and the NR-hybrid data listed in Table IV. The trends continue to higher mass ratios, where an NSBH signal becomes effectively indistinguishable from a BBH signal in any realistic detection. The matches between models are computed over the range \( [f_1, f_2] = [25, 8192] \) Hz assuming a AZDHP noise curve.

FIG. 3. The approximate SNR at which the waveforms for BNS (PhenomDfR) and BBH (the BBH-limit of PhenomNSBH) become distinguishable from NSBH (PhenomNSBH), considered over the entire parameter space of PhenomNSBH and projected onto the \( q-\Lambda \) plane. The top panel displays the distinguishability of PhenomNSBH from its BBH-limit, the middle panel the distinguishability of PhenomNSBH from PhenomDfR, and the bottom panel the maximum distinguishable SNR between PhenomNSBH and the two other models. Distinguishable SNRs below 10 are displayed as pink upside-down triangles and as blue triangles for SNRs above 100. The AZDHP noise curve is used to compute these results.

IV. DISCUSSION

In this paper we have outlined the construction of PhenomNSBH, an updated waveform model specific to signals from NSBH systems. This model uses an improved amplitude model that identifies distinct merger morphologies and a new tidal phase model, both of which have been calibrated using NR data. The model is valid for systems with mass-ratio ranging from \( q \in [1, 15] \) with NS masses between \( M_{NS} \in [1, 3]M_\odot \), BH spins aligned with the orbital angular momentum rang-
ing between $\chi \leq [0.5]$, and NS tidal deformabilities between $\Lambda \in [0, 5000]$. In addition, the model described here performs well when compared against available NSBH NR waveforms with spinning neutron stars, despite the amplitude model lacking such systems in its calibration.

We have shown in Figs. 2 and 3 that the NSBH-specific characteristics of PhenomNSBH are distinguishable from other waveform models in different regions of parameter space. As the merger transitions to the non-disruptive regime, the amplitude of the waveform deviates further from a BBH waveform amplitude, which will be distinguishable in ground-based detectors for moderately loud signals. As the merger type becomes less disruptive, the NSBH waveform will easily be distinguishable from a BNS waveform model (e.g., PhenomDNR) due to the taper at high frequency applied to the latter and lack of ringdown in the signal. The important conclusion to draw from these results is that for signals below an SNR of 50, there is only a small region of parameter space where it may be possible to unambiguously identify an NSBH system. This statement is limited to single observations, and to aligned-spin models that include only the dominant waveform harmonic.

The waveform model PhenomNSBH described in this paper is an improvement/extension of current NSBH waveform models, but there is certainly room for future advances. While recent cosmological simulations predict that the majority of NSBH systems will have relatively low mass-ratios ($q \sim [3, 5]$) [64], even at these low mass-ratios the effects of higher modes [44, 45] and precession [65–67] are vital to capture the essential physics from the waveform and should of higher modes [44, 45] and precession [65–67] are vital to capture the essential physics from the waveform and should be a primary focus of future NSBH waveform modeling efforts. Another avenue for improvement lies in calibrating the phase model against NSBH NR waveforms. These tasks will require a large catalog of new NR simulations at high resolution and spanning a large range of mass-ratios, spins, and tidal deformability.

V. ACKNOWLEDGMENTS

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Appendix A AMPLITUDE MODEL WORKFLOW

For the convenience of the reader, we now outline the construction of the amplitude model in more detail following the flowchart in Sec. II A. To begin, the compactness of the NS is determined from the input tidal deformability, as described in detail in Appendix B.

We compute the tidal disruption frequency, $\tilde{f}_{\text{tide}}$, which approximates the frequency at which the external quadrupolar tidal force acting on the NS from the companion BH is comparable in magnitude to the self-gravitating force maintaining the NS. This follows from the initial parameters of the binary according to [50, 72]

$$f_{\text{tide}} = \frac{1}{\pi \left( q_{\text{BH}} \sqrt{f_{\text{tide}}^2/M_{\text{BH}}} \right)}$$

$$\tilde{f}_{\text{tide}} = \xi_{\text{tide}} M_{\text{BH}} \frac{(1 - 2C)}{\mu}$$

where $\mu = qC$ and $\xi_{\text{tide}}$ is the largest positive real root of the following equation,

$$0 = \xi_{\text{tide}}^5 - 3\mu \xi_{\text{tide}}^4 + 2\sqrt{\mu} \xi_{\text{tide}}^2 - 3q \xi_{\text{tide}} - 3q \mu^2 \xi_{\text{tide}}$$

Next, the ratio of the baryonic mass of the torus remaining after merger to the initial baryonic mass of the NS, $M_{\text{torus}}/M_{\text{BH}}$, is determined according to fits from [50],

$$\frac{M_{\text{torus}}}{M_{\text{BH}}} = 0.296 \xi_{\text{tide}} (1 - 2C) - 0.171 q \xi_{\text{tide}}$$

where $\xi_{\text{tide}}$ is the radius of the innermost stable circular orbit of a unit-mass BH [73].

$$\tilde{r}_{\text{isco}} = \frac{3 + Z_2 - \text{sign}(\chi) \sqrt{(3 - Z_1)(3 + Z_1 + 2Z_2)}}{Z_1 = 1 + (1 - \chi^2)^{1/3} (1 + \chi)^{1/3} + (1 - \chi)^{1/3}}$$

$$Z_2 = \sqrt{3\chi^2 + Z_1^2}$$

The fit for $M_{\text{torus}}$ was recently updated in Ref. [74]; incorporating it in the amplitude model would require recalibrating the NSBH amplitude model itself as a whole and we leave this for future work.

The final mass, $M_f$, and final spin, $\chi_f$, of the remnant BH after merger are calculated using NSBH-specific fits for the remnant properties parameterized by tidal deformability [75],

$$F(\eta, \chi, \Lambda) = F_{\text{BBH}}(\eta, \chi) \frac{1 + p_1(\eta, \chi) \Lambda + p_2(\eta, \chi) \Lambda^2}{(1 + [p_3(\eta, \chi)^2] \Lambda^2)^2}$$

$$p_k(\eta, \chi) = p_k(\chi) \eta + p_k(\chi) \eta^2$$

$$p_{kj}(\eta, \chi) = p_{kj}(\chi) \eta + p_{kj}(\chi) \eta^2$$

The remnant model $F_{\text{BBH}}$ is the model for the final mass and spin of a BH coalescence described in [76], and the coefficients $p_{kj}$ for the final mass $M_f$ and final spin $\chi_f$ can be found in the supplementary material for [75]. Once the final
mass and spin are determined, we find the ringdown frequency $f_{\text{RD}}$ and quality factor $Q$ via,

$$f_{\text{RD}} = \frac{\Re(\bar{\omega})}{2\pi M f},$$

$$Q = \frac{\Re(\bar{\omega})}{2\Im(\bar{\omega})},$$

where $\bar{\omega}$ is a fit to the $(l, m, n) = (2, 2, 0)$ Kerr quasi-normal mode frequency given in [77].

The amplitude ansatz in Eq. (4) uses the merger-type-dependent frequencies $\bar{f}_0$, $\bar{f}_1$, and $\bar{f}_2$ to blend the post-Newtonian, pre-merger, and merger-ringdown amplitude contributions together. These frequencies are determined based on the conditions in Table I. We now list the specific functional form of the various component functions $x_{\text{ND}}$, $x'_{\text{ND}}$, $x_{\text{D}}$ and $x'_{\text{D}}$ of the merger-type dependent quantities given in [38]. The non-disruptive fitting functions $x_{\text{ND}}$ and $x'_{\text{ND}}$ also require the scaled ringdown frequency $f_{\text{RD}}$ calculated according to

$$f_{\text{RD}} = \begin{cases} 0.99 \times 0.98 f_{\text{RD}}, & \Lambda > 1 \\ (1 - 0.02 \Lambda + 0.01 \Lambda^2) \times 0.98 f_{\text{RD}}, & \Lambda \leq 1, \end{cases}$$

$$x_{\text{ND}} = \left( \frac{f_{\text{side}} - f_{\text{RD}}}{f_{\text{RD}}} \right)^2 - 0.571505C - 0.00508451 \chi,$$

$$x'_{\text{ND}} = \left( \frac{f_{\text{side}} - f_{\text{RD}}}{f_{\text{RD}}} \right)^2 - 0.657424C - 0.0259977 \chi,$$

$$x_{\text{D}} = \frac{M_{\text{B,torus}}}{M_{\text{B,NS}}} + 0.424912C + 0.363604 \sqrt{\eta} - 0.060559 \chi,$$

$$x'_{\text{D}} = \frac{M_{\text{B,torus}}}{M_{\text{B,NS}}} - 0.132754C + 0.576669 \sqrt{\eta} - 0.0603749 \chi - 0.0601185 \chi^2 - 0.0729134 \chi^3.$$

The amplitude component function for the inspiral, $A_{\text{PN}}$, is given by the Fourier transform of the time-domain amplitude given in Eq. (3.14) of [41] using the stationary phase approximation,

$$A_{\text{PN}}(x) = \sqrt{\frac{2\pi}{3x}} \frac{\sin x}{x} \sqrt{\frac{1}{3} \sum_{k=0}^{2} A_k x^{k/2}},$$

where $x = \omega^2/\tilde{x}$, $\omega$ is the orbital angular frequency of the binary, and $\tilde{x}$ is computed using the TaylorT4 expansion [78]: see [41] for the expansion coefficients $A_k$.

The phenomenological correction parameter $\gamma_1$ for the pre-merger region is calculated according to,

$$\gamma_1 = \begin{cases} 1.25, & \Lambda > 1 \\ 1 - 0.5 \Lambda - 0.25 \Lambda^2, & \Lambda \leq 1. \end{cases}$$

The merger-ringdown component function $A_{\text{RD}}$ is defined by [38],

$$A_{\text{RD}}(f) = \epsilon_{\text{side}} \delta_{\text{RD}} \left( \frac{\sigma^2}{(f - f_{\text{RD}})^2 + \sigma^2/4} \right)^{-7/6},$$

$$\sigma = \delta_{ff_{\text{RD}}}/Q,$$

where the phenomenological correction parameter $\delta_{\text{RD}}$ is calculated according to,

$$\delta_{\text{RD}} = \begin{cases} \frac{A}{2} \omega_{x_3 d_3} \left( \frac{f_{\text{side}} - f_{\text{RD}}}{f_{\text{RD}}} \right), & \Lambda > 1 \\ \delta_2 - 2 (\delta_2 - b_0) \Lambda + (\delta_2 - b_0) \Lambda^2, & \Lambda \leq 1 \end{cases},$$

with $A = 1.62496$, $x_3 = 0.0188092$, and $d_3 = 0.338737$, $b_0 = 0.81248$ and $\omega_{x_3 d_3}(f)$ is a hyperbolic tangent windowing function,

$$\omega_{x_3 d_3}(f) = \frac{1}{2} \left[ 1 + \tanh \left( \frac{4(f - f_0)}{d} \right) \right].$$

Note that the factor of 1/2 multiplying the windowing function $\omega_{x_3 d_3}$ in Eq. (29) corrects a typographical error in [38]. The PhenomC phenomenological parameters $\delta_1$, $\delta_2$ and $\gamma_1$ are given as an expansion in symmetric mass-ratio and spins by,

$$\delta_1, \delta_2, \gamma_1 \sim \sum_{i+j \in \{1,2\}} \zeta^{ij} \eta^i \chi^j,$$

with the coefficients $\zeta^{ij}$ in the $\delta_1$, $\delta_2$, and $\gamma_1$ fit parameters given in [41]. We impose the addition constraints that $\delta_1, \gamma_1 \geq 0$ and $\delta_2 \geq 10^{-4}$ to ensure that the amplitude function Eq. (4) remains positive for all regions of parameter space that PhenomNSBH is expected to be used in. It is necessary to invoke these constraints on these coefficients in the non-spinning limit for $q > 25$ and $q > 15$ for spinning cases. In this region the model no long remains sensible and comparisons between other BBH waveforms break down. This constraint on the coefficients motivates the suggested upper bound placed on the mass ratio for the parameter space of the model.

### Appendix B REPLACING EQUATION OF STATE

Removing explicit EOS-dependence from the NSBH amplitude model is achieved by finding the compactness $C$ of the NS from its tidal deformability parameter $\Lambda$ using the fit determined in Ref. [79] with an additional piecewise component for $\Lambda \leq 1$ from [80],

$$C(\Lambda) = \begin{cases} a_0 + a_1 \log \Lambda + a_2 (\log \Lambda)^2, & \Lambda > 1 \\ 0.5 + (3a_0 - a_1 - 1.5) \Lambda^2 + (a_1 - 2a_0 + 1) \Lambda^3, & \Lambda \leq 1, \end{cases}$$

where $a_0 = 0.360$, $a_1 = -0.0355$, and $a_2 = 0.000705$. In Fig. 4 we show how the compactness values yielded by this fit
FIG. 4. Comparison between the NS compactness as calculated from the EOS information presented in [37] by integrating the Tolman-Oppenheimer-Volkoff equations [47–49].

As the original model was calibrated only to a specific set of EOSs, replacing EOS-dependence with the fit in Eq. (32) will invariably introduce some error to the amplitude model. We conservatively estimate the effects of this error on the model in the following way.

The error in the fit model is given pessimistically as a 6% error in the computed value of $C$ across realistic NS EOSs [79]; for the EOSs used in the calibration of the amplitude model, the error in the fit is bounded by 5%. We invert the mapping in Eq. (32) and compute the spread in $\Lambda$ produced around a given $\Lambda_0$ by varying the compactness within the 6% error bounds. We then compute matches across the parameter space of PhenomNSBH between two waveforms with all parameters equal except the tidal deformability, which is fixed at $\Lambda_0$ for one waveform and allowed to vary between the bounds determined from the compactness error for the other. After sampling waveforms across the model’s parameter space, we find a maximum mismatch given by $\sim 10^{-3}$ for the pessimistic 6% error estimate in the fit.
