

QND measurements for future gravitational-wave detectors

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Abstract Second-generation interferometric gravitational-wave detectors will be operating at the Standard Quantum Limit, a sensitivity limitation set by the trade off between measurement accuracy and quantum back action, which is governed by the Heisenberg Uncertainty Principle. We review several schemes that allows the quantum noise of interferometers to surpass the Standard Quantum Limit significantly over a broad frequency band. Such schemes may be an important component of the design of third-generation detectors.

1 Introduction

The first generation large-scale laser interferometric gravitational-wave (GW) detectors (LIGO [1, 2], Virgo [3, 4], GEO600 [5, 6], and TAMA [7]) are either on duty now or have finished the first stage of their life cycle and are in preparation to an upgrade. Second-generation detectors, e.g., Advanced LIGO, Advanced Virgo, GEO-HF and LCGT aim at increasing sensitivity by about one order of magnitude by means of quantitative improvements (higher optical power, smaller losses) and evolutionary changes of the interferometer configurations, most notably, by introduction of the signal recycling mirror [8, 9, 10, 11, 12, 13].

As a result, the second-generation detectors will be *quantum noise limited*. At higher GW frequencies, the main sensitivity limitation will be due to phase fluctuations of the light inside the interferometer (shot noise). At lower frequencies, the random force

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created by the amplitude fluctuations (radiation-pressure noise) will be the main or among the major contributors into the sum noise. The best sensitivity point, where these two noise sources become equal, is known as the Standard Quantum Limit (SQL) [14], which, in a broader context, characterizes the regime in which the quantum measurement error (shot noise) becomes equal to the back action noise (radiation pressure noise) - the latter one being a consequence of the Heisenberg uncertainty principle.

Topologies of third-generation detectors are far from being established. For example, a triangular or a rectangular shape of the vacuum system for the *Einstein Telescope* (ET) [15]. It could accommodate several independent Michelson interferometers, but evidently can be used also more “synergetically” for non-Michelson topologies. If third-generation detectors are to improve sensitivities by yet another order of magnitude, the main noise sources we face would be: (i) the low-frequency portion of the SQL, (ii) thermal noises from suspension and mirror coatings, (iii) Newtonian gravity gradient and vibrational seismic noises, and (iv) shot noise, where (i) – (iii) are mostly in low frequencies (below 100 Hz), and (iv) is for high frequencies. Methods for tackling these noises are *orthogonal*: (i) argues for heavy mirrors, lower optical power, (ii) argues for heavy mirrors with large radii, and low temperature, (iii) requires careful design of the suspension system and noise cancellation by monitoring ground-motion, and (iv) argues for high optical power. Aside from increasing the arm length of the detector (which improves sensitivity in the entire band but incurs huge cost), we may have to consider separate detectors for coverage of the entire ground-based frequency window of 1 Hz up to 10 kHz.

This paper focuses on designs of interferometers that beat the SQL significantly in a broad frequency band, often named Quantum Non-Demolition (or QND) schemes.¹ In particular, we mainly consider three schemes: (i) the *variational readout scheme*, in which frequency-dependent homodyne detection is implemented by means of additional km-scale filter cavities, and allows broad-band back-action evasion for a broad-range of interferometers (Sec 2), (ii) the *speed meter*, which measures speed of test masses, and can easily evade back-action noise without broad-band frequency-dependent filtering (Sec. 3), and (iii) the *intracavity readout scheme*, in which effect of the GW is first transduced onto the motion of a mirror in its local inertial frame, via *optomechanical coupling*, and then detected by measuring this local motion (Sec. 4).

It is sometimes argued that instead of overcoming the SQL it is possible just to reduce its value by using heavier test masses which have naturally lower radiation-pressure noise. However, we believe that QND techniques are still very useful because: (i) the SQL scales with $1/\sqrt{M}$, and therefore significantly heavier mirrors will be needed, and they bring newer technical issues, (ii) conventional interferometer (will be defined explicitly in the next section) has a noise spectrum that touches the SQL at one frequency, and then increases sharply as f^{-2} at lower frequencies, which makes QND schemes useful even for such heavy mirrors. While it is most probable that QND schemes would be useful for low-frequency detectors, there is still indication

¹ Initially (see [16]) this term was proposed for the specific class of quantum measurements where the measured observable commutes with the unperturbed Hamiltonian and thus is not “demolished” during the measurement (for example, energy of the oscillator non-linearly coupled with the meter). In this case, monitoring of this observable with arbitrary high precision is possible, allowing to detect arbitrary small external perturbation. Today the term QND is frequently (and, in our opinion, imprecisely) applied to any mechanical measurement which can overcome the free mass SQL within a certain frequency range. The three schemes considered in this paper, strictly speaking, do not comply with the initial QND definition. However, they represent the closest approximation to it currently available.

Quantity	Description	Quantity	Description
c	Speed of light	T	Input mirror transmissivity
\hbar	Plank's constant	γ	interferometer's 1/2-bandwidth
ω_o	Optical pumping frequency	I_c	Circulating power
Ω	Signal (side-band) frequency	e^{-2r}	Power squeeze factor
L	Arm length	ζ	Homodyne angle
M	Mirror mass	η	Unified quantum efficiency

Table 1 Main notations used in this paper.

that configurations arising from the study of QND interferometers could improve high-frequency sensitivities.

Throughout our review, we will assume that frequency-independent squeezed vacuum (which can serve for improving the interferometers' sensitivity) is available for injection into any port of the interferometer. For the sake of formulae simplicity we confine ourselves to the particular case of phase quadrature squeezed light that is necessary to reduce the photon shot noise dominating at high signal frequencies, as it was first proposed by Caves [17]. More detailed analysis exceeds this paper frame and can be found, for example, in the articles [18, 19].

Main notations used throughout the paper are listed in Table 1.

2 Variational Readout Schemes

2.1 Quantum position meter

As a starting point, we consider a Michelson interferometer with Fabry-Perot cavities in its arms (as a *position meter*, in the sense that below the cavity linewidth, the output phase modulation is directly proportional to the position of mirrors), which is the standard design for the first and second generation detectors. We assume also that the pump laser frequency is equal to the eigenfrequency of the interferometer anti-symmetric (signal) mode. This means that either no signal recycling is used at all, or both the arm cavities and the signal recycling cavity are tuned in resonance [20].² We shall refer to this scheme, with a homodyne detection of the output phase quadrature, as a *conventional interferometer*. Ref. [18] gave a detailed treatment of quantum noises of Fabry-Perot Michelson position meters. In the ideal lossless case ($\eta = 1$), the quantum-noise spectral density of a position meter with homodyne detection angle ζ is

$$S_{\text{PM}}^h = \frac{h_{\text{SQL}}^2}{2} \frac{e^{-2r} + [\cot \zeta - \mathcal{K}_{\text{PM}}(\Omega)]^2 e^{2r}}{\mathcal{K}_{\text{PM}}(\Omega)}, \quad (1)$$

where

$$h_{\text{SQL}} = \sqrt{\frac{8\hbar}{M\Omega^2 L^2}}, \quad (2)$$

² In principle, the variant with non-zero opposite-sign detunings of the arm cavities and signal recycling cavity is also possible, while it can be hardly considered practical, as it provides that same result but for higher (experimental) "price".

is its SQL³, the function

$$\mathcal{K}_{\text{PM}}(\Omega) = \frac{2I_c}{I_c^{\text{SQL}}} \frac{\gamma^4}{\Omega^2(\gamma^2 + \Omega^2)} \quad (3)$$

describes the strength of optomechanical coupling (“PM” stands for “position meter”), γ is 1/2-linewidth of the arm cavity,

$$I_c = 4 I_{\text{BS}}/T \quad (4)$$

is the total optical power circulating in both arms of the interferometer, I_{BS} is the *input power* at the beamsplitter, T is the power transmissivity of the arm cavities input mirrors, and

$$I_c^{\text{SQL}} = \frac{McL\gamma^3}{4\omega_o}. \quad (5)$$

This is the characteristic power required by a conventional interferometer without squeezing to touch the SQL at $\Omega = \gamma$. By “conventional interferometer”, we mean the one with resonance pumping (no detuning) and with readout of output light phase quadrature ($\zeta = \pi/2$) that corresponds to the shot noise minimum (so-called classical optimization). The total quantum noise spectral density of the conventional interferometer is equal to

$$S_{\text{PM}}^h(\Omega) = \frac{h_{\text{SQL}}^2}{2} \left[\frac{e^{-2r}}{\mathcal{K}_{\text{PM}}(\Omega)} + \mathcal{K}_{\text{PM}}(\Omega)e^{2r} \right], \quad (6)$$

It never goes below $h_{\text{SQL}}^2(\Omega)$, but merely touches it at one given frequency defined by the condition $\mathcal{K}_{\text{PM}}(\Omega)e^{2r} = 1$ (in particular, if $I_c = I_c^{\text{SQL}}e^{-2r}$, then at $\Omega = \gamma$). For example, for the Advanced LIGO parameters set ($M = 40$ kg, $L = 4$ km), and for $\Omega = \gamma = 2\pi \times 100$ Hz, there will be $I_c^{\text{SQL}} \approx 2 \times 840$ kW.

2.2 Variational readout

The *variational measurement* technique of Kimble et al. [18] detects a frequency-dependent quadrature given by

$$\zeta(\Omega) = \text{arccot } \mathcal{K}_{\text{PM}}(\Omega), \quad (7)$$

by passing the light, leaving the main interferometer, through two additional Fabry-Pérot filter cavities (*Kimble filters*), before performing conventional homodyne detection [18]. More generally, as shown in Appendix A of Ref. [21] and in [22], any rotation of the form

$$\cot \zeta(\Omega) = \frac{\sum_{j=1}^n a_j \Omega^{2j}}{\sum_{j=1}^{2n} b_j \Omega^{2j}}, \quad a_n b_n \neq 0 \quad (8)$$

can be achieved with n filters.

³ We use the “one-sided” definition of the spectral density standard for the GW community. In equations, we suppress the Ω dependence of S^h and h_{SQL} .

The bandwidths and detuning frequencies of the filters has to be of the same order of magnitude as the detection frequency scale. In the ideal no-losses case, back-action cancelation leads to

$$S_{\text{PMVM}}^h = \frac{h_{\text{SQL}}^2 e^{-2r}}{2\mathcal{K}_{\text{PM}}(\Omega)}, \quad (9)$$

which only contains shot noise, and can in principle beat the SQL arbitrarily, given large enough circulating power I_c and/or squeeze factor e^{2r} .

2.3 Optical losses

Optical losses play a crucial role in variational readout schemes, because cancellation of radiation pressure noise is achieved with decreased signal content in the readout quadrature [18]. Optical losses can arise from several origins, e.g., lossy mirrors, imperfect mode matching, finite quantum efficiency of photodetectors. For simplicity, we use one effective noise that enters the final output field via an imaginary beamsplitter that mixes output of ideal interferometer with an additional vacuum, with weights $\sqrt{\eta}$ and $\sqrt{1-\eta}$, where η can be viewed as an effective quantum efficiency of the photodetector. In general, η depends on Ω . The main source of this dependence on frequency arise from the filter and (if $r \neq 0$) arm cavities. For them,

$$1 - \eta_{\text{cav}} \sim cA^2/(4L\gamma) \sim 10^2 \times A^2 \times (10 \text{ km}/L) \times (100 \text{ s}^{-1}/\gamma), \quad (10)$$

where A^2 is the loss per bounce. Assuming the moderately optimistic value of $A^2 \sim 10^{-5}$, $1 - \eta_{\text{cav}} \sim 10^{-3}$ is an order of magnitude better than the $1 - \eta \gtrsim 10^{-2}$ which can be provided by modern photodetectors and the auxiliary output optics. Therefore, we neglect in this section frequency dependence introduced by η_{cav} .

The total quantum noise spectral density of the lossy interferometer is

$$S_{\text{PM}}^h = \frac{h_{\text{SQL}}^2}{2} \times \frac{e^{-2r} + \xi_{\text{loss}}^4/\sin^2 \zeta + [\cot \zeta - \mathcal{K}_{\text{PM}}(\Omega)]^2 e^{2r}}{\mathcal{K}_{\text{PM}}(\Omega)}, \quad (11)$$

where we have introduced a convenient factor

$$\xi_{\text{loss}} = \sqrt[4]{(1-\eta)/\eta}. \quad (12)$$

In the conventional case of $r = 0$ and $\zeta = \pi/2$, the influence of optical losses is negligible: the factor $1/\eta$ only increases the shot noise by a few percents. However, losses limit the gain in the shot noise spectral density, provided by squeezing (and thus the gain in the optical power) by the value $(1-\eta)/\eta$. In the variational readout case, losses become even more important because ζ tends to be small [Cf. Eq. (3) and (7)]. A re-optimization of $\zeta(\Omega)$ in presence of loss leads to

$$\zeta(\Omega) = \text{arccot} \frac{\mathcal{K}_{\text{PM}}(\Omega)}{1 + \xi_{\text{loss}}^4 e^{-2r}}, \quad (13)$$

which results in a total noise spectrum of

$$S_{\text{PMVM}}^h = \frac{h_{\text{SQL}}^2}{2} \left[\frac{e^{-2r} + \xi_{\text{loss}}^4}{\mathcal{K}_{\text{PM}}(\Omega)} + \frac{\xi_{\text{loss}}^4 \mathcal{K}_{\text{PM}}(\Omega)}{1 + \xi_{\text{loss}}^4 e^{-2r}} \right], \quad (14)$$

where a back-action term, proportional to $\mathcal{K}_{\text{PM}}(\Omega)$, persists, albeit reduced by $\approx 1 - \eta$. This presence of back-action leads to

$$\frac{S_{\text{PMVM}}^h}{h_{\text{SQL}}^2} \geq \xi_{\text{loss}}^2 \sqrt{\frac{e^{-2r} + \xi_{\text{loss}}^4}{1 + \xi_{\text{loss}}^4 e^{-2r}}} \quad (15)$$

(see also [18]), with equality achievable at the unique frequency at which two terms in the square brackets in (14) are equal to each other (similar condition and estimate can be found in the abstract to [18]). Thus,

$$\sqrt{S_{\text{PMVM}}^h}/h_{\text{SQL}} = \xi_{\text{loss}} \quad (16)$$

is the best SQL-beating factor one can hope to achieve given η without squeezing. With sufficiently deep squeezing, $e^{-2r} \ll \xi_{\text{loss}}^4$, it is possible to achieve

$$\sqrt{S_{\text{PMVM}}^h}/h_{\text{SQL}} = \xi_{\text{loss}}^2. \quad (17)$$

For $\eta = 0.95$, which is moderately optimistic for current photodiodes, the best loss-limited SQL beating is $\sqrt{S^h}/h_{\text{SQL}} \simeq 0.5$ without squeezing and $\sqrt{S^h}/h_{\text{SQL}} \simeq 0.22$ with squeezing.

It is evident from this simple consideration that optical losses can become a real problem for sub-SQL sensitivity schemes that rely on quantum noise reduction based on optimal correlation between measurement and back action noise.

3 Quantum speed meter

3.1 Overview of speed meter topologies

One way of obtaining a sensitivity better than the SQL is to measure a QND observable that remains unperturbed by the meter's back action during a continuous measurement. Momentum p of a free mass is a QND observable, yet practical ways of directly measuring the momentum of a free mass has not been invented. The closest is to measure the speed v of a test mass — yet as soon as one couples v to an external observable, the canonical momentum p becomes different from mv — and even though the canonical momentum p remains QND, mv will be perturbed by a continuous measurement. Nevertheless, speed meters turn out to offer broadband beating of the SQL more easily than position meters. The basic idea of the quantum speed meter was first proposed by Braginsky and Khalili in [23].

The general approach to speed measurement is to use pairs of position measurements separated by a time delay $\tau \lesssim 1/\Omega$, where Ω is the characteristic signal frequency. The successive measurement should ideally be coherent, i.e., they should be performed by the same photons. In Ref. [24], Braginsky, Gorodetsky, Khalili and Thorne (BGKT) analyzed the microwave speed meter scheme first proposed in [23] in detail, as a possible realization of local meter for an intra-cavity GW detector that will be considered in Sec. 4. This scheme uses two identical coupled microwave resonators, as shown in Fig. 1 (left), one of which (2) is pumped on resonance through the input waveguide, so that another one (1) becomes excited at its frequency ω_e . The eigenfrequency of resonator 1 is modulated by the position x of the test mass, and puts a voltage signal proportional to position x into resonator 2, and a voltage signal proportional

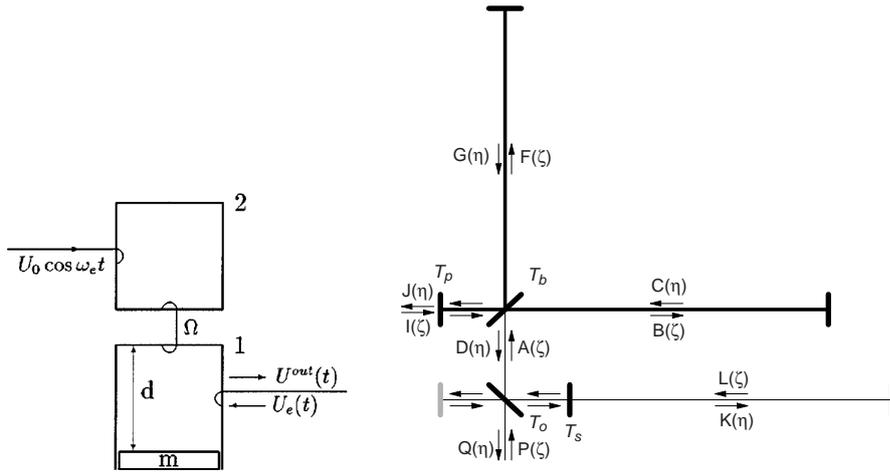


Fig. 1 Left: schematic diagram of the microwave speed meter on coupled cavities as given in [23, 24]. Right: optical version of coupled cavities speed meter proposed in [21].

to velocity dx/dt into resonator 1. The velocity signal flows from resonator 1 into an output waveguide, from which it is monitored. One can understand the production of this velocity signal as follows. The coupling between the resonators causes voltage signals to slosh periodically from one resonator to the other at the frequency Ω . After each cycle of sloshing, the sign of the signal is reversed, so the net signal in resonator 1 is proportional to the difference of the position at times t and $t + 2\pi/\Omega$, *i.e.* is proportional to the test-mass velocity so long as the test mass' frequencies ω of oscillation are $\omega \ll \Omega$. BGKT also proposed a scheme of an optical speed meter based on the same principle, namely to use two coupled Fabry-Pérot cavities, with one pumped resonantly, and the second one kept unexcited and serving as a “sloshing cavity” (see Fig. 4 of [24] for detail). This idea was further elaborated by Purdue, who found that the BGKT two-cavity scheme, although can beat the SQL broadband, requires huge pumping power, and can only evade classical laser noise if two such two-cavity schemes are used simultaneously [25]. Purdue and Chen [21] subsequently improved upon the BGKT two-cavity scheme, converting the differential mode of a Michelson interferometer into cavity 1, and an additional, km-scale cavity into cavity 2, thus making a practical interferometer configuration, see Fig. 1 (right).

Khalili and Levin [26] proposed another version of speed-meter-based GW detector, using a Doppler phase shift that appears in light wave after passing through a moving, rigid, impedance-matched Fabry-Pérot cavity. It was suggested in [26] to attach small rigid Fabry-Pérot resonators to test masses of GW detector and tune them in resonance when at rest. When the cavity starts moving it sees the incoming light Doppler shifted, and the light emerging from the other side gets phase shifted by $\delta\varphi = (\omega_o\tau^*/c)v$, where v is the cavity velocity, while ω_o and $\tau^* \sim \gamma^{-1}$ are its eigenfrequency and ringdown time, respectively. Unfortunately, the requirement that the cavity have to be a stiff one puts limitation on the cavities length and thus on the achievable values of the ringdown time τ^* . An estimate show, that due to this limitation, the optical power in this scheme have to be unrealistically high to compensate the small factor $\omega_o\tau^*/c$.

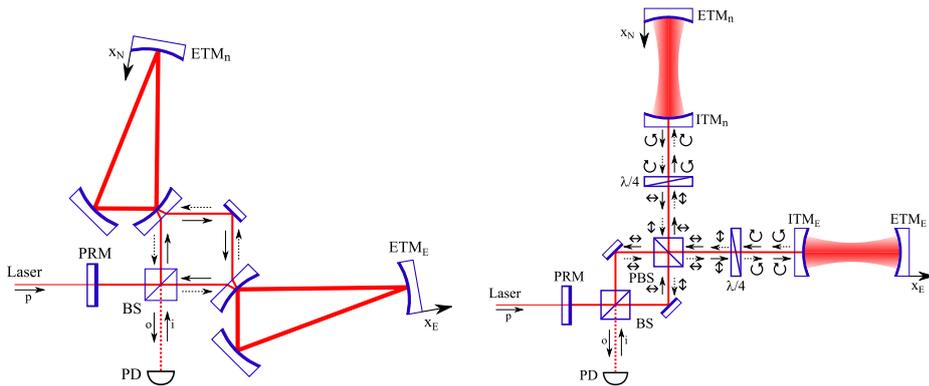


Fig. 2 Two possible optical realizations of zero area Sagnac speed meter. *Left panel:* The ring cavities can be used to spatially separate the ingoing fields from the outgoing ones, in order to redirect output light from one arm to another one [27]. *Right panel:* The same goal can be achieved idea is realized using optical circulator consisting of the polarization beamsplitter (PBS) and two $\lambda/4$ -plates [28, 29].

Later on, the idea to use the zero area Sagnac interferometer [30, 31, 32] as a speed meter was proposed independently by Chen and Khalili [27, 28]. Further analysis with account for optical losses was performed in Ref. [29] and with detuned signal-recycling in Ref. [33]. Suggested configurations are pictured in Fig. 2. The core idea is that light from the laser gets splitted by the beamsplitter (BS) and directed to Fabry-Pérot cavities in the arms, exactly as in conventional Fabry-Pérot—Michelson GW interferometers. However, after it leaves the cavity, it does not go back to the beamsplitter, but rather enters the cavity in the other arm, and only afterwards returns to the beamsplitter, and finally to the photo detector at the dark port. The scheme of Ref. [27] uses ring Fabry-Pérot cavities in the arms to spatially separate ingoing and outgoing light beams to redirect the light leaving the first arm to the second one evading the output beamsplitter. The variant analyzed in Ref. [28, 29] uses polarized optics for the same purposes: light beams after ordinary beamsplitter, having linear (*e.g.*, vertical) polarization, pass through the polarized beamsplitter (PBS), then meet the $\lambda/4$ plates that transforms their linear polarization into circular one, and then enter the Fabry-Pérot cavity. After reflection from the Fabry-Pérot cavity, light passes through $\lambda/4$ -plate again, changing its polarization again to linear, but orthogonal to the initial one. As a result, the PBS reflects it and redirects to another arm of the interferometer where it passes through the same stages, restores finally the initial polarization and comes out of the interferometer. With the exception of the implementation method for this round-robin pass of the light through the interferometer, both schemes has the same performance, and the same appellation “Sagnac speed meter” will be used for them below.

Visiting consequently both arms, counter propagating light beams acquire phase shifts proportional to a sum of end mirrors displacements of both cavities taken with time delay equal to average single cavity storage time τ_{arm} :

$$\delta\phi_R \propto x_N(t) + x_E(t + \tau_{\text{arm}}), \quad \delta\phi_L \propto x_E(t) + x_N(t + \tau_{\text{arm}}). \quad (18)$$

After recombining at the beamsplitter and photo detection the output signal will be proportional to the phase difference of clockwise (R) and counter clockwise (L) prop-

agating light beams:

$$\delta\phi_R - \delta\phi_L \propto [x_N(t) - x_N(t + \tau_{\text{arm}})] - [x_E(t) - x_E(t + \tau_{\text{arm}})] \propto \dot{x}_N(t) - \dot{x}_E(t) + O(\tau_{\text{arm}}) \quad (19)$$

that, for frequencies $\ll \tau_{\text{arm}}^{-1}$, is proportional to relative velocity of the interferometer end test masses. The presence of two counter propagating light beams exciting both arm cavities in a symmetric way allows to mostly keep the traditional optical layout of GW interferometers with two large scale high finesse Fabry-Pérot cavities, minimizing the cost and the operation complexity of this scheme and allowing to switch between the speed meter and ordinary position meter operation modes.

3.2 Speed meter sensitivity

As shown by Chen [27], a mapping exists between zero-area Sagnac and Michelson speed meters, if tuned signal recycling is considered: both are characterized by two optical resonators, with resonant frequencies located symmetrically around the carrier frequency. Henceforth, we will use Sagnac speed meters as representative for different possible speed meter realizations.

The quantum noise spectral density of a lossless speed meter is similar in form to Eq. (1)

$$S_{\text{SM}}^h = \frac{h_{\text{SQL}}^2}{2} \frac{e^{-2r} + [\cot \zeta - \mathcal{K}_{\text{SM}}(\Omega)]^2 e^{2r}}{\mathcal{K}_{\text{SM}}(\Omega)}, \quad (20)$$

where \mathcal{K}_{SM} is the optomechanical coupling of the speed meter as given in Ref. [27]

$$\mathcal{K}_{\text{SM}}(\Omega) = \frac{4I_c}{I_c^{\text{SQL}}} \frac{\gamma^4}{(\gamma^2 + \Omega^2)^2}, \quad (21)$$

and

$$I_c = 8 I_{\text{BS}}/T. \quad (22)$$

Note that for a given I_{BS} , this I_c is twice that of the position meter [Cf. Eq. (4)], because here each beam visits both arms sequentially after leaving the beamsplitter.

The key advantage of speed meters over position meters is that at low frequencies, $\Omega < \gamma$, \mathcal{K}_{SM} is approximately constant and reaches maximum there

$$\mathcal{K}_{\text{SM}}(\Omega \ll \gamma) \approx 4I_c/I_c^{\text{SQL}}. \quad (23)$$

As a consequence, a *frequency-independent* readout quadrature optimized for low frequencies can be used:

$$\zeta = \text{arccot} \mathcal{K}_{\text{SM}}(0) = \text{arccot}(4I_c/I_c^{\text{SQL}}), \quad (24)$$

which gives the following spectral density

$$S_{\text{SM LF}}^h = \frac{h_{\text{SQL}}^2(\Omega)}{2} \left[\frac{e^{-2r}}{\mathcal{K}_{\text{SM}}(\Omega)} + \frac{\Omega^4(2\gamma^2 + \Omega^2)^2}{\gamma^8} \mathcal{K}_{\text{SM}}(\Omega) e^{2r} \right]. \quad (25)$$

Here the radiation-pressure noise (second term in bracket) is significantly suppressed in low frequencies ($\Omega \lesssim \gamma$), and $S_{\text{SM LF}}^h$ can beat the SQL in a broad frequency band. By contrast, this is not possible for position meters, which have $\mathcal{K}_{\text{PM}} \sim 1/\Omega^2$, see Fig. 3 (left panel).

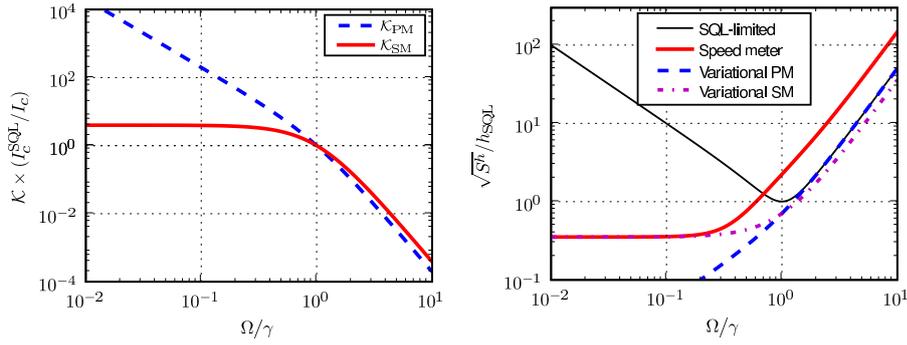


Fig. 3 Variational position meter compared with speed meter. Left panel: optomechanical coupling factors for position meter (\mathcal{K}_{PM} and speed meter (\mathcal{K}_{SM}) as functions of signal frequency Ω . Right panel: SQL beating factors $\sqrt{S^h}/h_{\text{SQL}}$ for low frequency optimized speed meter interferometer (Speed meter), variational position meter (Variational PM), variational speed meter (Variational SM), and SQL-limited interferometer. In all cases, $I_c e^{2r} = I_c^{\text{SQL}}$.

Variational readout technique [18] discussed in Sec. 2.2 can also be used to enhance the speed meters performance [21]. The optimal frequency-dependent readout quadrature is given by

$$\zeta = \text{arccot } \mathcal{K}_{\text{SM}}(\Omega), \quad (26)$$

which gives a noise spectral density without the back action term:

$$S_{\text{SM VM}}^h = \frac{h_{\text{SQL}}^2 e^{-2r}}{2\mathcal{K}_{\text{SM}}(\Omega)}. \quad (27)$$

In right panel of Fig. 3 we plot the SQL-beating factors $\sqrt{S^h}/h_{\text{SQL}}$ for low-frequency optimized speed meter (25), variational position (9) and speed meters (27). For comparison, $\sqrt{S^h}/h_{\text{SQL}}$ for the SQL-limited interferometer (6) is also given. One might conclude from these plots that the variational position meter is clearly better than the speed meter (except for high frequency area where the most sophisticated scheme of variational speed meter has some marginal advantage) — however in the next subsection we demonstrate that optical losses change this picture radically.

3.3 Optical losses in speed meters

In speed meters, optical losses in the arm cavities significantly affect the sum noise at low frequencies, even if $1 - \eta_{\text{cav}} \ll 1 - \eta$, because the radiation pressure noise component created by the arm cavities losses has frequency dependence similar to the one for position meters (remind that $\mathcal{K}_{\text{PM}}/\mathcal{K}_{\text{SM}} \rightarrow \infty$ if $\Omega \rightarrow 0$, see Fig. 3, left). In this paper, we will use the following expression for the lossy speed meter sum noise (which is still simplified, but takes the losses frequency dependence into account; more detailed treatment of the lossy speed meter can be found in papers [21, 29]):

$$S_{\text{SM}}^h = \frac{h_{\text{SQL}}^2}{2} \left\{ \frac{e^{-2r} + \xi_{\text{loss}}^4 / \sin^2 \zeta + [\cot \zeta - \mathcal{K}_{\text{SM}}(\Omega)]^2 e^{2r}}{\mathcal{K}_{\text{SM}}(\Omega)} + \xi_{\text{cav}}^4 \mathcal{K}_{\text{PM}}(\Omega) \right\}, \quad (28)$$

where $\xi_{\text{cav}} = \sqrt[4]{(1 - \eta_{\text{cav}})/\eta_{\text{cav}}}$.

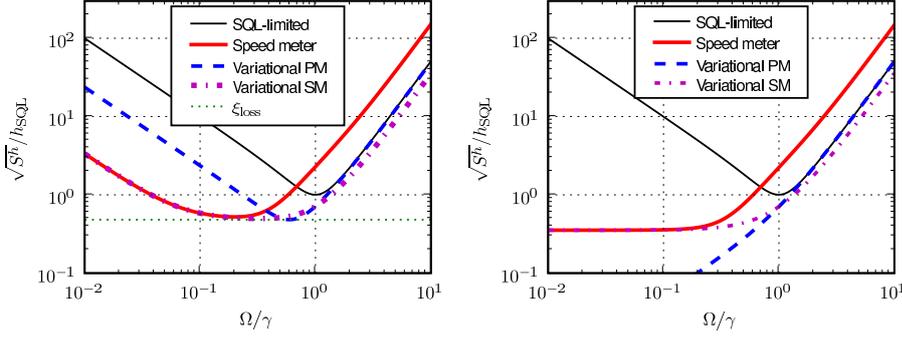


Fig. 4 SQL beating factors $\sqrt{S_h}/h_{\text{SQL}}$, in presence of optical losses ($\eta = 0.95$, $\eta_{\text{cav}} = 1 - 10^{-3}$), for: low frequency optimized Sagnac speed meter interferometer (Speed meter), variational position meter (Variational PM), variational Sagnac speed meter (Variational SM). Left panel: $I_c = I_c^{\text{SQL}}$ and $r = 0$ (no squeezing). Right panel: $I_c e^{2r} = 0.1 I_c^{\text{SQL}}$ and $e^{2r} = 10$. On both panels, $\sqrt{S_h}/h_{\text{SQL}}$ of lossless SQL-limited interferometer with $I_c e^{2r} = I_c^{\text{SQL}}$ is plotted for comparison (SQL-limited).

The low-frequency optimized detection angle, in presence of loss, is

$$\zeta = \arccot \frac{\mathcal{K}(0)}{1 + \xi_{\text{loss}}^4 e^{-2r}} = \arccot \frac{4I_c/I_c^{\text{SQL}}}{1 + \xi_{\text{loss}}^4 e^{-2r}}, \quad (29)$$

which gives

$$S_{\text{SM LF}}^h = \frac{h_{\text{SQL}}^2}{2} \left\{ \frac{e^{-2r} + \xi_{\text{loss}}^4}{\mathcal{K}_{\text{SM}}(\Omega)} + \frac{\mathcal{K}_{\text{SM}}(\Omega)}{1 + \xi_{\text{loss}}^4 e^{-2r}} \left[\frac{\Omega^4 (\Omega^2 + 2\gamma^2)^2}{\gamma^8} e^{2r} + \xi_{\text{loss}}^4 \right] + \xi_{\text{cav}}^4 \mathcal{K}_{\text{PM}}(\Omega) \right\}, \quad (30)$$

[compare with Eq. (25) and note the additional residual back action term similar to one in Eq. (14)].

For a lossy variational speedmeter, repeating calculations of Sec. 2.3, we obtain

$$\zeta(\Omega) = \arccot \frac{\mathcal{K}_{\text{SM}}(\Omega)}{1 + \xi_{\text{loss}}^4 e^{-2r}}, \quad (31)$$

which results in a total noise spectrum of

$$S_{\text{SM VM}}^h = \frac{h_{\text{SQL}}^2}{2} \left[\frac{e^{-2r} + \xi_{\text{loss}}^4}{\mathcal{K}_{\text{SM}}(\Omega)} + \frac{\xi_{\text{loss}}^4 \mathcal{K}_{\text{SM}}(\Omega)}{1 + \xi_{\text{loss}}^4 e^{-2r}} + \xi_{\text{cav}}^4 \mathcal{K}_{\text{PM}}(\Omega) \right]. \quad (32)$$

It is easy to see that both low-frequency optimized and variational speed meters, optical losses impose the same fundamental limitation (15) on the SQL beating factor $\sqrt{S_h}/h_{\text{SQL}}$.

In Fig. 4, the factors $\sqrt{S_h}/h_{\text{SQL}}$ for low frequency optimized lossy speed meter (30) and lossy variational position and speed meters (14, 32) are plotted, for $I_c = I_c^{\text{SQL}}$ without squeezing (left panel) and $I_c = 0.1 I_c^{\text{SQL}}$ with 10 dB squeezing (right panel). In both cases, realistic parameter $\eta = 0.95$ and $\eta_{\text{cav}} = 1 - 10^{-3}$ are assumed. These plots

indicate that in presence of optical loss, the speed meter provides better broadband low-frequency sensitivity than variational position meters.

These plots also suggest that the interferometer's bandwidth γ should be larger than the band of interest. This sets a minimum requirement for I_c^{SQL} [Cf. Eq. (5)], and thus the necessary optical circulating power I_c . However, if a speed meter is only used for lower frequencies, the necessary optical power may not be very high, even without the squeezing. For example, $M = 200$ kg, $L = 10$ km, and $\gamma = 100$ s $^{-1}$, then $I_c^{\text{SQL}} \approx 80$ kW — only four times as high as in the initial LIGO detector. On the other hand, for higher working frequencies, the power requirements increase sharply. For example, $\gamma = 2\pi \times 100$ s $^{-1}$ requires $I_c^{\text{SQL}} \approx 20$ MW.

3.4 Detuned speed meter and optical inertia

So far we considered only resonance tuned Sagnac speed meter. A convenient way of detuning the Sagnac interferometer is to use the signal-recycled topology originally proposed by Meers [34]: an additional mirror is placed at the dark output port of the interferometer, reflecting parts of the signal modulation fields back into the interferometer and forming a cavity together with the input mirrors of the interferometer's arm cavities. When this new cavity is neither resonant nor anti-resonant with respect to the carrier frequency, the signal mode of the interferometer also becomes detuned, and the interferometer has a peak sensitivity around a non-zero resonant frequency. Nearly all second generation GW detectors will make use of this technique.

In a detuned position meter, the optomechanical coupling induces a restoring force onto the differential mode of the arm-cavities mirrors [35, 36, 20]: motion of mirrors produce phase modulation of the out-going light, which, through detuning, gets converted into amplitude modulation and acts back onto the mirrors as a position-dependent force. This *optical spring* can shift the pendulum frequency of the mirror and move it into the detection band. In this case the interferometer's sensitivity has two peaks, one around the original optical resonance due to detuning, the other due to the upshifted mechanical resonance. A full explicit expression for the quantum noise spectral density can be found in Eq. (37) of Ref. [20].

The detuned Sagnac interferometer has also two resonances but both are of optical nature, due to the existence of two optical resonators in the system; differently from position meters, the optomechanical coupling in a Sagnac modifies the dynamical mass of the mirrors, adding an *optical inertia* [33, 37]. In a Sagnac, amplitude modulation a entering from the dark port act successively on both cavities, and in low frequencies

$$F_{\text{RP}}^{\text{N}} - F_{\text{RP}}^{\text{E}} \propto \dot{a}(t). \quad (33)$$

In a detuned situation, a contains some of the out-going phase modulation, which is proportional to $\dot{x}_{\text{N}} - \dot{x}_{\text{E}}$, and therefore the radiation-pressure force contains the mirrors' *acceleration*:

$$F_{\text{RP}}^{\text{N}} - F_{\text{RP}}^{\text{E}} \propto -M_{\text{opt}} (\ddot{x}_{\text{N}} - \ddot{x}_{\text{E}}). \quad (34)$$

Here M_{opt} is the effective optical inertia which can be either positive or negative. Because this treatment is true for all frequencies below the optical resonances, it is possible to achieve $M + M_{\text{opt}} \ll M$ for a broad frequency band — this leads to a broadband amplification of GW signal, and may allow us to circumvent the fundamental limit of (15) imposed by optical losses.

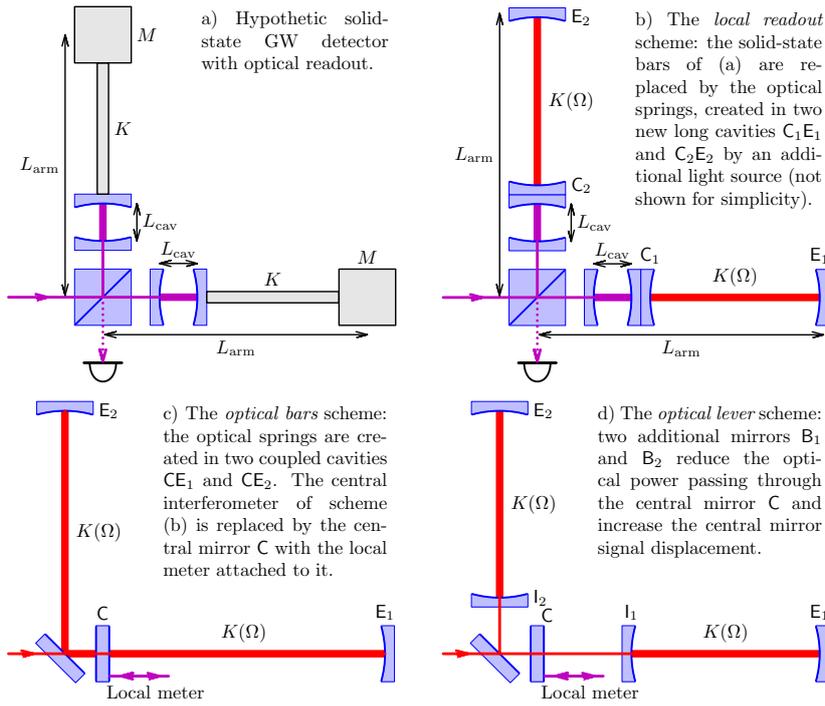


Fig. 5 Transition from the solid-state bar detector to the optical bars/optical lever intracavity readout scheme.

4 Intracavity measurement

4.1 The idea of “optical bars” and “optical lever” topologies

QND versions of traditional interferometer schemes, like, for example, quantum speed meter considered in the previous section, allow to suppress the back-action noise. What remains is (in the ideal lossless case) the pure measurement noise, which spectral density has the following general structure:

$$S^h = \frac{4}{L^2} S^x, \quad (35)$$

where the equivalent position noise spectral density S^x , for given value of γ , is proportional to the arms length L , see, *e.g.* Eqs. (9, 27), and inversely proportional to circulating power I_c . Therefore, the *displacement* sensitivity can be improved (that is, S_x can be reduced) by simple increase of power and by using interferometers with shorter arms length L . However, the signal displacement itself is proportional to the length of the arms:

$$x = Lh/2 \quad (36)$$

[hence the factor $4/L^2$ in Eq. (35)], and therefore, sensitivity for the GW signal h goes down with the arm length decrease.

In this reasoning, one important assumption was made silently, namely, that the values of L which appear in Eq. (36) and in S^x , are equal to each other. This is the

case for contemporary laser interferometric GW detectors, but is not, for example, for solid-state ones. Consider a hypothetic bar detector with optical readout shown in Fig. 5(a). Here two stiff bars transfer displacements of the test masses, produced by the GW signal, to end mirrors of the standard Fabry-Pérot—Michelson interferometer. In principle, in this case the arms length L_{arm} [which appears in Eq. (36)], can be much longer than the cavities length L_{cav} (which appears in S^x), and the optical power in the interferometer can be reduced proportionally to $L_{\text{cav}}/L_{\text{arm}}$ without loss of the sensitivity.

The “only” necessary condition here is that the bars rigidity K has to be strong enough to provide the lowest mechanical eigenfrequency higher than the signal frequency Ω . Of course, for kilometer-scale arms of modern GW detectors, this condition can not be fulfilled using ordinary solid-state bars. However, they can be replaced by two new long Fabry-Pérot cavities, where, using an additional detuned pumping, the optical spring can be created [38,39,36], see Fig. 5(b). In essence, this is the so-called *local readout* topology considered in [41].

The first proposed intracavity readout scheme, the *optical bars* one [42], was based on the same principle. It is shown in Fig. 5(c). Here optical springs are created in the system of two cavities CE_1 and CE_2 coupled by means of partly transparent central mirror C . Optical eigenfrequencies of this system form a set of doublets, with frequencies in each doublet separated by the sloshing frequency

$$\Omega_B = \frac{c\sqrt{T_C}}{L}, \quad (37)$$

where T_C is the central mirror power transmissivity. If the upper frequency mode of some of the doublets is pumped then optical field acts as two springs one of which is located between the mirrors E_1 and C and the second one (L-shaped) — between the mirrors E_2 and C , with the rigidities equal to

$$K(\Omega) \approx \frac{4\omega_o I_c^{\text{bar}}}{Lc} \frac{\Omega_B}{\Omega_B^2 - \Omega^2}, \quad (38)$$

where I_c^{bar} is the optical power circulating in each of these cavities. Similar to previous two schemes, these springs transfer displacement of the end mirrors E_1 , E_2 , produced by the GW signal, to the central mirror C_1 displacement. This displacement, in turn, has to be monitored by attaching *local meter* to it, which plays the role of the central interferometer in schemes of Figs. 5(a,b).

Mechanical dynamics of the *optical bars* system, with its three movable mirrors coupled by means of frequency-dependent rigidity (38), is quite sophisticated. Depending on mirrors masses, optical power I_c^{bar} and sloshing frequency Ω_B , it can have two resonances (the mechanical and the optical ones [36]), or one second-order resonance [39], which can significantly increase the central mirror signal displacement in narrow band. However, in typical broadband regimes with flat mechanical transfer function, which are more interesting for GW experiments, the signal displacements of the central mirror meter is equal to displacement of the end mirrors:

$$x_s(\Omega) = \frac{M_E}{2M_E + M_C} Lh(\Omega), \quad (39)$$

where $h(\Omega)$ is the GW signal (see the next subsection for more detail).

In the article [43] an improved version of the *optical bars* scheme, which allows to increase x_s , was proposed. It differs from the original one by two additional mirrors I_1

and l_2 , see Fig. 5(d), which turn the arms into two Fabry-Pérot cavities. This scheme was called *optical lever* because the signal displacement gain which it provides is similar to the one which can be obtained by ordinary mechanical lever with arms lengths ratio equal to

$$F = \frac{2}{\pi} \mathcal{F}, \quad (40)$$

where \mathcal{F} is the finesse of these Fabry-Pérot cavities. With this addition, Eq. (39) takes the following form:

$$x_s(\Omega) = \frac{F M_{\text{arm}}}{2M_{\text{arm}} + F^2 M_C} Lh(\Omega), \quad (41)$$

where

$$M_{\text{arm}} = \frac{M_E M_I}{M_E + M_I} \quad (42)$$

is the reduced mass of the new arm cavities mirrors.

4.2 The optical bars regimes

It follows from this consideration, that the optical bars approach allows to replace the task of measurement of tiny variations of relative position of test masses separated by kilometers-scale distances by much more easy task of measurement of the same or, in the *optical lever* case, even amplified displacements of test masses located close to each other (the central mirror C relative to a reference object placed outside of the optical field).

The evident price is the additional long cavities where optical bars have to be created. The optical power requirements for these cavities were estimated in Sec. 4 of paper [44]. Assuming, that the central mirror mass is sufficiently small:

$$M_C < \frac{M_{\text{arm}}}{F^2}. \quad (43)$$

which maximizes its signal displacement, and signal frequencies are below the sloshing frequency: $\Omega < \Omega_B$, three working regimes are available, depending on the optical power.

Strong pumping:

$$K(0) = \frac{4\omega_o I_c^{\text{bar}}}{Lc\Omega_B} > M_{\text{arm}}\Omega^2. \quad (44)$$

In this regime, optical bars work as absolutely stiff rods, transferring 100% of signal displacement of the end mirror to the central one [see Eqs. (39, 41)], and *vice versa*, the local meter back action force from the central mirror to the end ones. The simplest option for the local meter in this case is just an ordinary position meter with the sensitivity corresponding to the SQL for the equivalent mass M_{arm}/F^2 :

$$S_x^{\text{local}}(\Omega) \simeq \frac{2\hbar F^2}{M_{\text{arm}}\Omega^2}. \quad (45)$$

Due to amplification factor F , the net sensitivity in this case corresponds to the SQL for the mass M_{arm} :

$$S_x(\Omega) \simeq \frac{2\hbar}{M_{\text{arm}}\Omega^2}. \quad (46)$$

Of course, using a QND local meter with sub-SQL sum noise, proportionally better sensitivity can be obtained.

The optical power required to create such stiff optical bars is relatively high. It follows from Eq. (44), that there has to be

$$I_c^{\text{bar}} > \frac{M_{\text{arm}} L c \Omega_B^3}{4\omega_o}. \quad (47)$$

The right hand side is equal to I_c^{SQL} of the interferometer with the same arms length, mirrors mass, and with the bandwidth γ equal to Ω_B , see Eq. (5). It is important, however, that I_c^{bar} does not depend on the required sensitivity (which is defined by the local meter), while in the ordinary topologies, the power increases as square of the signal displacement which has to be detected, see, *e.g.*, Eqs. (9, 27).

Intermediate pumping:

$$F^2 M_C \Omega^2 < K(0) = \frac{4\omega_o I_c^{\text{bar}}}{L c \Omega_B} < M_{\text{arm}} \Omega^2. \quad (48)$$

This regime, being the most interesting one, was considered in detail in paper [45]. Here, the optical bars are stiff enough to provide Eqs. (39, 41), but not enough to transfer the local meter back action force to the heavy end mirrors. As a result, the local meter “sees” an additional back action noise. However, this noise can be excluded from the local meter output signal using frequency-independent cross correlation of the measurement and back-action noises. This kind of the noises correlation can be created relatively easy using homodyne detector with properly set homodyne angle ζ to measure local meter output signal. In this case, the same sensitivity (46) as in the previous case can be obtained, but with significantly less optical power in the “optical bar” cavities. Similar to the previous case, a QND local meter with sub-SQL sum noise will be able to provide proportionally better sensitivity.

It was shown in paper [45], that the most fundamental limitation on optical power in this regime is imposed by the power fluctuations in the “optical bar” cavities, created by the optical losses. Perturbation of the central mirror position by the random force, produced by these fluctuations, is characterized by the following spectral density:

$$S_{\text{loss}} \simeq \frac{\hbar L c}{4\omega_o I_c^{\text{bar}}} \gamma. \quad (49)$$

This equation has the the structure similar to the displacement noise spectral densities S^x of “ordinary” interferometers, with γ replaced by some frequency dependent factor of the same order of magnitude. However, in the latter case, there has to be $\gamma \gtrsim \Omega_{\text{GW}}$, where $\Omega_{\text{GW}} \sim 10 - 100 \text{ s}^{-1}$ is characteristic GW signal frequency, while in former one, γ is limited only by the optical losses in the arm cavities:

$$\gamma = \frac{c A^2}{4L} \quad (50)$$

and, for $L \sim 10 \text{ km}$ and $A^2 \sim 10^{-5}$, can be as small as $\gamma \sim 0.1 \text{ s}^{-1}$. This bandwidth corresponds to the 2-3 orders of magnitude smaller value of the noise spectral density for the same optical power, or, alternatively, to 2-3 orders of magnitude lower optical power for the same spectral density.

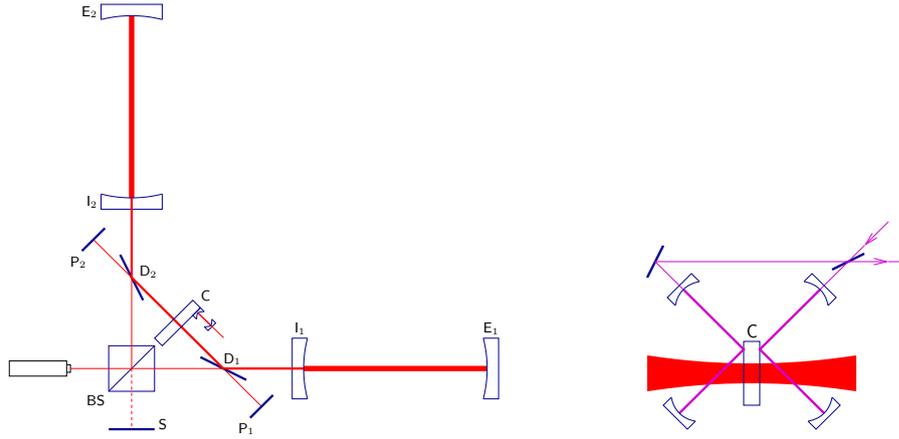


Fig. 6 Left: practical version of the *optical lever* intracavity scheme. Right: a possible topology of the local meter.

Weak pumping:

$$K(0) = \frac{4\omega_o I_c^{\text{arm}}}{Lc\Omega_B} < F^2 M_C \Omega^2. \quad (51)$$

In this regime, central mirror signal displacement does not reach the level of Eqs. (39, 41). Therefore, more sensitive QND local meter is required. Taking also into account that reduced optical power means increased noise (49), it can be concluded that at present this regime can not be considered as interesting one.

4.3 Implementation issues

It follows from the above estimates, that central mirror C, while being relatively small, has to tolerate significant incident optical power. In case of the original *optical bars* scheme, the reasonable mass of this mirror can be few kilograms, and the optical power — up to hundreds of kilowatts. In the *optical lever* scheme, light power impinging on central mirror is F times smaller, but the mass has to be F^2 lighter (down to sub-gram range). However, the power which *passes through* the central mirror can be radically decreased by using the mirror with both surfaces carrying reflective coatings. The short Fabry-Pérot cavity formed by these two coatings has to be tuned in anti-resonance. In this case, the amplitude transmissivity of this mirror will be equal to the square of one coating transmissivity, and power inside the mirror will be reduced by the factor equal to finesse of this cavity.

Some other implementation issues were addressed in paper [46], where more practical version of the *optical lever* intracavity topology, shown in Fig. 6, was considered. The following improvements were proposed.

Symmetrization of the topology. The evident disadvantage of simple schemes shown in Fig. 5(c,d) is their asymmetry: pumping power enters the “north” (vertical on the picture) arm first and only then, through the coupling mirror C, the “east” one. Due to this asymmetry the input optical field amplitude fluctuations will create differential

pondermotive force acting on the central mirror and imitating gravitational-wave signal. In order to eliminate this effect, symmetric power injection scheme has to be used. It consists of the beamsplitter BS and two power injection mirrors D_1 and D_2 placed symmetrically on both sides of the central mirror C.

Power recycling mirrors. Without power recycling mirrors P_1, P_2 one quarter of input power is reflected from the mirrors D_1 and D_2 back to the laser, another quarter is reflected to the side direction, and only one half enters the scheme. The mirrors P_1, P_2 cancel both reflected beams and increase twice the circulating power inside the scheme, for the same value of input power.

Signal recycling mirror. The power injection mirrors $D_{1,2}$ transmittances create an additional source of optical losses in the scheme. It can be removed using symmetry of the scheme. Indeed, similar to traditional interferometric gravitational-wave detectors topology, the mean value of optical power circulating inside the scheme depends on the bandwidth of the symmetric optical mode which is coupled to the “western” port of the beamsplitter, and the detector sensitivity depends on the bandwidth of anti-symmetric mode which is coupled to “south” port of the beamsplitter. The only difference is that in traditional topology the anti-symmetric mode bandwidth has to be close to the signal frequency Ω to provide optimal coupling to photodetector, while in the intracavity topology it has to be as small as possible. Therefore, high-reflectivity signal recycling mirror S has to be placed in the “south” port as shown in Fig. 6.

5 Discussion

Our estimates show that use of speed meter topology could provide at least two to threefold reduction of quantum noise level in relatively wide frequency band with respect to the level of free mass Standard Quantum Limit, with this limitation mostly owing to optical losses in readout photodetectors. Using injection of squeezed vacuum into the interferometer dark port, it is possible to overcome the SQL by 4-5 times, but in narrower band of frequencies (see formula (15) and the discussion thereunder). Optical losses in arm and filter cavities for variational readout schemes, though being order or two of magnitude lower than those of photodetectors, show up in low frequencies due to the inherent frequency dependence they enter the final quantum noise spectral density, thus limiting the useful frequency bandwidth of the interferometer.

However, as we have shown variational speed meter is less susceptible to this loss source than the position meter, thus making the former evident candidate for implementation, given the traditional Michelson-like topology and only slight deviation from well established and robust techniques of the first generation detectors are chosen as a strategy of development towards the third generation devices. Worth noting is the fact, that due to the flat low-frequency behavior of the speed meter quantum noise spectral density, even modest SQL-beating factor leads to a huge sensitivity gain compared to conventional SQL-limited interferometers, see for example Fig. 4, where this gain reaches two orders of magnitude.

An important issue is the optical power that has to circulate in the interferometers to achieve sub-SQL sensitivity. It depends sharply (as $\sim \Omega^3$) on the signal frequency Ω (in part, because the free mass SQL for GW signal h (and displacement x) itself

depends on frequency as $\sim \Omega^{-1}$) and could potentially be a serious problem for detectors, targeted at higher frequencies. The evident way to relax this requirement is to use squeezing. However, this solution is also severely limited by optical losses in photodetectors, deteriorating injected light squeeze factor as a result of mixing with loss related vacuum fields. For example, moderate optimistic value of the unified quantum efficiency $\eta = 0.95$ limits the effective squeeze factor to $\lesssim 13$ dB.

Another possibility to increase sensitivity we consider here is to use intracavity readout schemes. The main advantage of these schemes is that their sensitivity can be increased without increase of optical power. Only some fixed threshold value of the power is required in order to create sufficiently stiff optical springs. This value is governed mainly by optical losses and can be much smaller than I_c^{SQL} . The gain in the optical power is proportional to the ratio of interferometer bandwidths required for ordinary and intracavity readout schemes respectively. In the first case, the bandwidth has to be of the same order of magnitude as the desired GW signal band, namely $10 - 100 \text{ s}^{-1}$. In the second one, it is limited only by the mirrors absorption and can be as small as 0.1 s^{-1} [see discussion around equation (49)].

An important implementation advantage of the intracavity schemes is that costly part of the setup, namely kilometer-scale optical cavities, is, in essence, nothing more than a simplified version of the “ordinary” signal-recycled interferometer without any readout optics, except for those used for the scheme locking. On the other hand, the intracavity scheme performance is mostly defined by the sensitivity of its second, cheaper because of small size, but completely not developed part: the local meter. It is easy to see, that in the flat sensitivity area $\Omega < \Omega_B$, the SQL beating factor of the whole scheme is equal to one of the local meter. Therefore it has to make use of some QND technique described in our review, or others not mentioned here due to limited scope of this article.

Another important issue is classical noises in the local meter. On the one hand, smaller test mass means increased suspension and mirror surface noises (due to smaller laser beam radius). On the other hand, the optical lever topology allows to increase the signal displacement of the mirror. This issue was discussed briefly in the paper [40], where it was shown that reducing the mirror mass at least does not degrade the signal to noise ratio.

It is not obligatory for the local meter to be an optical device, moreover it could be a SQUID-based microwave QND-meter, like speed meters of [23,24], or some other high precision superconductive sensor. More traditional for laser gravitational-wave detectors optical sensors with time-domain variational readout (see [46] and references therein) could also be considered as an options.

An interesting intermediate variant which does not differ so radically from traditional schemes is a detuned signal-recycled Michelson interferometer where the differential motion of the end mirrors is coupled to the differential motion of the input ones by the optical springs, and the input mirrors motion is monitored by means of the second pump (the local readout scheme [41]). If the output port of the main interferometer is closed, then Eqs. (38, 39) also hold with Ω_B replaced by optical resonance frequency [36], I_c^{bar} by I_c , M_C by the mass of the input mirrors and M_E by the reduced mass of the end mirrors.

Summing up, we can conclude that intracavity schemes can potentially beat the SQL by larger factor than more traditional extracavity detectors using much smaller circulating optical power, given substantial research effort is put on development of high precision small scale local meter.

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